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1 General [general]

1.1 Scope [general.scope]

This Technical Specification describes requirements for implementations of an interface that computer programs written in the C++ programming language may use to invoke algorithms with parallel execution. The algorithms described by this Technical Specification are realizable across a broad class of computer architectures.

This Technical Specification is non-normative. Some of the functionality described by this Technical Specification may be considered for standardization in a future version of C++, but it is not currently part of any C++ standard. Some of the functionality in this Technical Specification may never be standardized, and other functionality may be standardized in a substantially changed form.

The goal of this Technical Specification is to build widespread existing practice for parallelism in the C++ standard algorithms library. It gives advice on extensions to those vendors who wish to provide them.

1.2 Normative references [general.references]

The following reference document is indepensible for the application of this document. For dated references, only the edition cited applies. For undated references, the latest edition of the referenced document (including any amendments) applies.

• ISO/IEC 14882:2011, Programming Languages – C++

ISO/IEC 14882:2011 is herein called the C++ Standard. The library described in ISO/IEC 14882:2011 clauses 17-30 is herein called the C++ Standard Library. The C++ Standard Library components described in ISO/IEC 14882:2011 clauses 25 and 26.7 are herein called the C++ Standard Algorithms Library.

Unless otherwise specified, the whole of the C++ Standard Library introduction [lib.library] is included into this Technical Specification by reference.

1.3 Namespaces and headers [general.namespaces]

Since the extensions described in this Technical Specification are experimental and not part of the C++ Standard Library, they should not be declared directly within namespace std. Unless otherwise specified, all components described in this Technical Specification are declared in namespace std::experimental::parallelism.

Unless otherwise specified, references to other entities described in this Technical Specification are assumed to be qualified with std::experimental::parallelism, and references to entities described in the C++ Standard Library are assumed to be qualified with std::.

Extensions that are expected to eventually be added to an existing header <meow> are provided inside the <experimental/meow> header, which shall include the standard contents of <meow> as if by

#include <meow>

1.4 Terms and definitions [general.defns]

For the purposes of this document, the terms and definitions given in the C++ Standard and the following apply.

2 Execution policies [execpol]

2.1 In general [execpol.general]

This subclause describes classes that represent execution policies. An execution policy is an object that expresses the requirements on the ordering of functions invoked as a consequence of the invocation of a standard algorithm. Execution policies afford standard algorithms the discretion to execute in parallel.

2.2 Header <experimental/execution_policy> synopsis [execpol.synop]

```
#include <type_traits>
namespace std {
namespace experimental {
namespace parallelism {
  // 2.3, execution policy type trait
  template<class T> struct is_execution_policy;
  // 2.4, sequential execution policy
  class sequential_execution_policy;
  // 2.5, parallel execution policy
  class parallel_execution_policy;
  // 2.6, vector execution policy
  class vector_execution_policy
  // 2.7, dynamic execution policy
  class execution_policy;
  // 2.8, specialized algorithms
  void swap(sequential execution policy &a, sequential execution policy &b);
  void swap(parallel_execution_policy &a, parallel_execution_policy &b);
  void swap(vector_execution_policy &a, vector_execution_policy &b);
  void swap(execution_policy &a, execution_policy &b);
  // 2.9, standard execution policy objects
  extern const sequential_execution_policy seq;
  extern const parallel_execution_policy
                                           par;
  extern const vector_execution_policy
                                           vec;
}
}
```

}

2.3 Execution policy type trait [execpol.type]

```
namespace std {
namespace experimental {
namespace parallelism {
  template < class T > struct is_execution_policy
    : integral_constant < bool, see below > { };
}
}
}
```

- 1. is_execution_policy can be used to detect parallel execution policies for the purpose of excluding function signatures from otherwise ambiguous overload resolution participation.
- 2. If T is the type of a standard or implementation-defined non-standard execution policy, is_execution_policy<T> shall be publicly derived from integral_constant
bool,true>, otherwise from integral_constant

bool,false>.
- 3. The effect of specializing is_execution_policy for a type which is not defined by the library is unspecified.

