

# AgentBoard: An Analytical Evaluation Board of Multi-Turn LLM Agents



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# Background

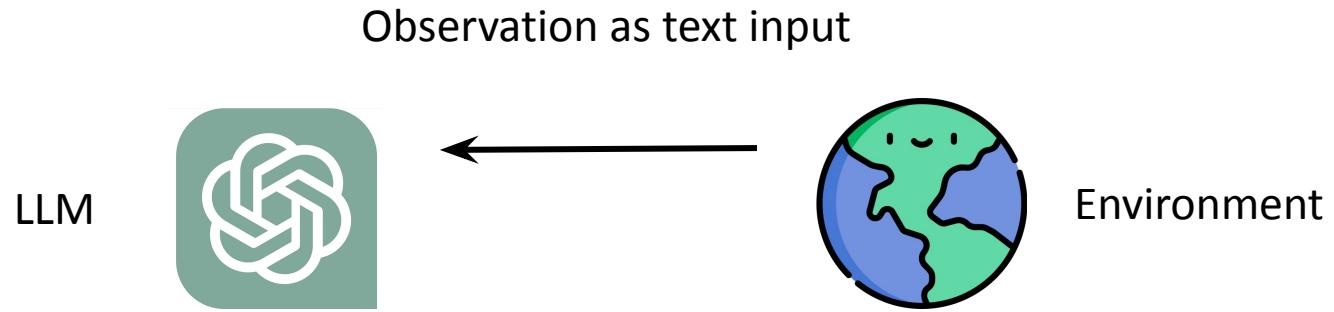
# LLM Powered Autonomous Agents

LLM

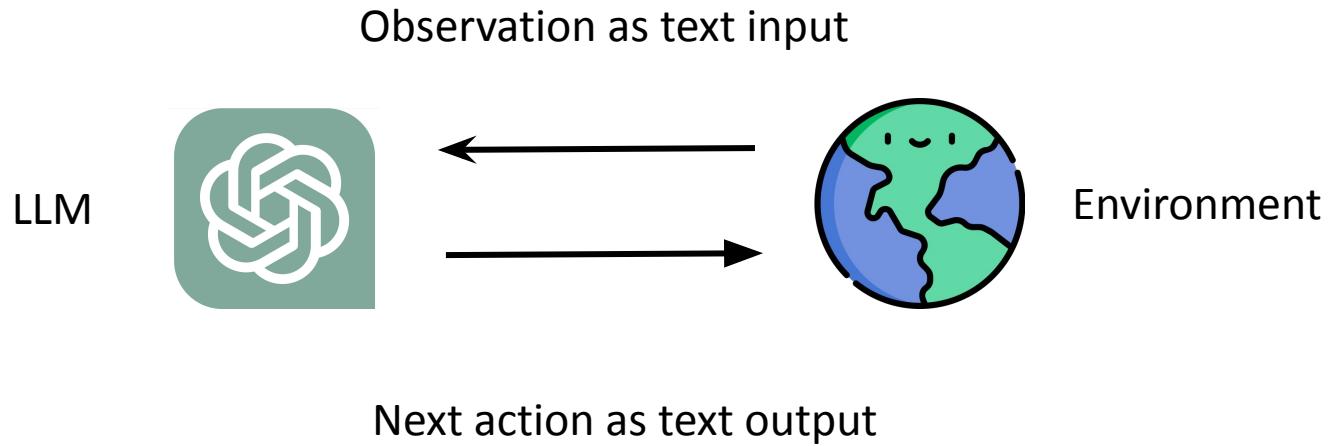


Environment

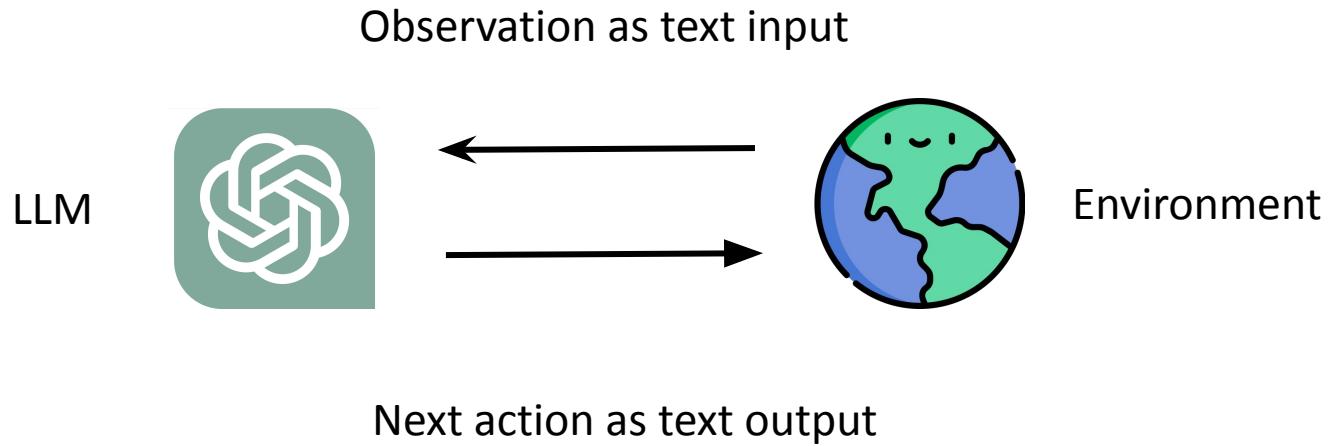
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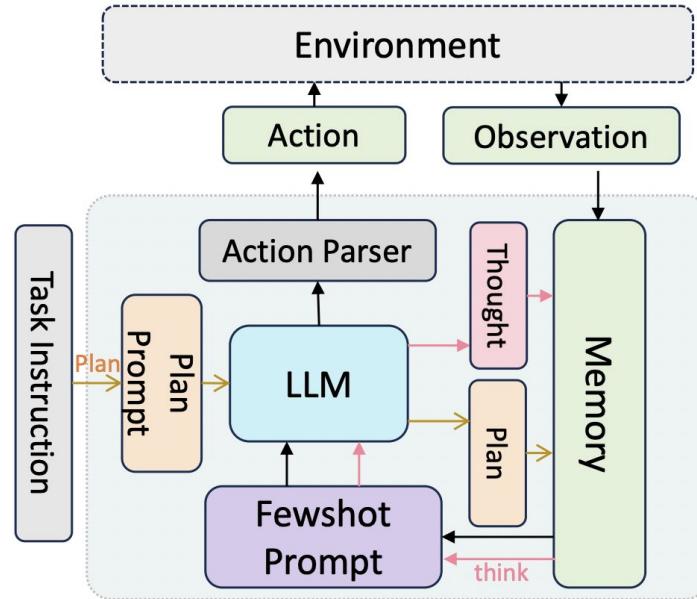


# LLM Powered Autonomous Agents



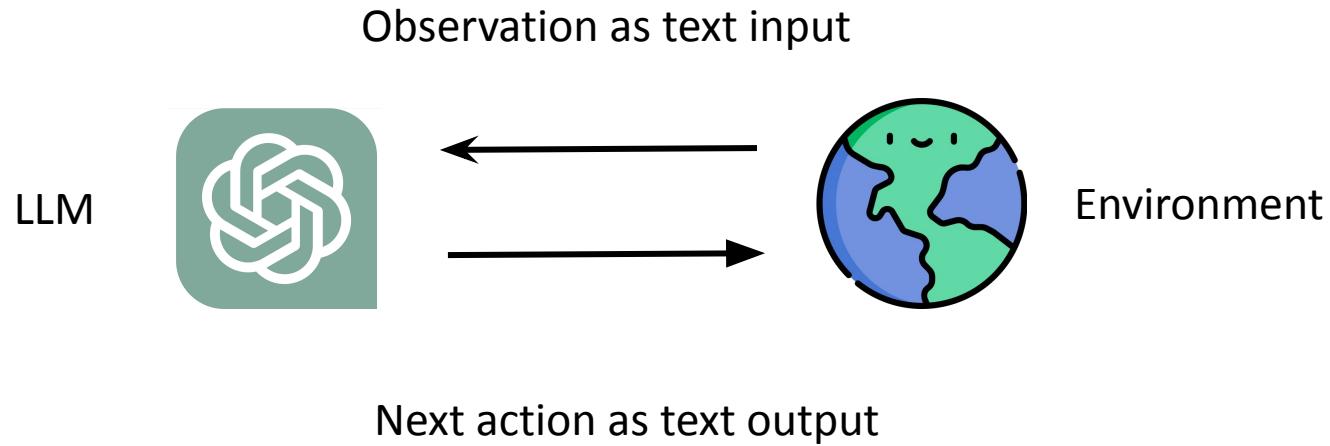
Autoregressive LLMs can reason and plan. They could interact with environments as agents.

# Evaluating LLM Agents

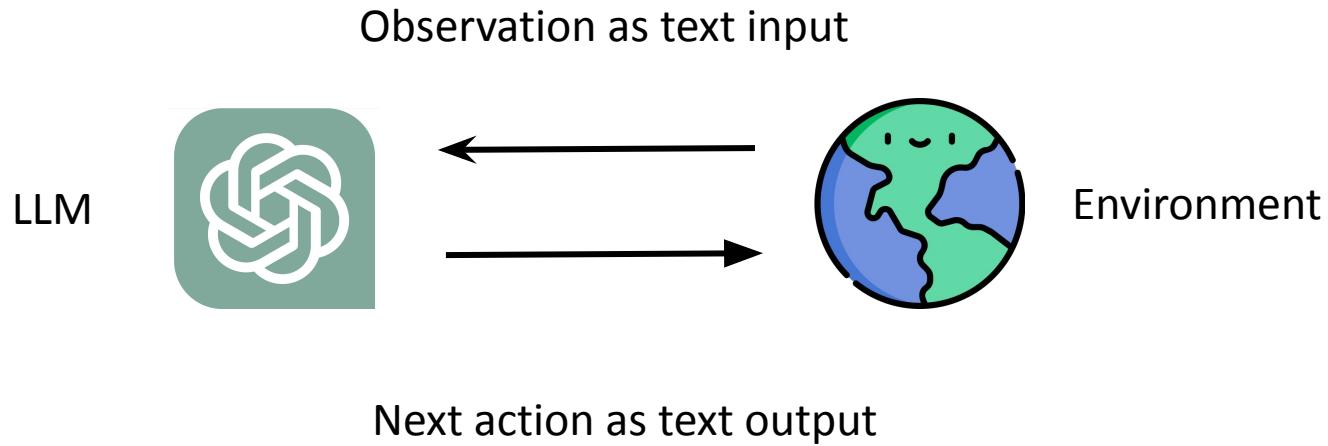


BOLAA, Liu et al 2023

# Evaluating LLM as Agents



# Evaluating LLM as Agents



Use simple, unified agent design to understand the varying agentic abilities of different LLM.

