

THE INITIAL STRESS SYMMETRY

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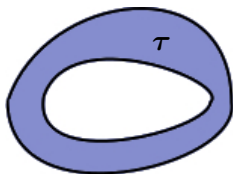


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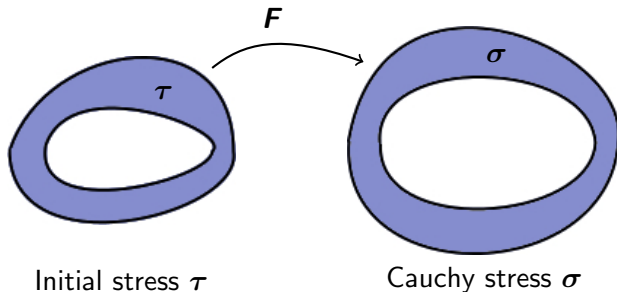
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From initial stress to Cauchy stress

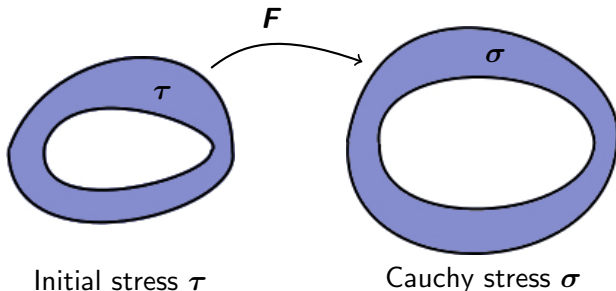


Initial stress τ

From initial stress to Cauchy stress

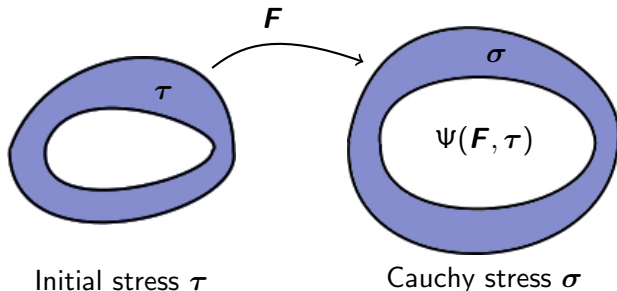


From initial stress to Cauchy stress



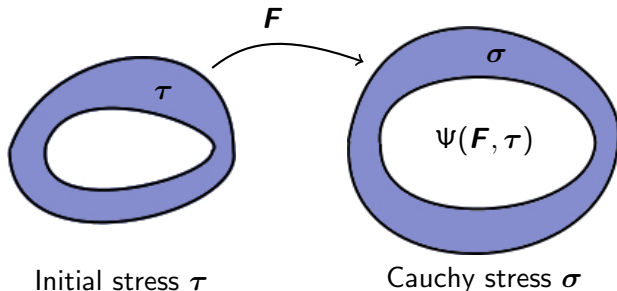
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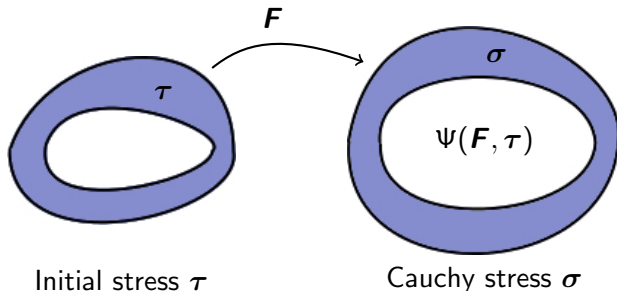
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Something like: $\Psi(F, \tau) = C_1 \text{tr}(F^T F) + C_2 \text{tr} \tau$.

From initial stress to Cauchy stress



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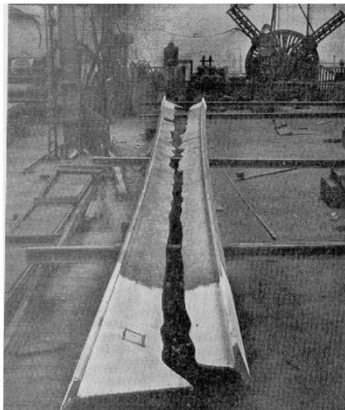
Something like: $\Psi(\mathbf{F}, \tau) = C_1 \text{tr}(\mathbf{F}^T \mathbf{F}) + C_2 \text{tr} \tau$.
(Great for in-vivo characterization!)

