



A central yellow circle contains the text "KTUNOTES" in a bold, black, brush-style font.

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$$\int_0^{2\pi} e^{j\omega_0 t - j\omega_0 t} dt$$

$$= \int_0^{2\pi} e^{j\omega_0 t (K-m)} dt$$

$$\begin{aligned} &= \int_0^{2\pi} [\cos(\omega_0 t + (K-m)) + j \sin(\omega_0 t + (K-m))] dt \\ &= \frac{1}{j\omega_0(K-m)} \left[e^{j\omega_0 t (K-m)} - 1 \right] \\ &\quad + \frac{1}{j\omega_0(K-m)} \left[e^{j\omega_0 t (K-m)} - 1 \right]^* \\ &= \frac{1}{j\omega_0(K-m)} \left[\cos(\omega_0 t (K-m)) + j \sin(\omega_0 t (K-m)) - 1 \right] \\ &= \frac{1}{j\omega_0(K-m)} [1 + 0 - 1] \\ &= \frac{1}{j\omega_0(K-m)} \end{aligned}$$

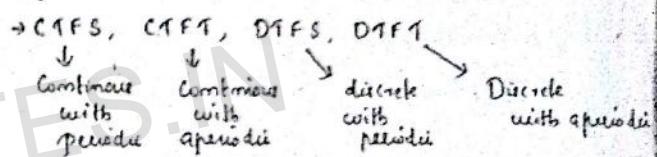
Hence, proved the given signal is orthogonal.

$$a_{m+n} = \int_{-\infty}^{\infty} x(t) e^{-j\omega_0 t} dt$$

MODULE - 3

CONTINUOUS TIME FOURIER SERIES

- Fourier transformation is used to convert time domain to frequency domain.
- If the signal is periodic signal, we use Fourier series and if it is aperiodic signal, we use Fourier transforms.



In discrete case continuous case;

$$x(t+T) = x(t)$$

$$T = 2\pi/\omega_0 \rightarrow \text{fundamental period}$$

$\cos \omega_0 t$ and $e^{j\omega_0 t}$ are periodic signals.

The eqn of Continuous time Fourier Series, is,

eqn is
called
synthesis
eqn.

$$x(t) = \sum_{k=-\infty}^{\infty} a_k e^{j\omega_0 k t}$$

when $K=0$, $x(t) = \text{constant}$

$$K=1, x(t) = a_1 e^{j\omega_0 t} + a_1 e^{-j\omega_0 t} \quad \left. \right\} 1^{\text{st}} \text{ harmonic}$$

$$K=\pm 2, x(t) = a_2 e^{j\omega_0 t} + a_2 e^{-j\omega_0 t} \quad \left. \right\} 2^{\text{nd}} \text{ harmonic}$$

Multiply both side of synthesis eqns by $e^{-j\omega_0 t}$, we get,

$$e^{-j\omega_0 t} x(t) = \sum_{k=-\infty}^{\infty} a_k e^{-jk\omega_0 t} e^{jk\omega_0 t}$$

Integrating,

$$\int e^{-j\omega_0 t} x(t) dt = \sum_{k=-\infty}^{\infty} a_k \int e^{j(k-n)\omega_0 t} dt$$

$$\int e^{j(k-n)\omega_0 t} dt = \cos((k-n)\omega_0 t) + j \sin((k-n)\omega_0 t)$$

$$= 0 + 0 - 1$$

$$\begin{cases} 1, & k=n \\ 0, & k \neq n \end{cases}$$



$$\therefore \int e^{-j\omega_0 t} x(t) dt = a_n T$$

$$A_m = \frac{1}{T} \int x(t) e^{-j\omega_0 t} dt \quad \left. \right\} \text{analysis eqn}$$

$$a_k = \frac{1}{T} \int x(t) e^{-jk\omega_0 t} dt \quad \left. \right\} \text{analysis eqn}$$

Calculate the frequency components in the following signals.

(i) $x(t) = \sin(\omega_0 t)$

Ans. Since, Sinusoid is continuous periodic signal, we use CTFS eqn.

By Euler's theorem,

$$\sin \theta = \frac{e^{j\theta} - e^{-j\theta}}{2j}$$

$$\therefore x(t) = \frac{e^{j\omega_0 t} - e^{-j\omega_0 t}}{2j} = \frac{1}{2j} e^{j\omega_0 t} - \frac{1}{2j} e^{-j\omega_0 t}$$

when this compare with synthesis eqn, we

$$K=1, a_1 = \frac{1}{2j}$$

$$K=-1, a_{-1} = -\frac{1}{2j}$$

$$K \text{ else}, a_k = 0$$

$$\left\{ \begin{array}{l} x(t) = \sum_{k=-\infty}^{\infty} a_k e^{jk\omega_0 t} \\ K=1, x(t) = \frac{1}{2j} e^{j\omega_0 t} \\ K=-1, x(t) = -\frac{1}{2j} e^{-j\omega_0 t} \end{array} \right.$$

→ Amplitude spectrum is $|a_k|$ vs K

→ Phase spectrum is $\angle a_k$ vs K .

We have $a_1 = \frac{1}{2}j$, $a_{-1} = -\frac{1}{2}j$
 $|a_1| = \sqrt{(1/2)^2} = \frac{1}{2}$

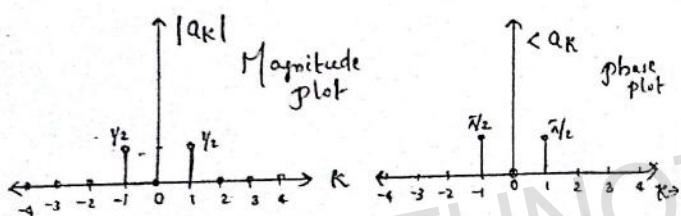
$|a_{-1}| = \frac{1}{2}$.

Now, $a_1 = 0 - j/2$.

$a_2 = 0 + j/2$

$\angle a_1 = \tan^{-1} \left(\frac{-j/2}{0} \right) = 90^\circ = \pi/2$

$\angle a_2 = \tan^{-1} \left(j/2 \right) = 90^\circ = \pi/2$



O/p is always discrete.

Q: Plot the magnitude & phase spectrum
 of $x(t) = 1 + 5 \sin \omega_0 t + a \cos \omega_0 t + \cos(\omega_0 t + \frac{\pi}{4})$

Ans. $x(t) = 1 + \frac{e^{j\omega_0 t} - e^{-j\omega_0 t}}{2j} + \frac{e^{j\omega_0 t} + e^{-j\omega_0 t}}{2} + \frac{e^{j(\omega_0 t + \pi/4)}}{2} + \frac{e^{-j(\omega_0 t + \pi/4)}}{2}$

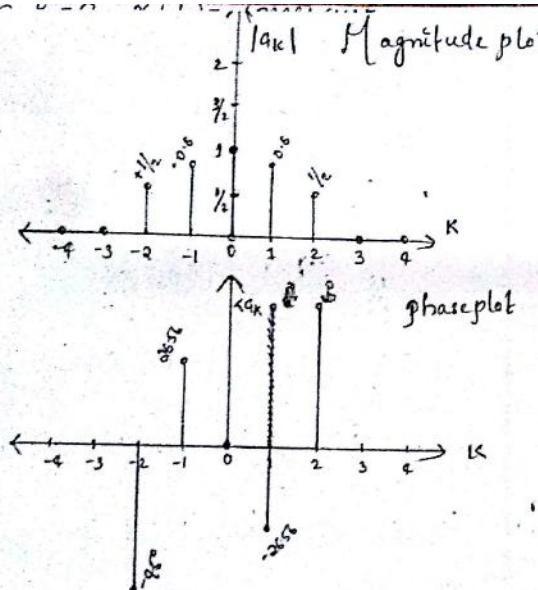
2

$$\begin{aligned}
 &= 1 + \frac{1}{2}j e^{j\omega_0 t} - \frac{1}{2}j e^{-j\omega_0 t} + e^{j\omega_0 t} \\
 &+ e^{-j\omega_0 t} + \frac{1}{2} e^{j(\omega_0 t + \pi/4)} + \frac{1}{2} e^{-j(\omega_0 t + \pi/4)} \\
 &= 1 + \left(\frac{1}{2}j + 1 \right) e^{j\omega_0 t} + \left(1 - \frac{1}{2}j \right) e^{-j\omega_0 t} + \\
 &\quad \frac{1}{2} e^{j(\omega_0 t + \pi/4)} + \frac{1}{2} e^{-j(\omega_0 t + \pi/4)} \\
 &= 1 + \left(\frac{1}{2}j + 1 \right) e^{j\omega_0 t} + \left(1 - \frac{1}{2}j \right) e^{-j\omega_0 t} + \\
 &\quad \frac{1}{2} e^{j\pi/4} \cdot e^{j\omega_0 t} + \frac{1}{2} e^{-j\pi/4} \cdot e^{-j\omega_0 t}
 \end{aligned}$$

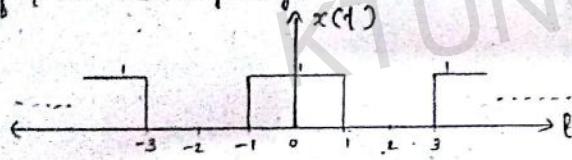
Now, compare with the synthesis eqn.,

$x(t) = \sum_{k=-\infty}^{\infty} a_k e^{jk\omega_0 t}$, then we get

$a_0 = 1$	$\angle a_0 = 0$	$ a_0 = 1$
$a_1 = 1 + j/2$	$\angle a_1 = \tan^{-1}(j/2)$	$ a_1 = \sqrt{5}/2$
$a_{-1} = 1 - j/2$	$\angle a_{-1} = \tan^{-1}(-j/2)$	$ a_{-1} = \sqrt{5}/2$
$a_2 = \frac{1}{2} e^{j\pi/4}$	$\angle a_2 = \pi/4 = 45^\circ$	$ a_2 = 1/2$
$a_{-2} = \frac{1}{2} e^{-j\pi/4}$	$\angle a_{-2} = -\pi/4 = -45^\circ$	$ a_{-2} = 1/2$



Obtain the Fourier series representation for the waveform.



Ans. Since, it is repeated; it is periodic.

Here, period, $T = 0.4$.

$$a_k = \frac{1}{T} \int_{-T/2}^{T/2} x(t) e^{-j k \omega_0 t} dt$$

$$a_k = \frac{1}{0.4} \int_{-0.2}^{0.2} x(t) e^{-j k \omega_0 t} dt$$

$$\omega_0 = \frac{2\pi}{T} = \frac{2\pi}{0.4} = \frac{\pi}{2}$$

$$= \frac{1}{0.4} \int_{-0.2}^{0.2} e^{-j k \frac{\pi}{2} t} dt$$

$$= \frac{1}{0.4} \left[\frac{e^{-j k \frac{\pi}{2} t}}{-j k \frac{\pi}{2}} \right]_{-0.2}^{0.2}$$

$$= \frac{1}{0.4} \left[\frac{e^{-j k \frac{\pi}{2}} - e^{j k \frac{\pi}{2}}}{-j k \frac{\pi}{2}} \right]$$

$$= \frac{1}{0.4} \left[\frac{e^{-j k \frac{\pi}{2}} - e^{j k \frac{\pi}{2}}}{2 \times -j k \frac{\pi}{2}} \right]$$

$$= \frac{1}{0.4} \times \left[\frac{e^{j k \frac{\pi}{2}} - e^{-j k \frac{\pi}{2}}}{2 j k \frac{\pi}{2}} \right]$$

$$= \frac{1}{0.4} \cdot \frac{\sin(k \frac{\pi}{2})}{k \frac{\pi}{2}}$$

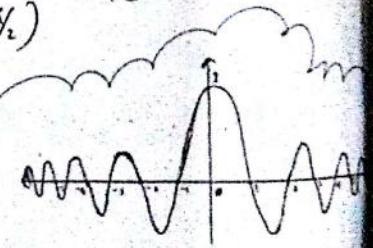
$\lim_{t \rightarrow 0}$
So neglect the limit
 $t = 0$
and take
limit changes
 $t \rightarrow 0$

$$\sin \theta = \frac{e^{j\theta} - e^{-j\theta}}{2j}$$

$$\therefore x(k) = a_k = \frac{1}{0.4} \frac{\sin(k \frac{\pi}{2})}{k \frac{\pi}{2}}$$

$$x(k) = \frac{1}{0.4} \frac{\sin(k \frac{\pi}{2})}{k \frac{\pi}{2}}$$

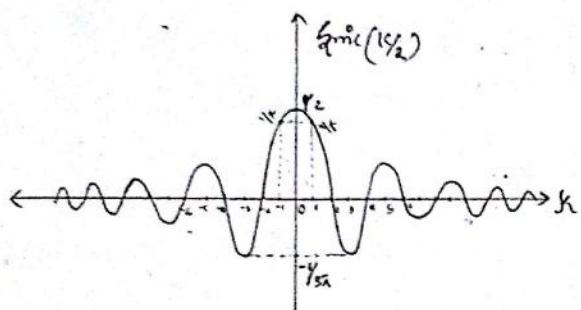
Now, we have
to plot its magnitude
& phase



$$\sin \theta = 1, \theta = 0$$

$$0, \theta = \pm \pi$$

$\frac{1}{k}$	0	1	-1	± 2	± 3	± 4
a_k	γ_2	γ_K	γ_K	0	$-\frac{1}{3\pi}$	0



CONVERGENCE OF FOURIER SERIES:

• Dirichlet's Condition:

(i) $x(t)$ absolutely integrable.

$$\therefore \int |x(t)| dt < \infty.$$

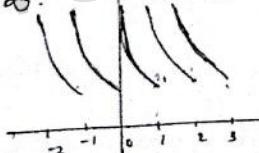
e.g:

$$\int x(t) dt < \infty$$

$$\int \frac{1}{t} dt = [\log t]$$

$$= \log 1 - \log 0 = 0 - (-\infty) = \infty.$$

Hence it is not absolutely integrable
∴ It is not exist.