# **How to Comprehensively benchmark LLM as Agents ?**

# Motivation - LLM Agent Benchmark

Goal:

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Compare key agentic abilities of LLM through benchmarking.

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Our Work: AgentBoard

# Motivation - LLM Agent Benchmark

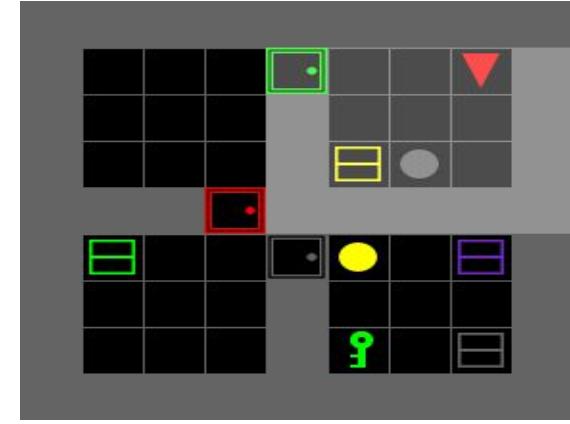
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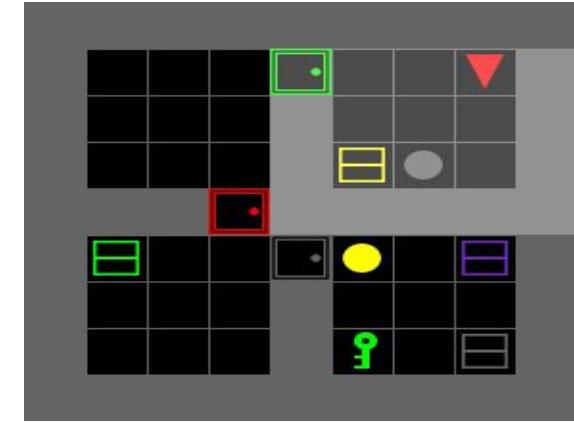
Our Work: AgentBoard

- Unified and Diverse Tasks

# Evaluating LLM as Generalist

A screenshot of a web-based 'Create submission' form. The page has a red header bar with tabs for 'Postroll', 'Forums', and 'Wiki'. Below the header, there are three main input fields: 'URL / image' (with a placeholder 'I'), 'Title' (empty), and 'Body' (empty). At the bottom of the form, there are sections for 'Markdown allowed' (with a 'Formatting help' link) and 'Forum' (a dropdown menu set to 'Choose one...'). A red 'Check submission' button is at the very bottom.

# Evaluating LLM as Generalist

A screenshot of a web-based 'Create submission' form. It includes fields for URL, Title, Body, and Forum selection. The forum dropdown is set to 'Choose one...'. A 'Submit' button is visible at the top right.

LLM Agents possess generalist ability. It's essential to evaluate LLM as Agents on a diverse set of tasks.

# Motivation - LLM Agent Benchmark

Goal:

Compare key agentic abilities of LLM through benchmarking.

Our Work: AgentBoard

- Unified and Diverse Tasks - **Multi-turn**

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- Unified and Diverse Tasks - **Multi-turn, Partially-observable**

# Motivation - LLM Agent Benchmark

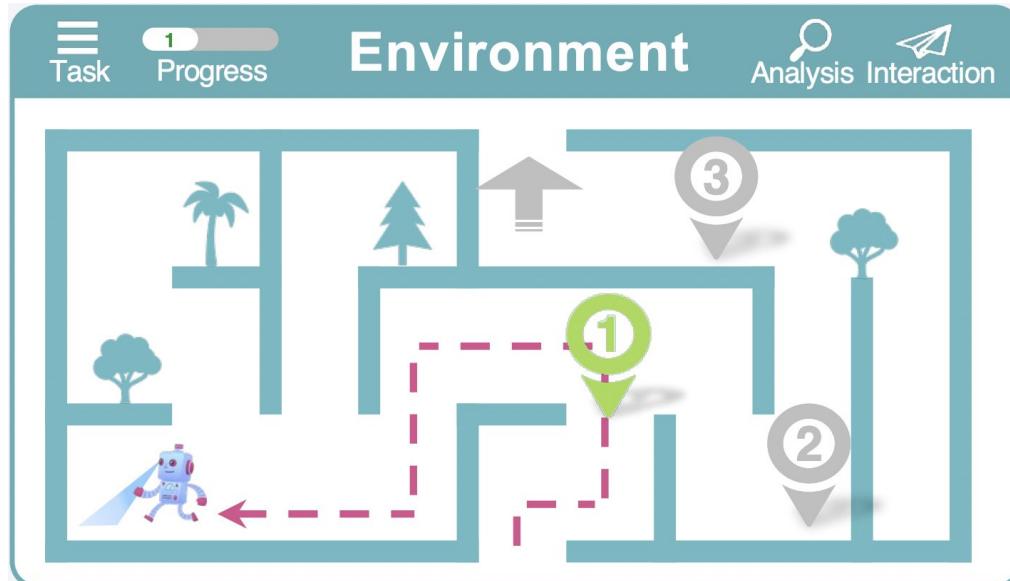
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Our Work: AgentBoard

