# Concurrent Internal Binary Search Trees



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## Overview

Local recovery

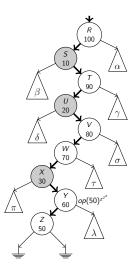
# Local recovery[PPoPP'16 Poster]

#### Overview

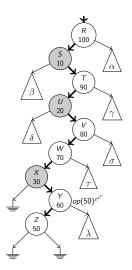
- a general technique for local recovery for concurrent BSTs
- reduces tree traversal cost during failures by restarting closer to an operations window

#### Motivation

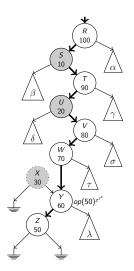
- in most concurrent BSTs, execution phase of an operation have constant time complexity
- seek phase is where an operation may end up spending most of its time (esp for large trees)
- this technique reduces the seek time



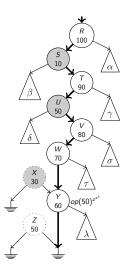
Operation op(50) is suspended at node Y during its traversal



All keys in subtree  $\pi$  are deleted one-by-one



Key 30 is deleted (simple delete); node X is removed

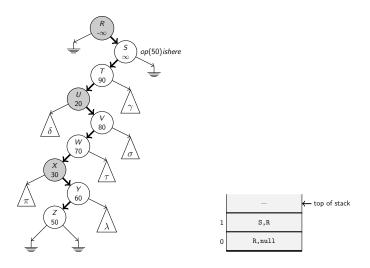


Key 20 is deleted (complex delete); key 20 is replaced with key 50 in node  $\it U$  and node  $\it Z$  is removed

#### Traversal Stack

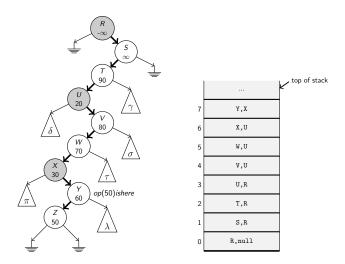
- a stack
- reduces tree traversal cost during failures by restarting closer to an operations window

### Traversal Stack



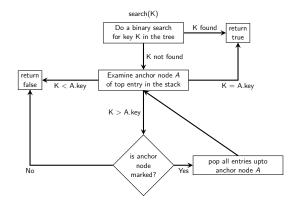
Operation op(50) starting at R and ending at Z along with the stack

### Traversal Stack

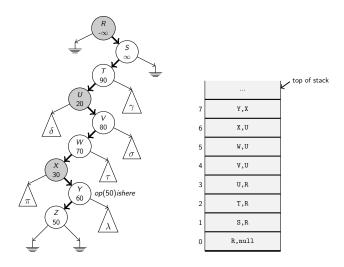


Operation op(50) starting at R and ending at Z along with the stack

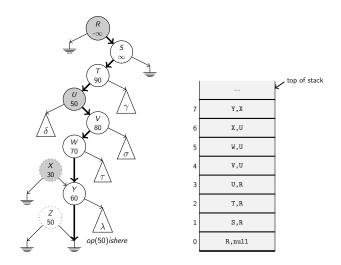
### search operations do not restart



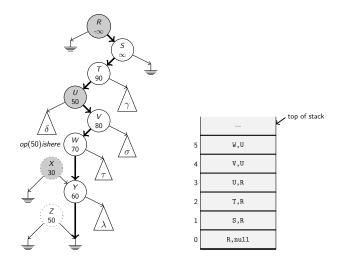
Sequence of steps in a search operation



Operation op(50) starting at R and ending at Z along with the stack



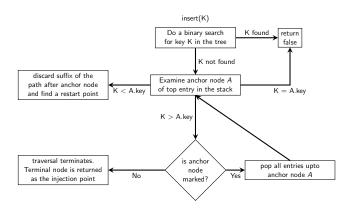
Key 20 is deleted (complex delete); key 20 is replaced with key 50 in node  $\it U$  and node  $\it Z$  is removed



Pop upto marked anchor node X. Top of stack is now W. Examine anchor node  ${\cal U}$ 

#### Insert

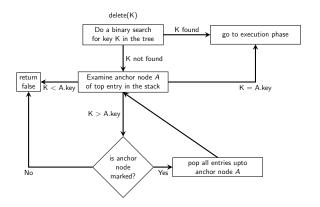
An insert operation needs to restart only if one of the anchor nodes in the path has become inconsistent



Sequence of steps in an insert operation

#### Delete

A delete operation do not restart except when there is a failure in the execution phase



Sequence of steps in a delete operation