Exploding residual stress

“Residual-stresses arising from metal forming and machining and the grounds for their induction have challenged the minds of engineers and scientists since the Industrial Revolution.” – Upshaw et al. (2011)

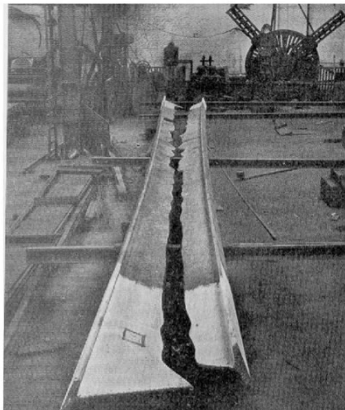
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Typically measuring residual stress in metal matrix composites involves cutting the component in half or drilling small holes.

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$$I_{\tau_1} = \text{tr } \boldsymbol{\tau}, \quad I_{\tau_2} = \frac{1}{2}[(I_{\tau_1}^2 - \text{tr}(\boldsymbol{\tau}^2))], \quad I_{\tau_3} = \det \boldsymbol{\tau},$$

$$J_1 = \text{tr}(\boldsymbol{\tau} \mathbf{C}), \quad J_2 = \text{tr}(\boldsymbol{\tau} \mathbf{C}^2), \quad J_3 = \text{tr}(\boldsymbol{\tau}^2 \mathbf{C}), \quad J_4 = \text{tr}(\boldsymbol{\tau}^2 \mathbf{C}^2).$$

where $\mathbf{C} = \mathbf{F}^T \mathbf{F}$.

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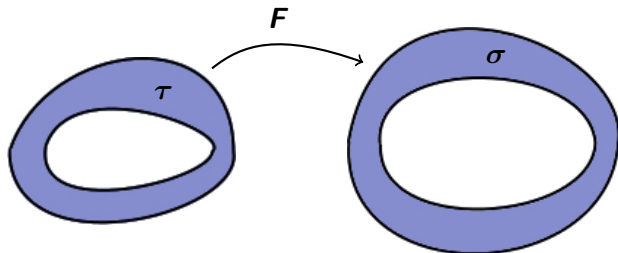
$$I_{\tau 1} = \text{tr } \boldsymbol{\tau}, \quad I_{\tau 2} = \frac{1}{2}[(I_{\tau 1}^2 - \text{tr}(\boldsymbol{\tau}^2))], \quad I_{\tau 3} = \det \boldsymbol{\tau},$$

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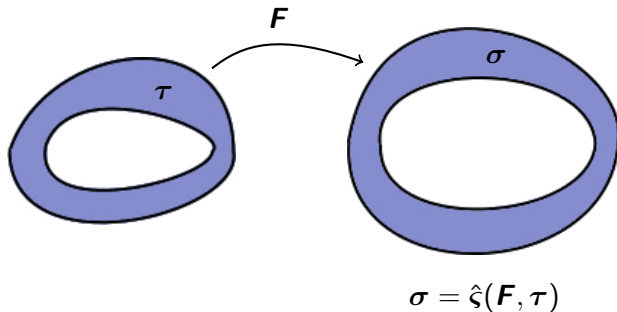
where $\mathbf{C} = \mathbf{F}^T \mathbf{F}$.

Shall we just drop a few invariants?