- Unified and Diverse Tasks - **Multi-turn, Partially-observable**

# Important Features for Agent Evaluation



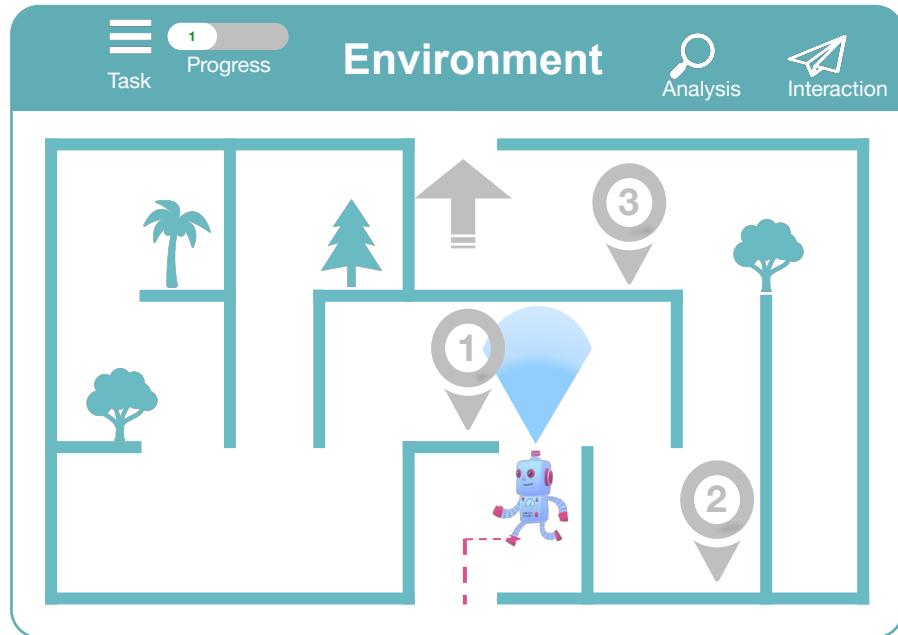
Multi-Turn



Partially Observable



# Important Features for Agent Evaluation



## 1. Multi-Turn

### Step 1:

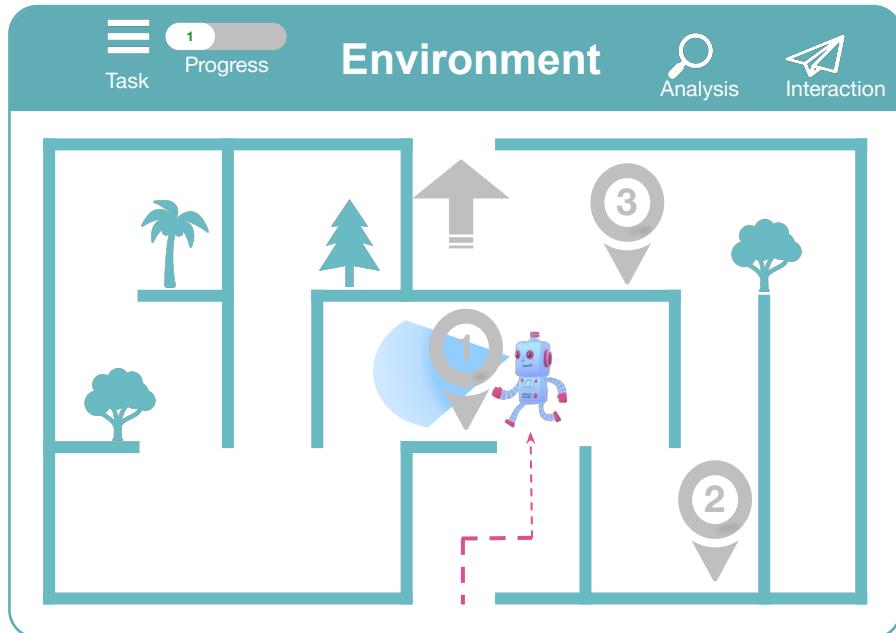


: Action 1



: Observation 1

# Important Features for Agent Evaluation



## 1. Multi-Turn

### Step 1:

 : Action 1 

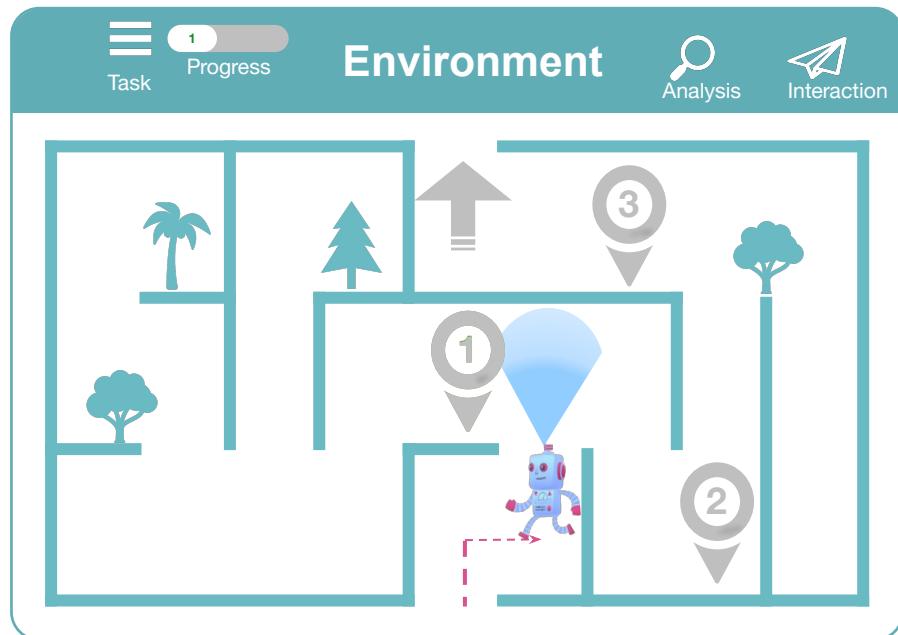
 : Observation 1

### Step 2:

 : Action 2 

 : Observation 2

# Important Features for Agent Evaluation



## 1. Multi-Turn

### Step 1:

 : Action 1 

 : Observation 1

### Step 2:

 : Action 2 

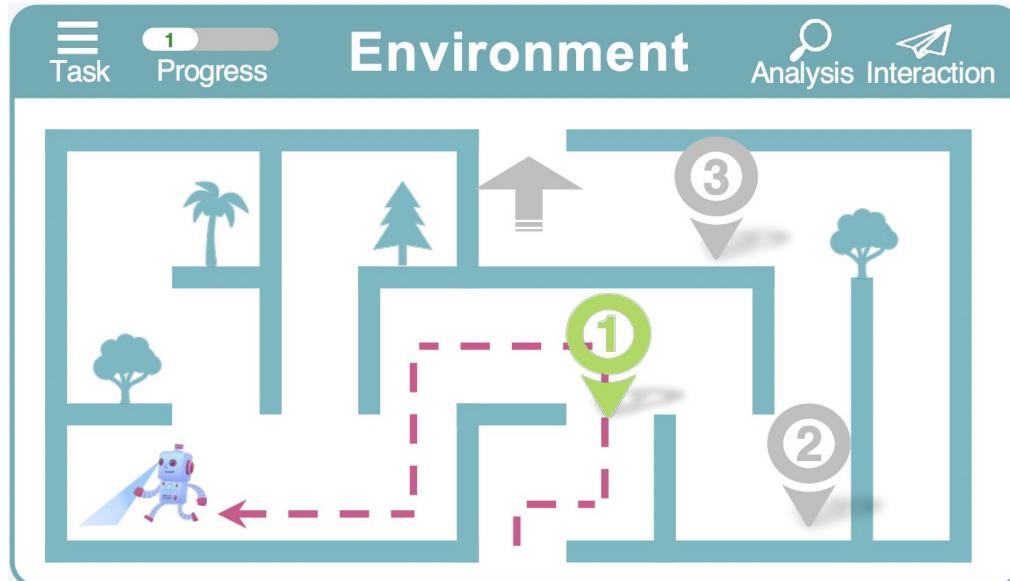
 : Observation 2

### Step 3:

 : Action 3 

 : Observation 3

# Important Features for Agent Evaluation



**Multi-Turn**



**Partially Observable**



# Unified and Diverse Tasks

## Task

### Web

- *WebShop*
- *WebArena*

### Tool

- *Query*
- *Operation*

### Embodied AI

- *AlfWorld*
- *ScienceWorld*
- *BabyAI*

### Game

- *Jericho*
- *PDDL*

Diverse testbeds:

- **9 Tasks**
- **1012 Environments**
- **6-20 Turns Interaction**
- **Diverse Action Space**

# Unified and Diverse Tasks

## Task

### Web

- *WebShop*
- *WebArena*

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- *AlfWorld*
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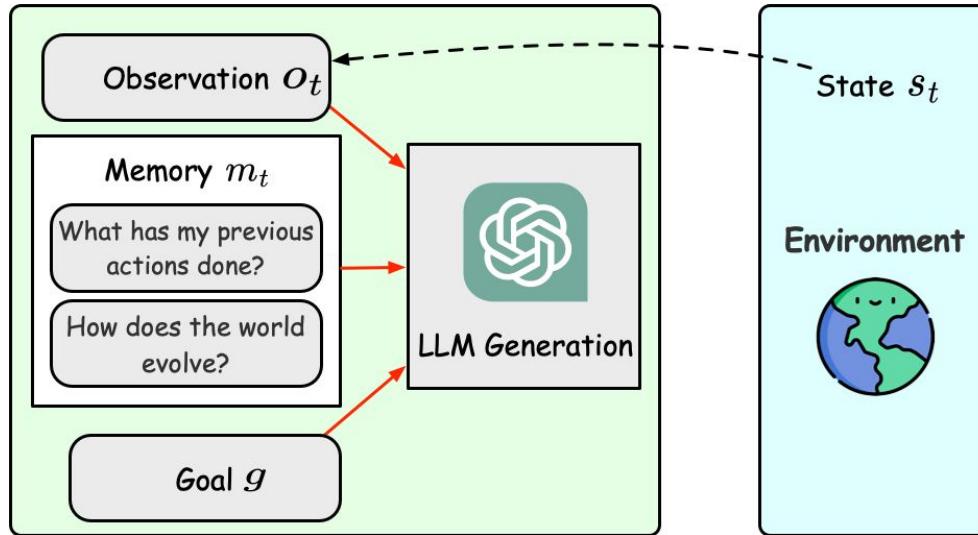
### Game

- *Jericho*
- *PDDL*

Unified Formatting:

- Multi-turn interactions.
- Natural language interface.
- Unified observations and actions format.

# Unified Framework for Evaluating LLM Agents



>[Instruction]: You are an agent in a virtual science school environment, tasked to interact with various elements. Here are commands that you can use: open, close, look around ...

>[Goal]: You should perform actions to accomplish the goal: boil some water.

>[Memory]:

**Observation:** This room is called the workshop. In it, you see: the agent, a table, a door to the hallway...

**Action:** go to kitchen

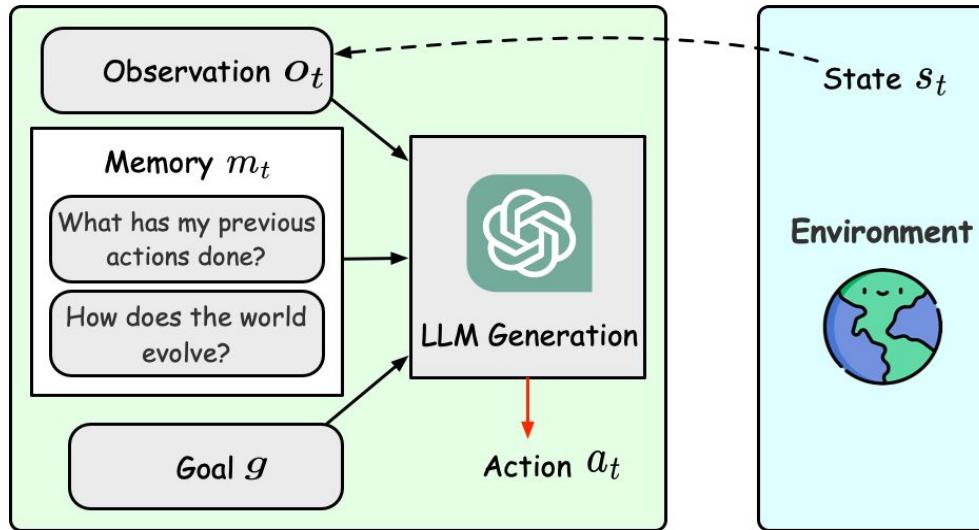
**Observation:** You move to the kitchen.

**Action:** open cupboard

**Observation:** The cupboard is open. There is a mug, a thermometer, and a cloth.

LLM is prompted with current task goal, observation, as well as previous **memory**.

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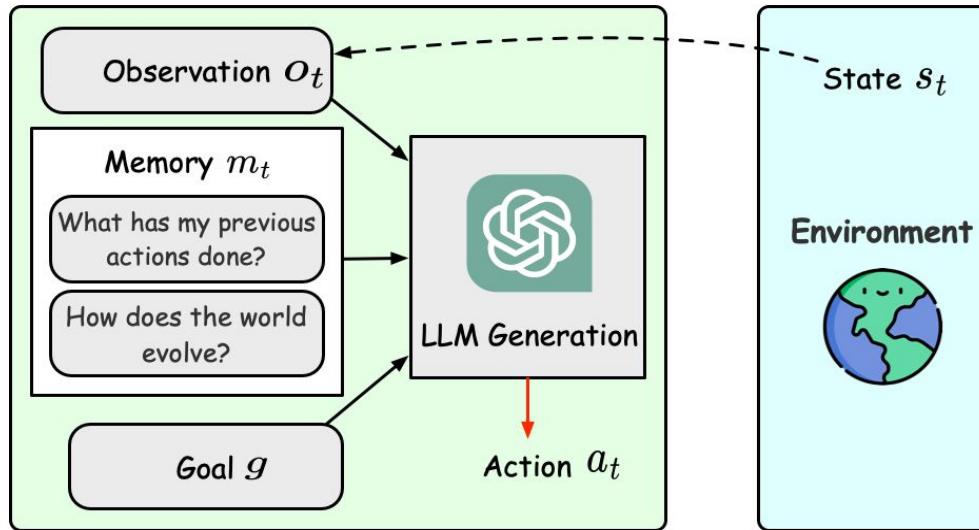
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**Action:**

