Arthur K. Zhang

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University of Michigan, Ann Arbor ***May 2022***
Bachelors in Science and Engineering in Computer Engineering *GPA: 3.9/4.0*
Coursework: Autonomous Robots, Embedded System Design, Embedded Control Systems, Circuit Analysis & Design

Work Experience

Amazon Studios (Software Engineering Intern) ***May - August 2021***
- Building Prime Video backend pipelines to handle high volume video processing and editing from content creators
- Designed REST API endpoint in Java to enable film studios to manage content publishing and distribution

Northrop Grumman (Control Systems Software Engineering Intern) ***May - August 2020***
- Built multithreaded TCP/IP socket to handle high speed satellite and ground station communications for command line app in C and flight software for distributing telemetry commands to avionics system
- Programmed Softbench in C and Simics to simulate real time avionics hardware for NASA's JPSS and Landsat9 satellites, improving flight software validation lifecycle by up to 6 months

Sandia National Laboratories (Software Engineering R & D Intern) ***May - August 2019***
- Architected noSQL database and full stack web components for automating data analysis for radiological instruments
- Optimized website user experience by implementing front end state management using Redux and a continuous integration/deployment pipeline (CI/CD) for unit and integration testing

Clinc (Software Engineering Intern) ***June - August 2018***
- Refactored REST APIs and integrated single page application to improve server response times by up to 50%
- Designed end-to-end automated testing infrastructure in Selenium that reduced bugs pushed to production by 40%

Projects

Autonomous Car Robot (https://eecs467.eecs.umich.edu/team-7) ***January - May 2021***
- Fully autonomous four wheeled robot capable of navigating environments and following moving targets using real time object detection and segmentation
- Implemented adaptive entropy particle filter for tracking targets, moving target D* Lite path planning algorithm, occupancy grid SLAM, and LCM communication over ethernet between three Linux computers

Pressurization Control PCB (https://github.com/KingArthurZ3/Pressurization-Control) ***May - December 2020***
- Designed custom PCB to actively balance tank pressures for liquid fuel rockets, complete with STM32 microcontroller, ADCs for analog peripheral sensing, and redundant RS-422 communication chips
- Architected virtual timer task scheduling system and embedded libraries for command and data handling, DC motor control, and PID controller calculations in C

Extracurricular Activities

Computational Autonomy and Robotics Lab (CURLY) ***May 2021 - Present***
- CURLY lab designs autonomous robot systems to understand and navigate environments in the field
- Programming MIT Mini Cheetah in C++ to compute robot position and velocity using invariant EKF and ROS

Michigan Aeronautical Science Association (MASA) ***August 2019 - Present***
- MASA is a collegiate rocketry organization that designs and manufactures liquid fuel rockets for launch competitions
- Leading firmware development on embedded PID controller project, RS-422 communications, and high performance peripheral libraries (ADCs and DC motors)

Miniature Tether Electrodynamics Experiment Lab (MiTEE) ***August 2019 - May 2021***
- MiTEE lab develops orbital satellites that use electrodynamic tethers to extend service period before failure
- Developed LQR controller in C to perform satellite stabilization using magnetorquers and reaction wheels

Skills

Computer Programming: C++, C, Javascript, Python, Java, Matlab, Tensorflow, React.js, Vue.js, Django, Selenium, MySQL
Computer-Aided Design: KiCAD, Altium PCB Designer, LTSpice, Autodesk Inventor, Autodesk Eagle, Solidworks