Practical - 1

AIM: Installation of NS-3 in Linux

Objective: To learn to Install NS3 in Ubuntu Linux

Step to Install:

After Installing Ubuntu 20.04 LTS successfully, you can now start with installing of NS3 packages.

List of Packages for Installing ns-3 in Ubantu Systems

Prequisite for installing NS3.32

- 1] sudo apt upgrade
- 2] Sudo apt update

```
mca@mca-To-be-filled-by-O-E-M: -
 To run a command as administrator (user "root"), use "sudo «command»".
Gee 'man sudo_root" for detells.
Get:1 http://security.ubuntu.com/ubuntu focal-security InRelease [114 kB]
Get:2 http://security.ubuntu.com/ubuntu focal-security/main 1386 Packages [425 k
  et:3 http://security.ubuntu.com/ubuntu focal-security/main amd64 Packages [1,41
 et:4 http://in.archive.ubuntu.com/ubuntu focal Inkelease [265 kB]
 et:5 http://in.archive.ubuntu.com/ubuntu focal Inmetease [265 kB]

et:5 http://in.archive.ubuntu.com/ubuntu focal-updates InRelease [114 kB]

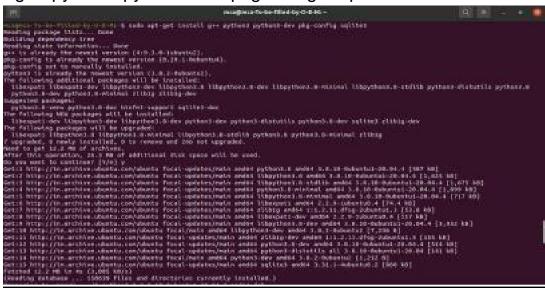
et:6 http://in.archive.ubuntu.com/ubuntu focal/main amd04 Packages [978 kB]

et:8 http://in.archive.ubuntu.com/ubuntu focal/main 1386 Packages [718 kB]
     9 http://security.ubuntu.com/ubuntu focal-security/main Translation-en [245
    :10 http://lm.archive.ubuntu.com/ubuntu focal/main Translation-en [586 kB]
```

3] **Minimal requirements for C++ users** apt-get install g++ python3

```
Reading package lists... Done
Building dependency tree
Reading state information... Done
python3 is already the newest version (3.8.2-Gubuntu2).
python3 set to manually installed.
The following additional packages will be installed:
binutils binutils-common binutils-x86-64-linux-gnu cpp-9 g++-9 gcc gcc-9
gcc-9-base libasan5 libatomic1 libbinutils libc-dev-bin libc6 libc6-dbg
libc6-dev libcrypt-dev libctf-nobfd8 libctf8 libgcc-9-dev libitm1 libisan8
libquadmath8 libstdc++-9-dev libtsan8 libubsan1 linux-libc-dev manpages-dev
Suggested packages:
binutils-doc gcc-9-locales g++-multilib g++-9-multilib gcc-9-doc
gcc-multilib make autocomf automake libtool flex bison gcc-doc
gcc-9-multilib glibc-doc libstdc++-9-doc
The following NEW packages will be installed:
binutils binutils-common binutils-x86-64-linux-gnu g++ g++-9 gcc gcc-9
libasan5 libatomic1 libbinutils libc-dev-bin libc6-dev libcrypt-dev
libctf-nobfd8 libctf8 libgcc-9-dev libitm1 liblsan8 libquadmath8
libstdc++-9-dev libtsan8 libubsan1 linux-libc-dev manpages-dev
```

4] **Minimal requirements for Python API users** apt-get install g++ python3 python3-dev pkg-config sqlite3