For the existing of fourier series there are 3 suff conditons
 $x(t) = \gamma_L, \text{ oct } t \in \mathbb{R}$

(ii) $x(t)$ must have a finite number of maxima and minima over a period.

e.g:

$$x(t) = \sin 2\pi t, 0 \leq t \leq 1$$

$$\text{when } t = 0.001, \sin 2000\pi$$

Hence, frequency is

Very high.

We cannot

count

Hence, no. of

maxima & minima is infinite.

Hence, the condition is not satisfied. It is not exist.

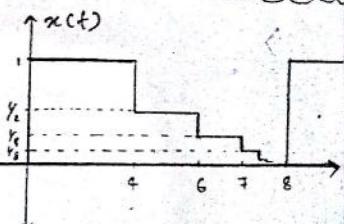
(iii) $x(t)$ must have finite & no. of discontinuities over a period.

finite
no. of
discontinuities

exist

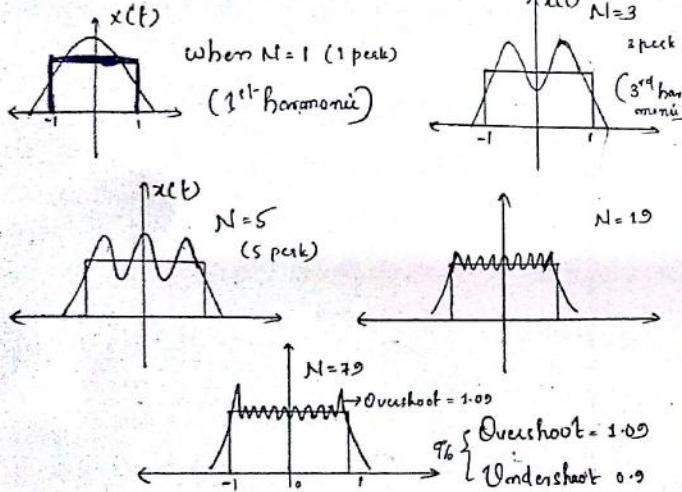
example:

Here, there are infinite no. of discontinuities. Hence, the fourier series doesn't exist.



{ Here, one period = 8, ∵ There are infinite no. of discontinuities over a period }

Gibbs Phenomenon:



when harmonics increases, there is only a single overshoot at the discontinuity point.

FOURIER SERIES (Types):

(i) Exponential FS:

$$x(t) = \sum_{k=-\infty}^{\infty} a_k e^{jk\omega_0 t}$$

$$a_k = \frac{1}{T} \int x(t) e^{-jk\omega_0 t} dt$$

(ii) Trigonometric FS:

$$x(t) = a_0 + \sum_{n=1}^{\infty} a_n \cos \omega_0 n t + \sum_{n=1}^{\infty} b_n \sin \omega_0 n t$$

$$\left\{ \text{actually} \right\} x(t) = \sum_{k=0}^{\infty} a_k \cos(k\omega_0 t) + \sum_{k=0}^{\infty} b_k \sin(k\omega_0 t)$$

when $k=0$, we get a_0 & $b_0=0$

$$\text{where, } a_0 = \frac{1}{T} \int x(t) dt$$

$$a_n = \frac{2}{T} \int x(t) \cos n\omega_0 t dt$$

$$b_n = \frac{2}{T} \int x(t) \sin n\omega_0 t dt$$

Polar Fourier Series:

$$x(t) = a_0 + \sum_{n=1}^{\infty} a_n \cos(n\omega_0 t + \phi_n)$$

Compare trigonometric FS with Polar FS, we get, $a_0 = a_0 = \frac{1}{T} \int x(t) dt$

$$a_n = \sqrt{a_n^2 + b_n^2}$$

$$\phi_n = \tan^{-1}(b_n/a_n)$$

Properties of CTFS:

LINEARITY:

$$\text{If } x(t) \xrightarrow{\text{FS}} X(k)$$

$$y(t) \xrightarrow{\text{FS}} Y(k),$$

$$\text{then } A x(t) + B y(t) \xrightarrow{\text{FS}} A X(k) + B Y(k)$$

Proof:

$$\text{We know } X(k) = \frac{1}{T} \int_{t_1}^{t_2} x(t) e^{-jku_0 t} dt.$$

$$Y(k) = \frac{1}{T} \int_{t_1}^{t_2} y(t) e^{-jku_0 t} dt$$

Let $x(t)$ be a real signal,

$$x(t) = A x(t) + B y(t)$$

$$\text{then } Z(k) = \frac{1}{T} \int_{t_1}^{t_2} z(t) e^{-jku_0 t} dt$$

$$= \frac{1}{T} \int_{t_1}^{t_2} [A x(t) + B y(t)] e^{-jku_0 t} dt$$

$$= \frac{1}{T} \int_{t_1}^{t_2} A x(t) e^{-jku_0 t} dt +$$

$$\frac{1}{T} \int_{t_1}^{t_2} B y(t) e^{-jku_0 t} dt$$

$$= A \frac{1}{T} \int_{t_1}^{t_2} x(t) e^{-jku_0 t} dt +$$

$$B \frac{1}{T} \int_{t_1}^{t_2} y(t) e^{-jku_0 t} dt$$

$$z(t) = A x(t) + B y(t)$$

$$\text{ie } A x(t) + B y(t) = A x(t) + B y(t)$$

Hence proved.

2. TIME SHIFTING:

$$\text{If } x(t) \leftrightarrow X(k)$$

$$\text{then } x(t - t_0) \xrightarrow{\text{FS}} e^{-jku_0 t_0} X(k)$$

Proof:

$$X(k) = \frac{1}{T} \int_{t_1}^{t_2} x(t) e^{-jku_0 t} dt$$

$$\text{let } y(t) = x(t - t_0)$$

$$\text{then } Y(k) = \frac{1}{T} \int_{t_1}^{t_2} y(t) e^{-jku_0 t} dt$$

$$Y(k) = \frac{1}{T} \int_{t_1}^{t_2} x(t - t_0) e^{-jku_0 t} dt$$

$$\text{let } \tau = t - t_0 \Rightarrow t = \tau + t_0$$

$$d\tau = dt$$

$$\text{then } Y(k) = \frac{1}{T} \int_{t_1}^{t_2} x(\tau) e^{-jku_0 (\tau + t_0)} d\tau$$

$$= \frac{1}{T} \int_{t_1}^{t_2} x(\tau) e^{-jku_0 \tau} \cdot e^{-jku_0 t_0} d\tau$$

$$= e^{-jku_0 t_0} \left[\frac{1}{T} \int_{t_1}^{t_2} x(\tau) e^{-jku_0 \tau} d\tau \right]$$

$$Y(k) = e^{-jku_0 t_0} X(k)$$

Hence proved.

$$\begin{aligned} y(t) &= x(t - t_0) \\ \text{ie } y(t) &\xrightarrow{\text{FS}} Y(k) \\ \text{ie } x(t - t_0) &\xrightarrow{\text{FS}} e^{-jku_0 t_0} \\ \text{ie } Y(k) &= e^{-jku_0 t_0} X(k) \end{aligned}$$

3. TIME REVERSAL:

If $x(t) \xrightarrow{\text{FS}} X(k)$

then $x(-t) \leftrightarrow X(-k)$

Proof :

$$\text{let } y(t) = x(-t)$$

$$\text{then } y(k) = \frac{1}{T} \int_{-T}^T y(t) e^{-j\omega_0 k t} dt \\ = \frac{1}{T} \int_{-T}^T x(-t) e^{-j\omega_0 k t} dt$$

$$\text{Now, let } \tau = -t$$

$$d\tau = -dt$$

$$\text{when } t \rightarrow 0, \tau \rightarrow 0$$

$$\tau \rightarrow T, t = -\tau$$

$$\text{then, } y(k) = \frac{1}{T} \int_{-T}^0 x(\tau) e^{j\omega_0 k \tau} (-d\tau) \\ = \frac{1}{T} \int_{-T}^0 x(\tau) e^{j\omega_0 k \tau} d\tau$$

$$\text{as } \left\{ \dots, \int_{-T}^0 (-d\tau) = \int_T^0 d\tau \right\}$$

$$= \frac{1}{T} \int_T^0 x(\tau) e^{-j\omega_0 k \tau} d\tau$$

$$y(k) = x(-k) \Rightarrow x(-t) \leftrightarrow X(-k)$$

Hence, proved.

$$\left\{ \begin{array}{l} \text{eg: } x(t) = \sin \omega_0 t \\ x(k) = \{-3, 2, 4\} \end{array} \right.$$

$$x(-t) = ? \quad x(-k) = \{4, 2, -3\}$$

4. TIME DIFFERENTIATION:

If $x(t) \xrightarrow{\text{FS}} X(k)$

then, $\frac{d}{dt} x(t) \leftrightarrow j\omega_0 k X(k)$

Proof:

$$W(t) =$$

$$x(t) = \sum_{k=-\infty}^{\infty} x(k) e^{j\omega_0 k t} \dots (1)$$

$$\text{then } \frac{d}{dt} x(t) = \frac{d}{dt} \left[\sum_{k=-\infty}^{\infty} x(k) e^{j\omega_0 k t} \right]$$

$$= \sum_{k=-\infty}^{\infty} x(k) \frac{d}{dt} e^{j\omega_0 k t}$$

$$\frac{d}{dt} x(t) = \sum_{k=-\infty}^{\infty} x(k) j\omega_0 k e^{j\omega_0 k t} \dots (2)$$

Comparing (1) & (2),

$$\frac{d}{dt} x(t) \leftrightarrow j\omega_0 k X(k)$$

Hence, proved.

$$\left(\frac{d^n}{dt^n} x(t) \leftrightarrow (j\omega_0 k)^n X(k) \right)$$

gen

5. TIME SCALING:

If $x(t) \xleftrightarrow{\text{F.S.}} X(k)$

then $x(\alpha t) \xleftrightarrow{\text{F.S.}} X(k) \Big|_{T \rightarrow T/\alpha}$

Proof:

$$\text{Let } y(t) = x(\alpha t)$$

$$Y(k) = \frac{1}{T} \int_0^T y(t) e^{-j\omega_0 k t} dt \\ = \frac{1}{T/\alpha} \int_0^{T/\alpha} x(\alpha t) e^{-j\omega_0 k \alpha t} d(\alpha t)$$

$$\text{Put } m = \alpha t$$

$$dm = \alpha dt$$

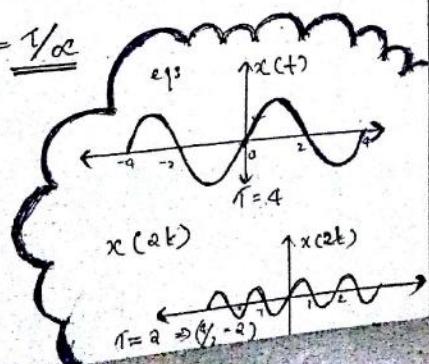
$$dt = dm/\alpha$$

$$= \frac{1}{(T/\alpha)} \int_0^{T/\alpha} x(m) e^{-j\omega_0 k m} dm$$

$$= X(k) \Big|_{T = T/\alpha}$$

Hence, proved.

Example:



6. FREQUENCY SHIFTING:

If $x(t) \xleftrightarrow{\text{F.S.}} X(k)$

then $e^{j\omega_0 k t} x(t) \xleftrightarrow{\text{F.S.}} X(k - K_0)$

Proof:

$$\text{Let } y(t) = e^{j\omega_0 k t} x(t).$$

$$Y(k) = \frac{1}{T} \int_0^T y(t) e^{-j\omega_0 k t} dt \\ = \frac{1}{T} \int_0^T x(t) e^{j\omega_0 k t} \cdot e^{-j\omega_0 k t} dt \\ = \frac{1}{T} \int_0^T x(t) e^{-j\omega_0 (k - K_0) t} dt$$

$$Y(k) = X(k - K_0)$$

Hence, proved.

7. MULTIPLICATION PROPERTY:

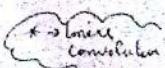
If $x(t) \xleftrightarrow{\text{F.S.}} X(k)$

$y(t) \xleftrightarrow{\text{F.S.}} Y(k)$

then

$$x(t)y(t) \xleftrightarrow{\text{F.S.}} X(k) * Y(k)$$

↳ Circular convolution



Proof :

$$\text{Let } z(t) = x(t) * y(t)$$

$$z(k) = \frac{1}{T} \int_{-\infty}^{\infty} z(t) e^{-j\omega_0 k t} dt$$

$$= \frac{1}{T} \int_{-\infty}^{\infty} x(t) y(t) e^{-j\omega_0 k t} dt$$

$$= \frac{1}{T} \int_{-\infty}^{\infty} \sum_{l=-\infty}^{\infty} x(l) e^{j\omega_0 l t} \cdot y(t) \cdot e^{-j\omega_0 k t} dt$$

$$= \sum_{l=-\infty}^{\infty} x(l) \left[\frac{1}{T} \int_{-\infty}^{\infty} y(t) e^{-j\omega_0 (k-l)t} dt \right]$$

$$= \sum_{l=-\infty}^{\infty} X(l) Y(k-l)$$

$$z(k) = x(k) * y(k)$$

Hence, proved.

