

Distributed Lag Non-linear Models (DLNMs)

Methodology and Application to Time Series Data Analysis

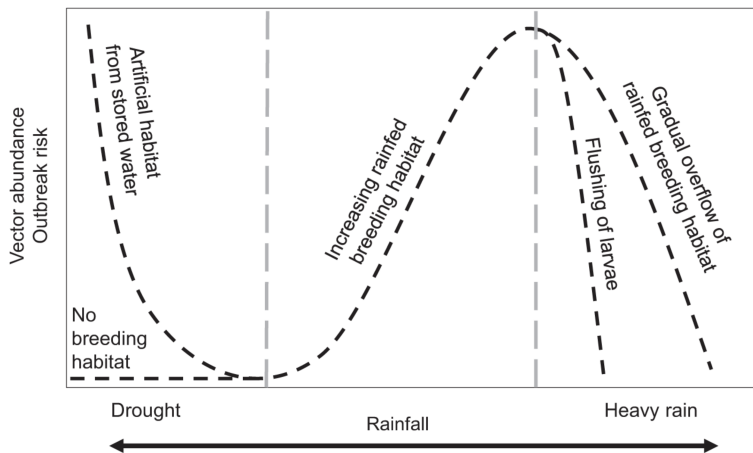
Vincent Arumadri

Department of Public Health

Erasmus MC

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Non-linear association between rainfall and vector abundance and outbreak risk



Caldwell et al. 2021, Nature Communications

DLNMs: Conceptual model



Rainfall
(Exposure)

Leads
→
Exposure-response



Malaria cases
(Response)



Rainfall
(Exposure)

Delayed effect?
→
Exposure-lag-response



Malaria cases
(Response)

Key definitions

- **Non-linear data associations**: data where there is no linear relationship between a dependent (**outcome/response**) and an independent (**exposure/predictor**) variable
- **Time series data**: a sequence of data points collected **over an interval of time** e.g daily rainfall measurements, weekly sales
- **Lag**: time difference between two observations in a sequence

| <i>Day</i> | <i>Value</i> | <i>Lag - 1</i> | <i>Lag - 2</i> |
|------------|--------------|----------------|----------------|
| 1 | 10 | NA | NA |
| 2 | 20 | 10 | NA |
| 3 | 30 | 20 | 10 |
| 4 | 40 | 30 | 20 |
| 5 | 50 | 40 | 30 |

Key definitions

- **Basis**: known family of **functions/transformations** e.g polynomials, thresholds, splines etc **applied to a predictor X to generate basis variables**: $b_1(X), b_2(X) \dots b_k(X)$.

$$y = \beta_0 + \beta_1 b_1(x) + \beta_2 b_2(x) + \dots + \beta_k b_k(x) + \epsilon \quad (1)$$

- **Basis function** for polynomial takes the form:

$$b_j(x) = x^j \quad (2)$$

polynomial function of degree j ↑ ↑ Raise predictor x to degree j

- Substituting equation (2) in (1) Degree 3 polynomial

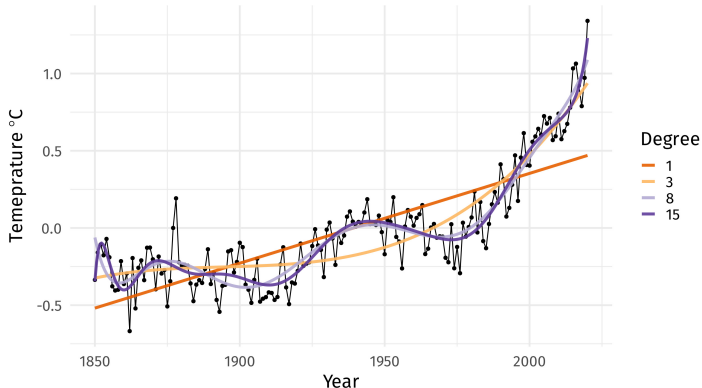
$$y = \beta_0 + \beta_1 x + \beta_2 x^2 + \beta_3 x^3 + \dots + \beta_d x^d + \epsilon$$