[Note: This provision reserves the privilege of creating non-standard execution policies to the library implementation. – end note.]

2.4 Sequential execution policy [execpol.seq]

1. The class sequential_execution_policy provides a mechanism to require a standard algorithm invocation to execute in a sequential order.

```
namespace std {
namespace experimental {
namespace parallelism {
    class sequential_execution_policy
    {
       void swap(sequential_execution_policy &other);
    };
}

void swap(sequential_execution_policy &other);
```

1. Effects: Swaps the state of *this and other.

2.5 Parallel execution policy [execpol.par]

1. The class parallel_execution_policy provides a mechanism to allow a standard algorithm invocation to execute in an unordered fashion when executed on separate threads, and indeterminately sequenced when executed on a single thread.

```
namespace std {
namespace experimental {
namespace parallelism {
   class parallel_execution_policy
   {
      void swap(parallel_execution_policy &other);
   };
}

void swap(parallel_execution_policy &other);
```

1. Effects: Swaps the state of *this and other.

2.6 Vector execution policy [execpol.vec]

1. The class vector_execution_policy provides a mechanism to allow a standard algorithm invocation to execute in an unordered fashion when executed on separate threads, and unordered when executed on a single thread.

```
namespace std {
namespace experimental {
namespace parallelism {
   class vector_execution_policy
   {
     void swap(vector_execution_policy &other);
   };
}
}
```

```
void swap(vector_execution_policy &other);
```

1. Effects: Swaps the state of *this and other.

2.7 Dynamic execution policy [execpol.dynamic]

1. The class execution_policy is a dynamic container for execution policy objects.

```
namespace std {
namespace experimental {
namespace parallelism {
  class execution_policy
    public:
      // 2.7.1, construct/assign/swap
      template<class T> execution_policy(const T &exec);
      template<class T> execution_policy &operator=(const T &exec);
      void swap(execution_policy &other);
      // 2.7.2, object access
      const type_info& target_type() const;
      template<class T> T *target();
      template<class T> const T *target() const;
  };
}
}
}
```

2.7.1 execution_policy construct/assign/swap

template<class T> execution_policy(const T &exec);

- 1. *Effects*: Constructs an execution_policy object with a copy of exec's state.
- 2. Remarks: This signature does not participate in overload resolution if is_execution_policy<T>::value is false.
 - $template\ execution_policy\ \& operator = (const\ T\ \& exec);$
- 3. Effects: Assigns a copy of exec's state to *this.
- 4. Returns: *this.

- 5. Remarks:* This signature does not participate in overload resolution ifis_execution_policy::valueisfalse'. void swap(execution_policy &other);
- 6. Effects: Swaps the stored object of *this with that of other.

2.7.2 execution_policy object access

```
const type_info &target_type() const;
```

- 1. Returns: typeid(T), such that T is the type of the execution policy object contained by *this.
 - template T *target(); template const T *target() const;
- 2. Returns: If target_type() == typeid(T), a pointer to the stored execution policy object; otherwise a null pointer.
- 3. Remarks:* This signature does not participate in overload resolution if is execution policy::value is false.

2.8 Execution policy specialized algorithms [execpol.algorithms]

```
void swap(sequential_execution_policy &a, sequential_execution_policy &b);
void swap(parallel_execution_policy &a, parallel_execution_policy &b);
void swap(vector_execution_policy &a, vector_execution_policy &b);
void swap(execution_policy &a, execution_policy &b);
```

1. Effects: a.swap(b).

2.9 Standard execution policy objects [execpol.objects]

```
namespace std {
namespace experimental {
namespace parallelism {
  extern const sequential_execution_policy seq;
  extern const parallel_execution_policy par;
  extern const vector_execution_policy vec;
}
}
}
```

- 1. The header <execution_policy> declares a global object associated with each standard execution policy.
- 2. Concurrent access to these objects shall not result in a data race.