8. CONVOLUTION PROPERTY:

$$\text{If } x(t) \xleftrightarrow{\text{FS}} X(k)$$

$$y(t) \xleftrightarrow{\text{FS}} Y(k)$$

then,

$$x(t) * y(t) \xleftrightarrow{\text{FS}} T \cdot X(k)Y(k)$$

Proof :

$$\begin{aligned} & \sum_{k=-\infty}^{\infty} x[k] y[m-k] \\ & \quad \text{---} \\ & \quad x[n] * y[n] \end{aligned}$$

$$\text{Let } z(t) = x(t) * y(t)$$

$$= \int_{t=T}^{\infty} x(t) y(t-\tau) d\tau$$

$$z(k) = \frac{1}{T} \int_{t=T}^{\infty} z(t) e^{-j\omega_0 k t} dt$$

$$= \frac{1}{T} \int_{t=T}^{\infty} \int_{\tau=T}^{\infty} x(\tau) y(\tau-\tau) d\tau e^{-j\omega_0 k t} d\tau$$

$$= \frac{1}{T} \int_{\tau=T}^{\infty} x(\tau) \int_{t=T}^{\infty} y(t-\tau) e^{-j\omega_0 k t} dt d\tau$$

$$\text{Now, } \int_{t=T}^{\infty} y(t-\tau) e^{-j\omega_0 k t} dt$$

$$\text{put } m = t - \tau, \quad t = m + \tau$$

$$= \int_{m=T}^{\infty} y(m) e^{-j\omega_0 k(m+\tau)} dm$$

$$= e^{-j\omega_0 k \tau} \times \frac{1}{T} \int_{m=T}^{\infty} y(m) e^{-j\omega_0 km} dm$$

$$= e^{-j\omega_0 k \tau} \times T \times Y(k) \dots (2)$$

(2) in (1) \Rightarrow

$$\begin{aligned} z(k) &= \frac{1}{T} \int_{\tau=T}^{\infty} x(\tau) T \cdot Y(k) e^{-j\omega_0 k \tau} d\tau \\ &= T \cdot Y(k) \left[\frac{1}{T} \int_{\tau=T}^{\infty} x(\tau) e^{-j\omega_0 k \tau} d\tau \right] \end{aligned}$$

Hence proved.

9. POWER OF A SIGNAL:

State Parseval's theorem for continuous periodic signal.

Proof:

$$\frac{1}{T} \int |x(t)|^2 dt = \sum_{k=-\infty}^{\infty} |x(k)|^2$$

$$\text{where } x(t) x^*(t) = |x(t)|^2$$

$$P = \frac{1}{T} \int x(t) x^*(t) dt \dots \dots (1)$$

$$x(t) = \sum_{k=-\infty}^{\infty} x(k) e^{j\omega_0 k t}$$

$$x^*(t) = \sum_{k=-\infty}^{\infty} x^*(k) e^{-j\omega_0 k t} \dots \dots (2)$$

Substitute (2) in (1),

$$\begin{aligned} P &= \frac{1}{T} \int x(t) \sum_{k=-\infty}^{\infty} x^*(k) e^{-j\omega_0 k t} dt \\ &= \sum_{K=-\infty}^{\infty} x^*(K) \times \frac{1}{T} \int x(t) e^{-j\omega_0 K t} dt \\ &= \sum_{K=-\infty}^{\infty} x^*(K) x(K) \end{aligned}$$

$$\begin{aligned} (a+jb) \\ (a-jb) \\ = |a+jb|^2 \\ = a^2+b^2 \end{aligned}$$

$$= \sum_{k=-\infty}^{\infty} |x(k)|^2$$

- Parseval's theorem states that the total average power in a periodic signal equals the sum of the average power in all of its harmonic components.

$$\text{Power spectral density} = |x(k)|^2 \text{ vs } k$$

* Symmetry Conditions:

$$x(t) = a_0 + \sum_{n=1}^{\infty} a_n \cos n\omega_0 t + \sum_{n=1}^{\infty} b_n \sin n\omega_0 t$$

$$a_m = \frac{2}{T} \int_0^T x(t) \cos m\omega_0 t dt$$

$$b_m = \frac{2}{T} \int_0^T x(t) \sin m\omega_0 t dt$$

$$a_m = \frac{2}{T} \int_0^{\pi/2} [x(t) + x(-t)] \cos m\omega_0 t dt$$

$$b_m = \frac{2}{T} \int_0^{\pi/2} [x(t) - x(-t)] \sin m\omega_0 t dt$$

Even:

$$a_m = \frac{2}{T} \int_0^{\pi/2} x(t) \cos m\omega_0 t dt$$

Symmetry

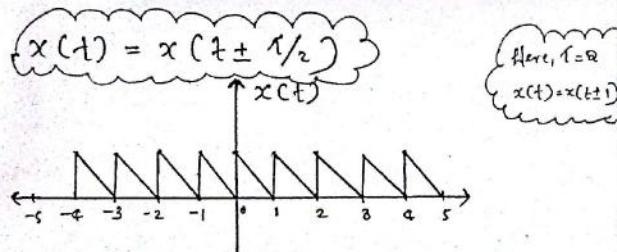
$$b_m = 0$$

Odd:

$$a_m = 0$$

$$b_m = \frac{1}{\pi} \int_{-\pi/2}^{\pi/2} x(t) \sin m\omega_0 t dt$$

★ HALF-HALVE SYMMETRY:



★ CTFT

- DTFS - Discrete-time periodic stable
- DTFT - " aperiodic " } Discrete Case
- FT - " unstable "
- CTFS - Continuous-time periodic stable } Continuous
- CTFT - " aperiodic stable "
- LT - " unstable "

★ Synthesis Equation: (CTFT)

$$x(t) = \frac{1}{2\pi} \int_{-\infty}^{\infty} X(j\omega) e^{j\omega t} d\omega$$

$$\text{Analysis Eqn: } X(j\omega) = \int_{-\infty}^{\infty} x(t) e^{-j\omega t} dt$$

★ CONVERGENCE OF FOURIER TRANSFORM

- (i) $x(t)$ should be absolutely integrable.

$$\therefore \int_{-\infty}^{\infty} |x(t)| dt < \infty$$

- (ii) $x(t)$ should have finite number of maxima and minima in any finite interval.

- (iii) $x(t)$ should have finite no. of finite discontinuities in any finite interval.

? Calculate the Fourier coefficients of a continuous time signal given by,

$$x(t) = e^{-at} u(t), \text{ where } a > 0$$

plot its magnitude and phase spectrum.

Ans: We have to calculate $X(j\omega)$. {Fourier coefficients}

$$\text{Where, } X(j\omega) = \int_{-\infty}^{\infty} x(t) e^{-j\omega t} dt$$

$$X(j\omega) = \int_{-\infty}^{\infty} e^{-at} u(t) e^{-j\omega t} dt$$

$$= \int_0^{\infty} e^{-at} \times 1 \times e^{-j\omega t} dt \quad (\text{since } u(t) \text{ is from } 0 \text{ to } \infty)$$

$$= \int_0^{\infty} e^{-(a+j\omega)t} dt = \left[\frac{e^{-(a+j\omega)t}}{a+j\omega} \right]_0^{\infty}$$

$$\begin{aligned} &= -\frac{1}{a+j\omega} \left[e^{-\infty} - e^0 \right] \\ &= -\frac{1}{a+j\omega} (0-1) \\ X(j\omega) &= \frac{1}{a+j\omega} \end{aligned}$$

Magnitude is given by,

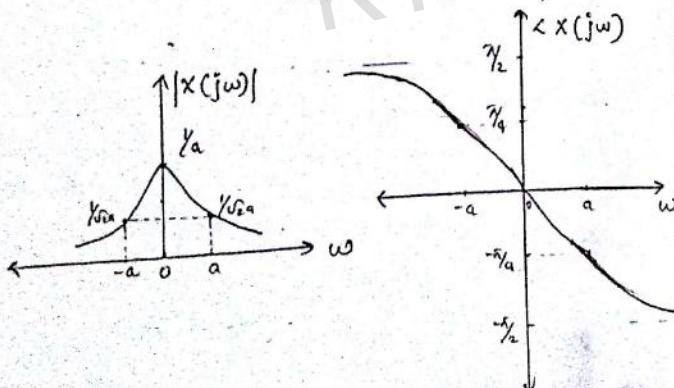
$$|X(j\omega)| = \sqrt{\frac{1}{a^2 + \omega^2}}$$

Now, phase, $\angle X(j\omega) = 0 - \tan^{-1}(\omega/a) = -\tan^{-1}(\omega)$

$$\omega = 0, |X(j\omega)| = \frac{1}{a}, \angle X(j\omega) = 0$$

$$\omega = a, |X(j\omega)| = \frac{1}{\sqrt{2}}, \angle X(j\omega) = -\pi/4$$

$$\omega = -a, |X(j\omega)| = \frac{1}{\sqrt{2}}, \angle X(j\omega) = \pi/4$$



$$x(t) = e^{at} u(-t), a > 0$$

Ans. We've

$$X(j\omega) = \int_{-\infty}^{\infty} x(t) e^{-j\omega t} dt$$

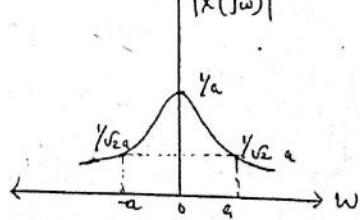
$$= \int_{-\infty}^{\infty} e^{at} u(-t) e^{-j\omega t} dt$$

$$= \int_{-\infty}^0 e^{at} \cdot e^{-j\omega t} dt$$

$$= \int_{-\infty}^0 (-j\omega + a)t dt = \left[\frac{e^{(a-j\omega)t}}{a-j\omega} \right]_{-\infty}^0$$

$$X(j\omega) = \frac{1}{a-j\omega} (e^0 - e^{-\infty}) = \frac{1}{a-j\omega}$$

$$|X(j\omega)| = \sqrt{\frac{1}{a^2 + \omega^2}}$$

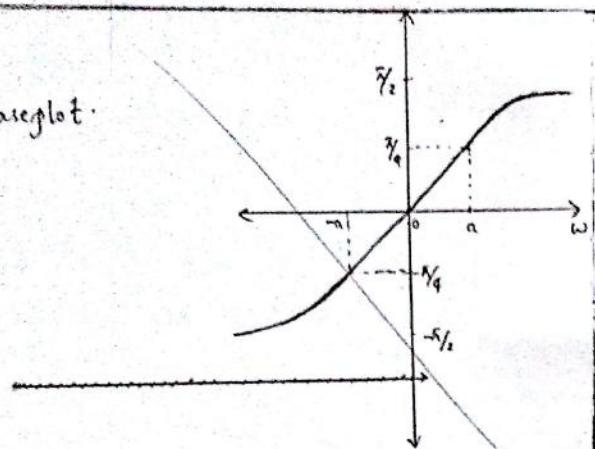


$$\omega = 0, |X(j\omega)| = \frac{1}{a}$$

$$\omega = a, |X(j\omega)| = \frac{1}{\sqrt{2}}$$

$$\omega = -a, |X(j\omega)| = \frac{1}{\sqrt{2}}$$

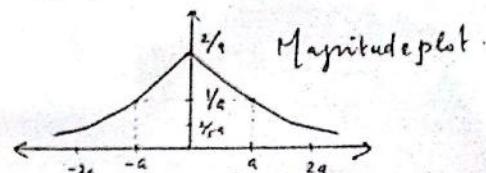
phase plot.



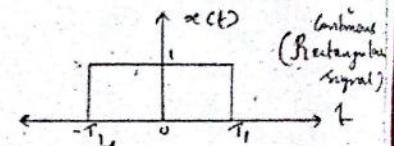
$$X(j\omega) = \frac{2a}{a^2 + \omega^2}$$

$$|X(j\omega)| = \frac{2a}{a^2 + \omega^2}$$

$$\angle X(j\omega) = 0^\circ$$



? Find the Fourier transform of signal given by $x(t)$.