5] **Netanim animator:** qt5 development tools are needed for Netanim animator; apt-get install qt5-default mercurial

```
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opposited packages:

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jython-mysalob python-apennal python-pypents wish pythonid-dec bitteri dev libroto-dec bitteri dev libroto-dev libroto-dev unixodec-dev
firebird-dev libps-dev Ubiquital-dev unixodec-dev
firebird-dev libps-dev libps-dev libglid-dev Ubiqui-deval-dev Ubiquital-dev Ubiquital-devil-dev libps-deval-dev libps-deval-dev libps-deval-dev-libps-deval-dev-libps-deval-dev-libps-deval-dev-libps-deval-dev-libps-deval-dev-libps-deval-dev-libps-deval-dev-libps-deval-dev-libps-deval-dev-libps-deval-dev-libps-deval-dev-libps-deval-dev-libps-dev-libps-dev-libps-dev-libps-dev-libps-dev-libps-dev-libps-dev-libps-dev-libps-dev-libps-dev-libps-dev-libps-dev-libps-dev-libps-dev-libps-dev-libps-dev-libps-dev-libps-dev-libps-dev-libps-dev-libps-dev-libps-dev-libps-dev-libps-dev-libps-dev-libps-dev-libps-dev-libps-dev-libps-dev-libps-dev-libps-dev-libps-dev-libps-dev-libps-dev-libps-dev-libps-dev-libps-dev-libps-dev-libps-dev-libps-dev-libps-dev-libps-dev-libps-dev-libps-dev-libps-dev-libps-dev-libps-dev-libps-dev-libps-dev-libps-dev-libps-dev-libps-dev-libps-dev-libps-dev-libps-dev-libps-dev-libps-dev-libps-dev-libps-dev-libps-dev-libps-dev-libps-dev-libps-dev-libps-dev-libps-dev-libps-dev-libps-dev-libps-dev-libps-dev-libps-dev-libps-dev-libps-dev-libps-dev-libps-dev-libps-dev-libps-dev-libps-dev-libps-dev-libps-dev-libps-dev-libps-dev-libps-dev-libps-dev-libps-dev-libps-dev-libps-dev-libps-dev-libps-dev-libps-dev-libps-dev-libps-dev-libps-dev-libps-dev-libps-dev-libps-dev-libps-dev-libps-dev-libps-dev-libps-dev-libps-dev-libps-dev-libps-dev-libps-dev-libps-d
```

6] ns-3-pyviz visualizer

apt-get install gir1.2-goocanvas-2.0 python-gi python-gi cairo pythonpygraphviz python3-gi python3-gi-cairo python3-pygraphviz gir1.2-gtk-3.0 ipython ipython3

```
Building dependency tree
Beading state information... done
       oed-gi is already the newest version (3.36.8-1)
pythor3-gl-cairo is already the newest version (3.36.6-1),
glr1.7-goocanvas-7.0 is already the newest version (2.0.4-1),
python-gi is already the newest version (3.36.6-1).
pythom-gl-cairo is already the newest version (3.36.0-1).
pythoe3-pygraphviz is already the newest version (1.5-4build1).
gtr3.2-gtk-3.0 ta already the newest version (3.24.20-GabuntuS.1).
 he following pickage was automatically installed and is no longer regained:
 libfwopdplogini.
0 upgraded, 0 newly installed, 0 to remove and 0 not upgraded.
```

7] Debugging:

8]apt-get install gdb valgrind

```
ica@mca-To-be-filled-by-0-E-M:=$ sudo apt-get install gdb valgrind
Reading package lists... Done
Building dependency tree
Reading state information... Done
gdb is already the newest version (9.2-Bubuntu1~20.04.1).
valgrind is already the newest version (1:3.15.0-lubuntu9.1).
The following package was automatically installed and is no longer required:
 libfwupdplugin1
Use 'sudo apt autoremove' to remove it.
0 upgraded, 0 newly installed, 0 to remove and 0 not upgraded.
```

9] Doxygen and related inline documentation:

apt-get install doxygen graphviz imagemagick

```
mca@mca-To-be-filled-by-O-E-M:-$ sudo apt-get install doxygen graphviz imagemagick
Reading package lists... Done
Building dependency tree
Reading state information... Done
doxygen is already the newest version (1.8.17-Bubuntu2).
graphviz is already the newest version (2.42.2-3build2).
imagemagick is already the newest version (8:6.9.10.23+dfsg-2.1ubuntu11.4).
```

apt-get install texlive texlive-extra-utils texlive-latex extra texlive-font-utils dvipng latexmk

```
Meading package lists... Done
Building dependency tree
Reading state information... Done
Reading package the newest version (2019.202000218-1).
Realive later extra is already the newest version (2019.202000218-1).
The following package was automatically installed and is no longer required:
Libfwapdplugini
Use 'sudo apt autorenove' to remove and 6 not apgraded.
```

10] The ns-3 manual and tutorial are written in reStructuredText for Sphinx (doc/tutorial, doc/manual, doc/models), and figures typically in dia (also needs the texlive packages above):

apt-get install python3-sphinx dia

```
mcagmcs-To-be-filled-by-0-E-M:-$ sudo apt-get install python3-sphinx dia
Reading package lists... Done
Building dependency tree
Reading state information... Done
python3-sphinx is already the newest version (1.8.5-7ubuntu3).
dia is already the newest version (6.97.3+git20160930-9).
The following package was automatically installed and is no longer required:
   libfwupdplugin1
Use 'sudo apt autoremove' to remove it.
0 upgraded, 0 newly installed, 0 to remove and 0 not upgraded.
```