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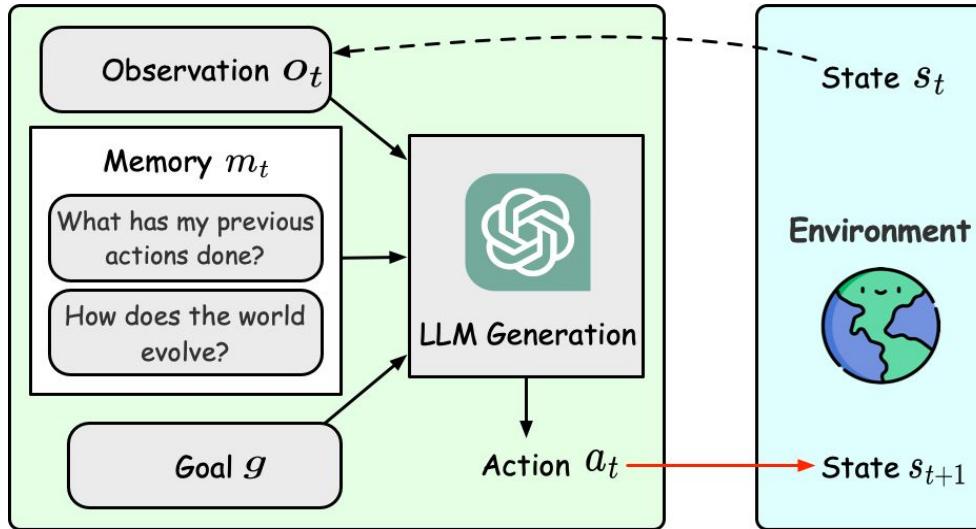
**Action:** open cupboard

**Observation:** The cupboard is open. There is a mug, a thermometer, and a cloth.



**Action:** pickup mug from the cupboard

# Unified Framework for Evaluating LLM Agents



**Action:** pickup mug from the cupboard



**Observation:** You move the mug to the inventory.

>**[Instruction]:** You are an agent in a virtual science school environment, tasked to interact with various elements. Here are commands that you can use: open, close, look around ...

>**[Goal]:** You should perform actions to accomplish the goal: boil some water.

>**[Memory]:**

**Observation:** This room is called the workshop. In it, you see: the agent, a table, a door to the hallway...

**Action:** go to kitchen

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**Action:** open cupboard

**Observation:** The cupboard is open. There is a mug, a thermometer, and a cloth.

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Our Work: AgentBoard

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-

# Motivation - LLM Agent Benchmark

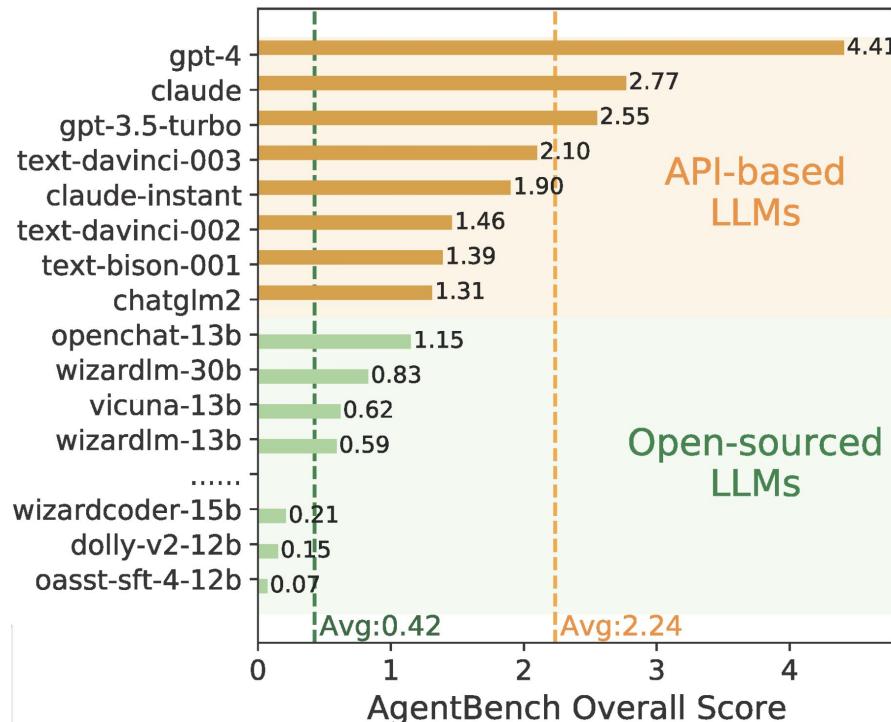
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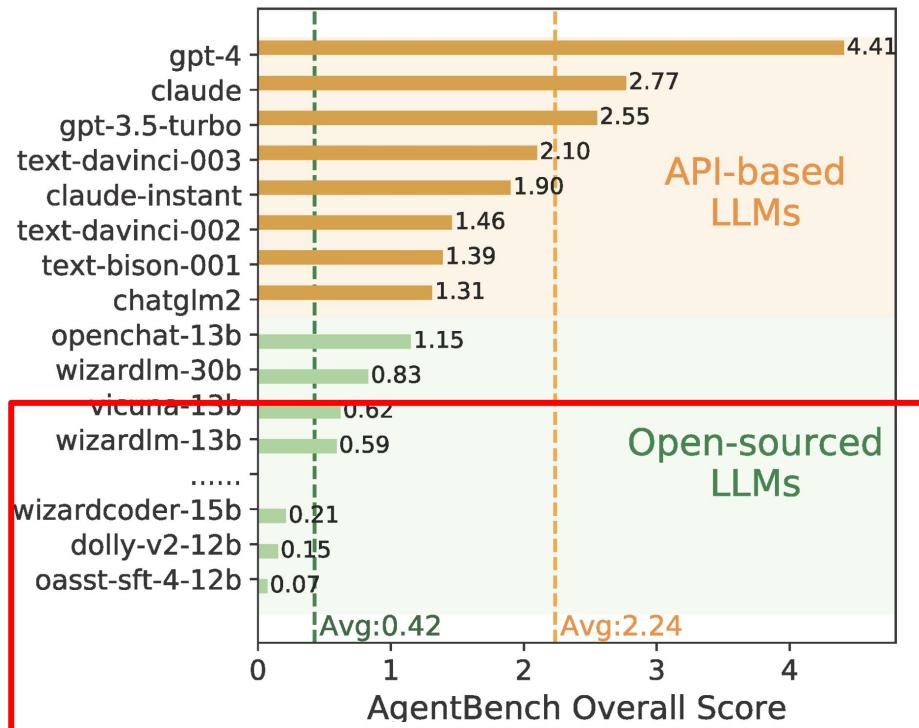
Our Work: AgentBoard

- Unified and Diverse Tasks - **Multi-turn, Partially-observable**
- Fine-grained Evaluation Metrics

# Why do we need Fine-grained Evaluation Metrics?



# Why do we need Fine-grained Evaluation Metrics?



Success rate is not discriminative enough for opensource models.

# Fine-grained Evaluation Metrics

Task: put a clean bowl in the fridge



go to countertop 1

pickup bowl 1

go to sinkbasin 1

clean bowl 1 in sinkbasin

put bowl 1 in fridge 1

Success rate: 0

Progress rate: 0.25

Success rate: 0

Progress rate: 0.5

Success rate: 0

Progress rate: 0.5

Success rate: 0

Progress rate: 0.75

Success rate: 1

Progress rate: 1

Progress rate metric accurately reflects LM agents' goal attainment at various stages.

# Fine-grained Progress Rate Calculation

$f(\text{goal state}, \text{current state})$

Match current state against goal state.

# Fine-grained Progress Rate Calculation

$f(\text{goal state}, \text{current state})$

Task: Insert "Nelson 99 75 80 79" and "Robert 63 75 92 72" into the "Sheet9" and sort this table by "Name" in ascending order.

| Nelson | Robert |
|--------|--------|
| 99     | 63     |
| 80     | 75     |
| 79     | 92     |
| 75     | 72     |

Progres Rate: 0.6

Progres-Rate-Match: Directly calculate state similarity.

# Fine-grained Progress Rate Calculation

$f(\text{goal state}, \text{current state})$



go to countertop 1

pickup bowl 1

go to sinkbasin 1

clean bowl 1 in sinkbasin

put bowl 1 in fridge 1



explore and find bowl  
Progress rate: 0.25

pickup and carry bowl  
Progress rate: 0.5

clean the bowl  
Progress rate: 0.75

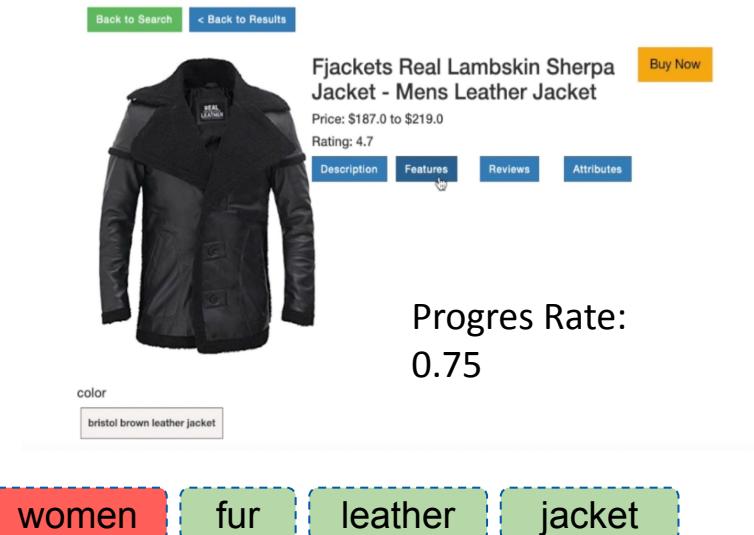
put the bowl in fridge  
Progress rate: 1.0

Progres-Rate-Subgoal: Human annotate subgoal decomposition.  
Calculate percentage of subgoals attained.

