

$$1. \begin{bmatrix} 1 \\ 2 \end{bmatrix} + \begin{bmatrix} 3 \\ 2 \end{bmatrix} = \begin{bmatrix} 4 \\ 4 \end{bmatrix}$$

$$\begin{bmatrix} 1 \\ 2 \\ 3 \end{bmatrix} + \begin{bmatrix} 3 \\ 2 \\ 1 \end{bmatrix} + \begin{bmatrix} 4 \\ 2 \\ 0 \end{bmatrix} = \begin{bmatrix} 8 \\ 6 \\ 4 \end{bmatrix}$$

$$\begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix} \begin{bmatrix} 1 \\ 2 \end{bmatrix} = \begin{bmatrix} 2 \\ 1 \end{bmatrix}$$

$$2. \begin{bmatrix} 1 & 2 & 3 \\ -1 & 4 & 2 \\ 0 & 6 & 5 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & 2 & 3 \\ 0 & 6 & 5 \\ 0 & 6 & 5 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & 2 & 3 \\ 0 & 6 & 5 \\ 0 & 0 & 0 \end{bmatrix}$$

Col space :  $\text{span} \{ [1, -1, 0]^T, [2, 4, 6]^T \}$

Null Space :  $\text{span} \{ [-4/3, -5/6, 1]^T \}$

b) No :  $AB \neq BA$  for 2 matrices A, B all the time  
 $\hookrightarrow$  matrix multiplication is not commutative

c) No : counterexample :

$$\begin{bmatrix} 1 & 2 \\ 1 & 2 \end{bmatrix} \begin{bmatrix} 2 & 2 \\ -1 & -1 \end{bmatrix} = \begin{bmatrix} 0 & 0 \\ 0 & 0 \end{bmatrix}$$

3. a)  $A = \begin{bmatrix} 1 & 2 & 0 \\ -1 & 4 & 6 \\ 1 & 2 & 0 \end{bmatrix}$  To minimize  $\|Ax - b\|$   
 we have:  $Ax = b$

$$A^T A x = A^T b$$

$$x = (A^T A)^{-1} A^T b$$

\*  $A^T A$  is invertible

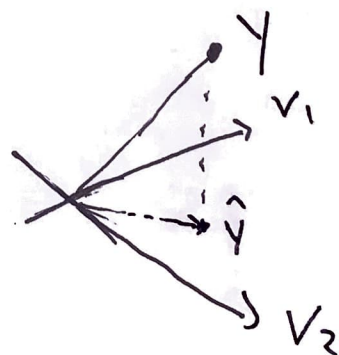
$$b = \begin{bmatrix} 3 \\ -1 \\ 5 \end{bmatrix}$$

recall  $A^{-1} = \frac{1}{|A|}$

$$\begin{bmatrix} \begin{vmatrix} a_{22} & a_{23} \\ a_{32} & a_{33} \end{vmatrix} & - & . \\ \begin{vmatrix} a_{23} & a_{21} \\ a_{33} & a_{31} \end{vmatrix} & - & . \\ \begin{vmatrix} a_{21} & a_{22} \\ a_{31} & a_{32} \end{vmatrix} & - & . \end{bmatrix}$$

$$\vec{x} = \begin{bmatrix} 6 \\ -1 \\ 3/2 \end{bmatrix}$$

b.)  $\begin{bmatrix} 1 & 2 & 0 \\ -1 & 4 & 6 \\ 1 & 2 & 0 \end{bmatrix} \begin{bmatrix} 6 \\ -1 \\ 3/2 \end{bmatrix} = \begin{bmatrix} 4 \\ -1 \\ 4 \end{bmatrix}$



c) distance = actual - proj

$$= \begin{bmatrix} 3 \\ -1 \\ 5 \end{bmatrix} - \begin{bmatrix} 4 \\ -1 \\ 4 \end{bmatrix} = \begin{bmatrix} -1 \\ 0 \\ 1 \end{bmatrix}$$

$$\begin{aligned}
 4) \quad L(w) &= \|Xw - y\|_2^2 + \lambda \|w\|_2^2 \\
 &= (Xw - y)^T (Xw - y) + \lambda w^T w \\
 \frac{\partial L}{\partial w} &= (w^T X^T X w - w^T X^T y - y^T X w + y^T y) + \lambda w^T w \\
 &= (w^T X^T X w - 2 w^T X^T y + y^T y) + \lambda w^T w
 \end{aligned}$$

$$\frac{\partial L}{\partial w} = 2X^T X w - 2X^T y + 2\lambda w = 0$$

↳ recall derivatives:  $x^T B x \rightarrow 2Bx$

$$* \quad x^T x \rightarrow 2x$$

$$* \quad x^T b \rightarrow b$$

$$w = (X^T X + \lambda I)^{-1} X^T y$$

$$w = (X^T X + \lambda I)^{-1} X^T y$$

The hyperparameter  $\lambda$  controls regularization:  
 a higher  $\lambda$  means higher penalty & less extreme / smaller model weights (this helps in cases of overfitting). The smaller  $\lambda$  is, the closer we get to normal least-squares regression (aka  $\lambda = 0$ ).