Programming task 10: Dimensionality Reduction

```
In [52]: import numpy as np
import matplotlib.pyplot as plt
%matplotlib inline
```

Exporting the results to PDF

Once you complete the assignments, export the entire notebook as PDF and attach it to your homework solutions. The best way of doing that is

- 1. Run all the cells of the notebook.
- 2. Export/download the notebook as PDF (File -> Download as -> PDF via LaTeX (.pdf)).
- 3. Concatenate your solutions for other tasks with the output of Step 2. On a Linux machine you can simply use pdfunite, there are similar tools for other platforms too. You can only upload a single PDF file to Moodle.

Make sure you are using nbconvert --version . Older versions clip lines that exceed page width, which makes your code harder to grade.

PCA

Given the data in the matrix X your tasks is to:

- Calculate the covariance matrix Σ .
- Calculate eigenvalues and eigenvectors of Σ .
- Plot the original data X and the eigenvectors to a single diagram. What do you observe? Which eigenvector corresponds to the smallest eigenvalue?
- Determine the smallest eigenvalue and remove its corresponding eigenvector. The remaining eigenvector is the basis of a new subspace.
- Transform all vectors in X in this new subspace by expressing all vectors in X in this new basis.

The given data X

```
In [53]: X = np.array([(-3,-2),(-2,-1),(-1,0),(0,1),(1,2),(2,3),(-2,-2),(-1,-1),
```

```
(0,0),(1,1),(2,2), (-2,-3),
(-1,-2),(0,-1),(1,0), (2,1),(3,2)])
```

Task 1: Calculate the covariance matrix Σ

Task 2: Calculate eigenvalues and eigenvectors of Σ .

Task 3: Plot the original data X and the eigenvectors to a single diagram.

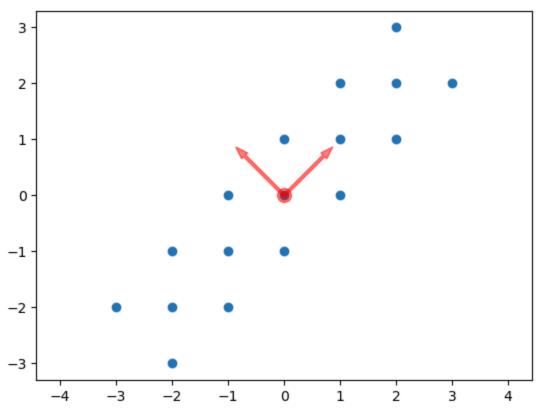
```
In [56]: %matplotlib inline
# plot the original data
plt.scatter(X[:, 0], X[:, 1])
plt.axis('equal')
```

```
# plot the mean of the data
mean_d1, mean_d2 = X.mean(0)
plt.plot(mean_d1, mean_d2, 'o', markersize=10, color='red', alpha=0.5)

# calculate the covariance matrix
Sigma = get_covariance(X)
# calculate the eigenvector and eigenvalues of Sigma
L, U = get_eigen(Sigma)
print(L)
print(U)

plt.arrow(mean_d1, mean_d2, U[0, 0], U[1, 0], width=0.05, color='red', alpha
plt.arrow(mean_d1, mean_d2, U[0, 1], U[1, 1], width=0.05, color='red', alpha
plt.show()
```

```
[5.625 0.375]
[[ 0.70710678 -0.70710678]
[ 0.70710678 0.70710678]]
```



What do you observe in the above plot? Which eigenvector corresponds to the smallest eigenvalue?

Write your answer here:

The datapoints are distributed in form of a 45 degree rotated rectangle. Along the width of the rectangle the variance is highest and corresponds to the biggest eigenvalue (5.625). On the other hand, the height of the rectangle corresponds to the smallest eigenvalue (0.375) with this eigenvecotr

[-0.7071, 0.7071]. The data is less disperse along the height.

Task 4: Transform the data

Determine the smallest eigenvalue and remove its corresponding eigenvector. The remaining eigenvector is the basis of a new subspace. Transform all vectors in X in this new subspace by expressing all vectors in X in this new basis.

```
In [57]: def transform(X, U, L):
             """Transforms the data in the new subspace spanned by the eigenvector co
             Parameters
             _____
             X : array, shape [N, D]
                Data matrix.
             L : array, shape [D]
                 Eigenvalues of Sigma_X
             U : array, shape [D, D]
                 Eigenvectors of Sigma_X
             Returns
             X_t : array, shape [N, 1]
                 Transformed data
             smallest_eigen= min(L)
             smallest index= np.argmin(L)
             trunc_L= np.delete(U, smallest_index, axis=1)
             X t= X@trunc L
             return X_t
In [58]: X_t = transform(X, U, L)
```

```
print(X_t)
```

```
[[-3.53553391]
[-2.12132034]
[-0.70710678]
[ 0.70710678]
[ 2.12132034]
[ 3.53553391]
[-2.82842712]
[-1.41421356]
[ 0.
[ 1.41421356]
[ 2.82842712]
[-3.53553391]
[-2.12132034]
[-0.70710678]
[ 0.70710678]
[ 2.12132034]
[ 3.53553391]]
```

SVD

Task 5: Given the matrix M find its SVD decomposition $M=U\cdot\Sigma\cdot V$ and reduce it to one dimension using the approach described in the lecture.

```
In [59]: M = np.array([[1, 2], [6, 3], [0, 2]])
In [60]: def reduce to one dimension(M):
             """Reduces the input matrix to one dimension using its SVD decomposition
             Parameters
             M : array, shape [N, D]
                 Input matrix.
             Returns
             M_t: array, shape [N, 1]
                 Reduce matrix.
             U, S, Vt = np.linalg.svd(M)
             M_t = U[:, 0].reshape(-1, 1) * S[0]
             return M_t
In [61]: M_t = reduce_to_one_dimension(M)
         print(M_t)
        [[-1.90211303]
         [-6.68109819]
         [-1.05146222]
```