Ans we have to find $X(j\omega)$.

$$X(j\omega) = \int_{-\infty}^{\infty} x(t) e^{-j\omega t} dt$$

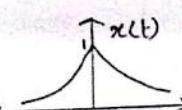
$$= \int_{-T_2}^{T_1} 1 \cdot e^{-j\omega t} dt$$

$$= \left[\frac{e^{-j\omega t}}{-j\omega} \right]_{-T_2}^{T_1} = \left[\frac{e^{-j\omega T_1} - e^{j\omega T_2}}{-j\omega} \right]$$

$$= \frac{[e^{j\omega T_1} - e^{-j\omega T_1}]}{+j\omega}$$

$$= 2\sqrt{\omega} \sin \omega T_1$$

? $x(t) = e^{-at|t|}, a < 1$



$$\text{Ans. } X(j\omega) = \int_{-\infty}^{\infty} x(t) e^{-j\omega t} dt$$

$$X(j\omega) = \int_{-\infty}^{\infty} e^{at} e^{-j\omega t} dt + \int_{-\infty}^{\infty} e^{-at} e^{-j\omega t} dt \text{ where } a > 0$$

$$= \frac{1}{a-j\omega} + \frac{1}{a+j\omega}$$

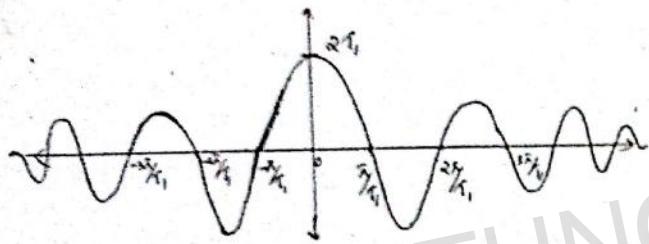
$$\begin{aligned} x(t) &= e^{-at} \\ &= e^{at} \\ &= e^{-at} \end{aligned}$$

$$\begin{aligned} x(t) &= e^{-at} \\ &= e^{at} \\ &= e^{-at} \end{aligned}$$

$$= \frac{2x \sin(\omega_1 t_1)}{\frac{\pi(\omega_1)}{T_1(\omega)}}$$

value $\sin \theta = \frac{\sin \pi \theta}{\pi}$, $\theta = 1, 2, 3, \dots$ for \sin
 $\{ \pi \theta = m\pi \}$
 $\theta = 1, 2, 3, \dots$

$$\therefore X(j\omega) = \underline{2 \pi_1 \operatorname{sinc} \left(\frac{\omega_1 t_1}{\pi} \right)}$$



$$\omega_1/\pi = 1, 2, 3, \dots \Rightarrow \omega = \frac{\pi}{\pi_1}, \frac{2\pi}{\pi_1}, \frac{3\pi}{\pi_1}, \dots$$

→ Fourier transform of a continuous rectangular function is a sinc function

$$\left\{ \begin{array}{l} x(b) = e^{-j\theta} \\ e^{jb_1} (e^{j\theta_1} - e^{-j\theta_1}) \\ 2j \frac{e^{-j\theta_1}}{2j} (e^{j\theta_1} - e^{-j\theta_1}) = 2j e^{-j\theta_1} \sin \theta_1 \end{array} \right.$$

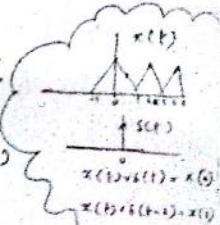


? Find the Fourier transform of impulse function
 Ans. $x(t) = \delta(t)$.

Properties of $\delta(t)$ are:

$$\int_{-\infty}^{\infty} x(t) \cdot \delta(t) dt = x(0) \dots (1)$$

$$\text{And } \int_{-\infty}^{\infty} x(t) \delta(t-b) dt = x(b)$$



Now, Fourier transform,

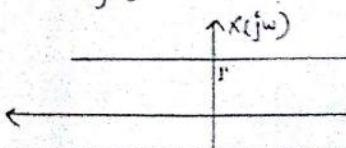
$$X(j\omega) = \int_{-\infty}^{\infty} x(t) e^{-j\omega t} dt$$

$$X(j\omega) = \int_{-\infty}^{\infty} \delta(t) e^{-j\omega t} dt \dots (2)$$

Compare (1) & (2), then $x(t) = e^{-j\omega t}$

$$\begin{aligned} \therefore X(j\omega) &= \int_{-\infty}^{\infty} \delta(t) e^{-j\omega t} dt \\ &= \int_{-\infty}^{\infty} \delta(t) x(t) dt = x(0) \\ &= e^{-j\omega \times 0} = e^0 = 1. \end{aligned}$$

$$\therefore X(j\omega) = 1.$$



Continuous time Fourier transform = $X(j\omega)$
 Fourier series = $x(t)$

Q) Calculate the signal $x(t)$ whose Fourier transform is given as follows.

$$X(j\omega) = \begin{cases} 1 & , |\omega| < W \\ 0 & , |\omega| > W \end{cases}$$

Ans $x(t) = \text{IFT of } X(j\omega)$

$$x(t) = \frac{1}{2\pi} \int_{-\infty}^{\infty} X(j\omega) e^{j\omega t} d\omega$$

$$= \frac{1}{2\pi} \int_{-W}^{W} 1 \cdot e^{j\omega t} d\omega$$

$$= \frac{1}{2\pi} \left[\frac{e^{j\omega t}}{j\omega} \right]_{-W}^{W}$$

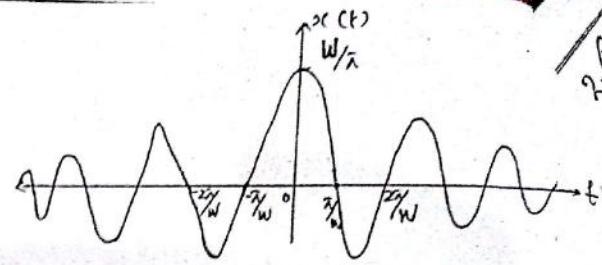
$$= \frac{1}{2\pi} \left[\frac{e^{jWt} - e^{-jWt}}{j\omega} \right]$$

$$= \frac{1}{\pi} t \sin Wt$$

$\text{sinc} \theta = \frac{\sin \theta}{\pi \theta}$

$$= \frac{1}{\pi} \frac{\sin(\frac{\pi Wt}{\pi})}{\frac{\pi Wt}{\pi}}$$

$$x(t) = \frac{W}{\pi} \frac{\sin(\frac{Wt}{\pi})}{\frac{Wt}{\pi}}$$



2. TIME
DL

* PROPERTIES OF (IFT):

1. LINEARITY:

If $x(t) \leftrightarrow X(j\omega)$

$y(t) \leftrightarrow Y(j\omega)$

then $a x(t) + b y(t) \leftrightarrow a X(j\omega) + b Y(j\omega)$.

Proof:

$$\text{Since } a x(t) = \int_{-\infty}^{\infty} a x(t) e^{-j\omega t} dt$$

$$b y(t) = \int_{-\infty}^{\infty} b y(t) e^{-j\omega t} dt$$

$$\text{Now } a x(j\omega) + b y(j\omega) = \int_{-\infty}^{\infty} a x(t) e^{j\omega t} dt + \int_{-\infty}^{\infty} b y(t) e^{j\omega t} dt$$

$$= \int_{-\infty}^{\infty} (a x(t) + b y(t)) e^{j\omega t} dt$$

$$= a X(j\omega) + b Y(j\omega)$$

2. TIME SHIFTING:

If $x(t) \leftrightarrow X(j\omega)$

then, $x(t-t_0) \leftrightarrow e^{j\omega t_0} X(j\omega)$

Proof:

$$X(j\omega) = \int_{-\infty}^{\infty} x(t) e^{-j\omega t} dt$$

Let $y(t) = x(t-t_0)$

$$\text{then } Y(j\omega) = \int_{-\infty}^{\infty} x(t-t_0) e^{-j\omega t} dt$$

$$\text{let } t-t_0 = \tau$$

$$t = t_0 + \tau \quad d\tau = dt$$

$$t = -\infty, \tau = -\infty \quad t = \infty, \tau = \infty$$

$$Y(j\omega) = \int_{-\infty}^{\infty} x(\tau) e^{-j\omega(\tau+t_0)} d\tau$$

$$= e^{-j\omega t_0} \int_{-\infty}^{\infty} x(\tau) e^{-j\omega\tau} d\tau$$

$$= e^{-j\omega t_0} X(j\omega)$$

$$Y(j\omega) = e^{-j\omega t_0} X(j\omega)$$

Hence, proved.

3. FREQUENCY SHIFTING:

If $x(t) \leftrightarrow X(j\omega)$

then $e^{j\omega_0 t} x(t) \leftrightarrow X(j(\omega-\omega_0))$

Proof:

$$\text{let } y(t) = e^{j\omega_0 t} x(t)$$

$$\text{then, } Y(j\omega) = \int_{-\infty}^{\infty} e^{j\omega_0 t} x(t) e^{-j\omega t} dt$$

$$= \int_{-\infty}^{\infty} x(t) e^{-j(t(\omega-\omega_0))} dt$$

$$Y(j\omega) = X(j(\omega-\omega_0))$$

Hence, proved.

4. TIME REVERSAL:

If $x(t) \leftrightarrow X(j\omega)$

then $x(-t) \leftrightarrow X(-j\omega)$

Proof:

$$\text{let } y(t) = x(-t)$$

$$\text{then } Y(j\omega) = \int_{-\infty}^{\infty} y(t) e^{-j\omega t} dt$$

$$= \int_{-\infty}^{\infty} x(-t) e^{j\omega_0 t} dt$$

Let $t = -\tau$, $\Rightarrow dt = -d\tau$.

when $t \rightarrow -\infty$, $\tau \rightarrow \infty$
 $t \rightarrow \infty$, $\tau \rightarrow -\infty$

$$\text{Then } Y(j\omega) = \int_{-\infty}^{\infty} x(\tau) e^{j\omega \tau} (-d\tau)$$

$$= \int_{-\infty}^{\infty} x(\tau) e^{j\omega \tau} d\tau$$

$$= \int_{-\infty}^{\infty} x(\tau) e^{-j\omega \tau (-\omega)} d\tau$$

$$Y(j\omega) = X(-j\omega)$$

Hence, proved.

5. TIME SCALING:

$$\text{If } x(t) \xleftrightarrow{FT} X(j\omega)$$

$$\text{then } x(\alpha t) \xleftrightarrow{FT} \frac{1}{|\alpha|} X(j\omega/\alpha)$$

Proof:

Case - 1: $\alpha > 0$

$$y(t) = x(\alpha t)$$

$$\text{then } Y(j\omega) = \int_{-\infty}^{\infty} y(t) e^{-j\omega t} dt$$

$$= \int_{-\infty}^{\infty} x(\alpha t) e^{-j\omega t} dt$$

$$\text{let } m = \alpha t$$

$$t = m/\alpha \Rightarrow dt = dm/\alpha$$

when $t = -\infty$, $m = -\infty$,

$t = \infty$, $m = \infty$

$$Y(j\omega) = \int_{-\infty}^{\infty} x(m) e^{-j\omega(m/\alpha)} dm/\alpha$$

$$= \frac{1}{\alpha} \int_{-\infty}^{\infty} x(m) e^{-j\omega m/\alpha} dm$$

$$Y(j\omega) = \frac{1}{\alpha} X(j\omega/\alpha)$$

• Case - 2: $\alpha < 0$

$$y(t) = x(-\alpha t)$$

$$\text{let } m = -\alpha t, \quad t = -m/\alpha$$

$$dm = -\alpha dt$$

$$t = -\infty, m = \infty, \quad t = \infty, m = -\infty$$

$$Y(j\omega) = \int_{\infty}^{-\infty} x(m) e^{-j\omega - m/\alpha} (-dm/\alpha)$$

$$= \frac{1}{\alpha} \int_{-\infty}^{\infty} x(m) e^{-j\omega m (-\omega/\alpha)} dm$$

$$Y(j\omega) = \frac{1}{\alpha} X(-j\omega/\alpha)$$

From these two, generally

$$x(\alpha t) \leftrightarrow \frac{1}{\alpha} X(j\omega/\alpha)$$

Hence, proved.

6. TIME DIFFERENTIATION:

If $x(t) \leftrightarrow X(j\omega)$.

Then $\frac{d}{dt} x(t) \leftrightarrow j\omega X(j\omega)$.

Proof :

$$\text{Let } x(t) = \frac{1}{2\pi} \int_{-\infty}^{\infty} X(j\omega) e^{j\omega t} d\omega$$

$$\frac{d}{dt} x(t) = \frac{1}{2\pi} \int_{-\infty}^{\infty} X(j\omega) \frac{d}{dt} e^{j\omega t} d\omega$$

$$= \frac{1}{2\pi} \int_{-\infty}^{\infty} j\omega X(j\omega) e^{j\omega t} d\omega$$

$$\frac{d}{dt} x(t) = j\omega X(j\omega)$$

Hence proved.

7. DIFFERENTIATION IN FREQUENCY:

If $x(t) \leftrightarrow X(j\omega)$

$$-jt x(t) \leftrightarrow \frac{d}{d\omega} X(j\omega)$$

Proof :

$$X(j\omega) = \int_{-\infty}^{\infty} x(t) e^{-j\omega t} dt$$

$$\frac{d}{d\omega} X(j\omega) = \int_{-\infty}^{\infty} x(t) \left(\frac{d}{d\omega} e^{-j\omega t} \right) dt$$

$$= \int_{-\infty}^{\infty} x(t) \cdot -jt e^{-j\omega t} dt$$

$$= -jt \int_{-\infty}^{\infty} x(t) e^{-j\omega t} dt$$

$$\frac{d}{d\omega} X(j\omega) = -jt x(t)$$

Hence, proved.

8. CONVOLUTION IN TIME:

If $x_1(t) \leftrightarrow X_1(j\omega)$

$x_2(t) \leftrightarrow X_2(j\omega)$

Then $x_1(t) * x_2(t) \leftrightarrow X_1(j\omega) \cdot X_2(j\omega)$

Convolution
Commutative
(property)

Proof:

$$\text{We have } y(t) = x_1(t) * x_2(t)$$

$$y(t) = \int_{-\infty}^{\infty} x_1(\tau) x_2(t-\tau) d\tau$$

$$\text{Now, } y(j\omega) = \int_{-\infty}^{\infty} y(t) e^{-j\omega t} dt$$

$$= \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} x_1(\tau) x_2(t-\tau) d\tau e^{-j\omega t} dt$$

$$= \int_{-\infty}^{\infty} x_1(\tau) \left[\int_{-\infty}^{\infty} x_2(t-\tau) e^{-j\omega t} dt \right] d\tau$$

$$= \int_{-\infty}^{\infty} x_1(\tau) \cdot \underbrace{e^{-j\omega \tau} \cdot x_2(j\omega)}_{\text{By time shifting property.}} d\tau$$

$$= x_2(j\omega) \int_{-\infty}^{\infty} x_1(\tau) e^{-j\omega \tau} d\tau$$

$$y(j\omega) = x_2(j\omega) \cdot x_1(j\omega)$$

Hence, proved.

