

High-Frequency Algorithmic Trading with Momentum and Order Imbalance

My goal is to establish and solve the stochastic optimal control problem that captures the momentum and order imbalance dynamics of the Limit Order Book (LOB). The solution will yield an optimal trading strategy that will permit statistical arbitrage of the underlying stock, which will then be backtested on historical data.

Progress Timeline

DATE	THESIS	STA4505
Dec-2014	• Complete CTMC calibration	
Dec-2014	• Backtest naive strategies based on CTMC	
Jan-May	• Study stochastic controls: ECE1639, STA4505	
Jun-5	• Establish models	Exam Study
Jun-12	• Establish performance criteria	Exam Study
Jun-15	• Derive DPP/DPE	EXAM
Jun-19	• Derive DPP/DPE	
Jun-26	• Derive continuous-time equations	
Jul-3	• Derive discrete-time equations	
Jul-10	• Set up MATLAB numerical integration	
Jul-17	• Integrate functions and plot dynamics	Integrate and analyze too!
Jul-24	• More dynamics, and calib/choose parameters	
Jul-31	• Backtest on historical data	Simulate results
Aug-7	• More backtesting, comparing with previous	
Aug-14	• Dissertation writeup / buffer	Project writeup
Aug-21	• Dissertation writeup / buffer	
Aug-28	• Dissertation writeup	Presentation

Whiteboard Inspirational Quote of the Week

What you do speaks so loudly that I cannot hear what you say.
- Ralph Waldo Emerson

For Our Readers in the Middle East...

<http://52weeksofrejection.com>

This morning I was officially out of protein powder. It's amazing because it's the sort of thing you see coming from a mile away, like it's a very steady linear decline in supply so it's really never a surprise. And yet almost every time, I don't have the resolve to order a resupply until *after* I suffer at least one juice-free disappointing day. Don't worry, banana cream pie is on its way. But so today I decided I'd make the morning smoothie and substitute a green apple instead of the protein powder, having realized a long time ago that the major role of the powder isn't the nutritional punch but the delicate dousing of deliciousness. But uh ... yeah never again.

Old Faithful is on life support. Multi-tabbing in Chrome is almost out of the cards. I don't really know what to do. I want a nice lightweight, 15-17", Linux-friendly machine as a replacement but I also have no disposable income anymore and I'm still somehow racking up monthly \$2000 visa bills.

Look man you asked me to record, in the moment, why I was doing it. Here's why: deep down I've got cosmic knowledge that this one isn't over, and I'm positive that if I let it go now then it WILL be. Maybe it's doomed due to timing as we said, and if so then I guess I'll know pretty soon, but regardless, what I'm doing now *does* seem like throwing everything away, and fuck that, that's not how we roll, we bury shit in the sand for a first date, you know what I'm saying? And in case you don't, I guess what I'm saying is that until it's 52-weeks worthy (ok, irony that it already did make it into 52weeks isn't lost on me...) I ain't just giving up.

The Academic Week in Review

We are trying to solve the following DPE:

$$\begin{aligned}
0 = \max \Bigg\{ & \sup_{\delta^\pm} \Bigg\{ \mathbb{E}_{\mathbf{w}} \Bigg[(s + \pi + \delta^-) L_k^- - (s - \pi - \delta^+) L_k^+ \\
& + (L_k^+ - L_k^-) (s + \eta_{0,z} T(\mathbf{z}, \omega)^{(2)} - \text{sgn}(q + L_k^+ - L_k^-) \pi) \\
& + q (\eta_{0,z} T(\mathbf{z}, \omega)^{(2)} - (\text{sgn}(q + L_k^+ - L_k^-) - \text{sgn}(q)) \pi) \\
& + h_{k+1}(T(\mathbf{z}, \omega), q + L_k^+ - L_k^-) - h_k(\mathbf{z}, q) \Bigg] \Bigg\} ; \\
& \sup_{\delta^\pm} \Bigg\{ \mathbb{E}_{\mathbf{w}} \Bigg[(s + \pi + \delta^-) L_k^- - (s - \pi - \delta^+) L_k^+ - (s + \pi) \\
& + (L_k^+ - L_k^- + 1) (s + \eta_{0,z} T(\mathbf{z}, \omega)^{(2)} - \text{sgn}(q + L_k^+ - L_k^- + 1) \pi) \\
& + q (\eta_{0,z} T(\mathbf{z}, \omega)^{(2)} - (\text{sgn}(q + L_k^+ - L_k^- + 1) - \text{sgn}(q)) \pi) \\
& + h_{k+1}(T(\mathbf{z}, \omega), q + L_k^+ - L_k^- + 1) - h_k(\mathbf{z}, q) \Bigg] \Bigg\} ; \\
& \sup_{\delta^\pm} \Bigg\{ \mathbb{E}_{\mathbf{w}} \Bigg[(s + \pi + \delta^-) L_k^- - (s - \pi - \delta^+) L_k^+ + (s - \pi) \\
& + (L_k^+ - L_k^- - 1) (s + \eta_{0,z} T(\mathbf{z}, \omega)^{(2)} - \text{sgn}(q + L_k^+ - L_k^- - 1) \pi) \\
& + q (\eta_{0,z} T(\mathbf{z}, \omega)^{(2)} - (\text{sgn}(q + L_k^+ - L_k^- - 1) - \text{sgn}(q)) \pi) \\
& + h_{k+1}(T(\mathbf{z}, \omega), q + L_k^+ - L_k^- - 1) - h_k(\mathbf{z}, q) \Bigg] \Bigg\} \Bigg\} \quad (1)
\end{aligned}$$

We'll begin by concentrating on the first case where $M^+ = M^- = 0$. Thus, we want to solve

$$\begin{aligned}
& \sup_{\delta^\pm} \Bigg\{ \mathbb{E}_{\mathbf{w}} \Bigg[(s + \pi + \delta^-) L_k^- - (s - \pi - \delta^+) L_k^+ \\
& + (L_k^+ - L_k^-) (s + \eta_{0,z} T(\mathbf{z}, \omega)^{(2)} - \text{sgn}(q + L_k^+ - L_k^-) \pi) \\
& + q (\eta_{0,z} T(\mathbf{z}, \omega)^{(2)} - (\text{sgn}(q + L_k^+ - L_k^-) - \text{sgn}(q)) \pi) \\
& + h_{k+1}(T(\mathbf{z}, \omega), q + L_k^+ - L_k^-) - h_k(\mathbf{z}, q) \Bigg] \Bigg\} \quad (2)
\end{aligned}$$

First, some preliminary results:

$$\begin{aligned}
\mathbb{P}[L_k^- = 1 | K_k^+ = 1] &= e^{-\kappa\delta^-} \\
\mathbb{P}[L_k^- = 0 | K_k^+ = 1] &= 1 - e^{-\kappa\delta^-} \\
\mathbb{P}[L_k^- = 0 | K_k^+ = n] &= (1 - e^{-\kappa\delta^-})^n \\
\mathbb{P}[L_k^- = 1 | K_k^+ = n] &= 1 - (1 - e^{-\kappa\delta^-})^n \\
\mathbb{P}[K_k^+ = n] &= \frac{e^{-\lambda\Delta t}(\lambda\Delta t)^n}{n!}
\end{aligned}$$

Theorem 1. $\mathbb{E}[L_k^-] = \mathbb{P}[L_k^- = 1] = 1 - e^{-e^{-\kappa\delta^-}\lambda\Delta t}$

Proof.

$$\begin{aligned}
\mathbb{E}[L_k^-] &= \sum_{n=0}^{\infty} \mathbb{P}[L_k^- = 1 | K_k^+ = n] \cdot \mathbb{P}[K_k^+ = n] \\
&= \sum_{n=0}^{\infty} [1 - (1 - e^{-\kappa\delta^-})^n] \frac{e^{-\lambda\Delta t}(\lambda\Delta t)^n}{n!} \\
&= 1 - e^{-\lambda\Delta t} \sum_{n=0}^{\infty} \frac{(1 - e^{-\kappa\delta^-})^n (\lambda\Delta t)^n}{n!} \\
&= 1 - e^{-\lambda\Delta t} \sum_{n=0}^{\infty} \frac{(\lambda\Delta t - e^{-\kappa\delta^-}\lambda\Delta t)^n}{n!} \\
&= 1 - e^{-\lambda\Delta t} e^{\lambda\Delta t - e^{-\kappa\delta^-}\lambda\Delta t} \\
&= 1 - e^{-e^{-\kappa\delta^-}\lambda\Delta t}
\end{aligned}$$