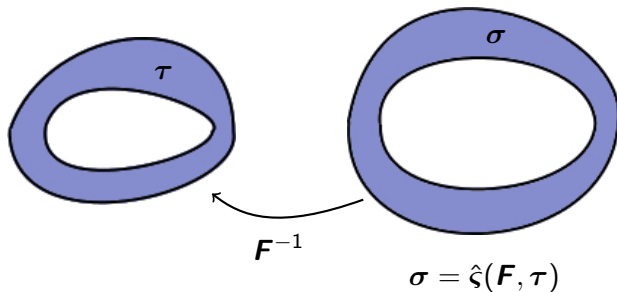
The Initial Stress Symmetry (ISS)



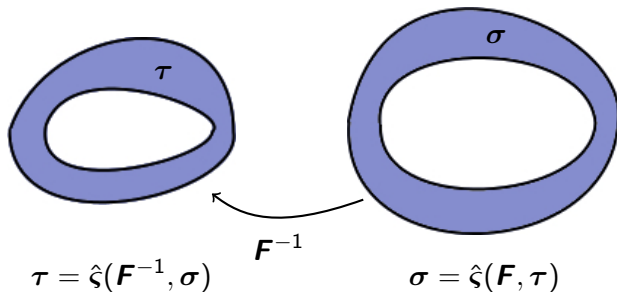
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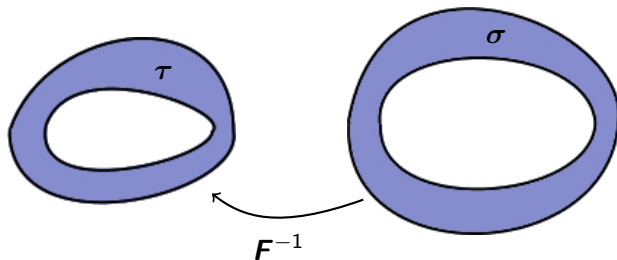
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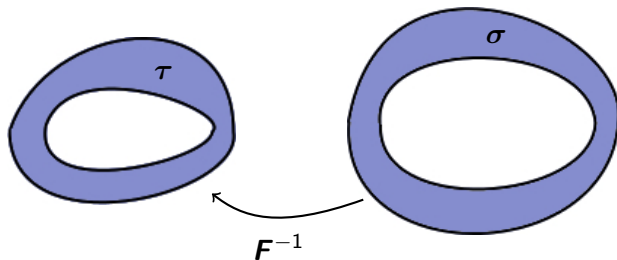
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Initial Stress Symmetry (ISS) :

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Turns out that ISS is automatically satisfied if τ is due to the deformation of a virtual stress-free configuration!

Elasticity

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$$4\Psi_{J_1}\Psi_{J_1}^\sigma = 1, \quad \frac{\Psi_{I_2}^\sigma}{\sqrt{\Psi_{J_1}^\sigma}} + \frac{\Psi_{I_2}}{\sqrt{\Psi_{J_1}}} = 0, \quad p\Psi_{J_1}^\sigma = \Psi_{I_1}^\sigma, \quad p_\tau\Psi_{J_1} = \Psi_{I_1},$$

where

$$\Psi_{I_k} = \Psi_{I_k}(\mathbf{F}, \boldsymbol{\tau}), \quad \Psi_{J_1} = \Psi_{J_1}(\mathbf{F}, \boldsymbol{\tau}), \quad (1)$$

$$\Psi_{I_k}^\sigma := \Psi_{I_k}(\mathbf{F}^{-1}, \boldsymbol{\sigma}), \quad \Psi_{J_m}^\sigma := \Psi_{J_m}(\mathbf{F}^{-1}, \boldsymbol{\sigma}), \quad (2)$$

p and p_τ are Lagrange multipliers due to incompressibility.

Examples of $\Psi(F, \tau)$

Examples that **do not** satisfy ISS:

$$\Psi = \frac{1}{2}\mu(l_1 - 3) + \frac{1}{2}(J_1 - l_{\tau 1}),$$

$$\Psi = \frac{1}{2}\mu(l_1 - 3) + \frac{1}{4}(J_2 - l_{\tau 1}),$$

$$\Psi = \frac{1}{2}\mu(l_1 - 3) + \frac{1}{2}\bar{\mu}(J_1 - l_{\tau 1})^2 + \frac{1}{2}(J_1 - l_{\tau 1}).$$

