

$$\textcircled{1} \sum_{k=0}^n \binom{n}{k} p^k (1-p)^{n-k} \stackrel{!}{=} 1$$

Wzór obinunowy Newtona:

$$[p + (1-p)]^n = 1^n$$

$$b) \sum_{k=0}^n \binom{n}{k} k p^k (1-p)^{n-k} = np$$

$$\sum_{k=1}^n \binom{n}{k} k p^k (1-p)^{n-k} = *$$

$$\binom{n-1}{k-1} = \frac{(n-1)!}{(k-1)! (n-1-(k-1))!} = \frac{(n-1)!}{(k-1)! (n-k)!}$$

$$\binom{n-1}{k-1} \frac{n}{k} = \binom{n}{k}, \quad k \neq 0$$

$$* = \sum_{k=1}^n k \cdot \frac{n}{k} \binom{n-1}{k-1} p^k (1-p)^{n-k}$$

$$= n \sum_{k=1}^n \binom{n-1}{k-1} p^k (1-p)^{n-k}$$

$$= n \sum_{k=0}^{n-1} \binom{n-1}{k} p^{k+1} (1-p)^{n-k-1} =$$

$$= np \underbrace{\sum_{k=0}^{n-1} \binom{n-1}{k} p^k (1-p)^{n-1-k}}_{(p+1-p)^{n-1}} = np$$

$$\textcircled{2} \text{ a) } \sum_{k=0}^{\infty} e^{-\lambda} \frac{\lambda^k}{k!} = 1$$

$$\frac{1}{e^{-\lambda}} \sum_{k=0}^{\infty} \frac{\lambda^k}{k!} \quad \begin{array}{l} \text{Szereg} \\ \text{Maclaurine} \end{array} \quad \text{dla } e^x = \sum_{n=0}^{\infty} \frac{x^n}{n!}$$

$$\frac{1}{e^{-\lambda}} \cdot e^{\lambda} = 1$$

$$\text{b) } \sum_{k=0}^{\infty} k e^{-\lambda} \frac{\lambda^k}{k!} = \lambda$$

$$\frac{1}{e^{-\lambda}} \sum_{k=0}^{\infty} \frac{k \lambda^k}{k!} = \frac{1}{e^{-\lambda}} \sum_{k=0}^{\infty} \frac{\lambda^k}{(k-1)!} = \frac{1}{e^{-\lambda}} \sum_{k=1}^{\infty} \frac{\lambda \lambda^{k-1}}{(k-1)!}$$

$$= \frac{\lambda}{e^{-\lambda}} \cdot \underbrace{\sum_{k=0}^{\infty} \frac{\lambda^k}{k!}}_{e^{-\lambda} \text{ Maclaurin}} = \frac{\lambda}{e^{-\lambda}} \cdot e^{-\lambda} = \lambda$$

$$\textcircled{3} \quad \Gamma(p) = \int_0^{\infty} t^{p-1} e^{-t} dt, \quad p > 0$$

$$T: \quad \Gamma(n) = (n-1)!, \quad n \in \mathbb{N}$$

$$\Gamma(1) = \int_0^{\infty} t^0 e^{-t} = \int_0^{\infty} e^{-t} = -e^{-t} \Big|_0^{\infty} = 1$$

Wystarczy pokazać że  $\Gamma(n) = n \Gamma(n-1)$

Corakujemy przez wzór  $\left[ \int f g' = f g - \int f' g \right]$

$$\int_0^{\infty} t^{p-1} (-e^{-t})' dt = \left[ t^{p-1} e^{-t} \right]_{t=0}^{\infty} - \int_0^{\infty} (p-1) t^{p-2} (-e^{-t}) dt$$

$$\underbrace{\left[ \frac{t^{p-1}}{e^t} \right]_{t=0}^{t=\infty}}_{=0} + \int_0^{\infty} (p-1) t^{p-2} e^{-t} dt =$$

$$(p-1) \int_0^{\infty} t^{p-2} e^{-t} dt = (p-1) \Gamma(p-1) \quad \blacksquare$$