□

For ease of notation, we'll write the probability of the $L_k^- = 0$ event as

$$p(\delta^-) = e^{-e^{-\kappa\delta^-}\lambda\Delta t}$$

and its derivative as

$$d(\delta^-) = \partial_{\delta^-} p(\delta^-) = \kappa\lambda\Delta t e^{-e^{-\kappa\delta^-}\lambda\Delta t - \kappa\delta^-}$$

This gives us the results:

$$\begin{aligned}
\mathbb{P}[L_k^- = 1] &= 1 - p(\delta^-) = \mathbb{E}[L_k^-] \\
\mathbb{P}[L_k^- = 0] &= p(\delta^-) \\
\partial_{\delta^-} \mathbb{P}[L_k^- = 1] &= -d(\delta^-) \\
\partial_{\delta^-} \mathbb{P}[L_k^- = 0] &= d(\delta^-)
\end{aligned}$$

Let's pre-compute some of the terms that we'll encounter in the supremum, namely the expectations of the random variables.

$$\begin{aligned}
\mathbb{E}[\text{sgn}(q + L_k^+ - L_k^-)] &= \mathbb{P}[L_k^- = 1] \cdot \mathbb{P}[L_k^+ = 1] \cdot \text{sgn}(q) \\
&\quad + \mathbb{P}[L_k^- = 1] \cdot \mathbb{P}[L_k^+ = 0] \cdot \text{sgn}(q - 1) \\
&\quad + \mathbb{P}[L_k^- = 0] \cdot \mathbb{P}[L_k^+ = 1] \cdot \text{sgn}(q + 1) \\
&\quad + \mathbb{P}[L_k^- = 0] \cdot \mathbb{P}[L_k^+ = 0] \cdot \text{sgn}(q) \\
&= (1 - p(\delta^-))(1 - p(\delta^+)) \text{sgn}(q) \\
&\quad + (1 - p(\delta^-))p(\delta^+) \text{sgn}(q - 1) \\
&\quad + p(\delta^-)(1 - p(\delta^+)) \text{sgn}(q + 1) \\
&\quad + p(\delta^-)p(\delta^+) \text{sgn}(q) \\
&= \text{sgn}(q) [1 - p(\delta^+) - p(\delta^-) + 2p(\delta^+)p(\delta^-)] \\
&\quad + \text{sgn}(q - 1) [p(\delta^+) - p(\delta^+)p(\delta^-)] \\
&\quad + \text{sgn}(q + 1) [p(\delta^-) - p(\delta^+)p(\delta^-)] \\
&= \begin{cases} 1 & q \geq 2 \\ 1 - p(\delta^+)(1 - p(\delta^-)) & q = 1 \\ p(\delta^-) - p(\delta^+) & q = 0 \\ -[1 - p(\delta^-)(1 - p(\delta^+))] & q = -1 \\ -1 & q \leq -2 \end{cases} \tag{3} \\
&= \Phi(q, \delta^+, \delta^-) \tag{4}
\end{aligned}$$

Hence, we can also compute the partial derivatives of this expectation:

$$\partial_{\delta^-} \Phi(q, \delta^+, \delta^-) = \begin{cases} 0 & q \geq 2 \\ d(\delta^-)p(\delta^+) & q = 1 \\ d(\delta^-) & q = 0 \\ d(\delta^-)(1 - p(\delta^+)) & q = -1 \\ 0 & q \leq -2 \end{cases} \tag{5}$$

$$\partial_{\delta^+} \Phi(q, \delta^+, \delta^-) = \begin{cases} 0 & q \geq 2 \\ -d(\delta^+)(1 - p(\delta^-)) & q = 1 \\ -d(\delta^+) & q = 0 \\ -d(\delta^+)p(\delta^-) & q = -1 \\ 0 & q \leq -2 \end{cases} \tag{6}$$