11] To read pcap packet traces

apt-get install tcpdump

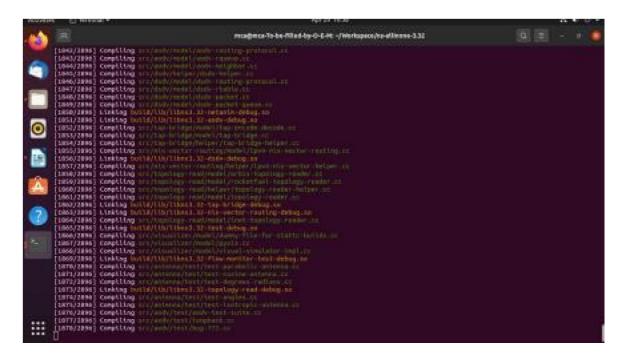
```
Reading package lists... Done
Bullding dependency tree
Reading state information... Done
tcpdump is already the newest version (4.9.3-4ubuntu8.1).
The following package was automatically installed and is no longer required:
libfwupdplugin1
Use 'sudo apt autoremove' to remove it.
0 upgraded, 0 newly installed, 0 to remove and 0 not upgraded.
```

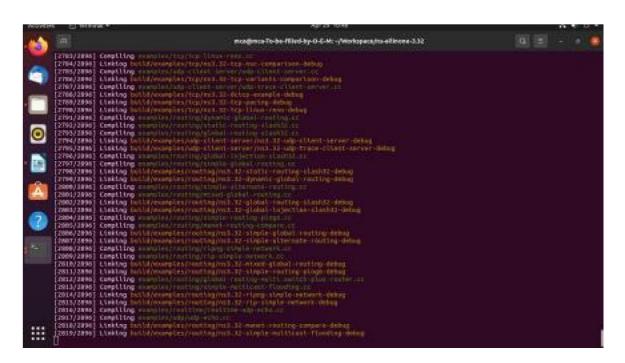
12] **Support for generating modified python bindings** apt-get install cmake libc6-dev libc6-dev-i386 libclang 6.0-dev llvm-6.0-dev automake python3-pip

```
Reading package lists... Done
Building dependency tree
Building dependency tree
Building dependency tree
Beading state information... Done
Building dependency tree
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Building Building Building Building Building Building Building Building Building Building Building Building Building Building Building Building Building Building Building Building Building Building Building Building Building Building Building Building Building Building Building Building Building Building Building Building Building Building Building Building Building Building Building Building Building Building Building Building Building Building Building Building Building Building Building Building Building Building Building Building Building Building Building Building Building Building Building Building Building Building Building Building Building Building Building Building Building Building Building Building Building Building Building Building Building Building Building Building Building Building Building Building Building Building Building Building Building Building Building Building Building Building Building Building Building Building Building Building Building Building Building Building Building Building Building Building Building Building Building Building Building Building Building Building Building Building Building Building Building Building Building Building Building Building Building Building Building Building Building Building Building Building Building Building Building Building Building Building Building Building Building Building Building Building Bui
```

After installing the required packages,

- 1. create a folder named workspace in the home directory and then put the NS3 tar package into the workspace.
- 2. Go to terminal and input these commands consecutively after each command finishes executing:
- 2.1. cd
- 2.2. cd workspace tar xjf <name of NS3 downloaded file name>
- 2.3. cd <name of extracted NS3>
- 2.4. ./build.py --enable-examples --enable-tests
- 2.5. It takes time be patient !!
- 3. Test the NS3 build and installation success by running test.py in the ns directory using the following commands:
- 3.1. cd ns-<version number>
- 3.2. ./test.py





MCAL 26 – Skill based Lab Course Networking with Linux Lab Page 7		
Practical No - 2		
AIM: Installation of Net anim in Linux		
Objective: To learn to Install Net anim in Ubuntu Linux		
Name : - Patel Arun Roll No:- 26		

After Installing Ubuntu 20.04 LTS successfully, you can now start with installing of Net anim packages.

List of Packages for Installing ns-3 in Ubantu Systems

Prequisite for installing NS3.32

- 1] sudo apt upgrade
- 2] Sudo apt update

```
To run a command as administrator (user "root"), use "sudo *command*".

See 'man sudo_root' for details.

**magnica-To-be-filled-by-O-I-R:-$ sudo apt upgrade

[sudo] password for mca:

Reading package lists... Done

Building dependency tree

Reading state information... Done

Calculating upgrade... Done

0 upgraded, 0 newly installed, 0 to remove and 0 not upgraded,

**magnica-To-be-filled-by-O-I-R:-$ sudo apt update

Cet:1 http://security.ubuntu.com/ubuntu focal-security InRelease [114 kB]

Get:2 http://security.ubuntu.com/ubuntu focal-security/main 1386 Packages [425 kB]

Get:3 http://security.ubuntu.com/ubuntu focal-security/main ando4 Packages [1,41 7 kB]

Get:4 http://in.archive.ubuntu.com/ubuntu focal-backports InRelease [114 kB]

Get:5 http://in.archive.ubuntu.com/ubuntu focal-backports InRelease [188 kB]

Get:6 http://in.archive.ubuntu.com/ubuntu focal-backports InRelease [188 kB]

Get:7 http://in.archive.ubuntu.com/ubuntu focal-main ando4 Packages [778 kB]

Get:8 http://in.archive.ubuntu.com/ubuntu focal/main 1386 Packages [718 kB]

Get:9 http://in.archive.ubuntu.com/ubuntu focal/main Translation-en [245 kB]

Get:10 http://in.archive.ubuntu.com/ubuntu focal/main Translation-en [586 kB]
```

3] Minimal requirements for C++ users apt-get install g++ python3

Reading package lists... Done

Building dependency tree

Reading state information... Done

python3 is already the newest version (3.8.2-Oubuntu2).

python3 set to manually installed.