9: MULTIPLICATION IN TIME:

$$\text{If } x_1(t) \longleftrightarrow X_1(j\omega)$$

$$x_2(t) \longleftrightarrow X_2(j\omega)$$

then, $x_1(t) \cdot x_2(t) = \frac{1}{2\pi} (X_1(j\omega) * X_2(j\omega))$ DUALITY

Proof:

$$\text{Let } y(t) = x_1(t) \cdot x_2(t).$$

$$Y(j\omega) = \int_{-\infty}^{\infty} y(t) e^{-j\omega t} dt$$

$$= \int_{-\infty}^{\infty} x_1(t) \cdot x_2(t) e^{-j\omega t} dt$$

$$= \int_{-\infty}^{\infty} \frac{1}{2\pi} \int_{-\infty}^{\infty} x_1(j\lambda) e^{j\lambda t} d\lambda x_2(t) e^{-j\omega t} dt$$

$$= \frac{1}{2\pi} \int_{-\infty}^{\infty} x_1(j\lambda) \left(\int_{-\infty}^{\infty} x_2(t) e^{-j\omega t} e^{j\lambda t} dt \right) d\lambda$$

$$= \frac{1}{2\pi} \int_{-\infty}^{\infty} x_1(j\lambda) \left(\int_{-\infty}^{\infty} x_2(t) e^{-j(t(\omega-\lambda))} dt \right) d\lambda$$

$$= \frac{1}{2\pi} \int_{-\infty}^{\infty} x_1(j\lambda) x_2(j(\omega-\lambda)) d\lambda$$
 freq. shifting

$$\text{We have } \int_{-\infty}^{\infty} x_1(\tau) x_2(t-\tau) d\tau = x_1(t) * x_2(t)$$

$$\therefore Y(j\omega) = \frac{1}{2\pi} \int_{-\infty}^{\infty} (x_1(j\omega) * x_2(j\omega)) d\omega$$

Hence, proved.

* 10. DUALITY PROPERTY:

If $x(t) \xleftrightarrow{FT} X(\omega)$

then

$$X(t) \leftrightarrow 2\pi x(-\omega)$$

Proof:

$$x(t) = \frac{1}{2\pi} \int_{-\infty}^{\infty} X(\omega) e^{j\omega t} d\omega$$

$$2\pi x(t) = \int_{-\infty}^{\infty} X(\omega) e^{j\omega t} d\omega$$

Now, put $t = -t$

$$\text{then } 2\pi x(-t) = \int_{-\infty}^{\infty} X(\omega) e^{-j\omega t} d\omega$$

Now, interchanging $t \leftrightarrow \omega$,

$$2\pi x(-\omega) = \int_{-\infty}^{\infty} \underbrace{X(t)}_{\text{FT of } x(t)} e^{-j\omega t} dt$$

$$\text{i.e., } X(t) \xleftrightarrow{FT} 2\pi x(-\omega).$$

Hence proved.

11. PARSEVAL'S THEOREM:

$$\int_{-\infty}^{\infty} |x(t)|^2 dt \Leftrightarrow \frac{1}{2\pi} \int_{-\infty}^{\infty} |X(j\omega)|^2 d\omega$$

Proof:

$$|x(t)|^2 = x(t) \cdot x^*(t)$$

$$\therefore \int_{-\infty}^{\infty} |x(t)|^2 dt = \int_{-\infty}^{\infty} x(t) \cdot x^*(t) dt$$

$$= \int_{-\infty}^{\infty} x(t) x^*(t) dt$$

$$x(t) = \frac{1}{2\pi} \int_{-\infty}^{\infty} X(j\omega) e^{j\omega t} d\omega$$

$$x^*(t) = \frac{1}{2\pi} \int_{-\infty}^{\infty} X^*(j\omega) e^{-j\omega t} d\omega$$

$$\therefore \Rightarrow \int_{-\infty}^{\infty} [x(t) \cdot \frac{1}{2\pi} \int_{-\infty}^{\infty} X^*(j\omega) e^{-j\omega t} d\omega] dt$$

$$= \frac{1}{2\pi} \int_{-\infty}^{\infty} X^*(j\omega) \int_{-\infty}^{\infty} x(t) e^{-j\omega t} dt d\omega$$

$$= \frac{1}{2\pi} \left(\int_{-\infty}^{\infty} X^*(j\omega) X(j\omega) d\omega \right)$$

$$= \frac{1}{2\pi} \int_{-\infty}^{\infty} |X(j\omega)|^2 d\omega$$

Hence proved.

12. INTEGRATION PROPERTY:

If $x(t) \xleftrightarrow{FT} X(j\omega)$

$$\text{then } \int_{-\infty}^{\infty} x(t) dt \longleftrightarrow X(j\omega) + \pi x(0) \delta(\omega)$$

Proof:

$$x(t) * u(t) = \int_{-\infty}^t x(\tau) u(t-\tau) d\tau$$

$$\text{where } u(t-\tau) = 1, \quad (t-\tau) > 0$$

$$\Rightarrow \int_0^t x(x) \times df = 0, \quad (t - T) < 0$$

Now, we have $x(t) * u(t) \leftrightarrow X(j\omega) \cdot U(j\omega)$

$$X(j\omega) \cdot U(j\omega);$$

$$\text{But } V(j\omega) = \frac{1}{j\omega + K} S(\omega)$$

$$= X(j\omega) \left[\frac{1}{j\omega} + \pi \delta(\omega) \right]$$

$$= X(j\omega) \Big|_{j\omega} + \pi X(j\omega) \delta(\omega)$$

But from product properties,

$$\left\{ \begin{array}{l} x(t)s(t) = x(0)s(t) \\ x(t)s(t-t_0) = x(t_0)s(t-t_0). \end{array} \right.$$

$$= X(j\omega) / j\omega + \pi X(0) S(\omega) //$$

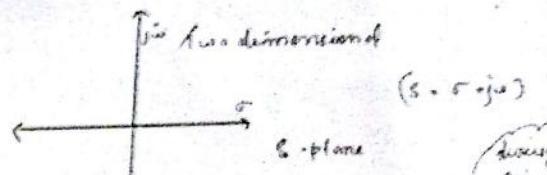
flower proved.

LAPLACE TRANSFORM

$$x(t) \xleftrightarrow{Ls} X(s)$$

where $X(s) = \int_{-\infty}^{\infty} x(t) e^{-st} dt$

$$\text{Now, ILT, } X(t) = \frac{1}{2\pi} \int_{-\infty}^{\sigma+j\infty} x(s) e^{st} ds.$$



$$\text{we've } x(s) = \int_{-\infty}^s x(t) e^{-st} dt$$

$$X(s) = \int_{-\infty}^{\infty} x(t) e^{-(\sigma+j\omega)t} dt$$

$$= \int_{-\infty}^{\tau} (x(t) e^{-\sigma t}) e^{-j\omega t} dt$$

$$(\therefore \mathfrak{f}\{x(t)\} = x(j\omega) = \int_{-\infty}^{\infty} x(t) e^{-j\omega t} dt)$$

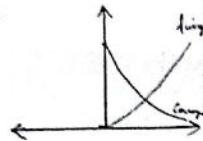
$$; L\{x(t)\} = F\{x(t)e^{-st}\}.$$

This is the relation b/w Fourier & Laplace

→ we know that, laplace transform is only for unstable signals. Therefore, when $x(t)$ is multiplied with e^{-rt} , then it also become unstable (since $\mathcal{L}\{x(t)\} = F\{x(t)e^{-rt}\}$)

Therefore, e^{-rt} is called convergence factor.

$$\left\{ \begin{array}{l} t \rightarrow \infty, x(t) \rightarrow 0 \rightarrow \text{convergence} \\ t \rightarrow \infty, x(t) \rightarrow \infty \rightarrow \text{divergence} \end{array} \right.$$



* Regions of Convergence (ROC):

→ Fourier transform existing points of $x(t)$ is called region of convergence.

→ or, the points at which the $x(t)$ is stable & converges, is called region of convergence

? Calculate the laplace transform of a signal

$$x(t) = e^{-at} u(t).$$

$$\text{Ans. } X(s) = \int_{-\infty}^{\infty} x(t) e^{-st} dt$$

$$= \int_{0}^{\infty} e^{-at} u(t) e^{-st} dt$$

$$u(t) = \begin{cases} 1 & t \geq 0 \\ 0 & t < 0 \end{cases}$$

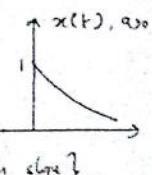
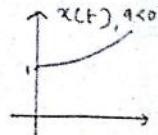
if limit is from 0 to ∞ .

$$\begin{aligned} \int_{0}^{\infty} e^{-at} e^{-st} dt &= \int_{0}^{\infty} e^{-(a+s)t} dt \\ &= \left[e^{-(a+s)t} / -(a+s) \right]_{0}^{\infty} \\ X(s) &= \frac{1}{s+a} \end{aligned}$$

$x(t), a > 0$

(when $a > 0$, $x(t) = e^{at} u(t)$
→ positive slope)

{ when $a < 0$, $x(t) = e^{-at} u(t)$
→ negative / decaying slope }.



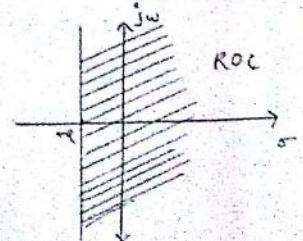
For convergence, we want $a > 0$.

$$\begin{aligned} X(s) &= \int_{0}^{\infty} e^{-at} e^{-st} dt \\ &= \int_{0}^{\infty} e^{-at} e^{-(\sigma+j\omega)t} dt \\ &= \int_{0}^{\infty} e^{-(a+\sigma)t} e^{-j\omega t} dt \end{aligned}$$

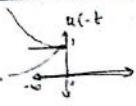
Here
for convergence, ~~$a > 0$~~ $(a+\sigma) > 0$

$$\sigma > -a$$

& ROC $\Rightarrow \text{Re}\{s\} > -a$



$$? x(t) = e^{-at} u(-t)$$



$$\text{Ans. } X(s) = \int_{-\infty}^{\infty} x(t) e^{-st} dt$$

$$= \int_{-\infty}^{0} e^{-at} u(-t) e^{-st} dt$$

$$= \int_{-\infty}^{0} e^{-at} e^{-st} dt$$

$$= \left[-e^{-(a+s)t} \right]_{-\infty}^{0}$$

$$= \left[e^{0} / -(a+s) \right] - \left[e^{0} / -(a+s) \right] = \frac{1}{-(a+s)}$$

$$X(s) = \frac{1}{-(a+s)} = \frac{1}{s+a}$$

~~$$\therefore X(s) = \frac{1}{s+a}$$~~

Now, $a > 0$, $x(t) = e^{-at} u(-t)$

~~$$a > 0, x(t) = e^{-at} u(-t)$$~~

~~$$X(s) = \int_{-\infty}^{\infty} e^{-at} e^{-st} dt$$~~

~~$$= \int_{-\infty}^{0} e^{-at} e^{-(a+st)} dt$$~~

~~$$= \int_{-\infty}^{0} e^{-a(t+s)} e^{-j\omega t} dt$$~~

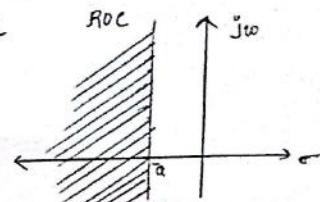
$x(t) = e^{-at}$
 • Signal right side
 $= a > 0$
 for converge
 • Signal left side
 $= a < 0$
 for converge

$$X(s) = - \int_{-\infty}^{\infty} e^{-at} e^{-st} e^{-j\omega t} dt$$

$$= - \int_{-\infty}^{\infty} e^{-(a+s)t} e^{-j\omega t} dt$$

for convergence
 $\Rightarrow a + s > 0$
 $s < -a$

$\therefore \text{Re}\{s\} < -a$



$$\begin{cases} x(t) = e^{-at} u(t) & \frac{X(s)}{s+a} \\ x(t) = -e^{-at} u(-t) & \frac{X(s)}{s+a} \end{cases} \quad \begin{cases} \text{ROC} & \sigma > -a \\ \text{ROC} & \sigma < -a \end{cases}$$

$$? x(t) = e^{at} u(t)$$

$$\text{Ans. } X(s) = \int_{-\infty}^{\infty} x(t) e^{-st} dt$$

$$= \int_{-\infty}^{\infty} e^{at} e^{-st} dt$$

$$= \int_{-\infty}^{\infty} e^{(a-s)t} dt$$

$$= \left[e^{(a-s)t} \right]_{-\infty}^{\infty} = \left[\frac{e^{-[s-a]t}}{-s+a} \right]_{0}^{\infty}$$

$$= \left[e^{-\infty} - e^{0} / -s+a \right] = 0 - \frac{1}{-s+a} = \frac{1}{s-a}$$

Time domain $\rightarrow x(t) \forall t$
 freq domain $\rightarrow X(s) \forall s$

Note:

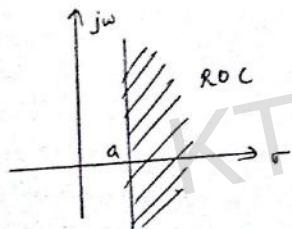
TC

$$X(s) = \frac{1}{s-a}$$

Now, for convergence, $a > 0$

$$\begin{aligned} X(s) &= \int_0^\infty e^{at} e^{-st} dt \\ &= \int_0^\infty e^{at} e^{-(s+j\omega)t} dt \\ &= \int_0^\infty e^{(a-s)t} e^{-j\omega t} dt \end{aligned}$$

for convergence, $(a-s) < 0$
 $a < s \Rightarrow s > a$.

