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In [18]: #Importing the necessary libraries
import numpy as np
import activations
import torch
from sklearn.metrics import confusion_matrix
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In [19]: import matplotlib
import matplotlib.pyplot as plt
import seaborn as sn
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In [1]: def convert(imgf, labelf, outf, n):
    f = open(imgf, "rb")
    o = open(outf, "w")
    l = open(labelf, "rb")

    f.read(16)
    l.read(8)
    images = []

    for i in range(n):
        image = [ord(l.read(1))]
        for j in range(28*28):
            image.append(ord(f.read(1)))
        images.append(image)

    for image in images:
        o.write(",".join(str(pix) for pix in image)+"\n")
    f.close()
    o.close()
    l.close()

convert("train-images-idx3-ubyte", "train-labels-idx1-ubyte",
        "mnist_train.csv", 60000)
convert("t10k-images-idx3-ubyte", "t10k-labels-idx1-ubyte",
        "mnist_test.csv", 10000)
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In [20]: def load_data(path):
    def one_hot(y):
        table = np.zeros((y.shape[0], 10))
        for i in range(y.shape[0]):
            table[i][int(y[i][0])] = 1
        return table

    def normalize(x):
        x = x / 255
        return x

    data = np.loadtxt('{}'.format(path), delimiter = ',')
    return normalize(data[:,1:]), one_hot(data[:,1])

train_data, train_label = load_data('mnist_train.csv')
test_data, test_label = load_data('mnist_test.csv')
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In [27]: class NeuralNetwork:
    def __init__(self, X, y, batch = 64, lr = 0.01, epochs = 15):
        self.input = X
        self.target = y
        self.batch = batch
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self.epochs = epochs
self.lr = lr
self.size=[784,500,250,100,10]
self.testerror=[]

self.x = self.input[:self.batch]
self.y = self.target[:self.batch]
self.loss = []
self.batchloss=[]
self.acc = []

self.init_weights()
self.yhat=[]

def init_weights(self):

    def glorot_initialization(inputsize, outputsize):
        wij = np.sqrt(6/(inputsize+outputsize))
        return np.random.uniform(-wij, wij, (outputsize, inputsize))

    self.W1 = glorot_initialization(500,self.size[0])
    self.W2 = glorot_initialization(250,self.size[1])
    self.W3 = glorot_initialization(100,self.size[2])
    self.W4 = glorot_initialization(self.y.shape[1],self.size[3])

    self.b1 = np.zeros(self.W1.shape[1],)
    self.b2 = np.zeros(self.W2.shape[1],)
    self.b3 = np.zeros(self.W3.shape[1],)
    self.b4 = np.zeros(self.W4.shape[1],)

def relu(self, x):
    return np.maximum(0,x)

def drelu(self,x):
    return 1 * (x > 0)

def sigmoid(self,x):
    return 1/(1+np.exp(-x))

def dsigmoid(self,x):
    return self.sigmoid(x)*(1-self.sigmoid(x))

def tanh(self,x):
    return np.tanh(x)

def dtanh(self,x):
    return (1 - (np.tanh(x))**2)

def softmax(self, z):
    z = z - np.max(z, axis = 1).reshape(z.shape[0],1)
    return np.exp(z) / np.sum(np.exp(z), axis = 1).reshape(z.shape[0],1)

def shuffle(self):
    idx = [i for i in range(self.input.shape[0])]
    np.random.shuffle(idx)
    self.input = self.input[idx]
    self.target = self.target[idx]

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def feedforward(self):
    assert self.x.shape[1] == self.W1.shape[0]
    self.z1 = self.x.dot(self.W1) + self.b1
    self.a1 = self.relu(self.z1)

    assert self.a1.shape[1] == self.W2.shape[0]
    self.z2 = self.a1.dot(self.W2) + self.b2
    self.a2 = self.relu(self.z2)

    assert self.a2.shape[1] == self.W3.shape[0]
    self.z3 = self.a2.dot(self.W3) + self.b3
    self.a3 = self.relu(self.z3)

    assert self.a3.shape[1] == self.W4.shape[0]
    self.z4 = self.a3.dot(self.W4) + self.b4
    self.a4 = self.softmax(self.z4)

    self.error = self.a4 - self.y
    self.yhat.append(self.a4)

def backprop(self):
    dz4 = (1/self.batch)*self.error
    dw4 = np.dot(self.a3.T,dz4)

    dz3 = np.matmul(self.W4,dz4.T) * self.drelu(self.z3).T
    dw3 = np.dot(dz3,self.a2).T