The following additional packages will be installed:

binutils binutils-common binutils-x86-64-linux-gnu cpp-9 g++-9 gcc gcc-9

gcc-9-base libasan5 libatomic1 libbinutils libc-dev-bin libco libco-dbg

libco-dev libcrypt-dev libctf-nobfd0 libctf0 libgcc-9-dev libitm1 libisan0

libquadmath0 libstdc++-9-dev libtsan0 libubsan1 linux-libc-dev manpages-dev

Suggested packages:

binutils-doc gcc-9-locales g++-multilib g++-9-multilib gcc-9-doc

gcc-nultilib make autoconf automake libtool flex bison gcc-doc

gcc-9-multilib glibc-doc libstdc++-9-doc

The following NEW packages will be installed:

binutils binutils-common binutils-x86-64-linux-gnu g++ g+-9 gcc gcc-9

libasan5 libatomic1 libbinutils libc-dev-bin libco-dev libcrypt-dev

libctf-nobfd0 libctf0 libgcc-9-dev libitm1 libisan0 libquadmath0

libstdc++-9-dev libtsan0 libubsan1 linux-libc-dev manpages-dev

4] Minimal requirements for Python API usersapt-get install g++ python3 python3-dev pkg-config sqlite3

```
mca@mca-To-be-filled-by-O-E-M:-$ sudo apt-get install g++ python3 python3-dev pkg-config sqlite3
Reading package lists... Done
Reading package lists... Done
Reading state in matter... Done
R
```

5] Netanim animator: qt5 development tools are needed for Netanim animator; apt-get install qt5-default mercurial

```
Reading package lists... Done

Building dependency Free

Reading state Information... Done

The following additional packages will be installed:

Itadouble-conversions libepl-dev libepli libpl-dev libgli libples2 libglui-mesa-dev libglynd@ libplx-dev libglx@ libpcre2-16-0

Ithpthread-stubs0-dev libpython2-stdlib libpython2.7-minial libpython2.7-stdlib libptsconcurrent5 libqtScoresa libqtSdbus5 libqtStest5 libqtStates5 libqtStates5
```

6] ns-3-pyviz visualizer

apt-get install gir1.2-goocanvas-2.0 python-gi python-gi- cairo python-pygraphviz python3-gi python3-gi-cairo python3-pygraphviz gir1.2-gtk-3.0 ipython ipython3

```
phviz gir1.2-gik-3.0

Reading package lists... Done

Building dependency tree

Reading state information... Done

python3-gi is already the newest version (3.36.0-1).

python3-gi is already the newest version (3.36.0-1).

gir1.2-goocanvas-2.0 is already the newest version (2.0.4-1).

python-gi is already the newest version (3.36.0-1).

python-gi cairo is already the newest version (3.36.0-1).

python-gi-cairo is already the newest version (3.36.0-1).

python3-pygraphviz is already the newest version (3.5-4build1).

gir1.2-gik-3.0 is already the newest version (3.24.20-0ubuntu1.1).

The following package was automatically installed and is no longer required:

lib*hupdplugin1

Use 'sudo apt autoremove' to remove and 0 not upgraded.
```

7] Debugging:

8] apt-get install gdb valgrind

```
Reading package lists... Done

Building dependency tree

Reading state information... Done

gdb is already the newest version (9.2-Oubuntu1~20.04.1).

valgrind is already the newest version (1:3.15.0-1ubuntu9.1).

The following package was automatically installed and is no longer required:

libfwupdplugin1

Use 'sudo apt autoremove' to remove it.

O upgraded, O newly installed, O to remove and O not upgraded.
```

9] Doxygen and related inline documentation: apt-get install doxygen graphviz imagemagick

```
mcagmca-To-be-filled-by-U-E-M:~$ sudo apt-get install doxygen graphviz imagemagick
Reading package lists... Done
Building dependency tree
Reading state information... Done
doxygen is already the newest version (1.8.17-Oubuntu2).
graphviz is already the newest version (2.42.2-3build2).
imagemagick is already the newest version (8:6.9.10.23+dfsg-2.1ubuntu11.4).
```

apt-get install texlive texlive-extra-utils texlive-latex- extra texlive-font-utils dvipng latexmk

```
Reading package lists... Done

Reading dependency tree

Reading state information... Done

Reading state information... Supported in the information in the info
```