$$④ f(x) = \lambda \exp(-\lambda x), \lambda > 0$$

$$a) \int_0^{\infty} f(x) dx$$

$$\int_0^{\infty} \lambda e^{-\lambda x} dx \quad \begin{matrix} -\lambda x = t \\ -\lambda dx = dt \end{matrix}$$

$$= \int_0^{\infty} e^t dt = - (e^t) \Big|_{t=0}^{\infty}$$

$$\lim_{T \rightarrow \infty} \left( -\frac{1}{e^{\lambda T}} - (-e^0) \right) = 1$$

$$b) \int_0^{\infty} x f(x) dx = \int_0^{\infty} x \lambda e^{-\lambda x} dx$$

$$\int_0^{\infty} x \lambda (-e^{-\lambda x})' = \underbrace{\int_0^{\infty} [x(-e^{-\lambda x})]}'_{\text{"przez części"}} - \int_0^{\infty} -e^{-\lambda x} dx =$$

$$\left[ -\frac{e^{-\lambda x}}{-\lambda} \right]_{x=0}^{\infty} = \frac{e^0}{\lambda} = \frac{1}{\lambda}$$

$$⑤ \quad D_n = \begin{bmatrix} 1 & -1 & -1 & \dots & -1 \\ 1 & 1 & & & \\ 1 & & 1 & & \\ \vdots & & & \ddots & \\ 1 & & & & 1 \end{bmatrix} \rightarrow \begin{bmatrix} n & 0 & 0 & \dots & 0 \\ 1 & 1 & & & \\ 1 & & 1 & & \\ \vdots & & & \ddots & \\ 1 & & & & 1 \end{bmatrix}$$

Dodajemy  $w_1 := \sum_{k=2}^n w_k$ , gdzie  $w_i$  -  $i$ -ty wiersz macierzy  
 Otrzymujemy macierz trójkątną której wyznacznik  
 łatwo policzyć

$$D_n = n \cdot 1 \cdot 1 \cdot 1 \dots \cdot 1 = n$$



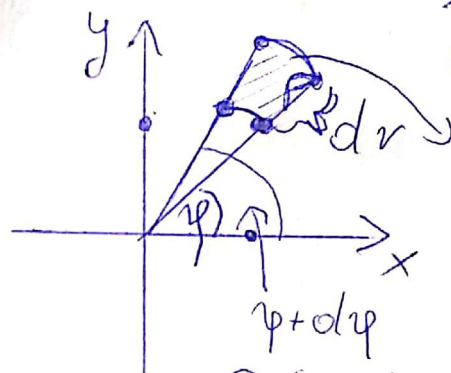
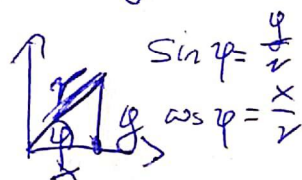
$$\textcircled{6} \quad I = \int_{-\infty}^{\infty} \exp\left(-\frac{x^2}{2}\right) dx$$

$$I^2 = \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} \exp\left\{-\frac{x^2+y^2}{2}\right\} dy dx$$

$x = r \cos \varphi, y = r \sin \varphi$  - współrzędne biegunowe

$T: I^2 = 2\pi \quad x^2 + y^2 = r^2$  - koło

$(x, y) \rightarrow (r, \varphi)$



$$\int dr d\varphi$$

Jakobian przekształcenie liniowego

$$x = r \cos \varphi$$

$$y = r \sin \varphi$$

$$|J| = \frac{\partial(x, y)}{\partial(r, \varphi)} = \begin{vmatrix} \frac{\partial x}{\partial r} & \frac{\partial x}{\partial \varphi} \\ \frac{\partial y}{\partial r} & \frac{\partial y}{\partial \varphi} \end{vmatrix} = \begin{vmatrix} \cos \varphi & -r \sin \varphi \\ \sin \varphi & r \cos \varphi \end{vmatrix}$$

$$= r \cos^2 \varphi + r \sin^2 \varphi = r(\cos^2 \varphi + \sin^2 \varphi) = \underline{r}$$