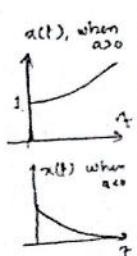


$$x(t) = 3e^{-at} u(t) - 2e^{-t} u(t). \text{ Find}$$

Laplace transform.

$$\text{Ans. } x_1(t) = 3e^{-at} u(t), x_2(t) = 2e^{-t} u(t)$$

$$\begin{aligned} X_1(s) &= \int_0^\infty 3e^{-at} e^{-st} dt \\ &= 3 \int_0^\infty e^{-(a+s)t} dt \end{aligned}$$



$$= 3 \left[e^{-(-a-s)t} \right]_0^\infty$$

$$= 3 \left[e^{-\infty/-(-a-s)} - e^0/-(-a-s) \right]$$

$$= 3 [0 + \frac{1}{a+s}] = \frac{3}{a+s}$$

$$\therefore X_1(s) = \frac{3}{a+s}$$

$$\text{Now, } X_2(s) = \int_0^\infty 2 \cdot e^{-t} e^{-st} dt$$

$$= 2 \int_0^\infty e^{-(s+1)t} dt$$

$$= 2 \left[e^{-\infty/-(-s-1)} \right]_0^\infty$$

$$= 2 \left[e^{-\infty/-(-s-1)} - e^0/-(-s-1) \right]$$

$$= 2 [0 + \frac{1}{s+1}]$$

$$X_2(s) = \frac{2}{s+1}$$

$$\therefore X(s) = X_1(s) - X_2(s)$$

$$= \frac{3}{a+s} - \frac{2}{s+1} = \frac{3s+3-4-2s}{2s+2+s^2+s}$$

$$= \frac{s-1}{s^2+3s+2} = \frac{s-1}{(s+1)(s+2)}$$

ROC of $X_1(s)$ is,

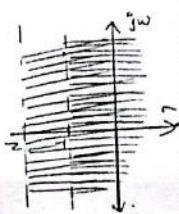
$x(t)$ is in the form $x(t) = e^{-at} u(t)$

$$\therefore \text{ROC} = \sigma > -a$$

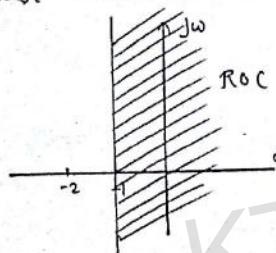
$$\text{ROC of } X_1(s) = \sigma > -a$$

ROC of $X_2(s)$ is, $\sigma > -a$

$$\therefore \sigma > -1$$



Final ROC is given by,



$$x(t) = e^{-at} u(t) + e^{-t} \cos(3t) u(t)$$

$$\text{Ans. } X(s) = e^{-at} u(t) + e^{-t} \left(\frac{e^{3j\omega} + e^{-3j\omega}}{2} \right) u(t)$$

$$x(t) = e^{-at} u(t) + \frac{e^{-t} e^{3j\omega}}{2} u(t) + \frac{e^{-t} e^{-3j\omega}}{2} u(t)$$

$$X_1(s) = \int_0^\infty e^{-at} e^{-st} dt$$

$$= \left[e^{-(a+s)t} \right]_0^\infty = \left[0 - \frac{1}{-(a+s)} \right]$$

$$X_1(s) = \frac{1}{2+s}$$

$$\text{Now, } X_2(s) = \int_0^\infty \frac{e^{-t}}{2} e^{j3\omega t} e^{-st} dt$$

$$= \frac{1}{2} \int_0^\infty e^{-(1-3j+s)t} dt$$

$$= \frac{1}{2} \left[\frac{e^{-(1-3j+s)t}}{-(1-3j+s)} \right]_0^\infty$$

$$= \frac{1}{2} \left[0 - \frac{1}{-(1-3j+s)} \right]$$

$$X_2(s) = \frac{1}{2(1-3j+s)}$$

$$X_2(s) = \int_0^\infty \frac{e^{-t}}{2} e^{-3j\omega t} e^{-st} dt$$

$$= \frac{1}{2} \left[\frac{e^{-(1+3j+s)t}}{-(1+3j+s)} \right]_0^\infty$$

$$X_3(s) = \frac{1}{2(1+3j+s)}$$

$$X(s) = \frac{1}{2+s} + \frac{1}{2(1-3j+s)} + \frac{1}{2(1+3j+s)}$$

$$= 2s^2 + 5s + 12 / (s^2 + as + 10)(s+a)$$

ROC of $X_1(s) = \sigma > -2$

ROC of 2nd term is, $\sigma > -1$.

∴ Final ROC is, $\sigma > -1$.

★ Zeros & Poles:

→ The points at which $X(s) = 0$, for rational L.T., are called zeros. (Roots of numerator = zeros) $X(s) = 0 \Rightarrow P(s) = 0$. (Roots of denominator which)

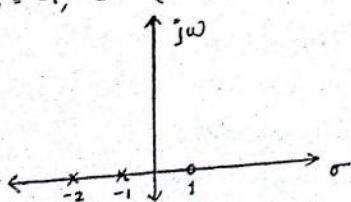
→ The points at $X(s) = \infty$, is called poles. (Roots of denominator).

→ Zeros are represented as 'o' and poles as 'x'.

Example; $X(s) = \frac{s-1}{s^2+3s+2}$

Zeros: $s=1$ ($X(s)=0$)

Poles: $s=-1, -2$ ($X(s)=\infty$)



∴ Here, poles = 2, zeros = 1

i.e., zeros < poles, then we can say that

(2-1) zeros at $s = \infty$.

• When $P < \sigma$, then $(\sigma - P)$ poles at $s = \infty$.

$$? X(s) = 2s^2 + 5s + 12 / (s^2 + 2s + 10) (s + 2)$$

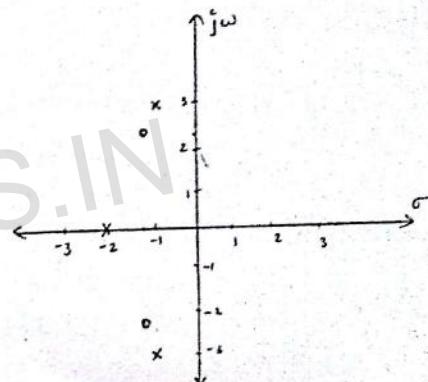
$$\text{Ans. Zeros, } \Rightarrow 2s^2 + 5s + 12 = 0$$

$$8s + 15s + 12 = 0 \Rightarrow s_1 = -1.25 \text{ and } s_2 = -2.1$$

$$\text{Poles, } \Rightarrow (s^2 + 2s + 10) = 0$$

$$s = -1 + 3j, -1 - 3j, -2$$

$$\therefore \text{poles} = -1 + 3j, -1 - 3j, -2$$



★ PROPERTIES ROC:

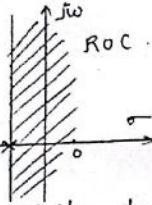
→ (i) ROC of $X(s)$ consists of strips parallel to the $j\omega$ axis in the s -plane.

→ (ii) For rational Laplace transforms, ROC doesn't contain any poles.

Example, $X(s) = s^{-1}/(s+2)(s+1)$

ROC is $\sigma > -1$

i.e., there is no poles in ROC.



→ (iii) If $x(t)$ is of finite duration and is absolutely integrable, then the ROC is the entire s -plane.

Example:

If $x(t)$ have finite duration and (and hence) or it is absolutely integrable, then ROC is the entire s -plane.

→ (iv) If $x(t)$ is right sided, and if the line $\operatorname{Re}\{s\} = \sigma_0$ is in the ROC, then all values of s for which $\operatorname{Re}\{s\} > \sigma_0$ will also be in the ROC.

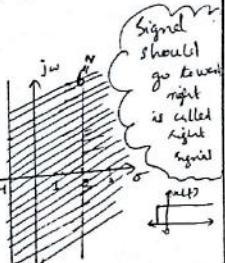
Example; $x(t) = e^{-t} u(t)$

Here, $\text{ROC } \sigma = \sigma > -1$

Now, $\operatorname{Re}\{s\} = \sigma_0 \Rightarrow \sigma = \sigma_0$

i.e., let $\sigma = 2$ in the ROC

then $\operatorname{Re}\{s\} > \sigma_0 \Rightarrow \sigma > \sigma_0 \Rightarrow \sigma > 2$ also in the ROC.



(v) If $x(t)$ is left-sided signal and if the line $\operatorname{Re}\{s\} = \sigma_0$ is in the ROC, ROC of $e^{\sigma_0 t} u(t) \Rightarrow \sigma < \sigma_0$ the right side of the pole.

Example; $x(t) = e^{-at} u(t)$

Let $\sigma = -4$ lies in the ROC,

then

$\sigma < -4$
is also lies
in the ROC

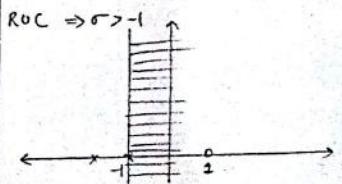


$\sigma = \sigma_0 = 1$ is in the ROC, then $\sigma_0 = 1$ is also in $b/w -2$ to 2 (in ROC).

(vi) If laplace transform of $x(t)$ is rational, and its ROC is bounded by poles at $\pm \infty$.

Example: $x(t) = e^{-at} u(t) + e^{bt} u(t)$

$$X(s) = s^{-1}/(s+a)(s+b)$$



Example; $x(t) = e^{-at} u(t)$
when $a > 0$, $a = 2$

$$x(t) = e^{-2t} u(t)$$

$$x(t) = e^{-2t} u(t) + e^{2t} u(-t)$$



(vii) If the laplace transform of $x(t)$ is rational, then if $x(t)$ is right sided, then ROC is

the region in the s-plane to the right of the rightmost pole.

Example : $X(s) = \frac{s-1}{(s+1)(s+2)}$

(Some example).

- If $x(t)$ is left-sided, then the ROC is the region in the s-plane to the left of the leftmost pole.

* INVERSE LAPLACE TRANSFORM

$\bullet X(t) = e^{-at} u(t)$

$L^{-1} = \frac{1}{s+a}, \text{ ROC} = \sigma > -a$

$\bullet X(t) = -e^{-at} u(-t)$

$L^{-1} = \frac{1}{s+a}, \text{ ROC} = \sigma < -a$

$\bullet X(t) = e^{at} u(t)$

$L^{-1} = \frac{1}{s-a}, \text{ ROC} = \sigma > a$

$\bullet X(t) = -e^{at} u(-t),$

$L^{-1} = \frac{1}{s-a}, \text{ ROC} = \sigma < a$

$\bullet X(t) = u(t) \left\{ \begin{array}{l} e^{-at} u(t) = e^{at} u(t) \\ (\because a = -a) \end{array} \right.$

$L^{-1} = \frac{1}{s}, \text{ ROC} = \sigma > 0$

? $X(s) = \frac{1}{(s+1)(s+2)}, \text{ ROC} > -1$

Find ILT (ie, $x(t)$).

Ams. $X(s) = A/s+1 + B/s+2$

$$= A(s+2) + B(s+1) \quad (s+1)(s+2)$$

$$= s(A+B) + 2A+B \quad \begin{matrix} A(s+1) \\ + B(s+1) \\ \hline B = A+1 \end{matrix}$$

$$s=0 \Rightarrow A=+1, B=-1$$

$X(s) = \frac{1}{s+1} - \frac{1}{s+2}$

$x(t) = e^{-t} u(t) - e^{-2t} u(t)$

? $X(s) = \frac{1}{(s+1)(s+2)}, \sigma < -2$

Ams. $X(s) = \frac{A}{s+1} + \frac{B}{s+2}$

$A=1, B=-1$

$X(s) = \frac{1}{s+1} - \frac{1}{s+2}$

$\therefore x(t) = -e^{-t} u(t) - e^{-2t} u(t)$

$x(t) = -e^{-t} u(-t) + e^{-2t} u(-t)$

? $X(s) = \frac{1}{(s+1)(s+2)}, -2 < \sigma < -1$

Ams. $-1 < \sigma < -2 \Rightarrow \sigma > -2 \times \sigma < 2$

$X(s) = \frac{A}{s+1} + \frac{B}{s+2}$

$A=1, B=-1$

$\therefore X(s) = \frac{1}{s+1} - \frac{1}{s+2}$

$x(t) = e^{-t} u(t) + 1/e^{-2t} u(t)$

$= -e^{-2t} u(-t) - e^{-2t} u(t)$

$x(t) = -e^{-t} u(-t) - e^{-2t} u(t)$

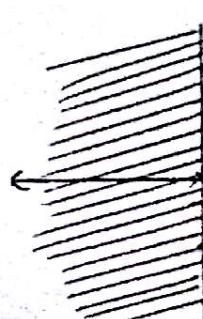
★ STABILITY:

3) \rightarrow for an LTI system, if impulse response $h(t)$ is absolutely integrable, then the system is stable.

$$\text{i.e., } \int_{-\infty}^{\infty} h(t) dt < \infty \Rightarrow \text{stable.}$$

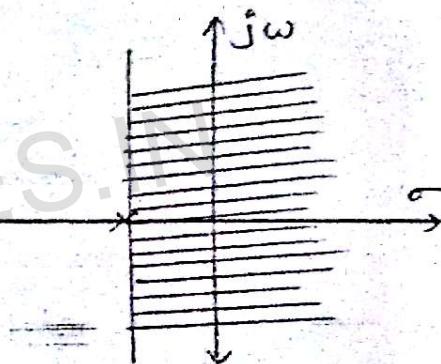
\rightarrow In the case of Laplace transform, $H(s)$ should include the $j\omega$ axis, for stability.