10] The ns-3 manual and tutorial are written in reStructuredText for Sphinx (doc/tutorial, doc/manual, doc/models), and figures typically in dia (also needs the texlive packages above):apt-get install python3-sphinx dia

```
mca@mca-To-be-filled-by-O-E-M:-$ sudo apt-get install python3-sphinx dia
Reading package lists... Done
Building dependency tree
Reading state information... Done
python3-sphinx is already the newest version (1.8.5-7ubuntu3).
dia is already the newest version (0.97.3+git20160930-9).
The following package was automatically installed and is no longer required:
libfwupdplugin1
Use 'sudo apt autoremove' to remove it.
0 upgraded, 0 newly installed, 0 to remove and 0 not upgraded.
```

11] To read pcap packet traces apt-get

install tcpdump

```
Reading package lists... Done
Building dependency tree
Reading state information... Done
tcpdump is already the newest version (4.9.3-4ubuntu0.1).
The following package was automatically installed and is no longer required:
   libfwupdplugin1
Use 'sudo apt autoremove' to remove it.
0 upgraded, 0 newly installed, 0 to remove and 0 not upgraded.
```

12] Support for generating modified python bindings aptget install cmake libc6-dev libc6-dev-i386 libclang- 6.0-dev llvm-6.0-dev automake python3-pip

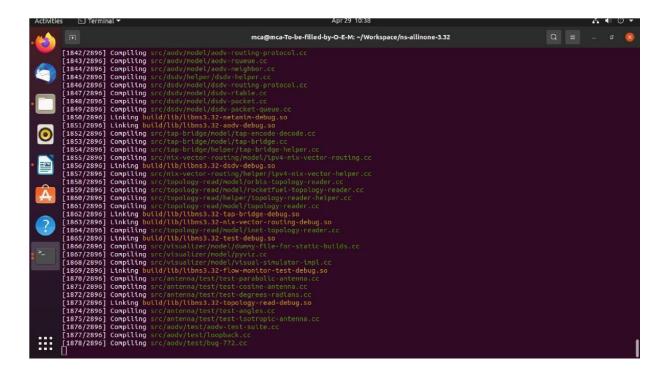
```
Mcdamca-10-be-Titled-by-U-E-M:-$ Sudo apt-get install cmake tipco-dev tipco-dev-1386 tipclang-6.0-dev tivm-6.0-dev automake pythons-pip Reading package lists... Done
Building dependency tree
Reading state information... Done
automake is already the newest version (1:1.16.1-4ubuntu6).
cmake is already the newest version (3:16.3-lubuntu1).
libclang-6.0-dev is already the newest version (1:6.0.1-14).
llvm-6.0-dev is already the newest version (1:6.0.1-14).
llbc6-dev is already the newest version (2:31-0ubuntu9.7).
libc6-dev-1386 is already the newest version (2.31-0ubuntu9.7).
python3-pip is already the newest version (20.0.2-5ubuntu1.6).
The following package was automatically installed and is no longer required:
libfwupdplugin1
Use 'sudo apt autoremove' to remove and 0 not upgraded.
```

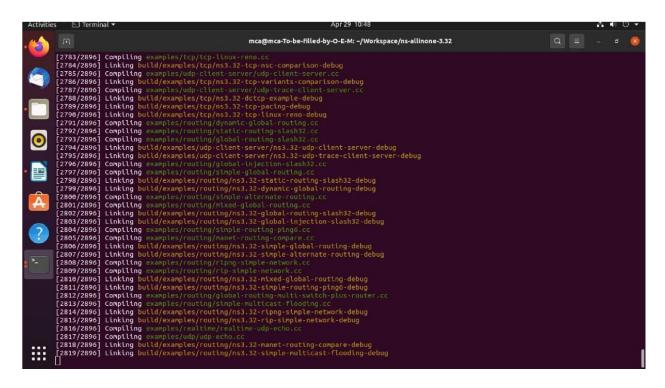
After installing the required packages,

- 4. create a folder named workspace in the home directory and then put the NS3 tar package into the workspace.
- Go to terminal and input these commands consecutively after each command finishes executing:

5.1. cd

- 5.2. cd workspace tar xjf <name of NS3 downloaded file name>
- 5.3. cd <name of extracted NS3>
- 5.4. ./build.py --enable-examples --enable-tests
- 5.5. It takes time be patient !!
- 6. Test the NS3 build and installation success by running test.py in the ns directory using the following commands:
- 6.1. cd ns-<version number>
- 6.2. ./test.py