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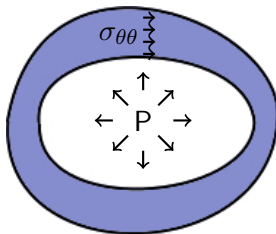
Examples that **do** satisfy ISS:

$$\Psi = \frac{1}{2}(p_\tau(\tau, 1)l_1 + J_1 - 3\mu) \quad (\text{Incompressible neo-Hookean}),$$

$$\Psi = \frac{1}{2}l_3^{-1/3}(p_\tau(\tau, l_3)l_1 + J_1 - f(\tau, l_3)) \quad (\text{Compressible}).$$

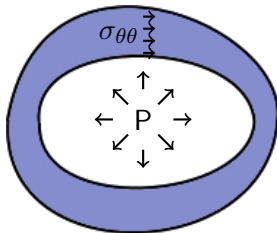
Choose any σ

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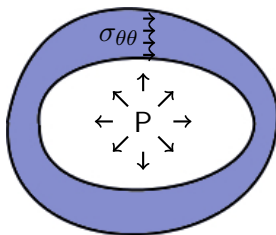
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ISS in the form $\tau = \hat{\zeta}(\mathbf{F}^{-1}, \sigma)$ suggests that for any choice of σ , there will exist an initial stress τ that supports σ .

So first solve for your ideal σ then find τ !

Choose any σ

So we can drop hyperelasticity and minimize

$$\frac{1}{b-a} \int_a^b \|\nabla \sigma\|^2 dr,$$

with inner and outer radius a and b .

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For radial symmetry the solution is

$$\begin{aligned}\sigma_{rr} &= -P(1-\rho)(1-\rho\beta+\rho^2\beta^2) + O(\beta^3) P, \\ \sigma_{\theta\theta} &= P\beta^{-1}(1+\beta^3\rho^2(4\rho-3)) + O(\beta^3) P,\end{aligned}$$

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$\sigma_{zz} = 0$, where

$$\rho = \frac{r-a}{b-a} \quad \text{and} \quad \beta = \frac{b-a}{a} \quad (\approx 0.07).$$

Choose any σ

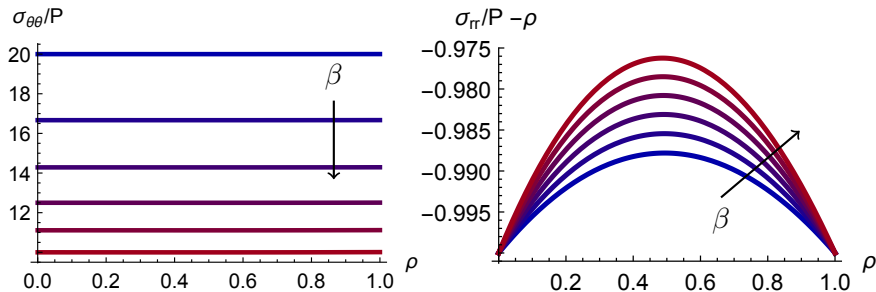


Figure: the ideal adimensional Cauchy stress against the adimensional radius ρ , where β goes from 0.05 to 0.1.

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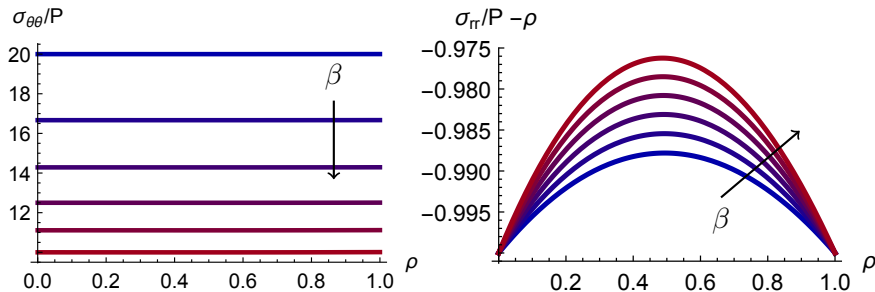


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To make predictions we need to choose $\Psi(\mathbf{F}, \tau)$,