Degree 1 (linear term) ↑ ↑ Degree 2 polynomial ↑ Degree d polynomial

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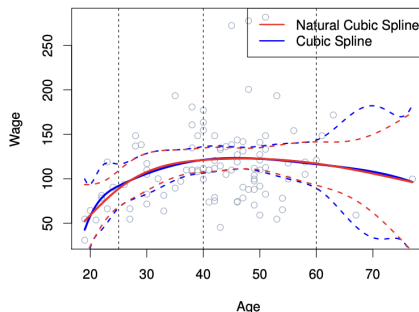
Modelling non-linear data associations

- **Polynomials** and **cubic splines (degree 3 polynomials)** are the most common **basis** used to fit non-linear associations
- Unusual to use d greater than **3 or 4, overfitting and wiggly**



Natural (restricted) cubic spline

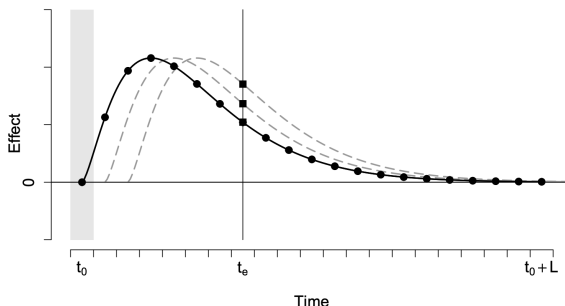
- **Natural cubic spline**: cubic spline with **additional boundary constraints**, enforcing linearity beyond boundary knots
- Produce more **stable estimates at boundaries** (narrower confidence intervals) than cubic splines



- **How are these concepts used in DLNMs?**

DLNMs: Modelling framework

- DLNMs capture a detailed representation of the **time-course** of the **exposure-lag-response relationship**
- Risk associated with individual exposure events at each lag **assigned a weight** that contributes to **overall cumulative risk**



- Statistical issue is to model this risk!**

Basic model

- A general statistical model representation to describe the **time series of outcomes** Y_t with $t = 1, \dots, n$ is given by:

Link function

Smoothed predictor

$$g(\mu_t) = \alpha + \sum_{j=1}^J s_j(x_{tj}; \beta) + \sum_{k=1}^K \gamma_k u_{tk}$$

Other predictors with linear effects

- x_{tj} is the transformed (**non-linear/smoothed**) exposure at time t through basis function j
- β is (**linear**) unknown coefficient of x_{tj} to be estimated

Exposure-lag-response associations

- The risk is represented by a function $s(x, t)$ defined in terms of both **intensity** and **timing** of a series of **past exposures**:
 - an **exposure-response** function $f(x)$ for **exposure** x
 - a **lag-response** function $w(\ell)$ for **lag** ℓ
- Generating a **bi-dimensional exposure-lag-response** function

$$s(x, t) = f(x) \cdot w(\ell)$$

that describes **simultaneously** both the **intensity** and **timing** of **past exposures**

Basis for exposure-response function

- Given, a timeseries of exposure X and assuming a **maximum lag of 2**, we can compute, q_{xt} (**vector of lagged exposure histories of X**)
- Applying a **linear transformation** to q_{xt} we get R_{xt} (**basis variables for lagged occurrences of X**)

| t | x | lag 0 | lag 1 | lag 2 |
|-----|-----|-------|-------|-------|
| 1 | 10 | 10 | NA | NA |
| 2 | 20 | 20 | 10 | NA |
| 3 | 30 | 30 | 20 | 10 |
| 4 | 40 | 40 | 30 | 20 |
| 5 | 50 | 50 | 40 | 30 |