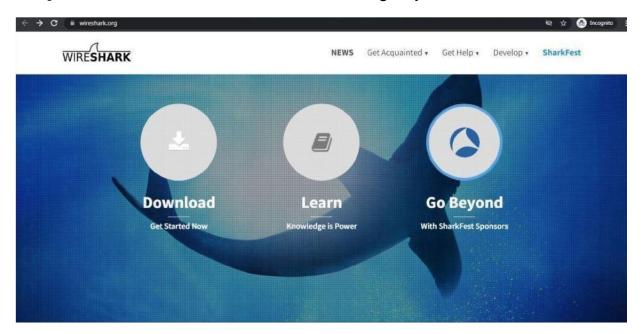
Practical No - 3

AIM: Installation of Wire Shark

Objective: To learn to Install Wire Shark in Ubuntu Linux

Step to Install:

1] Visit the official Wireshark website using any web browser.



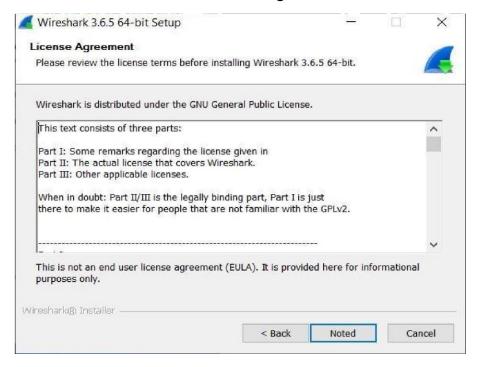
2] Click on Download, a new webpage will open with different installers of Wireshark



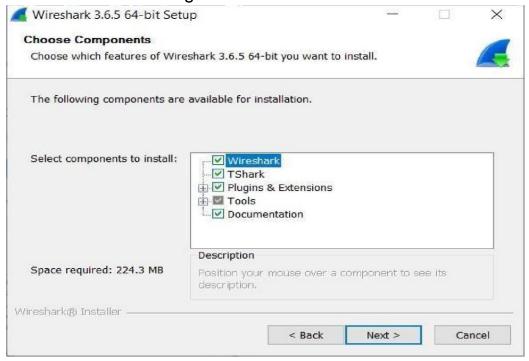
- 3] Downloading of the executable file will start shortly. It is a small 73.69 MB file that will take some time
- 4] Now check for the executable file in downloads in your system and run i
- 5] It will prompt confirmation to make changes to your system. Click on Ye
- 6] Setup screen will appear, click on Next.



7] The next screen will be of License Agreement, click on Noted.

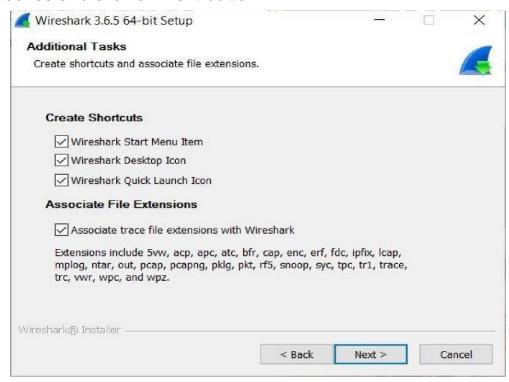


8] This screen is for choosing components, all components are already marked so don't change

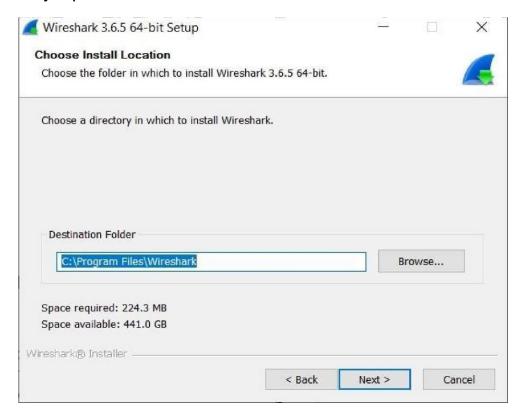


anything just click on the Next button.

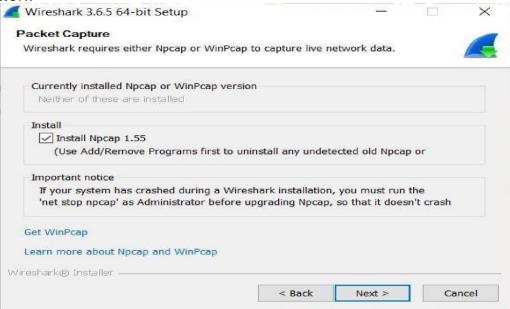
9] This screen is of choosing shortcuts like start menu or desktop icon along with file extensions which can be intercepted by Wireshark, tick all boxes and click on Next button.