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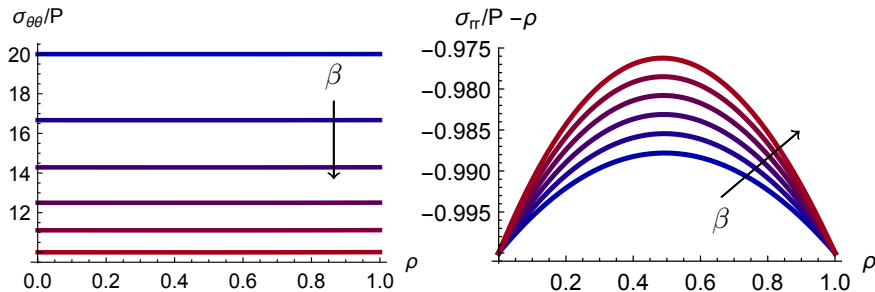


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To make predictions we need to choose $\Psi(\mathbf{F}, \tau)$, then we obtain τ from

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and unloaded boundary conditions.

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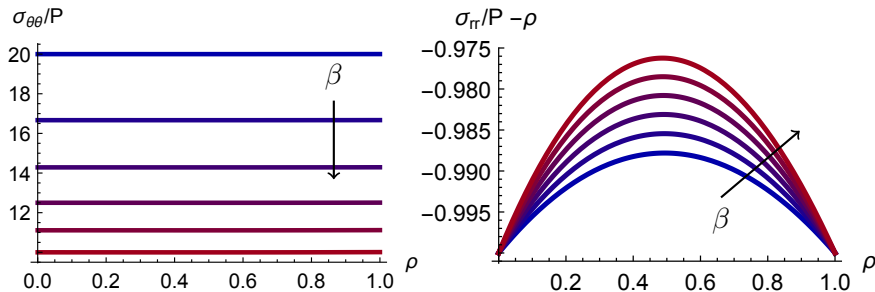


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and unloaded boundary conditions. Now on to predictions!

Predictions for ideal σ

For the neo-Hookean $\Psi(\mathbf{F}, \tau)$.

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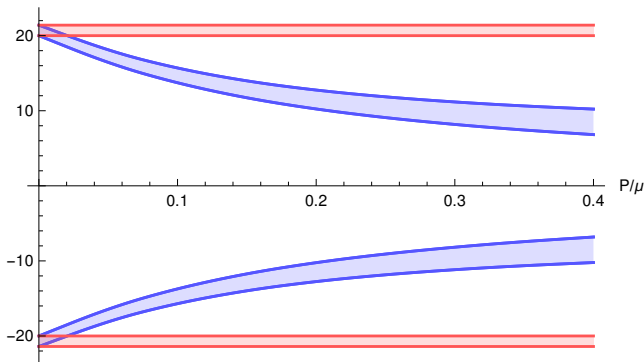


Figure: The **loaded aorta** wall is red and the **unloaded aorta** wall is blue. The parameters are for the descending thoracic aorta: loaded inner radius = 20mm, outer radius = 21.4mm and $\beta = 0.07$.

Predictions for ideal σ

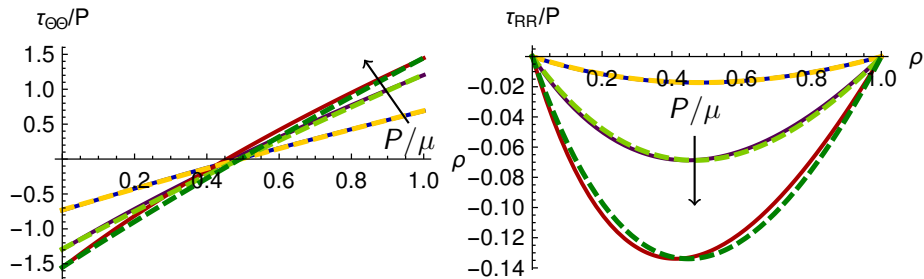


Figure: the adimensional residual stress against the adimensional radius ρ . The dashed curves are from the opening angle method while the solid curves are from the ideal stress σ , both with $P/\mu = 0.05, 0.2$ or 0.35 .

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Thanks for listening! Any questions?

- Chuong, C. and Y. Fung (1986). "Residual stress in arteries". In: *Frontiers in Biomechanics*. Springer, pp. 117–129.
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