\Rightarrow

| | | |
|----|----|----|
| 10 | NA | NA |
| 20 | 10 | NA |
| 30 | 20 | 10 |
| 40 | 30 | 20 |
| 50 | 40 | 30 |

\Rightarrow

| | | |
|----|----|----|
| 10 | NA | NA |
| 20 | 10 | NA |
| 30 | 20 | 10 |
| 40 | 30 | 20 |
| 50 | 40 | 30 |


Basis for lag-response function

- Applying **polynomial transformation of degree 2** to the lag vector, $\ell(0,1,2)$
- First step is to scale the lag vector by dividing by the maximum lag:

$$(0, 1, 2)/2 \Rightarrow (0, 0.5, 1)$$

- Obtaining **C** (**basis variables for each lag for polynomial degrees $d = 0,1,2$**)

| x^d | x^0 | x^1 | x^2 |
|-------------|-------|-------|-------|
| lag 0 (0) | 1 | 0 | 0 |
| lag 1 (0.5) | 1 | 0.5 | 0.25 |
| lag 2 (1) | 1 | 1 | 1 |

 $\Rightarrow C = \begin{bmatrix} 1 & 0 & 0 \\ 1 & 0.5 & 0.25 \\ 1 & 1 & 1 \end{bmatrix}$


Special tensor product

- **Simultaneously** captures the **intensity and timing of past exposures**

$$A_{xt} = (\underset{\text{Hadamard product}}{1_{v\ell}} \otimes R_{xt}) \odot (C \otimes \underset{\text{Kronecker product}}{1_{vx}})$$

- $1_{v\ell}$: Vector of 1's of dimensional length of **lag vector**

$$\ell(0, 1, 2) \Rightarrow 1_{v\ell} = [1, 1, 1]$$

- 1_{vx} : Vector of 1's of dimensional length of **exposure vector**

| t | x |
|---|----|
| 1 | 10 |
| 2 | 20 |
| 3 | 30 |
| 4 | 40 |
| 5 | 50 |

 $\Rightarrow 1_{vx} = \begin{bmatrix} 1 \\ 1 \\ 1 \\ 1 \\ 1 \end{bmatrix}$

$$1_{vl} \otimes R_{xt}$$

$$[1, 1, 1] \otimes \begin{bmatrix} 10 & \text{NA} & \text{NA} \\ 20 & 10 & \text{NA} \\ 30 & 20 & 10 \\ 40 & 30 & 20 \\ 50 & 40 & 30 \end{bmatrix} = \begin{bmatrix} 10 & 10 & 10 \\ 20 & 20 & 20 \\ 30 & 30 & 30 \\ 40 & 40 & 40 \\ 50 & 50 & 50 \\ \text{NA} & \text{NA} & \text{NA} \\ 10 & 10 & 10 \\ 20 & 20 & 20 \\ 30 & 30 & 30 \\ 40 & 40 & 40 \\ \text{NA} & \text{NA} & \text{NA} \\ \text{NA} & \text{NA} & \text{NA} \\ 10 & 10 & 10 \\ 20 & 20 & 20 \\ 30 & 30 & 30 \end{bmatrix}$$

$$C \otimes 1_{vx}$$

$$\begin{bmatrix} 1 & 0 & 0 \\ 1 & 0.5 & 0.25 \\ 1 & 1 & 1 \end{bmatrix} \otimes \begin{bmatrix} 1 \\ 1 \\ 1 \\ 1 \\ 1 \\ 1 \\ 1 \end{bmatrix} = \begin{bmatrix} 1 & 0 & 0 \\ 1 & 0 & 0 \\ 1 & 0 & 0 \\ 1 & 0 & 0 \\ 1 & 0 & 0 \\ 1 & 0.5 & 0.25 \\ 1 & 0.5 & 0.25 \\ 1 & 0.5 & 0.25 \\ 1 & 0.5 & 0.25 \\ 1 & 0.5 & 0.25 \\ 1 & 1 & 1 \\ 1 & 1 & 1 \\ 1 & 1 & 1 \\ 1 & 1 & 1 \\ 1 & 1 & 1 \end{bmatrix}$$