That is, if a system includes $j\omega$ in the ROC, then the system is a stable system and otherwise, it is unstable =



doesn't includes $j\omega$.

It is not stable



Includes $j\omega$.

Hence, it is stable

Here, $H(s)$ = transfer function.

$$= L \{ h(t) \}$$

$$x(t) \rightarrow h(t) \rightarrow y(t)$$

$$y(t) = x(t) * h(t)$$

$$Y(s) = X(s) \cdot H(s) \Rightarrow H(s) = Y(s)/X(s)$$

→ Transfer function is the ratio of Laplace transform of output to the Laplace transform of input.

$$H(s) = \frac{Y(s)}{X(s)} = \frac{\mathcal{L}\{y(t)\}}{\mathcal{L}\{x(t)\}}$$

? A transfer function $H(s) = \frac{s-1}{(s+1)(s-2)}$ is given.

Calculate the impulse response $h(t)$.

Ans: we have to find ILT.

$$\frac{s-1}{(s+1)(s-2)} = \frac{A}{(s+1)} + \frac{B}{(s-2)}$$

$$(s-1) = A(s-2) + B(s+1)$$

$$\text{when } s=2 \Rightarrow 1 = B(2) \Rightarrow B = \frac{1}{3}$$

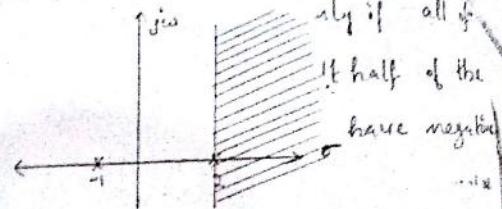
$$\text{when } s = -1 \Rightarrow -2 \Rightarrow A(-3) = A = \frac{2}{3}$$

$$H(s) = \frac{2}{3(s+1)} + \frac{1}{3(s-2)}$$

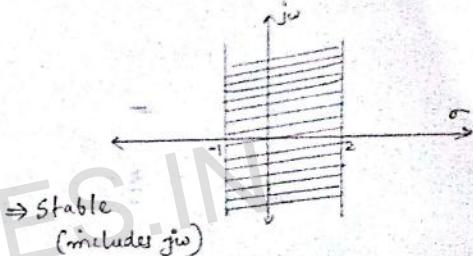
$$(1) h(t) = \frac{2}{3} e^{-t} u(t) + \frac{1}{3} e^{2t} u(t)$$

⇒ Unstable

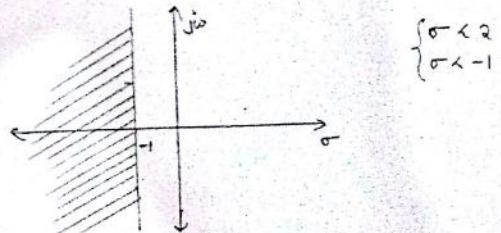
Here, poles are, $+1 \pm j\omega$



$$(2) h(t) = \frac{2}{3} e^{-t} u(t) - \frac{1}{3} e^{at} u(-t) \quad \begin{cases} \sigma > -1 \\ \sigma < -2 \end{cases}$$



$$(3) h(t) = -\frac{2}{3} e^{-t} u(t) - \frac{1}{3} e^{at} u(-t) \quad \begin{cases} \sigma < 2 \\ \sigma < -1 \end{cases}$$



→ Transferability:

analog LTI system, it is causal when input \rightarrow , for $t < 0$.

$x=0$, for $t < 0 \Rightarrow$ right-sided signal.

∴ ROC should be right side of the right most pole, in the case of causal signals.

Note → ROC for a causal system is the right half plane.

→ for a system with rational transfer function (s/m^m), causality of system is equivalent to the ROC being the right half plane to the right of the right most pole.

Example: $h(t) = e^{-t} u(t)$. check whether the system is causal.

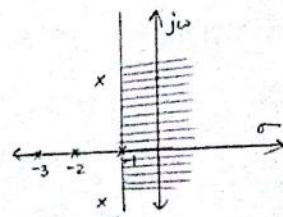
$$\text{Ans. } H(s) = \frac{1}{s+1}$$

$$\text{ROC, } \sigma > -\alpha \Rightarrow \sigma > -1$$

∴ ROC being the right of the rightmost pole. Hence the system is both causal & stable bcz, ROC contains jw axis.

Imp. A causal system with rational transfer function $H(s)$ is stable if and only if all of the poles of $H(s)$ lie in the left half of the s-plane. That is, all of the poles have negative real parts.

for both causal & stable,
all the poles
should be
in the
left half



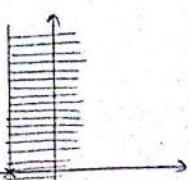
$x(t)$	$X(s)$	ROC
$\cos \omega_0 t u(t)$	$\frac{s}{s^2 + \omega_0^2}$	$\sigma > 0$

$\sin \omega_0 t u(t)$	$\frac{\omega_0}{s^2 + \omega_0^2}$	$\sigma > 0$
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$e^{-\alpha t} \cos \omega_0 t u(t)$	$\frac{(s+\alpha)}{(s+\alpha)^2 + \omega_0^2}$	$\sigma > -\alpha$
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$e^{-\alpha t} \sin \omega_0 t u(t)$	$\frac{\omega_0}{(s+\alpha)^2 + \omega_0^2}$	$\sigma > -\alpha$
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$t^n u(t)$	$\frac{n!}{s^{n+1}}$	not defined
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$$? X(s) = \frac{s^2 + 12}{s(s+2)(s+3)}$$

Calculate $x(t)$.

$$\text{Ans } \frac{s^2 + 12}{s(s+2)(s+3)} = \frac{A}{s} + \frac{B}{s+2} + \frac{C}{s+3}$$

$$s^2 + 12 = A(s+2)(s+3) + Bs(s+3) + Cs(s+2)$$

when $s = -2$

$$16 = B(-2)(-2+3) \Rightarrow 16 = B(-2)$$

$$B = 16/-2 = -8 //$$

when $s = -3$,

$$21 = 0 + 0 + -3C(-1)$$

$$21 = 3C \Rightarrow C = 21/3 = 7 //$$

when $s = 0$, $12 = A(2)(3)$

$$A = 12/6 = 2 //$$

$$A = 2,$$

$$B = -8,$$

$$C = 7.$$

$$\therefore \frac{s^2 + 12}{s(s+2)(s+3)} = \frac{2}{s} + \frac{-8}{s+2} + \frac{7}{s+3}$$

$$\text{Q.E.D. } x(t) = 2u(t) - 8e^{-2t}u(t) + 7e^{-3t}u(t)$$

$$x(t) = [2 - 8e^{-2t} + 7e^{-3t}]u(t)$$

ROC, $\sigma > 0 \quad \{ \sigma > 0, \sigma > -2, \sigma > -3 \} \Rightarrow \sigma > 0$

? Calculate $x(t)$ of a signal whose $X(s)$ is given by, $X(s) = \frac{20}{(s+3)(s^2 + 8s + 25)}$

$$\text{Ans } \frac{20}{(s+3)(s^2 + 8s + 25)} = \frac{A}{s+3} + \frac{Bs+C}{s^2 + 8s + 25}$$

$$\text{when } s = -3, \quad A = \frac{20}{9 - 24 + 25} = \frac{20}{10} = 2 //$$

$$\text{put } s = 0, \quad \frac{20}{3(25)} = \frac{A}{3} + \frac{C}{25}$$

$$-\frac{20}{3 \cdot 25} = \frac{2}{3} + \frac{C}{25}$$

$$\frac{20}{75} - \frac{2}{3} = \frac{C}{25} \Rightarrow C = -10$$

when $s = 1$,

$$\frac{20}{4 \cdot 34} = \frac{A}{4} + \frac{B+C}{34}$$

$$\frac{20}{4 \cdot 34} = \frac{2}{4} + \frac{B-10}{34}$$

$$\frac{5}{34} - \frac{2}{4} + \frac{10}{34} = \frac{B}{34}$$

$$\left(\frac{15}{34} - \frac{2}{4}\right) \times 34 = B \Rightarrow B = -2 //$$

$$\therefore X(s) = \frac{2}{s+3} + \frac{-2s-10}{s^2 + 8s + 25}$$

$$\begin{aligned}
 &= \frac{2}{s+3} + -\frac{2s-10}{(s+4)^2+9} \\
 &= \frac{2}{s+3} + -\frac{2s-10}{[s^2+8s+16]+9} \\
 &= \frac{2}{s+3} + -\frac{2s-10}{(s+4)^2+9} \\
 &= \frac{2}{s+3} + \frac{-2(s+4) - 2}{(s+4)^2+9} \\
 &= \frac{2}{s+3} - \frac{2(s+4)}{(s+4)^2+9} - \frac{2}{(s+4)^2+9} \\
 &= \frac{2}{s+3} - \frac{2(s+4)}{(s+4)^2+9} - \frac{2 \times 3}{3[(s+4)^2+9]} \\
 x(t) &= 2e^{-3t} u(t) - 2e^{-4t} \cos 3t u(t) - \frac{2}{3} e^{-4t} \sin 3t u(t)
 \end{aligned}$$

$$\begin{cases}
 \frac{1}{s} \leftrightarrow u(t) \\
 \frac{1}{s^2} \leftrightarrow t u(t) \\
 \frac{1}{s+1} \leftrightarrow e^{-t} u(t) \\
 \frac{1}{(s+1)^2} \leftrightarrow e^{-t} u(t) \times t = t e^{-t} u(t)
 \end{cases}$$

$$\begin{cases}
 \frac{1}{s^3} \leftrightarrow t^{\frac{2}{2}} u(t) \\
 \frac{1}{(s+1)^3} \leftrightarrow e^{-t} u(t) \times t^{\frac{2}{2}} = t^{\frac{2}{2}} e^{-t} u(t) \\
 \frac{1}{(s-1)^3} \leftrightarrow t^{\frac{2}{2}} e^t u(t)
 \end{cases}$$

Unilateral LT	Bilateral LT
$X(s) = \int_0^\infty x(t) e^{st} dt$	$X(s) = \int_{-\infty}^\infty x(t) e^{st} dt$
No need to specify ROC	ROC is must
Only causal	Causal & non causal
Evaluation of inverse is same	Evaluation of inverse is same
Applications:	Application:
Used to solve linear constant coefficient differential equations with more zero initial condition.	System stability, causality.

? Find unilateral LT and bilateral LT of $x(t)$

$$x(t) = e^{-\alpha(t+1)} u(t+1)$$

$$x(s) = \int_{-\infty}^\infty e^{-\alpha(t+1)} u(t+1) e^{st} dt$$

Ans. BLT,

$$\begin{aligned} X(s) &= \int_{-\infty}^{\infty} e^{-\alpha(t+1)} u(t+1) e^{-st} dt \\ &= \int_{-1}^{\infty} e^{-\alpha(t+1)} \times 1 e^{-st} dt \quad \text{↑ } u(t+1) \\ &= \int_{-1}^{\infty} e^{-\alpha t} \cdot e^{-\alpha} \cdot e^{-st} dt \\ &= e^{-\alpha} \int_{-1}^{\infty} e^{-t(\alpha+s)} dt = e^{-\alpha} \left[\frac{e^{-t(\alpha+s)}}{-(\alpha+s)} \right]_{-1}^{\infty} \\ &= e^{-\alpha} \left[e^{-\infty} - e^{(\alpha+s)} \right] \\ &= \frac{e^{-\alpha} \cancel{-} e^{(\alpha+s)}}{\cancel{-}(\alpha+s)} = \frac{e^{-\alpha} \cdot e^{(\alpha+s)}}{\alpha+s} \\ &= \frac{e^{-\alpha} \cdot e^{-\alpha} \cdot e^s}{\alpha+s} = \frac{e^s}{\alpha+s} \end{aligned}$$

Now, VLT,

$$\begin{aligned} X(s) &= \int_0^{\infty} e^{-st} x(t) dt \\ &= \int_0^{\infty} e^{-\alpha(t+1)} u(t+1) e^{-st} dt \quad \text{This is right side} \\ &\quad \text{↓ } 0 \text{ to } \infty \end{aligned}$$

$$\begin{aligned} &= e^{-\alpha} \int_0^{\infty} e^{-t(\alpha+s)} dt \\ &= e^{-\alpha} \left[\frac{e^{-t(\alpha+s)}}{-(\alpha+s)} \right]_0^{\infty} = e^{-\alpha} \left[0 - 1 \right] \end{aligned}$$

$$X(s) = \frac{e^{-\alpha}}{s+\alpha} \quad //$$

* PROPERTIES OF LAPLACE TRANSFORM:

(i) LINEARITY:

If $x_1(t) \xrightarrow{LT} X_1(s)$ with ROC = R_1 ,

and $x_2(t) \xrightarrow{LT} X_2(s)$ with ROC = R_2 ,

then $\alpha x_1(t) + \beta x_2(t) \xrightarrow{LT} \alpha X_1(s) + \beta X_2(s)$ with ROC = $R_1 \cap R_2$.