As it'll be required for later, we'll additionally introduce the shorthand notation

$$\frac{\partial_{\delta^-} \Phi(q, \delta^+, \delta^-)}{d(\delta^-)} = \Psi(q, \delta^+) \tag{7}$$

$$\frac{\partial_{\delta^+} \Phi(q, \delta^+, \delta^-)}{d(\delta^+)} = \Upsilon(q, \delta^-) \quad (8)$$

If we call \mathbf{P} the transition matrix for the Markov Chain \mathbf{Z} , with $\mathbf{P}_{\mathbf{z}, \mathbf{j}} = \mathbb{P}[\mathbf{Z}_{k+1} = \mathbf{j} | \mathbf{Z}_k = \mathbf{z}]$, then we can also write:

$$\begin{aligned} \mathbb{E}[h_{k+1}(T(\mathbf{z}, \omega), q + L_k^+ - L_k^-)] &= \sum_{\mathbf{j}} \mathbf{P}_{\mathbf{z}, \mathbf{j}} \left[h_{k+1}(\mathbf{j}, q) [1 - p(\delta^+) - p(\delta^-) + 2p(\delta^+)p(\delta^-)] \right. \\ &\quad + h_{k+1}(\mathbf{j}, q - 1) [p(\delta^+) - p(\delta^+)p(\delta^-)] \\ &\quad \left. + h_{k+1}(\mathbf{j}, q + 1) [p(\delta^-) - p(\delta^+)p(\delta^-)] \right] \end{aligned} \quad (9)$$

and its partial derivatives as

$$\begin{aligned} \partial_{\delta^-} \mathbb{E}[h_{k+1}(T(\mathbf{z}, \omega), q + L_k^+ - L_k^-)] &= \sum_{\mathbf{j}} \mathbf{P}_{\mathbf{z}, \mathbf{j}} \left[h_{k+1}(\mathbf{j}, q) [-d(\delta^-) + 2p(\delta^+)d(\delta^-)] \right. \\ &\quad + h_{k+1}(\mathbf{j}, q - 1) [-p(\delta^+)d(\delta^-)] \\ &\quad \left. + h_{k+1}(\mathbf{j}, q + 1) [d(\delta^-) - p(\delta^+)d(\delta^-)] \right] \end{aligned} \quad (10)$$

$$\begin{aligned} &= d(\delta^-) \sum_{\mathbf{j}} \mathbf{P}_{\mathbf{z}, \mathbf{j}} \left[h_{k+1}(\mathbf{j}, q) [-1 + 2p(\delta^+)] \right. \\ &\quad + h_{k+1}(\mathbf{j}, q - 1) [-p(\delta^+)] \\ &\quad \left. + h_{k+1}(\mathbf{j}, q + 1) [1 - p(\delta^+)] \right] \end{aligned} \quad (11)$$

$$\begin{aligned} \partial_{\delta^+} \mathbb{E}[h_{k+1}(T(\mathbf{z}, \omega), q + L_k^+ - L_k^-)] &= d(\delta^+) \sum_{\mathbf{j}} \mathbf{P}_{\mathbf{z}, \mathbf{j}} \left[h_{k+1}(\mathbf{j}, q) [-1 + 2p(\delta^-)] \right. \\ &\quad + h_{k+1}(\mathbf{j}, q - 1) [1 - p(\delta^-)] \\ &\quad \left. + h_{k+1}(\mathbf{j}, q + 1) [-p(\delta^-)] \right] \end{aligned} \quad (12)$$

Now we tackle solving the supremum in equation ???. First we consider the first-order condition on δ^- , namely that the partial derivative with respect to it must be equal to zero.