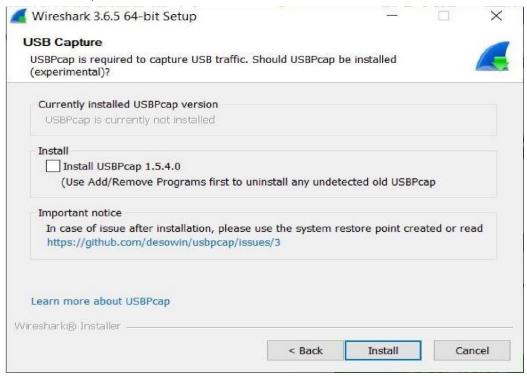
6] The next screen will be of installing location so choose the drive which will have sufficient memory space for installation. It needed only a memory space of 224.3 MB



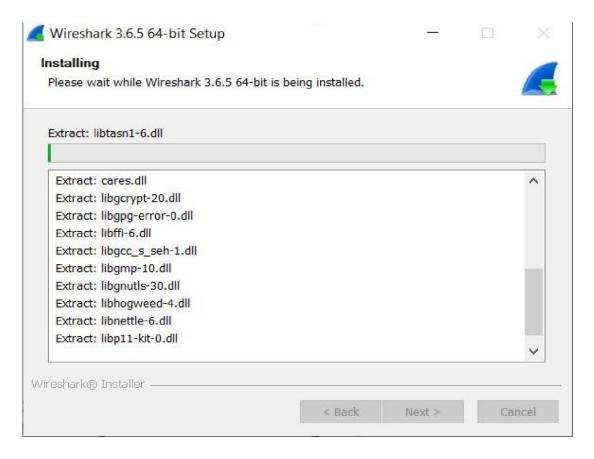
7] Next screen has an option to install Npcap which is used with Wireshark to capture packets pcap means packet capture so the install option is already checked don't change anything and click the next button.



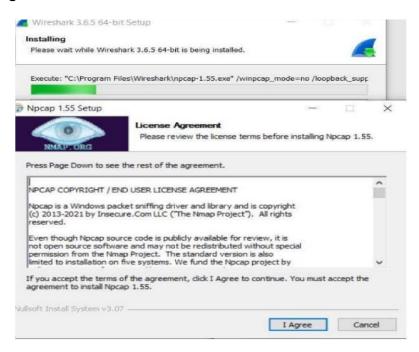
6] Next screen is about USB network capturing so it is one's choice to use or not, click on Install.



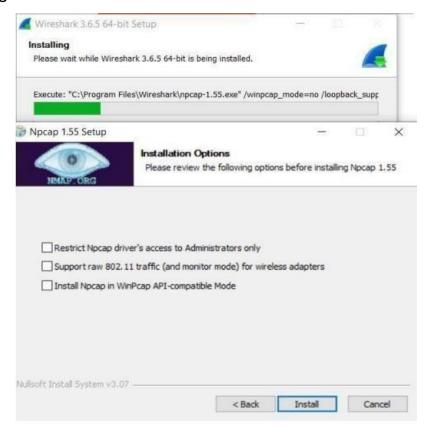
7] After this installation process will start.



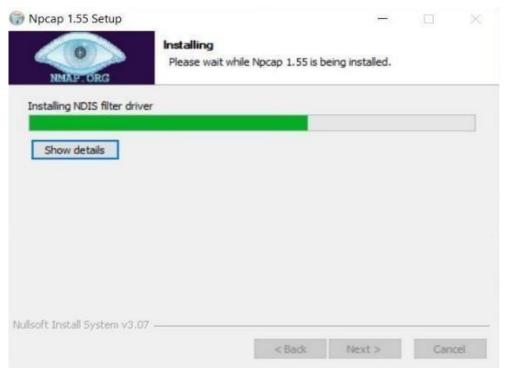
6] This installation will prompt for Npcap installation as already checked so the license agreement of Npcap will appear to click on the I Agreebutton.



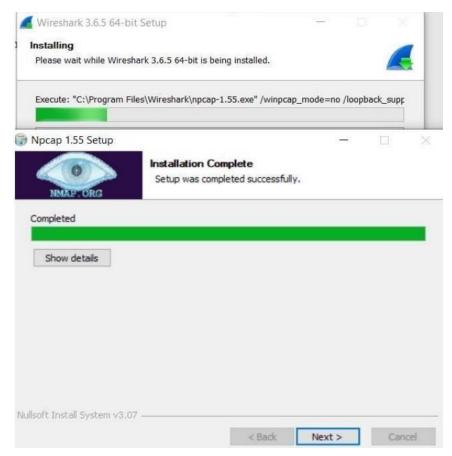
6] Next screen is about different installing options of npcap, don't do anything click on Install



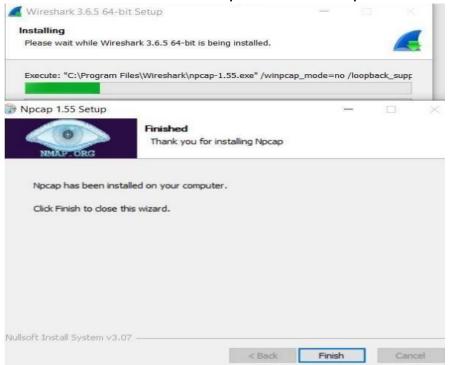
7] After this installation process will start which will take only a minute.