$$(1_{v\ell} \otimes R_{xt}) \odot (C \otimes 1_{vx}) = A_{xt}$$

| | | | | | | | | | | |
|----|----|----|--|---|-----|------|--|----|----|-----|
| 10 | 10 | 10 | | 1 | 0 | 0 | | 10 | 0 | 0 |
| 20 | 20 | 20 | | 1 | 0 | 0 | | 20 | 0 | 0 |
| 30 | 30 | 30 | | 1 | 0 | 0 | | 30 | 0 | 0 |
| 40 | 40 | 40 | | 1 | 0 | 0 | | 40 | 0 | 0 |
| 50 | 50 | 50 | | 1 | 0 | 0 | | 50 | 0 | 0 |
| NA | NA | NA | | 1 | 0.5 | 0.25 | | NA | NA | NA |
| 10 | 10 | 10 | | 1 | 0.5 | 0.25 | | 10 | 5 | 2.5 |
| 20 | 20 | 20 | | 1 | 0.5 | 0.25 | | 20 | 10 | 5 |
| 30 | 30 | 30 | | 1 | 0.5 | 0.25 | | 30 | 15 | 7.5 |
| 40 | 40 | 40 | | 1 | 0.5 | 0.25 | | 40 | 20 | 10 |
| NA | NA | NA | | 1 | 1 | 1 | | NA | NA | NA |
| NA | NA | NA | | 1 | 1 | 1 | | NA | NA | NA |
| 10 | 10 | 10 | | 1 | 1 | 1 | | 10 | 10 | 10 |
| 20 | 20 | 20 | | 1 | 1 | 1 | | 20 | 20 | 20 |
| 30 | 30 | 30 | | 1 | 1 | 1 | | 30 | 30 | 30 |

Cumulative risk of exposures across lags

- From Gasparrini et al 2010 "...array A_{xt} is then re-arranged **summing along the third dimension of lags** to obtain the **final matrix of cross-basis functions, w_{xt}** ."

$$A_{xt} \Rightarrow \begin{bmatrix} 10 & 0 & 0 \\ 20 & 0 & 0 \\ 30 & 0 & 0 \\ 40 & 0 & 0 \\ 50 & 0 & 0 \end{bmatrix} \oplus \begin{bmatrix} \text{NA} & \text{NA} & \text{NA} \\ 10 & 5 & 2.5 \\ 20 & 10 & 5 \\ 30 & 15 & 7.5 \\ 40 & 20 & 10 \end{bmatrix} \oplus \begin{bmatrix} \text{NA} & \text{NA} & \text{NA} \\ \text{NA} & \text{NA} & \text{NA} \\ 10 & 10 & 10 \\ 20 & 20 & 20 \\ 30 & 30 & 30 \end{bmatrix}$$

$$\text{Direct} - \text{sum}(\oplus) \Rightarrow \begin{bmatrix} \text{NA} & \text{NA} & \text{NA} \\ \text{NA} & \text{NA} & \text{NA} \\ 60 & 20 & 15 \\ 90 & 35 & 27.5 \\ 120 & 50 & 40 \end{bmatrix} = w_{xt}\beta$$

Crossbasis functions

```
# Load package
pacman::p_load("dlnm")

# data
x <- data.frame(
  t = 1:5,
  value = c(10, 20, 30, 40, 50)
)
x

##    t value
## 1 1    10
## 2 2    20
## 3 3    30
## 4 4    40
## 5 5    50

# crossbasis
cb.x <- crossbasis(x$value, lag=2,
  argvar=list(fun = "lin"),
  arglag=list(fun="poly", degree=2))

# crossbasis matrix
head(cb.x, 5)

##      v1.11 v1.12 v1.13
## [1,]    NA    NA    NA
## [2,]    NA    NA    NA
## [3,]    60    20   15.0
## [4,]    90    35   27.5
## [5,]   120    50   40.0
```

Distributed lag non-linear models (DLNMs)

- **Bi-dimensional exposure-lag-response** function $f(x) \cdot w(l)$:

$$s(x, t) = \int_{\ell_0}^L f(x_{t-\ell}) \cdot w(\ell) d\ell$$

- Approximation obtained through a **discretization of the lag period into equally spaced time units, q_{x_t}**

$$s(x_{t-\ell_0}, \dots, x_{t-L}) \approx \sum_{\ell=\ell_0}^L f(x_{t-\ell}) \cdot w(\ell)$$