# Fine-grained Progress Rate Calculation

$f(\text{goal state}, \text{current state})$

Task: buy women fur leather jacket



Progres Rate:  
0.75

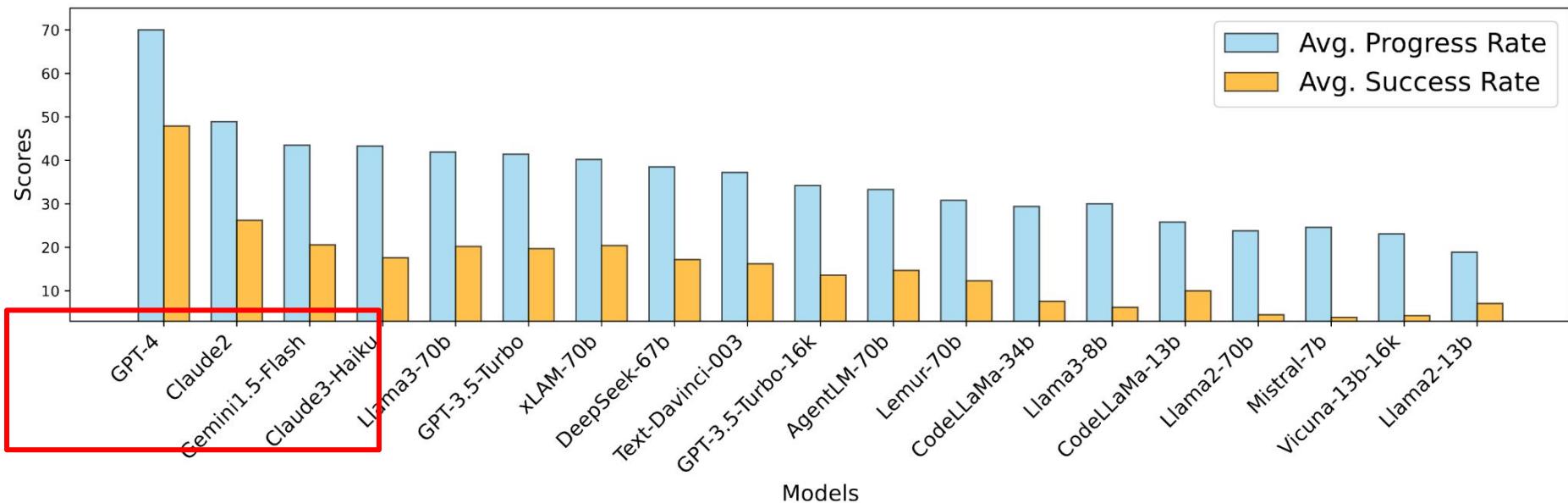
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0.6

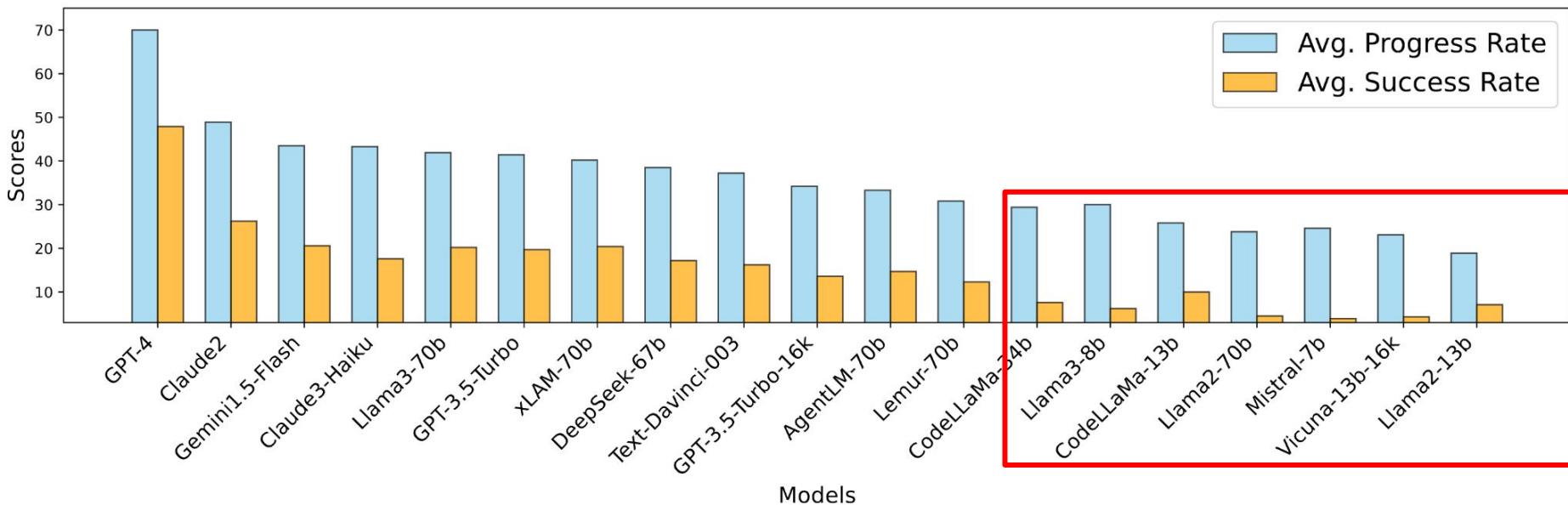
Progres-Rate-Match: Directly calculate state similarity.

# Main Results



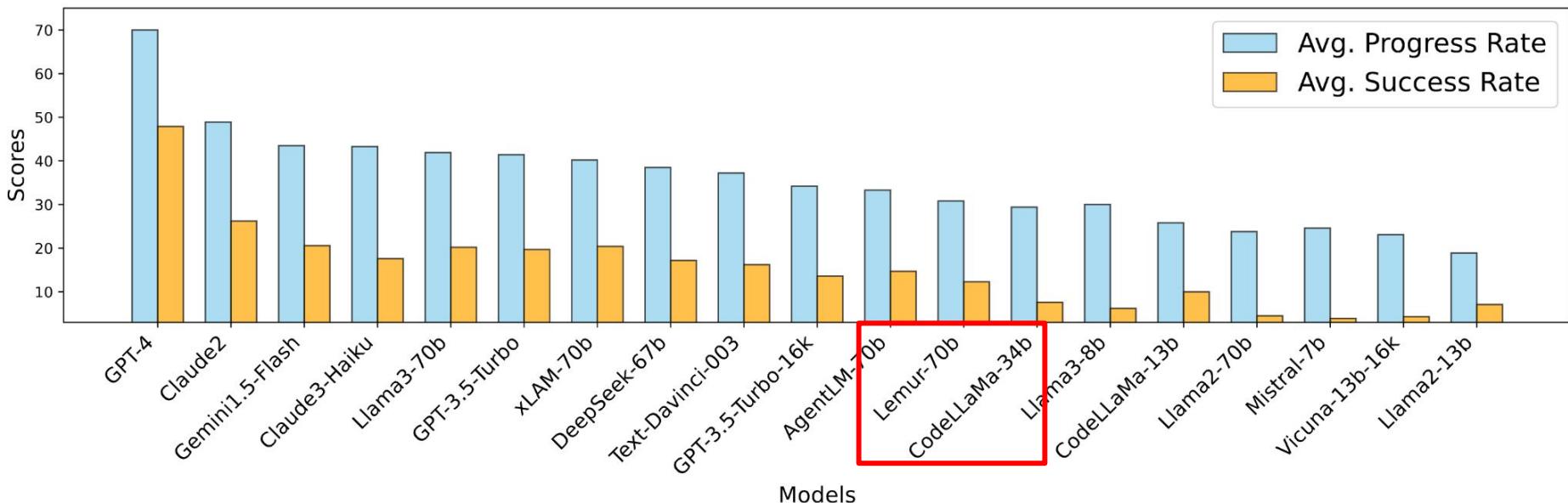
Proprietary models outperform the open-weight ones.

# Main Results



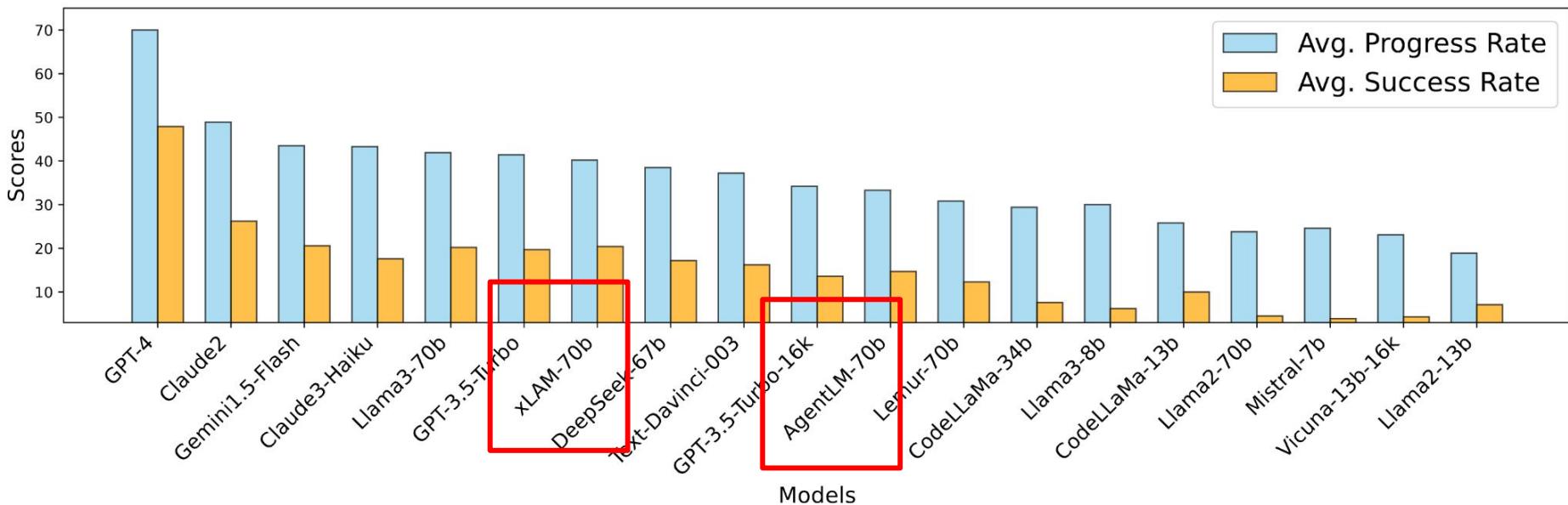
Progress Rate is more informative and discriminative than success rate.

# Main Results



Strong coding skills help agent tasks.

