

Lecture 2 : Formal definitions

Def 1 (Block code): An (n, M) block code is a subset $\mathcal{L} \subseteq \mathcal{X}^n$ with $|\mathcal{L}| = M$.

\downarrow
Blocklength

We hence have rate $R = \frac{\log M}{n}$.

Eg: (i) Rate of repetition code $\mathcal{L} = \{000, 111\}$ is $\frac{1}{3}$ and \mathcal{L} is a $(3, 2)$ block code.

(ii) Rate of single parity-check code $\mathcal{L} \subseteq \{0, 1\}^n$ is ? and it is a $(-, -)$ block code.

(Recall): From basic communication theory, for a given noisy channel $W = (P(y|\underline{c}) : \underline{c} \in \mathcal{L}, y \in \mathcal{Y})$, the decoder that minimizes the error probability is the "maximum a-posteriori probability" (MAP) decoder:

$$\hat{\underline{c}} = \arg \max_{\underline{c} \in \mathcal{L}} P(\underline{c} | y).$$

HW0: Provide / read up a proof of this fact.

Now, suppose that $\underline{c} \sim \text{Unif}(\mathcal{L})$. Then,

$$\hat{\underline{c}} = \underset{\underline{c} \in \mathcal{L}}{\operatorname{argmax}} \frac{P(y|\underline{c})P(\underline{c})}{P(y)}$$

$$= \underset{\underline{c} \in \mathcal{L}}{\operatorname{argmax}} \frac{1}{M P(y)} \cdot P(y|\underline{c}) = \underset{\underline{c} \in \mathcal{L}}{\operatorname{argmax}} P(y|\underline{c})$$

constant!

\triangleq ML decoder
(“maximum likelihood”).

What is ML decoding for the BSC?

For a fixed $\underline{c} \in \mathcal{L}$ and any $\underline{y} \in \{0,1\}^n$,

$$P(y|\underline{c}) = p^{d(\underline{c}, \underline{y})} (1-p)^{n-d(\underline{c}, \underline{y})},$$

where $d(\underline{c}, \underline{y}) = d(\underline{y}, \underline{c}) \triangleq d$ is the “Hamming distance” b/w \underline{c} and \underline{y} ,

i.e., the # positions where \underline{c} & \underline{y} differ.

Hence, $ML(\underline{y}) = \underset{\underline{c} \in \mathcal{L}}{\operatorname{argmax}} P(\underline{y}|\underline{c}) = \underset{\underline{c} \in \mathcal{L}}{\operatorname{argmin}} d(\underline{c}, \underline{y})$, when $p < \frac{1}{2}$.

Lemma 1 : $d(\cdot, \cdot)$ is a metric over \mathcal{X}^n .

Pf: HW.

Def 2 (Minimum distance) : The minimum distance of a block code \mathcal{L}

$$d(\mathcal{L}) = d_{\min}(\mathcal{L}) = \min_{\substack{\underline{c}_1, \underline{c}_2 \in \mathcal{L}, \\ \underline{c}_1 \neq \underline{c}_2}} d(\underline{c}_1, \underline{c}_2).$$

An (n, M) block code with min. dist. d is written as an (n, M, d) block code.

