

Overlap Add method for linear convolution

AIM

Write a MATLAB program to perform linear convolution through overlap add method and verify the result through direct convolution using the MATLAB builtin function - **conv**

THEORY

Linear filtering methods based on DFT

Suppose a finite duration sequence $x[n]$ of length L is applied as the input to an FIR filter of length M . The output of the filter in time domain can be expressed as the linear convolution of $x[n]$ & $h[n]$ as,

$$y[n] = \sum_{k=0}^{M-1} h[k]x[n-k]$$

The length of the linear convolution of $x[n]$ & $h[n]$ will be $L + M - 1$

We know that the IDFT of the product $X[k]H[k]$ will give us the circular convolution of $x[n]$ & $h[n]$.

We can ensure that this circular convolution has the effect of linear convolution by padding both $x[n]$ & $h[n]$ with enough zeros to make each sequence have a length of $L + M - 1$.

Thus we can get the filtered output sequence $y[n]$ using DFT-IDFT method to compute the circular convolution of the zero-padded $x[n]$ & $h[n]$

Filtering of long data sequences

The input sequence $x[n]$ is often very long especially in real-time signal monitoring applications. For linear filtering via the DFT, the signal must be limited in size due to memory requirements. To solve this issues, we use a strategy which involves:

- Segmenting the input signal into fixed-size blocks prior to processing
- Computing the DFT-based linear filtering of each block separately via the FFT
- Fitting the output blocks together in such a way that the overall output is equivalent to linear filtering $x[n]$ directly

The main advantage of this strategy is that samples of the output $y[n]$ will be available in real-time on a block-by-block basis.

Assume that the input sequence is segmented into blocks of length L & M is the length of the FIR filter and $L \gg M$.

There are two methods utilizing this strategy:

- Overlap-Add Method
- Overlap-Save Method

Overlap-Add Method:

Here, we segment the long input sequence into fixed size input data blocks of length L .

To each data block, we append $M - 1$ zeros to produce the N -length subsequences $x_m[n]$; $m = 1, 2, \dots$

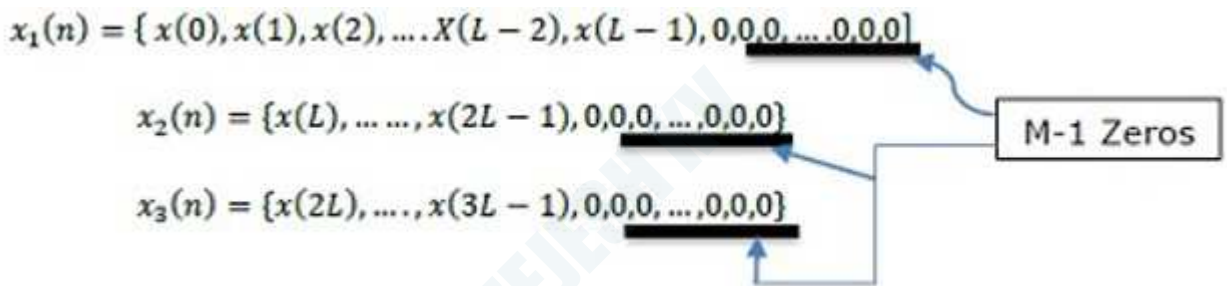


Figure 4.1: Formation of input subsequences: Overlap-Add Method

The lengths of DFTs & IDFTs used in this method are $N = L + M - 1$.

We take each subsequence, $x_m[n]$, and compute its N -point DFT, $X_m[k]$.

The impulse response of the FIR filter is increased in length by appending $L - 1$ zeros and an N -point DFT, $H[k]$, is computed once and stored.

For each subsequence $x_m[n]$, we multiply the two N -point DFTs together to form,

$$Y_m[k] = H[k]X_m[k]; k = 0, 1, \dots, N-1$$

Taking the N -point IDFT of this result, yields the N -length output data block $y_m[n]$ which is free of aliasing.

The last $M - 1$ blocks from each output block must be overlapped and added to the first $M - 1$ points of the succeeding block to get the final output sequence $y[n]$ as shown in the figure below.