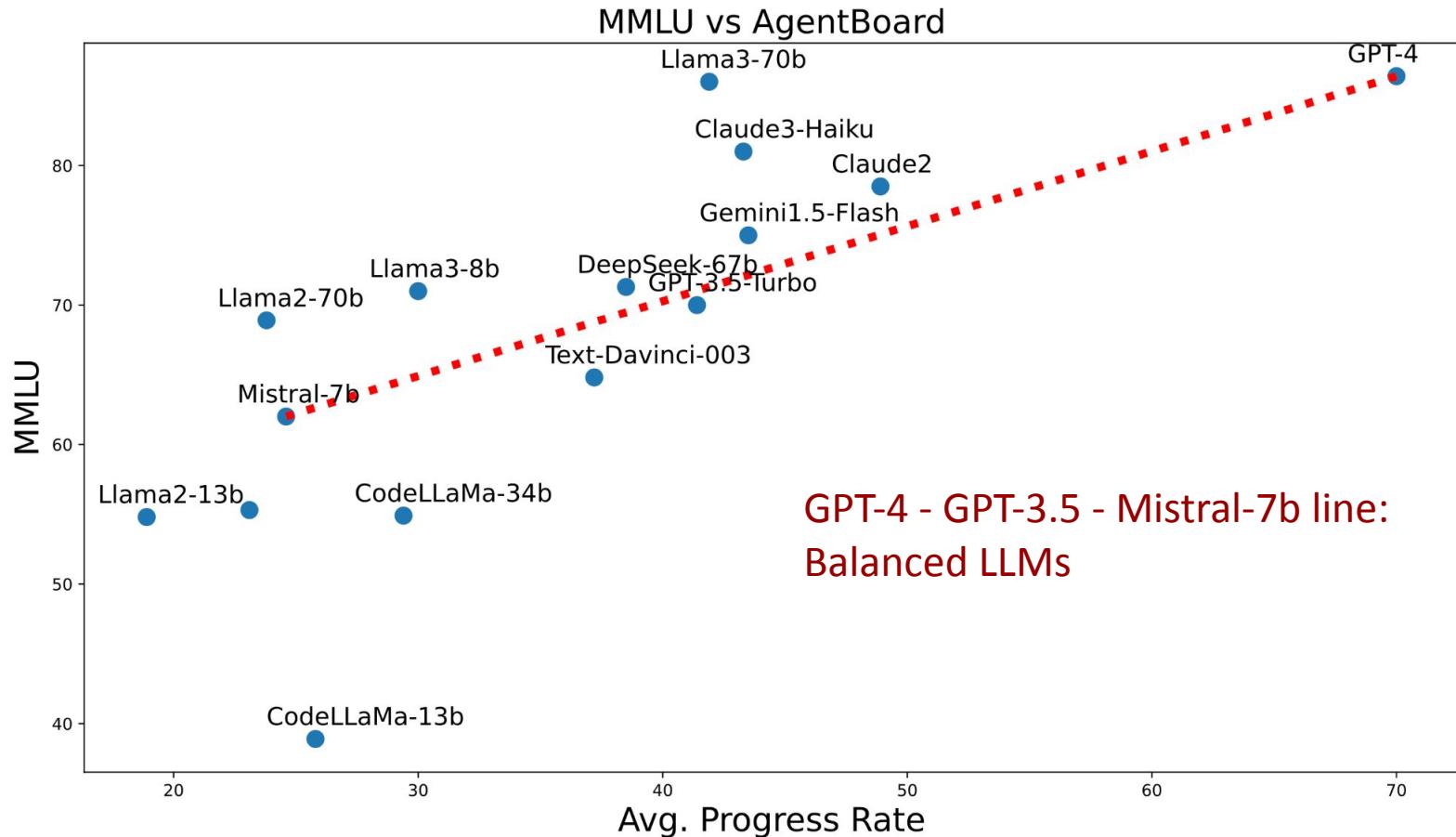
# Main Results



Agent tuning improves general agentic abilities of LLM.

# **Analytical Benchmarking: What makes a LLM better as agents?**

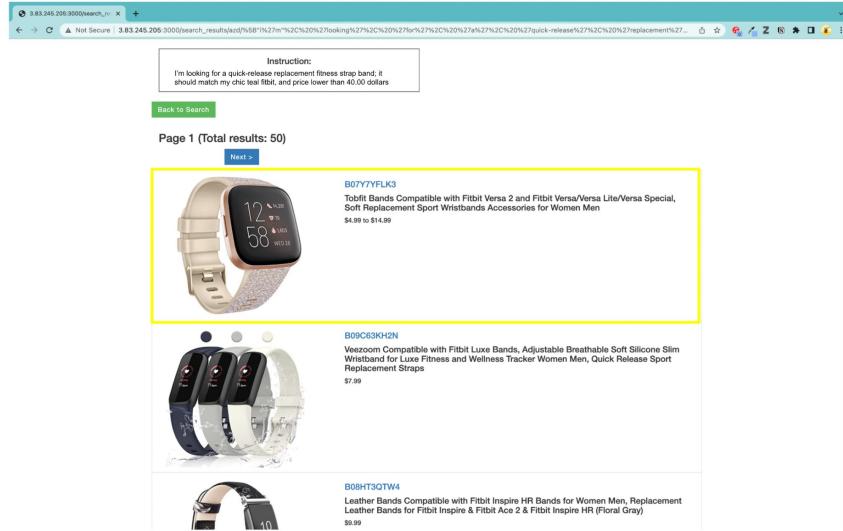
# Better LLMs may not be better agent models



# What makes a LLM a better agent ?

Understanding why some LLMs are better agents require independent evaluation of **Each Agent Ability**.

# LLM Grounding Ability



## Available Actions:

Click [back to search]

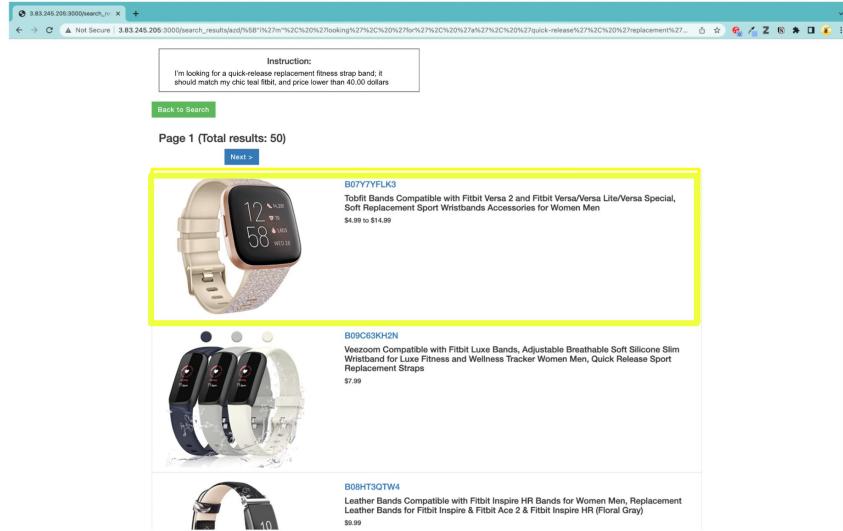
Click [Next >]

Click [Tobfit Bands...]

Click [Veezoom Compatible ...]

Click [Leather Bands ...]

# LLM Grounding Ability



Available Actions:

Click [back to search]

Click [Next >]

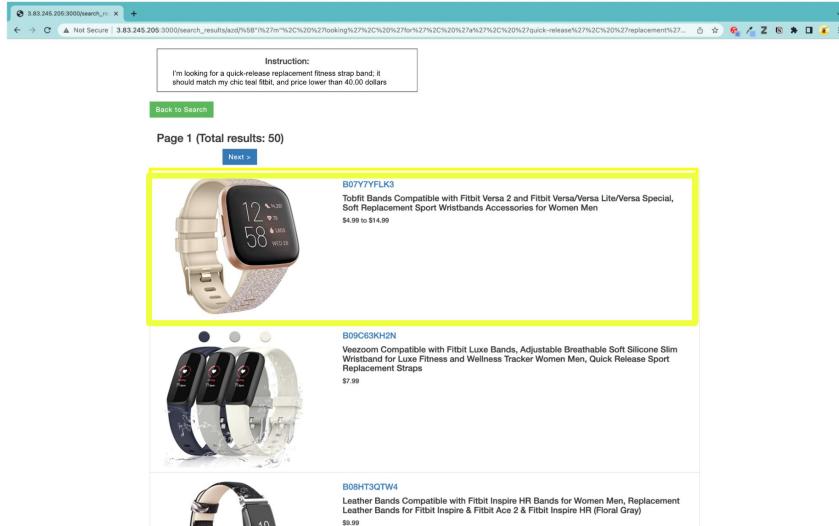
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# LLM Grounding Ability



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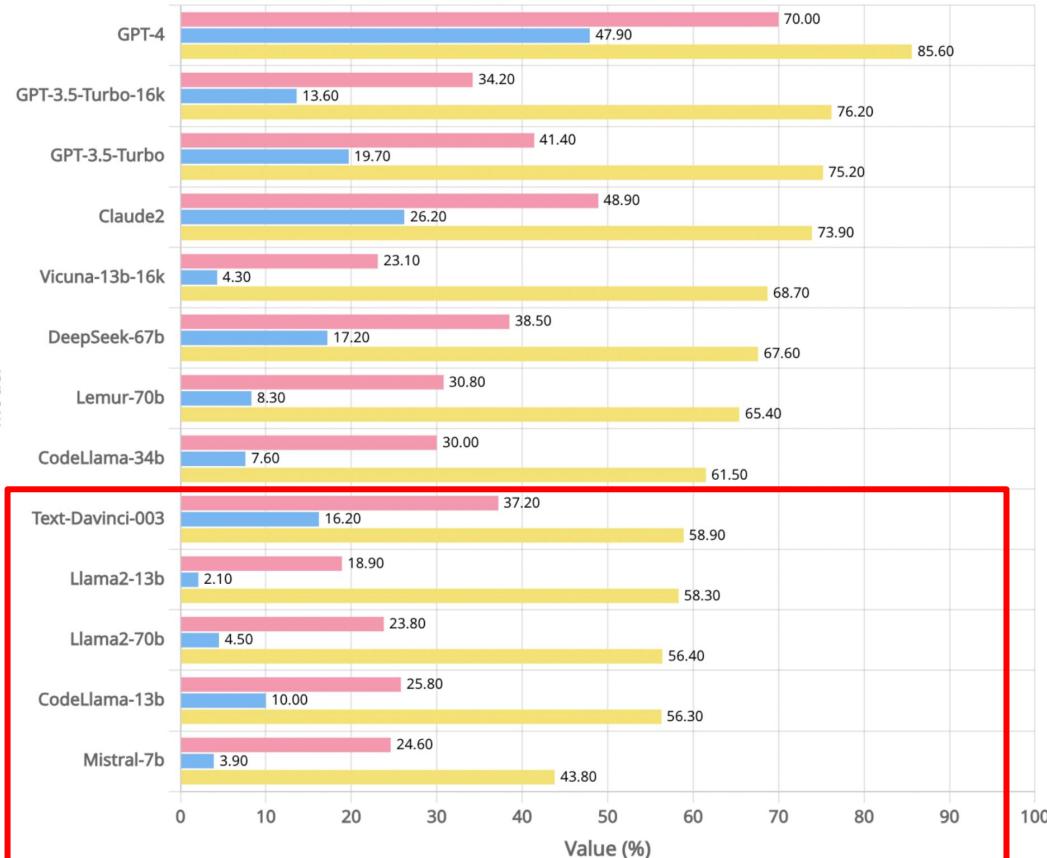
Click [Leather Bands ...]