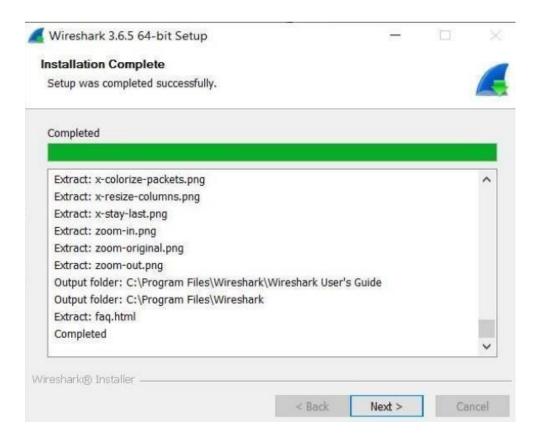
8] After this installation process will start which will take only a minute.



9] Click on Finish after the installation process is complete..



10] After this installation process of Wireshark will complete click on the Next button



11] Click on Finish after the installation process of Wireshark is complete.



12] Wireshark is successfully installed on the system and an icon is created onthe desktop

MCAL 26 – Skill based Lab Course Networking with Linu	ıx Lab Page 23
Name : - Patel Arun	Roll No:- 26

MCAL 26 – Skill based Lab Course Networking with Linu	ıx Lab Page 24
Name : - Patel Arun	Roll No:- 26

MCAL 26 – Skill based Lab Course Networking with Lin	ux Lab Page 25
Name : - Patel Arun	Roll No:- 26

MCAL 26 – Skill based Lab Course Networking with Lin	ux Lab Page 26
Name : - Patel Arun	Roll No:- 26

MCAL 26 – Skill based Lab Course Networking with Line	ux Lab Page 27
Name : - Patel Arun	Roll No:- 26

Practical No-4

AIM: Program to simulate traffic between two nodes

Objective: To learn simulate traffic between two nodes and print String

Code:

```
Hello-Simulator.cc
/* -*- Mode:C++; c-file-style:"gnu"; indent-tabs-mode:nil; - *- */
#include "ns3/core-module.h" using
namespace ns3;
NS_LOG_COMPONENT_DEFINE ("HelloSimulator");
Int
main (int argc, char *argv[])
{
NS_LOG_UNCOND ("Hello Simulator");
}
```

First.cc #include "ns3/core-module.h" #include "ns3/network-module.h" #include "ns3/internet-module.h" #include "ns3/point-to-point-module.h" #include "ns3/applications-module.h" // Default Network Topology // // 10.1.1.0 // n0 ----- n1 // point-to-point using namespace ns3; NS_LOG_COMPONENT_DEFINE ("FirstScriptExample"); int main (int argc, char *argv[]) CommandLine cmd (__FILE__); cmd.Parse (argc, argv); Time::SetResolution (Time::NS); LogComponentEnable ("UdpEchoClientApplication", LOG_LEVEL_INFO); LogComponentEnable ("UdpEchoServerApplication", LOG LEVEL INFO); NodeContainer nodes: nodes.Create (2);

Name: - Patel Arun Roll No:- 26

PointToPointHelper pointToPoint;

```
pointToPoint.SetDeviceAttribute ("DataRate", StringValue
("5Mbps"));
pointToPoint.SetChannelAttribute ("Delay", StringValue
("2ms"));
NetDeviceContainer devices; devices
= pointToPoint.Install (nodes);
InternetStackHelper stack;
stack.Install (nodes);
Ipv4AddressHelper address; address.SetBase
("10.1.1.0", "255.255.255.0");
Ipv4InterfaceContainer interfaces = address.Assign
(devices):
//server
UdpEchoServerHelper echoServer (9);
ApplicationContainer serverApps = echoServer.Install
(nodes.Get (1)); serverApps.Start
(Seconds (1.0));
serverApps.Stop (Seconds (10.0));
//client
UdpEchoClientHelper echoClient (interfaces.GetAddress (1),
9);
echoClient.SetAttribute ("MaxPackets", UintegerValue (1));
echoClient.SetAttribute ("Interval", TimeValue (Seconds
(1.0));
echoClient.SetAttribute ("PacketSize", UintegerValue
(1024));
ApplicationContainer clientApps = echoClient.Install
(nodes.Get (0)); clientApps.Start
(Seconds (2.0)); clientApps.Stop
(Seconds (10.0));
Simulator::Run ();
Simulator::Destroy ();
return 0;
}
```