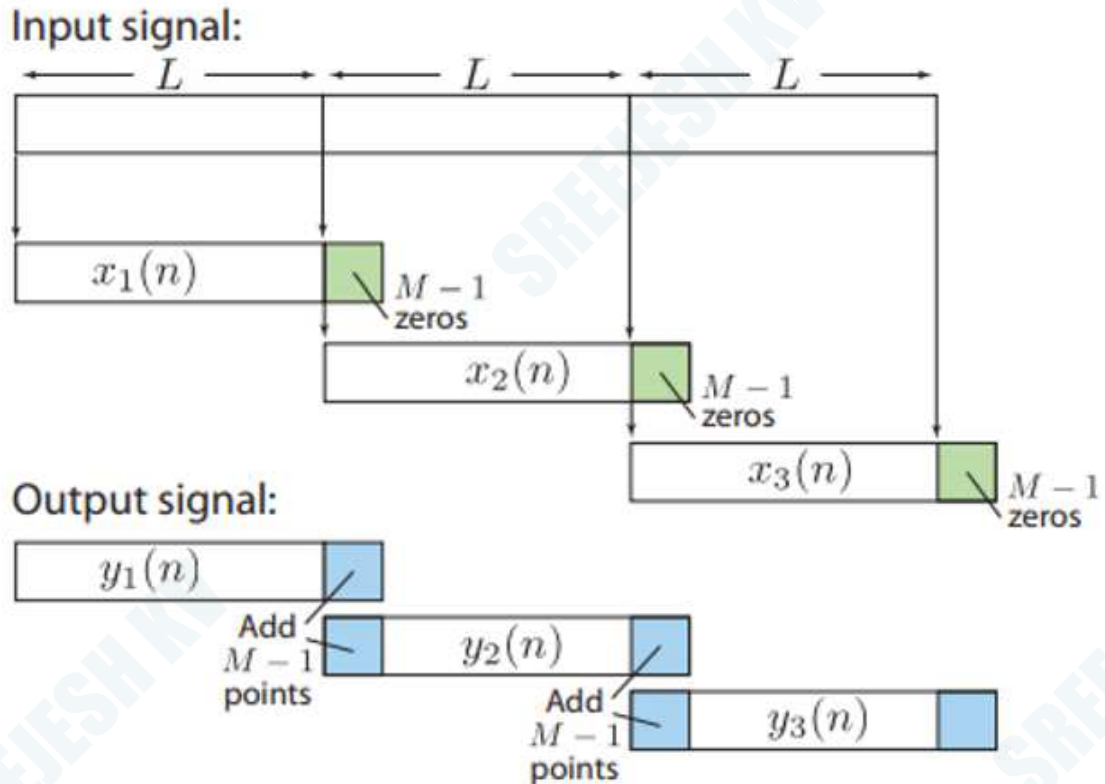


Figure 4.2: Overlap-Add Method

MATLAB FUNCTIONS USED

randi

Pseudorandom integers from a uniform discrete distribution

$R = \text{randi}([IMIN, IMAX], [M, N])$ returns an M by N array containing integer values drawn from the discrete uniform distribution on $IMIN:IMAX$.

ALGORITHM

- Step 1. Start
- Step 2. Define the input sequence $x[n]$, its length $N1$, the filter coefficients $h[n]$, its length M , block length L , DFT length $N = L + M - 1$
- Step 3. Zero pad $x[n]$ to the length $N2$ which is the next higher multiple of L after $N1$.
- Step 4. Zero-pad the sequence $h[n]$ to $M + L - 1$ -length and compute its N point DFT $H[k]$

- Step 5. Create non-overlapping subsequences of length L from $x[n]$ and follow each subsequence by $M - 1$ zeros.
- Step 6. Find the N point DFT of each subsequence, multiply it with $H[k]$ and find the inverse DFT to get $y_m[n]$
- Step 7. Obtain the output sequence $y[n]$ by fitting each output subsequences in such a way that last $M - 1$ values of an output- subsequence are overlapped and added with the first $M - 1$ values from the next output-subsequence.
- Step 8. Verify the result obtained using MATLABs inbuilt **conv** function
- Step 9. Stop

PROGRAM

```

1 %Title: Program to Perform linear convolution through overlap add ...
   method
2 %and verify the results using the builtin function - conv
3
4 %Author: Sreejesh K V, Dept. of ECE, GCEK
5 %Date: 25/09/2022
6
7 clc;
8 clear;
9 close all;
10
11 x=randi([-15 15],[1 32]);% Generating a random 32 length sequence ...
   of integers in the range -15 to 15
12 h=[1 0.2 -2];% FIR filter's impulse response
13
14 L=6;%number of nonzero values in each subsequence
15 N1=length(x);%input sequence length
16 M=length(h);%filter length
17 N=L+M-1;%DFT length
18 lclength=N1+M-1;% length of linear convolution sequence
19
20 % --direct linear convolution using inbuilt function for ...
   verification --%
21 lc=conv(x,h);
22
23 % -- Overlap Add method for computing the linear convolution -- %
24 x=[x zeros(1,mod(-N1,L))];%zero pad x to the length which is the ...
   next multiple of L
25 N2=length(x);% N2 will be a multiple of L
26 h=[h zeros(1,L-1)];%zero-padding the sequence h[n] to M+L-1 length
27 H=fft(h,N);%N=L+M-1 point DFT of h[n]
28
29 S=N2/L;%number of segments
30 index=1:L;%index of first set of L values to be taken from x[n]
```