Click [Buy Now]



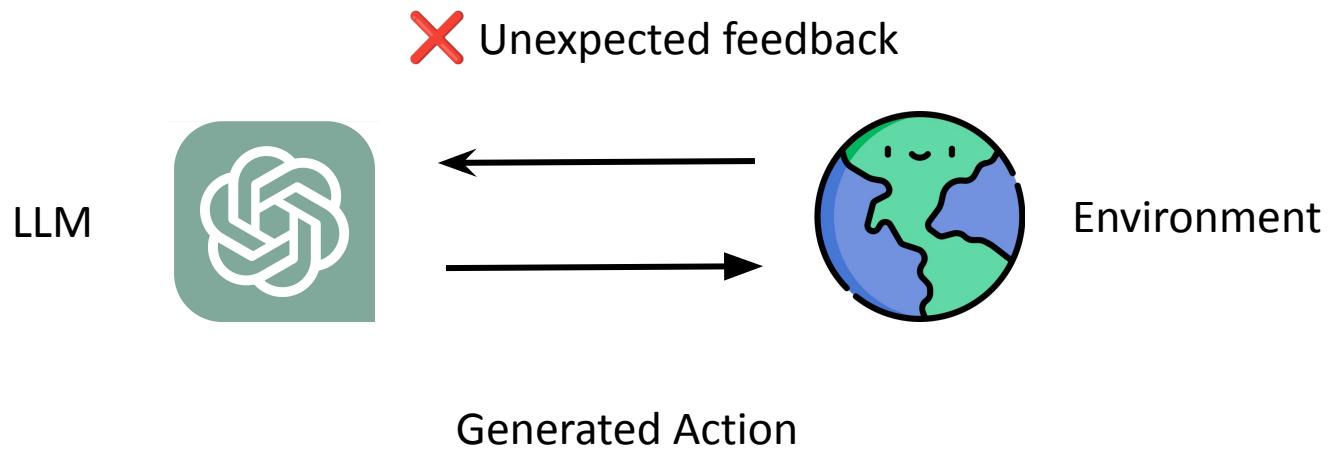
Grounding investigates whether LLM could map high-level plans to executable steps

# Can LLM Perform Grounding Well ?

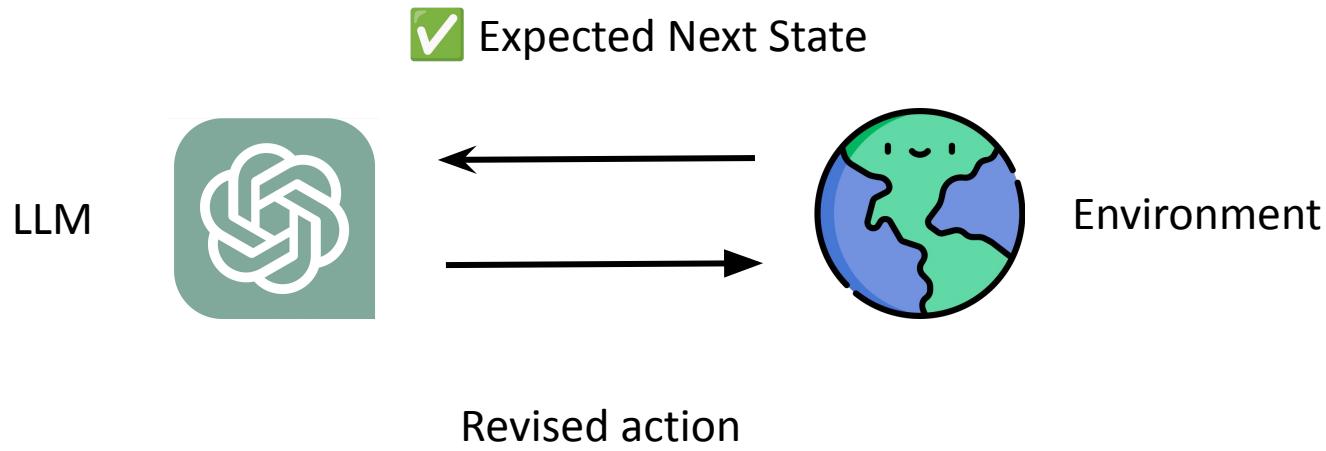


Grounding is crucial to the performance of LLM as agents.

# LLM Reflection Ability

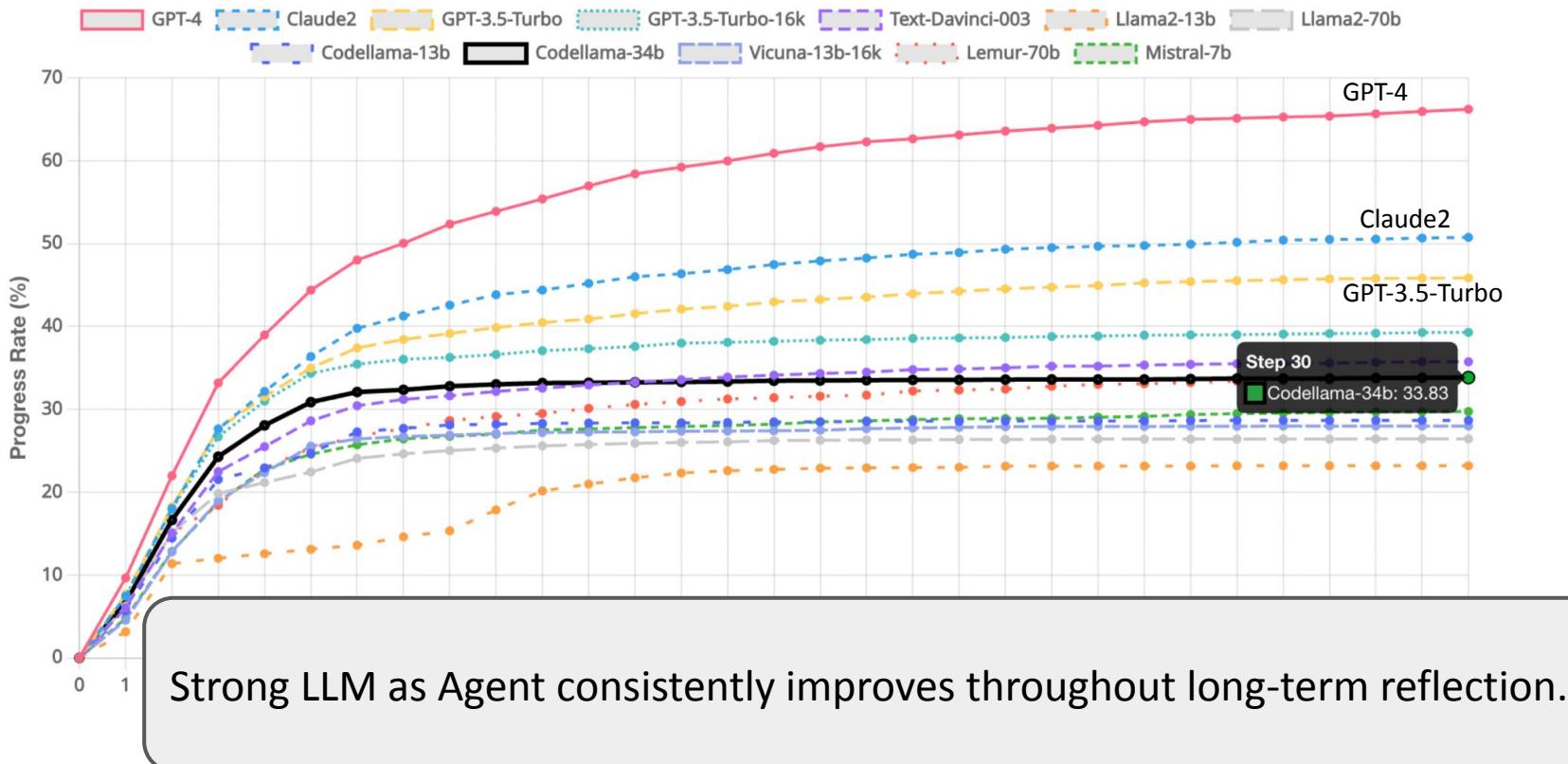


# LLM Reflection Ability

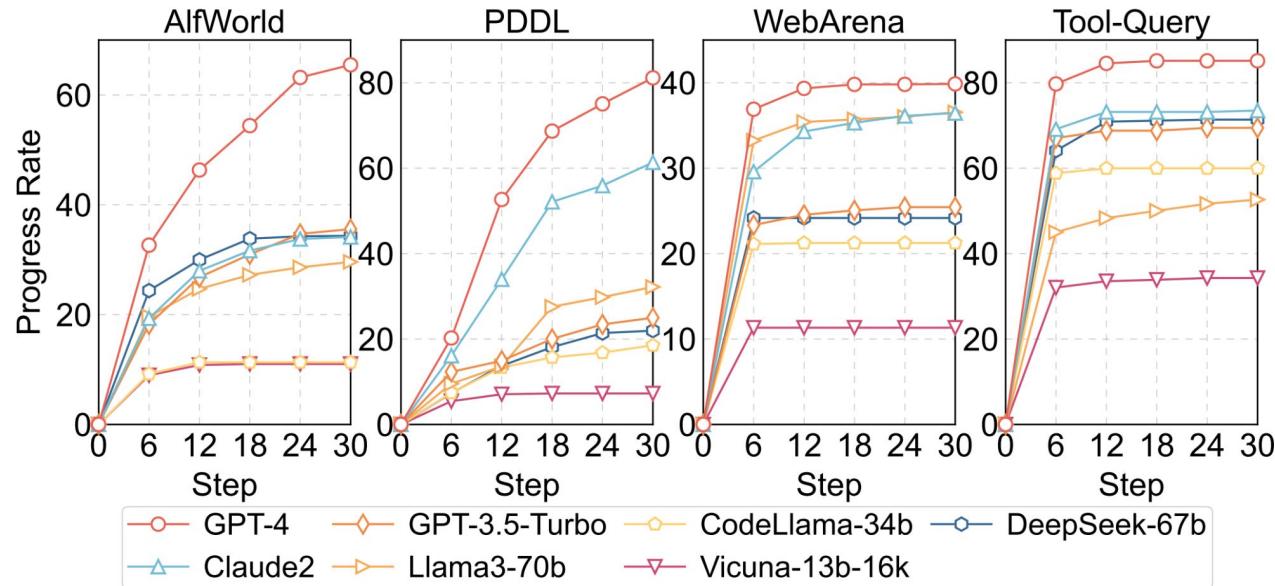


Reflection enables LLM to correct and improve its actions.