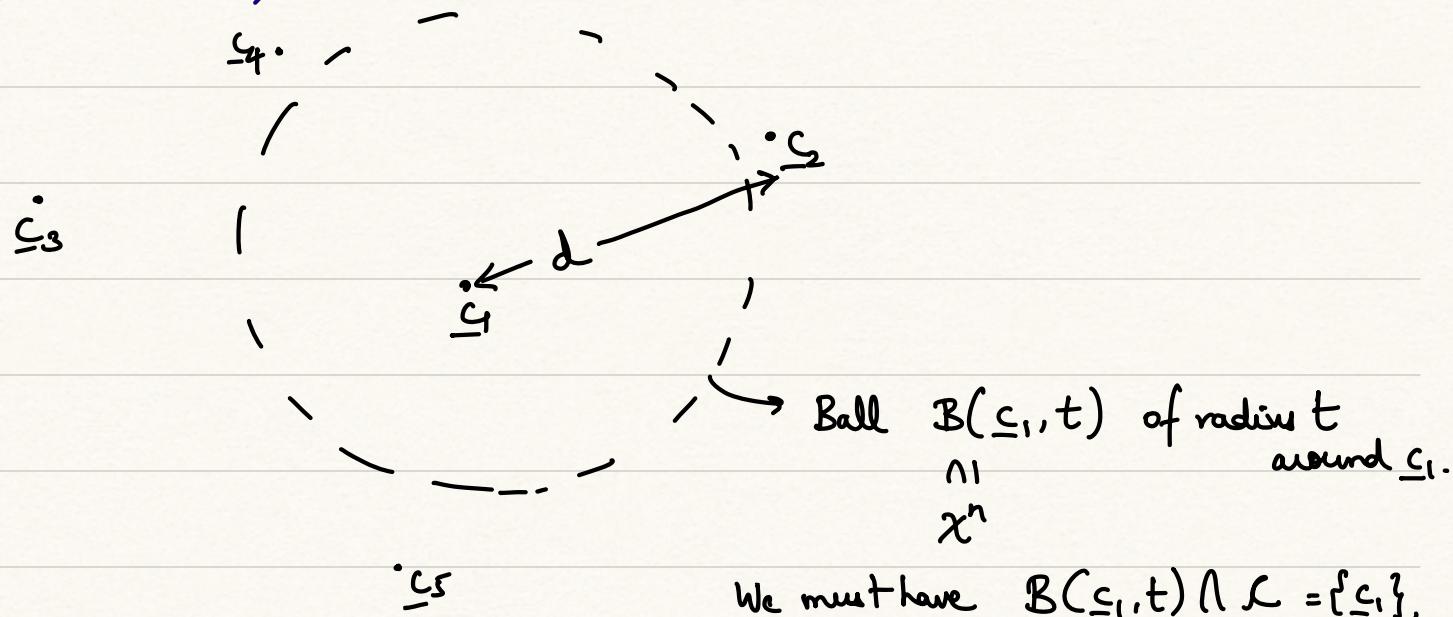
Error detection/correction tied to distance

Thm 1: For an (n, M, d) block code \mathcal{L} , \exists a decoder that detects up to $d-1$ bit-flip errors.

This decoder obeys

$$D(y) = \begin{cases} \underline{c}, & \text{if } y \in \mathcal{L}, \\ \text{Error, o.w.} & \end{cases}$$

Pf: (Picture)

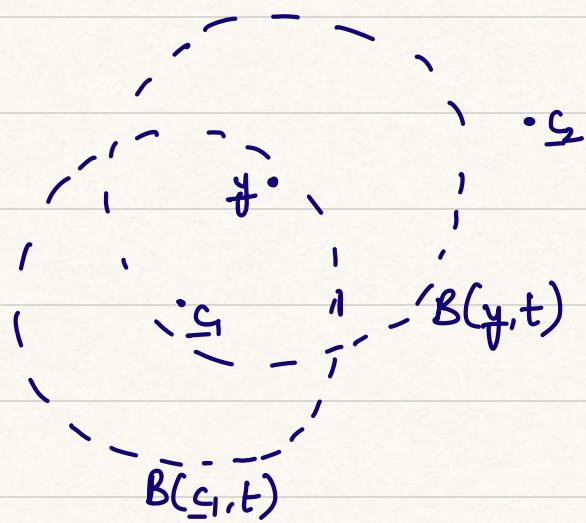


Thm 2: For an (n, M, d) block code \mathcal{L} , \exists a decoder that
corrects $t \leq \left\lfloor \frac{d-1}{2} \right\rfloor$ bit-flip errors.

This decoder is the **minimum distance decoder**

$$d(y) = \underline{c}, \text{ if } B(y, t) \cap \mathcal{L} = \{\underline{c}\}.$$

Pf: (Picture)



We cannot have $\underline{c}_1 \neq \underline{c}_2$ s.t. $\underline{c}_1 \in B(y, t)$, as then

$$\begin{aligned} d(c_1, c_2) &\leq d(c_1, y) + d(c_2, y) \\ &\leq 2t \leq 2 \cdot \left\lfloor \frac{d-1}{2} \right\rfloor < d, \end{aligned}$$

a contradiction. \square

An aside: Erasures are channel noise that behave as follows:

$$\underline{c} = (c_1, c_2, \dots, c_{n-1}, c_n) \xrightarrow[\text{channel}]{\text{Erasures}} \underline{y} = (c_1, ?, c_3, \dots, c_{n-1}, ?)$$

- Selected codeword symbols are replaced with a '?'.

Thm : For an (n, M, d) block code \mathcal{L} , there is a decoder that
corrects up to $d-1$ errors.

Pf : HW. (state a decoder and prove its ~~maxim~~-correction property).