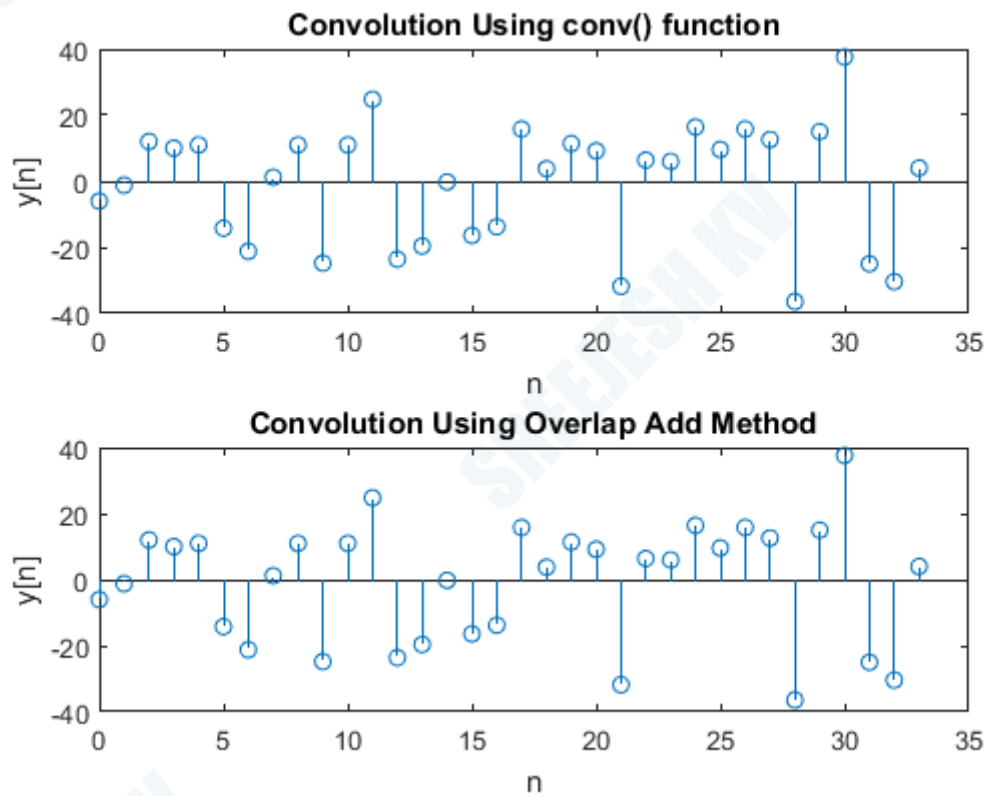
```

31 y=zeros(1, M-1);%the output sequence-initialized with M-1 zeros
32 for stage=1:S
33 xm=[x(index) zeros(1,M-1)]; % Selecting the subsequence to ...
    process & proceed with M-1 zeros
34 Xm=fft(xm,N);%N point FFT of subsequence
35 Ym=Xm.*H;%multiplying subsequence DFT with filter DFT
36 ym=ifft(Ym,N);%taking IDFT- will give the N point circular convln ...
    of x_m[n]& h[n]
37
38 %Z is the M-1 point sequence obtained by Overlapping & adding ...
    first M-1 values of ym to last M-1 values of y
39 Z=y((length(y)-M+2):length(y))+ym(1:M-1);%
40
41 y=[y(1:(stage-1)*L) Z ym(M:M+L-1)];%concatenating the sequences
42 index=(stage*L)+1:(stage+1)*L;%set the index to next set of L ...
    values from x[n]
43 end
44 i=1:lclength;
45 y=y(i);%trimming the zero values at the end
46
47 % -- time values (values of n) for plotting -- %
48 n=0:lclength-1;%first value of the sequence corresponds to n=0
49
50 % -- Plotting the sequences -- %%
51 figure()
52 subplot(2,1,1)
53 stem(n,lc);
54 title('Convolution Using conv() function')
55 xlabel('n');
56 ylabel('y[n]');
57
58 subplot(2,1,2)
59 stem(n,y);
60 title('Convolution Using Overlap Add Method')
61 xlabel('n');
62 ylabel('y[n]');

```

OUTPUT & OBSERVATIONS

Figure Window Output:



RESULTS

A program to compute the linear convolution of two sequences using overlap-add method was written and executed in MATLAB and the result was verified using the inbuilt function **conv**