Arvi Gjoka
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Present Address
New York, NY

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Education

PhD, New York University, New York, NY

(Anticipated) Summer 2025

- Geometry Computing Lab, GPA 3.8
- Focus on differentiable simulation, inverse design and soft robotics
- NeurIPS reviewer (2022, 2023, 2024)
- Course Assistant for graduate Computer Graphics and Geometry Processing courses

BA, New York University, New York, NY

May 2018

- Dual Degree in Physics and Computer Science, GPA 3.9
- Honors: Phi Beta Kappa, Society of Physics Students

Publications

• Soft Pneumatic Actuator Design using Differentiable Simulation,

 $\bf Arvi~Gjoka,$ Espen Knoop, Moritz Bächer , and Denis Zorin, Daniele Panozzo, SIGGRAPH 2024

• Differentiable solver for time-dependent deformation problems with contact,

Zizhou Huang, Davi Colli Tozoni, **Arvi Gjoka**, Zachary Ferguson, Teseo Schneider, Daniele Panozzo, Denis Zorin,

ACM Transaction on Graphics, 2024

• An Extensible Benchmark Suite for Learning to Simulate Physical Systems,

Karl Otness, **Arvi Gjoka**, Joan Bruna, Daniele Panozzo, Benjamin Peherstorfer, Teseo Schneider, Denis Zorin, NeurIPS, 2021

• The iWildCam 2020 Competition Dataset,

Sara Beery, Elijah Cole, Arvi Gjoka,

CVPR, 2020, Fine-Grained Visual Categorization Workshop

• HistoryTracker: Minimizing Human Interactions in Baseball Game Annotation,

Jorge Piazentin Ono, **Arvi Gjoka**, Justin Salamon, Carlos A. Dietrich, Cludio T. Silva, CHI, 2019

Research and Work Experience

Intern, Disney, Zurich, CH

Summer 2022

Worked on finite element method based optimization for applications in soft robotics

Software Engineer, Google, New York, NY

Sept 2019 - Sept 2020

• Working as an engineer in the space of Fine Grained Visual Classification within Google Research

Engineering Resident, Google, New York, NY

Sept 2018 - Sept 2019

- Rotated between two teams in Google Research and Google Maps
- Worked on improving pipeline quality through feature engineering on geospatial data

Research Assistant, VIDA Lab at NYU Tandon, Brooklyn, NY

Summer 2018

• Worked on a human-in-the-loop approach to generating baseball position tracking using historical data (granted patent)

Computer Vision Intern, Entrupy, New York, NY

Summer 2017

- Developed classical vision and machine learning algorithms on surface textures (leather, cloth)
- Explored failure modes of vision algorithms on in house imaged surfaces of luxury goods

Computer Skills

- Proficiency in C/C++ (libigl, Eigen), Python (SciPy packages, OpenCV, Pytorch)
- Actively maintain and extend functionality in PolyFEM, a differentiable C++ finite element simulator
- Experience with ray tracing engines, geometry processing, machine learning pipelines, numerical methods for differential equations, microelectronics