# Long-Range Interaction - Reflection Challenge



# Long-Range Interaction - Reflection Challenge



Most open-source models performance saturate after around 6 steps, while strong models like GPT-4 improves consistently through 30 steps.

# LLM Planning Ability

Task: put a clean bowl in the fridge



explore and find bowl



pickup and carry bowl



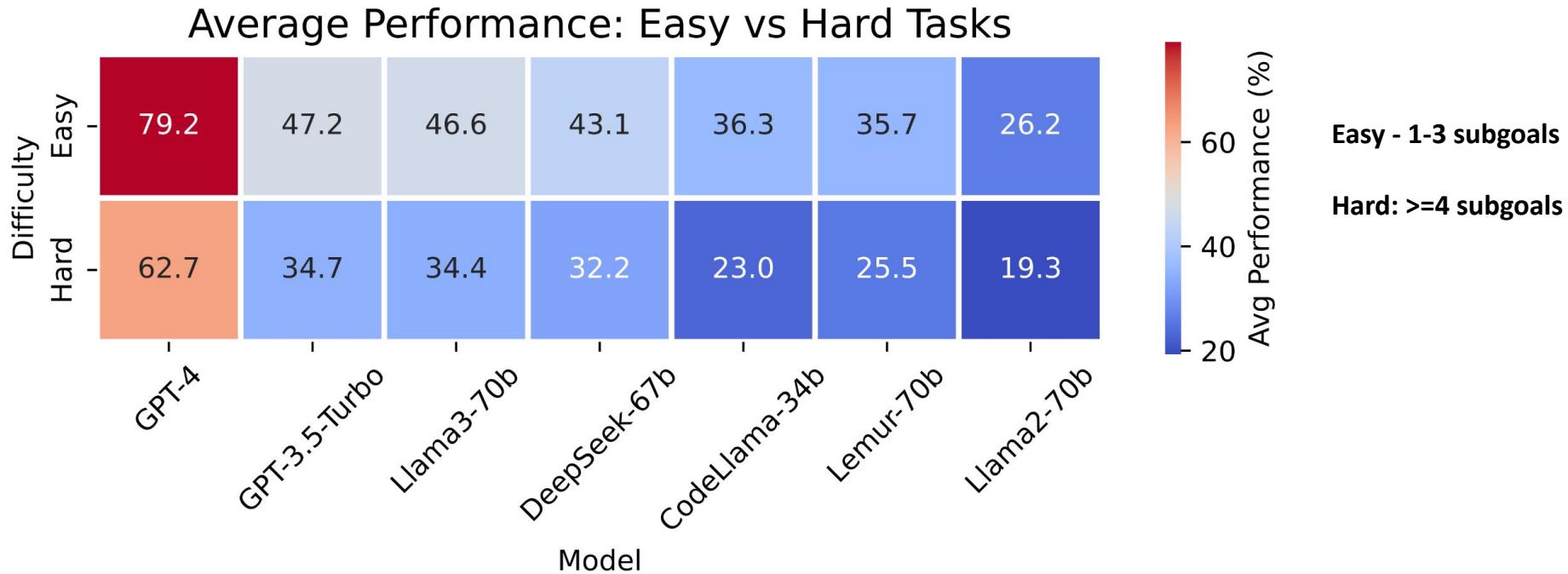
clean the bowl



place the bowl in fridge

Decompose a complex goal into several manageable subgoals.

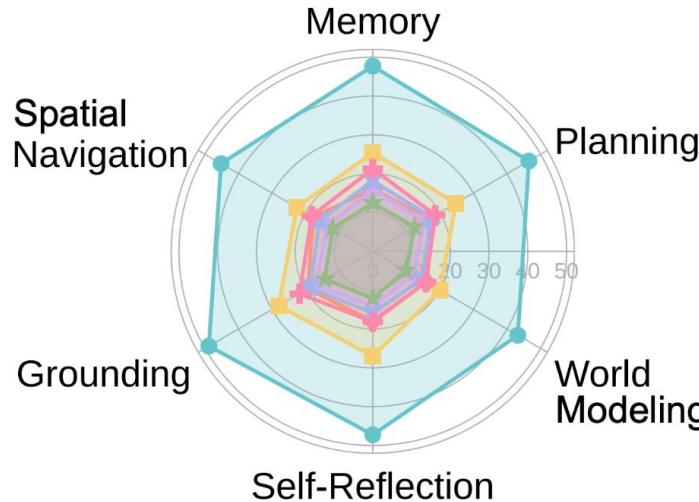
# Is LLM planning sensitive to task complexity ?



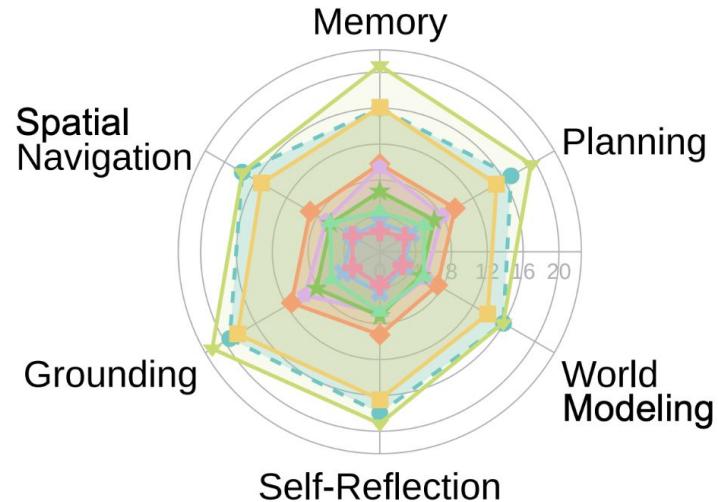
All LLMs perform badly when task complexity scales, showing deficiency in long planning.

# Agent Abilities are Multi-fold

- GPT-4
- Claude2
- GPT-3.5-Turbo
- Text-Davinci-003
- GPT-3.5-Turbo-16k
- Claude3-Haiku
- Gemini-1.5-Flash



- GPT-3.5-Turbo
- DeepSeek-67b
- CodeLlama-13b
- Lemur-70b
- CodeLlama-34b
- Vicuna-13b-16k
- Mistral-7b
- Llama3-70b
- Llama3-8b



Effective agent models exhibit balanced and robust capabilities in all areas.

# **Convenient Analysis and Visualization**

# Analytical Visualization Board

Run AgentBoard benchmarking and visualize all analysis on WandB with a single command.



runs.summary["scienceworld/predictions"]

|  | id | is_done | env.difficulty | env.goal  | env.task_name     | reward | grounding_accuracy | reward_wrt_step | trajectory   |
|--|----|---------|----------------|---|-------------------|--------|--------------------|-----------------|--|
|  | 28 |         | hard           | Your task is to find a dove egg in the outside. First, focus on the thing. Then, move it to the red box in the bathroom.        | find-living-thing | 1      | 0.3333             |                 | <b>Step 0 Goal:</b> Your task is to find a dove egg in the outside. First, focus on the thing. Then, move it to the red box in the bathroom.   |
|  | 29 | True    |                |   |                   |        |                    |                 | <b>Step 0 Observation:</b> This room is called the greenhouse. In it, you see: the agent a substance called air a bee hive. The bee hive door is closed. a flower pot 1 (containing a apple tree in the adult stage, soil) ... |
|  |    |         |                |   |                   |        |                    |                 | <b>Step 0 Action:</b> go to outside  |
|  |    |         |                |   |                   |        |                    |                 | <b>Step 0 Observation:</b> You move to the outside.  |
|  |    |         |                |   |                   |        |                    |                 | <b>Step 0 Reward:</b> 0.2  |
|  |    |         |                |   |                   |        |                    |                 | <b>Step 1 Action:</b> look around  |
|  | 29 |         | hard           | Your task is to find a butterfly egg in the outside. First, focus on the thing. Then, move it to the green box in the bathroom. | find-living-thing | 0.8    | 0.2333             |                 | <b>Step 0 Goal:</b> Your task is to find a butterfly egg in the outside. First, focus on the thing. Then, move it to the green box in the bathroom.  |
|  | 30 | False   |                |   |                   |        |                    |                 | <b>Step 0 Observation:</b> This room is called the hallway. In it, you see: the agent a substance called air a drawing. You also see: ...  |
|  |    |         |                |   |                   |        |                    |                 | <b>Step 0 Action:</b> go to outside  |
|  |    |         |                |   |                   |        |                    |                 | <b>Step 0 Observation:</b> No known action matches that input.   |
|  |    |         |                |   |                   |        |                    |                 | <b>Step 0 Reward:</b> 0.0  |
|  |    |         |                |   |                   |        |                    |                 | <b>Step 1 Action:</b> open door to outside   |
|  |    |         |                |   |                   |        |                    |                 | <b>Step 1 Observation:</b> No known action matches that input.   |

## Details of Each Problem Trajectory



## Takeaways: Fine-grained Evaluation + Analysis

- LLM Agents are complex systems that involve multiple abilities. Improving each ability is necessary for building good LLMs for agents.
- We need to perform analytical benchmarking of its various abilities to interpret whether the agent is good or why it works badly.
- Evaluating the process is as important as evaluating the final results !



Homepage



Code and Data