Czyli liczymy  $\int_0^{2\pi} \int_0^{\infty} \exp\left\{-\frac{r^2}{2}\right\} r dr d\varphi$

$x: (-\infty, +\infty) \rightarrow r: (0, +\infty), y: (-\infty, +\infty) \rightarrow \varphi: (0, 2\pi)$

$u = -\frac{r^2}{2} \quad du = -r dr$

$$\int_0^{2\pi} \int_0^{\infty} -e^u du d\varphi = \int_0^{2\pi} \int_{-\infty}^0 e^u du d\varphi = \int_0^{2\pi} 1 d\varphi = \underline{2\pi}$$

Czyli  $I^2 = 2\pi$  ■

⑦  $\bar{s}$  - sredina  $s_1, \dots, s_n$

$$\sum_{k=1}^n (x_k - \bar{x})^2 = \sum_{k=1}^n x_k^2 - n\bar{x}^2$$

$$\sum_{k=1}^n (x_k^2 - 2x_k\bar{x} + \bar{x}^2) = \sum_{k=1}^n x_k^2 - 2n\bar{x}^2 =$$

$$\sum_{k=1}^n -2x_k\bar{x} + 2(n\bar{x}^2) = -2\bar{x} \underbrace{\left(\sum_{k=1}^n x_k - n\bar{x}\right)}_0 = 0$$

$$b) \sum_{k=1}^n (x_k - \bar{x})(y_k - \bar{y}) = \sum_{k=1}^n x_k y_k - n\bar{x}\bar{y}$$

$$\sum_{k=1}^n x_k y_k + \sum_{k=1}^n \bar{x} \bar{y} - \sum_{k=1}^n x_k \bar{y} - \sum_{k=1}^n \bar{x} y_k - \sum_{k=1}^n x_k y_k + n\bar{x}\bar{y}$$

$$2n\bar{x}\bar{y} - \bar{y} \sum_{k=1}^n x_k - \bar{x} \sum_{k=1}^n y_k =$$

$$2n\bar{x}\bar{y} - \left(\frac{\sum_{k=1}^n y_k}{n} \cdot \sum_{k=1}^n x_k\right) - \left(\frac{\sum_{k=1}^n x_k}{n} \cdot \sum_{k=1}^n y_k\right) = 0$$



$$\textcircled{8} \vec{u}, X \in \mathbb{R}^n, \Sigma \in \mathbb{R}^{n \times n}$$

RPIS 3/4

$$S = (X - \vec{u})^T \Sigma^{-1} (X - \vec{u}), Y = AX$$

$$T: S = (Y - A\vec{u})^T (A \Sigma A^T)^{-1} (Y - A\vec{u})$$

$$(AB)C = A(BC)$$

prawy:  $|A| = A|A| = A$  (1)

$$A(B+C) = AB + AC$$
 (2)

$$M = (M^T)^T, (M+N)^T = M^T + N^T, (MN)^T = N^T M^T$$
 (3)

$$M = (M^{-1})^{-1}, (M^T)^{-1} = (M^{-1})^T, (MN)^{-1} = N^{-1} M^{-1}$$
 (4)

Najpierw  $Y = AX$

$$S = (AX - A\vec{u})^T (A \Sigma A^T)^{-1} (AX - A\vec{u})$$

$$[A(X - \vec{u})]^T (A \Sigma A^T)^{-1} A(X - \vec{u}) =$$

$$(X - \vec{u})^T \underbrace{A^T [A \Sigma A^T]^{-1} A}_{(*)} (X - \vec{u}) = (*)$$

$$[A(\Sigma A^T)]^{-1} = (\Sigma A^T)^{-1} A^{-1} = (A^T)^{-1} \Sigma^{-1} A^{-1}$$

$$(*) (X - \vec{u})^T \underbrace{A^T (A^T)^{-1}} \underbrace{\Sigma^{-1} A^{-1} A}_{=I} (X - \vec{u}) =$$

$$(X - \vec{u})^T \Sigma^{-1} (X - \vec{u})$$