PROOF:

$$\alpha X_1(s) = \int_{-\infty}^{\infty} \alpha x_1(t) e^{-st} dt \quad \dots \dots (1) \quad \text{ROC} = R_1$$

$$\beta X_2(s) = \int_{-\infty}^{\infty} \beta x_2(t) e^{-st} dt \quad \dots \dots (2) \quad \text{ROC} = R_2.$$

$$\begin{aligned} (1) + (2) \Rightarrow \alpha X_1(s) + \beta X_2(s) &= \int_{-\infty}^{\infty} (\alpha x_1(t) + \beta x_2(t)) e^{-st} dt \\ &= \int_{-\infty}^{\infty} [\alpha x_1(t) + \beta x_2(t)] e^{-st} dt \end{aligned}$$

$$\therefore \alpha x_1(t) + \beta x_2(t) \xrightarrow{LT} \alpha X_1(s) + \beta X_2(s)$$

2. TIME SHIFTING:

If $x(t) \xrightarrow{LT} X(s)$ with ROC = R

Then $x(t-t_0) \xrightarrow{LT} e^{-st_0} X(s)$ with ROC = R

PROOF:

$$LT\{x(t-t_0)\} = \int_{-\infty}^{\infty} x(t-t_0) e^{-st} dt$$

put $t-t_0 = \tau$ thus $dt = d\tau$.

$$= \int_{-\infty}^{\infty} x(\tau) e^{-s(\tau+t_0)} d\tau = e^{-st_0} \int_{-\infty}^{\infty} x(\tau) e^{-s\tau} d\tau$$

$$= e^{-st_0} X(s)$$

$$\text{Similarly, } x(at+b) \xrightarrow{LT} \frac{1}{|a|} e^{sb/a} X(s/a)$$

3. SHIFT IN S-DOMAIN:

If $x(t) \xrightarrow{LT} X(s)$ with ROC = R

then $e^{st_0} \cdot x(t) \xrightarrow{LT} X(s-s_0)$ with ROC = R + Re{s_0}

Proof:

$$LT\{x(t) e^{st_0}\} = \int_{-\infty}^{\infty} x(t) \cdot e^{s_0 t} e^{-st} dt$$

$$= \int_{-\infty}^{\infty} x(t) \cdot e^{(s-s_0)t} dt$$

$$= X(s-s_0)$$

4. TIME SCALING:

If $x(t) \xrightarrow{LT} X(s)$ with ROC = R

then $x(at) \xrightarrow{LT} \frac{1}{|a|} X(s/a)$ with ROC = |a|R

PROOF:

By definition,

$$LT[x(at)] = \int_{-\infty}^{\infty} x(at) e^{-st} dt$$

put $at = \tau$, thus $dt = d\tau/a$

$$= \int_{-\infty}^{\infty} x(\tau) \cdot e^{-s\tau/a} d\tau/a = \frac{1}{a} \int_{-\infty}^{\infty} x(\tau) \cdot e^{-s\tau/a} d\tau$$

$$= \frac{1}{a} X(s/a)$$

a is real constant may be positive or negative
so, generalising it.

$$LT[x(at)] = \frac{1}{|a|} X(s/a)$$

5. TIME REVERSAL:

If $x(t) \xrightarrow{LT} X(s)$ with ROC = R

then $x(-t) \xrightarrow{LT} X(-s)$ with ROC = -R

PROOF:

$$\text{Let } y(t) = x(-t)$$

$$Y(s) = \int_{-\infty}^{\infty} y(t) \cdot e^{-st} dt$$

$$= \int_{-\infty}^{\infty} x(-t) \cdot e^{-st} dt$$

put $-t = m$, $-dt = dm$

when $t \rightarrow -\infty$, $m \rightarrow \infty$
 $t \rightarrow \infty$, $m \rightarrow -\infty$

$$\therefore Y(s) = \int_{-\infty}^{\infty} x(m) \cdot e^{sm} (-dm)$$

$$= \int_{-\infty}^{\infty} x(m) \cdot e^{sm} dm + \int_{-\infty}^{\infty} x(m) \cdot e^{-(m)s} dm$$

$$= X(-s).$$

$$\therefore x(-t) \xleftrightarrow{L} X(-s)$$

6 DIFFERENTIATION IN TIME:

If $x(t) \xleftrightarrow{L} X(s)$ with ROC=R

then $\frac{dx(t)}{dt} \xleftrightarrow{L} sX(s)$ with ROC containing R.

PROOF:

By definition of inverse Laplace transform,

$$x(t) = \frac{1}{2\pi j} \int_{c-j\infty}^{c+j\infty} X(s) \cdot e^{st} ds.$$

differentiating both sides, we obtain

$$\frac{dx(t)}{dt} = \frac{1}{2\pi j} \int_{c-j\infty}^{c+j\infty} [sX(s)] e^{st} ds$$

$$= L^{-1}[sX(s)]$$

$$\therefore \frac{dx(t)}{dt} \xleftrightarrow{L} sX(s).$$

7 INTEGRATION IN TIME DOMAIN:

If $x(t) \xleftrightarrow{L} X(s)$ with ROC=R

then $\int_0^t x(\tau) d\tau \xleftrightarrow{L} X(s)/s$ with
 ROC=R \cap Re\{s\}

PROOF:

Consider the convolution $x(t) * u(t)$

$$= \int_{-\infty}^{\infty} x(\tau) u(t-\tau) d\tau$$

Since $u(t-\tau)=1$, for $t>\tau$ ($\tau>t$)

$$x(t) * u(t) = \int_0^t x(\tau) d\tau$$

$$L \left[\int_0^t x(\tau) d\tau \right] = L[x(t) * u(t)] = X(s) \cdot U(s) = \frac{X(s)}{s}$$

$$\text{Thus } \int_0^t x(\tau) d\tau \xleftrightarrow{L} X(s)/s$$

(viii) CONVOLUTION IN TIME DOMAIN:

Convolution in time domain corresponds to multiplication in S-domain

If $x_1(t) \xleftrightarrow{\text{LT}} X_1(s)$ with ROC = R_1 ,
and $x_2(t) \xleftrightarrow{\text{LT}} X_2(s)$ with ROC = R_2 ,
then $x_1(t) * x_2(t) \xleftrightarrow{\text{LT}} X_1(s) \cdot X_2(s)$ with
 $\text{ROC} = R_1 \cap R_2$.

PROOF:

$$\begin{aligned} L\left[x_1(t) * x_2(t)\right] &= \int_{-\infty}^{\infty} [x_1(t) * x_2(t)] e^{-st} dt \\ &= \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} x_1(\tau) \cdot x_2(t-\tau) e^{-st} d\tau \cdot dt \end{aligned}$$

On rearranging, we get,

$$\begin{aligned} &= \int_{-\infty}^{\infty} x_1(\tau) e^{-s\tau} d\tau \int_{-\infty}^{\infty} x_2(t-\tau) e^{-s(t-\tau)} dt \\ &= X_1(s) \cdot X_2(s). \end{aligned}$$

9. MULTIPLICATION IN TIME DOMAIN:

Multiplication in time domain corresponds to

Convolution in S-domain.

If $x_1(t) \xleftrightarrow{\text{LT}} X_1(s)$ with ROC = R_1 ,
and $x_2(t) \xleftrightarrow{\text{LT}} X_2(s)$ with ROC = R_2 ,

then $x_1(t) \cdot x_2(t) \xleftrightarrow{\text{LT}} \frac{1}{2\pi j} [X_1(s) * X_2(s)]$
with ROC containing $R_1 \cap R_2$.

PROOF:

$$\begin{aligned} L\left[x_1(t) \cdot x_2(t)\right] &= \int_{-\infty}^{\infty} x_1(t) \cdot x_2(t) e^{-st} dt \\ &= \int_{-\infty}^{\infty} x_1(t) \left[\frac{1}{2\pi j} \int_{c-j\infty}^{c+j\infty} X_2(s) e^{st} ds \right] e^{-st} dt \end{aligned}$$

On rearranging we get,

$$\frac{1}{2\pi j} \int_{c-j\infty}^{c+j\infty} X_2(s) \cdot \int_{-\infty}^{\infty} \{x_1(t) e^{st}\} e^{-st} dt \cdot ds.$$

From the use of frequency shifting property, we

$$\text{get, } = \frac{1}{2\pi j} \int_{c-j\infty}^{c+j\infty} X_2(s) \cdot X_1(s-s_0) ds_0$$

$$= \frac{1}{2\pi j} \left\{ X_2(s) * X_1(s) \right\} = \frac{1}{2\pi j} \left\{ X_1(s) * X_2(s) \right\}$$

$$\text{Thus, } x_1(t) \cdot x_2(t) \xleftrightarrow{\text{LT}} \frac{1}{2\pi j} \left\{ X_1(s) * X_2(s) \right\}$$

10 DIFFERENTIATION IN S-DOMAIN:

If $x(t) \xrightarrow{LT} X(s)$ with ROC=R

$\therefore -t \cdot x(t) \xrightarrow{LT} \frac{d}{ds} X(s)$ with ROC=R

PROOF:

$$X(s) = \int_{-\infty}^{\infty} x(t) e^{-st} dt$$

Differentiating with respect to 's':

$$\frac{d}{ds} X(s) = \int_{-\infty}^{\infty} x(t) \cdot \{ -t \} \cdot e^{-st} dt$$

$$\frac{d}{ds} X(s) = \int_{-\infty}^{\infty} \{ -t \cdot x(t) \} \cdot e^{-st} dt$$

$$= LT \{ -t \cdot x(t) \}$$

$$\therefore -t \cdot x(t) \xrightarrow{LT} \frac{d}{ds} X(s)$$

Similarly, $(-t)^n x(t) \xrightarrow{LT} \frac{d^n}{ds^n} X(s)$.

Hence, proved.

11 INTEGRATION IN S-DOMAIN:

If $x(t) \xrightarrow{LT} X(s)$ with ROC=R

then $x(t)/t \xrightarrow{LT} \int_{-\infty}^{\infty} X(s) \cdot ds$

PROOF:

$$X(s) = \int_{-\infty}^{\infty} x(t) e^{-st} dt$$

Integrating both the sides w.r.t. s from st.

$$\int_{-\infty}^{\infty} X(s) ds = \int_{s-\infty}^{\infty} \int_{-\infty}^{\infty} x(t) \cdot e^{-st} dt \cdot ds = \int_{-\infty}^{\infty} x(t) \left[\int_{s-\infty}^{\infty} e^{-st} dt \right] ds$$

$$= \int_{-\infty}^{\infty} x(t) \cdot \left[e^{-st} \Big|_{s-\infty} \right] ds$$

$$= \int_{-\infty}^{\infty} x(t) \cdot \left[e^{-st} \Big|_{\infty} \right] dt$$

$$\int_{-\infty}^{\infty} X(s) ds = \int_{-\infty}^{\infty} (x(t) \Big|_{\infty}) e^{-st} dt = LT \left[x(t) \Big|_{\infty} \right]$$

$$\therefore x(t) \Big|_{\infty} \xrightarrow{LT} \int_{-\infty}^{\infty} X(s) \cdot ds$$

11. INTEGRATION IN S-DOMAIN:

If $x(t) \xrightarrow{LT} X(s)$ with ROC=R

then $\frac{x(t)}{t} \xrightarrow{LT} \int_{-\infty}^{\infty} X(s) \cdot ds$

PROOF:

$$X(s) = \int_{-\infty}^{\infty} x(t) \cdot e^{-st} dt$$

Integrating both sides w.r.t. s,

from $s \rightarrow \infty$,

$$\begin{aligned} \int_s^{\infty} x(s) ds &= \int_s^{\infty} \int_{-\infty}^{\infty} x(t) \cdot e^{-st} dt \cdot ds \\ &= \int_{-\infty}^{\infty} x(t) \left[\int_s^{\infty} e^{-st} ds \right] dt \\ &= \int_{-\infty}^{\infty} x(t) \cdot \left[e^{-st} \Big|_{-t}^{\infty} \right] dt \\ &= \int_{-\infty}^{\infty} x(t) \cdot \left[e^{-st} / t \right] dt \end{aligned}$$

$$\int_s^{\infty} x(s) ds = \int_s^{\infty} \left[\frac{x(t)}{t} \right] e^{st} dt = L^{-1} \left[\frac{x(t)}{t} \right]$$

$$\therefore \frac{x(t)}{t} \xleftrightarrow{L^{-1}} \int_s^{\infty} x(s) ds.$$

MODULE - IV

ANALYSIS OF LTI SYSTEM

(Continuous time)

* DIFFERENTIAL EQUATION :

$$\sum_{k=0}^N a_k \frac{d^k y(t)}{dt^k} = \sum_{k=0}^M b_k \frac{d^k x(t)}{dt^k} \quad \dots \quad (1)$$

(1) \Rightarrow differential eqn
order n
 $y(t) = f(t)$
 $x(t) = g(t)$

When $N=M=1$

$$\sum_{k=0}^1 a_k \frac{d^k y(t)}{dt^k} = \sum_{k=0}^1 b_k \frac{d^k x(t)}{dt^k}$$

$y(t) = f(t)$
 $x(t) = g(t)$

$$a_0 y(t) + a_1 \frac{dy(t)}{dt} = b_0 x(t) + b_1 \frac{dx(t)}{dt}$$

* FREQUENCY RESPONSE :

$$H(j\omega) = \frac{Y(j\omega)}{X(j\omega)} = \frac{F^{-1}\{0/p\}}{F^{-1}\{i/p\}}$$

Transfer fun?

The frequency response of (1) is given by,

$$\sum_{k=0}^N a_k (j\omega)^k Y(j\omega) = \sum_{k=0}^M b_k (j\omega)^k X(j\omega)$$

(by Fourier transforming on both sides).

$$\text{Now, } Y(j\omega) \left[\sum_{k=0}^N a_k (j\omega)^k \right] = X(j\omega) \left[\sum_{k=0}^M b_k (j\omega)^k \right]$$