- The **problem reduces to choosing a basis function** for **exposure-response (q_{x_t})** and **lag-response (ℓ)** space

Effect of temperature and ozone on mortality

```
# Load packages and data
pacman::p_load("dlnm", "splines")
chicagoNMMAPS <- chicagoNMMAPS

# Objective: to investigate the effects of temperature and
# Ozone on mortality up to lag 30 and 5, respectively

# crossbasis ozone
cb.o3 <- crossbasis(chicagoNMMAPS$o3, lag=5,
                    argvar=list(fun="thr", thr=40.3),
                    arglag=list(fun="thr"))

# crossbasis temperature
cb.temp <- crossbasis(chicagoNMMAPS$temp, lag=30,
                     argvar=list(fun = "ns", df=5),
                     arglag=list(fun="bs"))

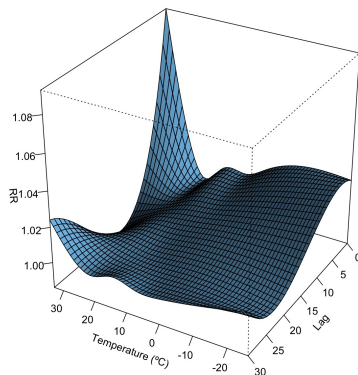
# model
model <- glm(death ~ cb.o3 + cb.temp + dow,
             family=quasipoisson(), chicagoNMMAPS)

# pred (extract estimated associations predicted by model)
pred.temp <- crosspred(cb.temp, model, cen=21)
pred.o3 <- crosspred(cb.o3, model, at=c(0:65,40.3))

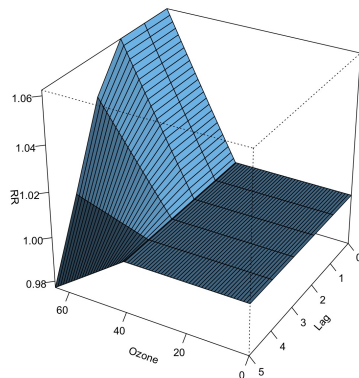
# plots
plot(pred.temp, xlab="Temperature (°C)", zlab="RR",
     main="3D graph of temperature effect on mortality")
```

Effect of temperature and ozone on mortality

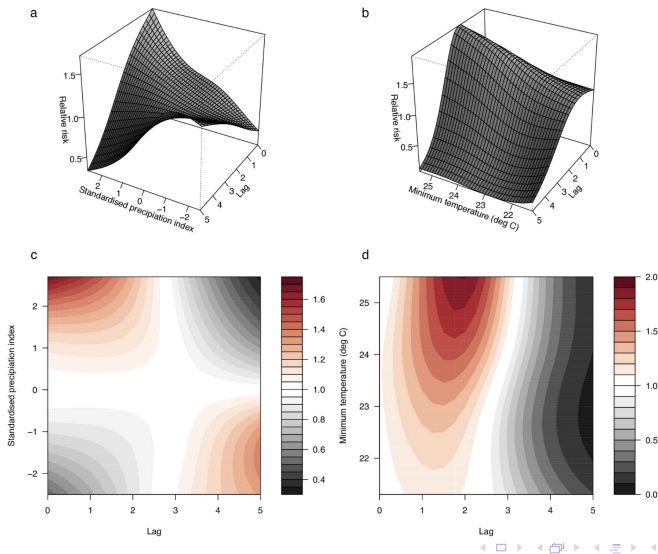
3D graph of temperature effect on mortality



3D graph of ozone effect on mortality



Effect of rainfall and temperature on dengue risk



References

- A. Gasparrini, Armstrong, and Kenward 2010
- Antonio Gasparrini 2011
- Gareth James • Daniela Witten • Trevor Hastie and Robert Tibshirani 2013
- Antonio Gasparrini and Leone 2014
- Aßenmacher 2016
- Lowe et al. 2018

Thank you!

Slides: <https://github.com/arumadri/dlnm>