    dz2 = np.dot(self.W3,dz3)* self.drelu(self.z2).T
    dw2 = np.dot(dz2,self.a1).T

    dz1 = np.dot(self.W2,dz2)*self.drelu(self.z1).T
    dw1 = np.dot(dz1,self.x).T

    db4 = np.sum(dz4,axis=0)
    db3 = np.sum(np.matmul(dz4,self.W4.T) * self.drelu(self.z3),axis = 0)
    x = np.matmul(dz4,self.W4.T) * self.drelu(self.z3)
    y = np.dot(x,self.W3.T)*self.drelu(self.z2)
    db2 = np.sum(y,axis=0)
    y1 = np.dot(y,self.W2.T) * self.drelu(self.z1)
    db1 = np.sum(y1,axis=0)

    assert dw4.shape == self.W4.shape
    assert dw3.shape == self.W3.shape
    assert dw2.shape == self.W2.shape
    assert dw1.shape == self.W1.shape

    assert db4.shape == self.b4.shape
    assert db3.shape == self.b3.shape
    assert db2.shape == self.b2.shape
    assert db1.shape == self.b1.shape

    self.W4 = self.W4 - self.lr * dw4
    self.W3 = self.W3 - self.lr * dw3
    self.W2 = self.W2 - self.lr * dw2
    self.W1 = self.W1 - self.lr * dw1

    self.b4 = self.b4 - self.lr * db4

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self.b3 = self.b3 - self.lr * db3
self.b2 = self.b2 - self.lr * db2
self.b1 = self.b1 - self.lr * db1

def train(self):
    for epoch in range(self.epochs):
        l = 0
        acc = 0
        self.shuffle()
        count=0
        for batch in range(self.input.shape[0]//self.batch-1):
            start = batch*self.batch
            end = (batch+1)*self.batch
            self.x = self.input[start:end]
            self.y = self.target[start:end]
            self.feedforward()
            self.backprop()
            count+=1
            if(count%200==0):
                for i in range(64):
                    l+=-np.sum(self.y[i,:]*np.log(self.a4[i,:]))
                self.batchloss.append(l/64)
            acc+= np.count_nonzero(np.argmax(self.a4,axis=1) == np.argmax(self.y))

        self.loss.append(l/(self.input.shape[0]//self.batch))
        self.acc.append(acc*100/(self.input.shape[0]//self.batch))

def plot(self):
    plt.figure(dpi = 125)
    plt.plot(self.batchloss, '--', color='green')
    plt.grid(True)
    plt.xlabel("Batches")
    plt.ylabel("Loss")
    plt.title("Every 200 batch loss for ReLU activation")

def acc_plot(self):
    plt.figure(dpi = 125)
    plt.plot(self.acc, '--', color='green')
    plt.xlabel("Epochs")
    plt.ylabel("Accuracy")
    plt.grid(True)
    plt.title("Accuracy with ReLU activation")

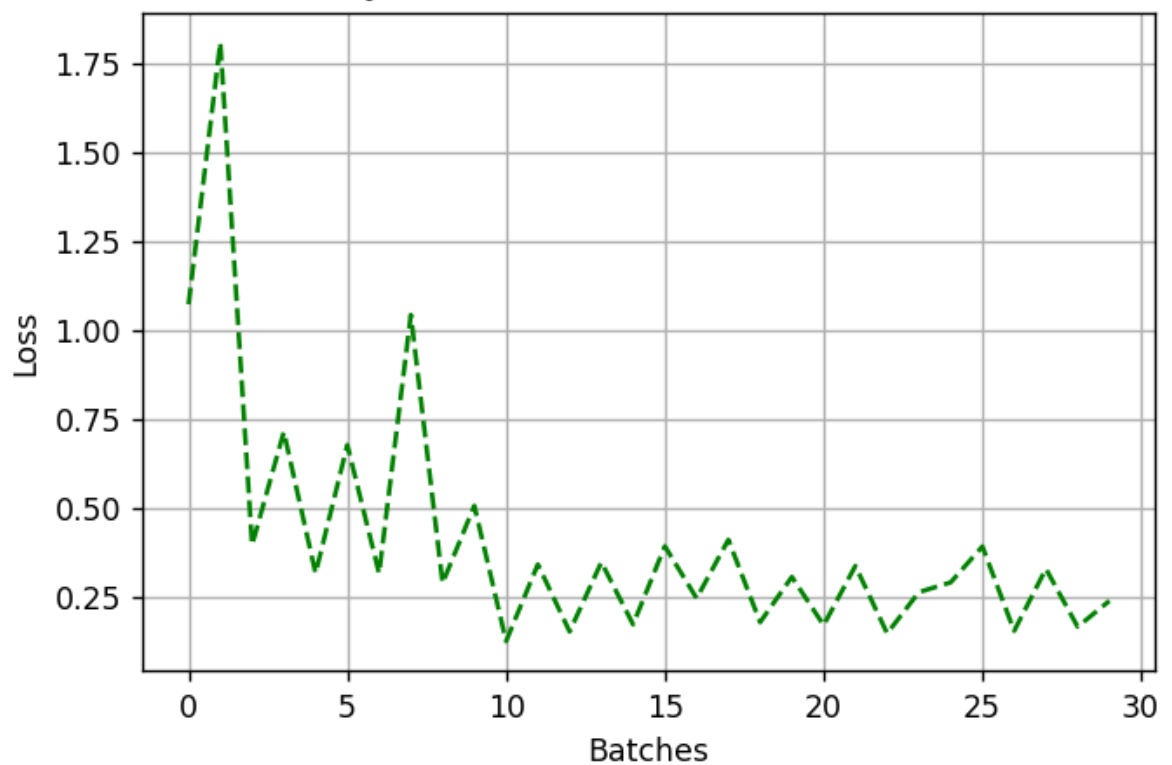
def confusion_matrix(self):
    k = np.argmax(self.y_hat,axis=0)
    cm=confusion_matrix(k, self.y)
    plt.figure(figsize=(8,8))
    sn.heatmap(confusion_matrix(k, self.y),annot=True,fmt='d')
    plt.xlabel('Predicted')
    plt.ylabel('truth')

