No of Pages : 2 Course Code : 12XW22

Roll No:

(To be filled in by the candidate)

PSG COLLEGE OF TECHNOLOGY, COIMBATORE - 641 004

SEMESTER EXAMINATIONS, MAY - 2013

MSc - SOFTWARE ENGINEERING Semester : 2

12XW22 APPLIED LINEAR ALGEBRA

Time : 3 Hours Maximum Marks : 100

INSTRUCTIONS:

- Group I, Group II and Group III questions should be answered in the Main Answer Book.
- Ignore the box titled as "Answers for Group III" in the Main Answer Book.
- Answer ALL questions from GROUP I.
- Answer any 4 questions from GROUP II.
- Answer any ONE question from GROUP III.

GROUP - I Marks : 10 × 3 = 30

- In order to know that a linear system is consistent with unique solution, what would you
 have to know about the pivot columns in the augmented matrix of the system?
- Is it possible to have a vector space with exactly two distinct vectors in it? Justify.
- 3. Is the set of all points on the circle x₁² + x₂² = 1 a subspace of R²? Why or why not?
- Give an example to each of the following: i) a set of vectors that spans R² but not linearly independent; ii) a linearly independent set of vectors that does not span R³.
- 5. What is the standard matrix of the transformation on R² that first rotates each vector through an angle 60° anti-clockwise, then projects it on the x-axis, and then reflects it about the line y = x?
- Let Ax = 0 be a homogeneous linear system of three equations in three unknowns. If
 the column space of A is a line through the origin, what kind of geometric object is the
 null space of A? What kind of geometric object is the column space of A^T?
- Find two vectors u and v in R² that are orthonormal with respect to the inner product
 (u, v) = 3u₁v₁ + 2u₂v₂ but are not orthonormal with respect to the Euclidean inner
 product.
- Indicate whether each of the following statements is always true or sometimes false.
 Justify your answer by giving a logical argument or a counterexample.
 - A linearly dependent set of vectors in an inner product space cannot be orthonormal.
 - Every matrix with a nonzero determinant has a QR-decomposition.
- The characteristic polynomial of some matrix A is found to be (λ 1)(λ 3)²(λ 4)³.
 What is the order of A? Is A invertible? How many eigen-spaces does A have?
- 10. What is Singular Value Decomposition (SVD) of a matrix? Why do we need it?

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Marks : $4 \times 12.5 = 50$

An economy consists of three sectors - Coal, Power, and Steel. The output from each sector is distributed among the various sectors as in Table 1. Formulate a system of linear equations that leads to prices at which each sector's income matches its expenses. Solve the system to determine the equilibrium prices.

Input to Coal Power Steel 0.4 Coal 0 0.6 Power 0.4 0.5 0.1 Steel 0.6 0.2 0.2

Output from

- Show that the set of all real matrices of the form with addition and scalar multiplication defined by $\begin{bmatrix} a & 1 \\ 1 & b \end{bmatrix} + \begin{bmatrix} c \\ 1 \end{bmatrix}$ $\begin{bmatrix} 1 \\ b+d \end{bmatrix}$ and $k \begin{bmatrix} a & 1 \\ 1 & b \end{bmatrix} = \begin{bmatrix} ka & 1 \\ 1 & kb \end{bmatrix}$ is a vector space.
- Let $T: \mathbb{R}^5 \to \mathbb{R}^4$ be the transformation defined by $T[(x_1, x_2)] = (x_1 + 2x_2, -x_1, 0)$. Find the matrix of T with respect to the bases $B = \{u_1, u_2\}$ and $C = \{v_1, v_2, v_3\}$ where $u_1 = (1, 3), u_2 = (-2, 4), v_1 = (1, 1, 1), v_2 = (2, 2, 0), and v_3 = (3, 0, 0).$ Using the matrix obtained, find the image of (8,3) under T.
- To measure the takeoff performance of an airplane, the horizontal position of the plane was measured every 2 seconds from t = 0 to t = 10. The positions (in feet) are 0, 29.9 104.7, 222.0, 380.4, and 517.7. Fit a least-squares quadratic $y = \beta_0 + \beta_1 t + \beta_2 t^2$ for the data. Use the result to estimate the velocity of the plane when t = 4.5.
- 15. Applying Gram-Schmidt process, obtain an ortho-normal basis for the Euclidean inner product space R^4 from the basis $B = \{(1,0,1,1), (1,1,0,1), (1,1,1,0), (0,1,1,1)\}$.

GROUP - III Marks :
$$1 \times 20 = 20$$

16. a) Let
$$C_1, C_2, \dots, C_5$$
 denote the columns of the matrix $A = \begin{bmatrix} 5 & 1 & 2 & 2 & 0 \\ 3 & 3 & 2 & -1 & -12 \\ 8 & 4 & 4 & -5 & 12 \\ 2 & 1 & 1 & 0 & -2 \end{bmatrix}$

and $B = [C_1 \ C_2 \ C_4]$

- Explain why C_3 and C_5 are in the column space of B.
- Find a set of vectors that spans the null space of A.
- iii) Let $T: \mathbb{R}^5 \to \mathbb{R}^4$ be the transformation defined by T[x] = Ax. Explain why T is neither one one nor onto.
- b) Determine the Kernel, Range, Nullity, and Rank of the transformation defined in (iii) above. Also verify Rank-Nullity theorem.
- a) Discuss the geometric interpretation of eigen-values and eigen-vectors. Mention any two real-life applications of eigen-values and eigen-vectors.

b) Diagonalize the matrix
$$A = \begin{bmatrix} 9 & -3 & 3 \\ -3 & 6 & -6 \\ 3 & -6 & 6 \end{bmatrix}$$
 if possible. [14]

FD/RL