$$\begin{aligned} 0 &= (1 - p(\delta^-)) - d(\delta^-)(s + \pi + \delta^-) + d(\delta^-)(s + \mathbb{E}[\eta_{0, \mathbf{z}} T(\mathbf{z}, \omega)^{(2)}] - \Phi(q, \delta^+, \delta^-)\pi) \\ &\quad - \partial_{\delta^-} \Phi(q, \delta^+, \delta^-)\pi(p(\delta^-) - p(\delta^+)) - q\pi \partial_{\delta^-} \Phi(q, \delta^+, \delta^-) + d(\delta^-) \sum_{\mathbf{j}} \mathbf{P}_{\mathbf{z}, \mathbf{j}} \\ &\quad \times \left[h_{k+1}(\mathbf{j}, q) [-1 + 2p(\delta^+)] + h_{k+1}(\mathbf{j}, q - 1) [-p(\delta^+)] + h_{k+1}(\mathbf{j}, q + 1) [1 - p(\delta^+)] \right] \end{aligned} \quad (13)$$

and diving through by $d(\delta^-)$, which is nonzero, we get

$$\begin{aligned}
&= \frac{1 - p(\delta^-)}{d(\delta^-)} - (s + \pi + \delta^-) + (s + \mathbb{E}[\eta_{0,z}T(\mathbf{z}, \omega)^{(2)}] - \Phi(q, \delta^+, \delta^-)\pi) \\
&\quad - \pi(p(\delta^-) - p(\delta^+))\Psi(q, \delta^+) - q\pi\Psi(q, \delta^+) \\
&\quad + \sum_{\mathbf{j}} \mathbf{P}_{\mathbf{z}, \mathbf{j}} \left[h_{k+1}(\mathbf{j}, q) [-1 + 2p(\delta^+)] + h_{k+1}(\mathbf{j}, q - 1) [-p(\delta^+)] + h_{k+1}(\mathbf{j}, q + 1) [1 - p(\delta^+)] \right]
\end{aligned} \tag{14}$$

Re-arranging and collecting terms in δ^- on the left-hand side:

$$\begin{aligned}
&\frac{1 - p(\delta^-)}{d(\delta^-)} + \delta^- + \pi\Phi(q, \delta^+, \delta^-) + \pi p(\delta^-)\Psi(q, \delta^+) \\
&= \mathbb{E}[\eta_{0,z}T(\mathbf{z}, \omega)^{(2)}] + \pi (-1 + p(\delta^+)\Psi(q, \delta^+) - q\Psi(q, \delta^+)) \\
&\quad + \sum_{\mathbf{j}} \mathbf{P}_{\mathbf{z}, \mathbf{j}} \left[h_{k+1}(\mathbf{j}, q) [-1 + 2p(\delta^+)] + h_{k+1}(\mathbf{j}, q - 1) [-p(\delta^+)] + h_{k+1}(\mathbf{j}, q + 1) [1 - p(\delta^+)] \right]
\end{aligned} \tag{15}$$

$$\frac{1 - p(\delta^-)}{d(\delta^-)} = \frac{e^{\kappa\delta^-} \left(e^{\lambda\Delta t e^{-\kappa\delta^-}} \right)}{\kappa\lambda\Delta t}$$

Looking Ahead

Look, this week has been a bit of a bust for a variety of reasons. Academically speaking, it's because I'm fucking stuck. I don't see where these derivations are going, because they're just fucking messy. When I finally came to this conclusion I immediately reached out to both Sebastian and Gabe but only the latter wrote back and said he'd look at it. I know, I've gotta be more pushy. I'll follow up with Seb again tomorrow.

There's good news, though. Realistically I don't need to do all this linearly, and I can begin looking at the numerical integration part that's due next week anyway. In fact, yes, precisely. I can just shelf this till I can get either of their help and move the fuck on. Efficiency, bitches! Equally in the good news department is that I already did a couple hours of discussion with my dad on the topic of numerical solutions, as it turns out I've never *actually* done it, although I guess in a very true sense Monte Carlo sims are exactly that. Anyway, word on the street is that you can use virtually whatever fucking method you want, we've got a few contenders, probably will go with the most complicated one to get my money's worth from these 8 CPU's.