def test(self,xtest,ytest):
    self.x = xtest
    self.y = ytest
    self.feedforward()
    acc = np.count_nonzero(np.argmax(self.a4,axis=1) == np.argmax(self.y))
    print("Accuracy:", 100 * acc, "%")

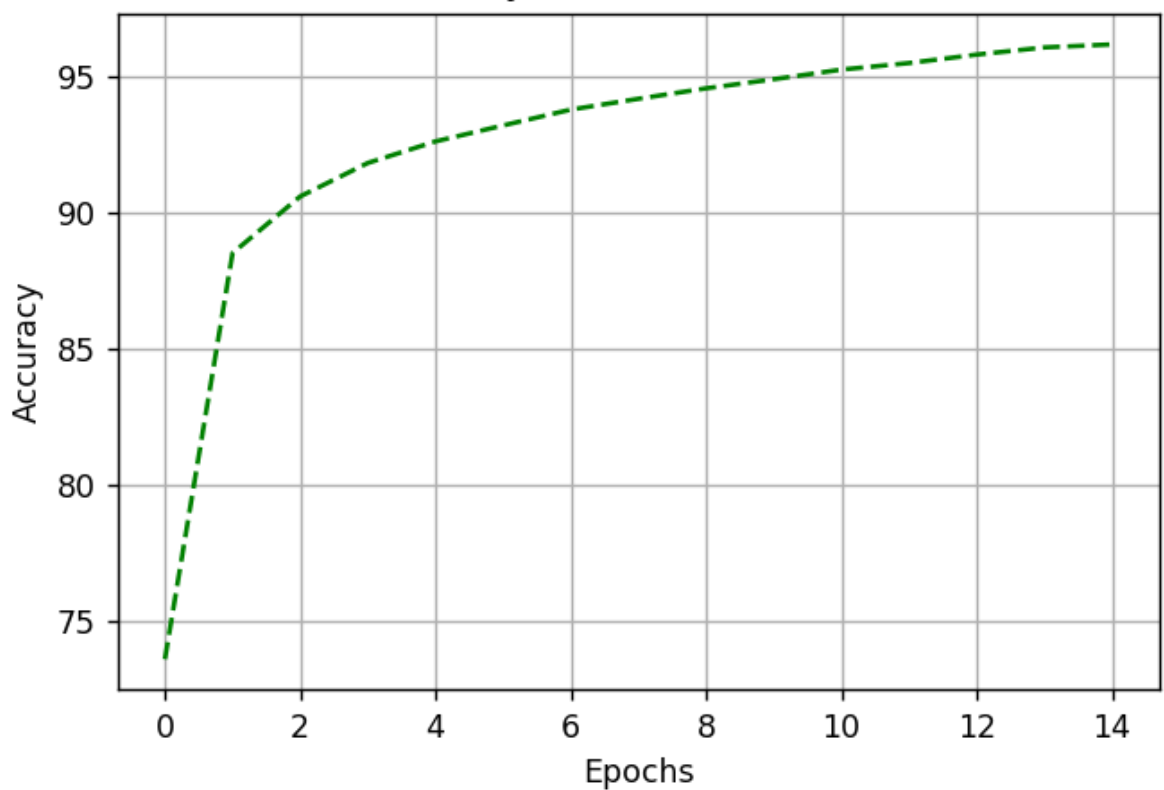
```

```
NN = NeuralNetwork(train_data[:30000], train_label[:30000])  
NN.train()  
NN.plot()  
NN.acc_plot()  
NN.confusion_matrix()
```

Every 200 batch loss for ReLU activation



Accuracy with ReLU activation



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In [28]: NN.test(test_data, test_label)
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Accuracy: 95.74000000000001 %