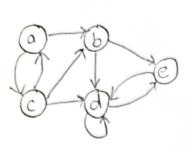
Q1·)



- a) AGF (a -> xd) = AGF (xd V -a)
- (e) => For every path, F(xd v -a) holds globally in the future
  - ⇒ For every path (xd v -a) holds sometime globally in the future

Cone I) When node = a  $AGF(xd) \text{ holds because } d \text{ is reachable from a to e } \\ viz b \rightarrow d, c \rightarrow d, d \rightarrow d, e \rightarrow d, a \rightarrow b \rightarrow d$ 

(are II) When node ≠ a

Xd V ¬a ,irrespective of xd , this is always true

∴ AGF(a→ Xd) is correct

b) EG  $(b \rightarrow AFd) = EG (AFd \vee \neg b)$ In simpler terms, this means there exists a path globally where  $(AFd \vee \neg b)$  holds.

(are I.) When node = b , then EGr (AFd)

From b, there exists a path where AFd holds globally in

future.

This is true because at some point of time d will

eventually hold as from b, you compulsarily will

have to go through d for all possible paths.

b. b re

Alternatively, we can think this to be EG(AFd) > There exist path for all nodes where there is cut to d

cut de .: EG(b - AFd) holds.

c) EFAG!c
In simple terms, there exists a poth in future where for every path globally there's no c

a 
c 
d 
d 
every paths without c

in future

: . EFAGIC holds

Q2-a.] A simple method instead of keeping a track on all paths is to count number of bubbles, since all paths lead to one

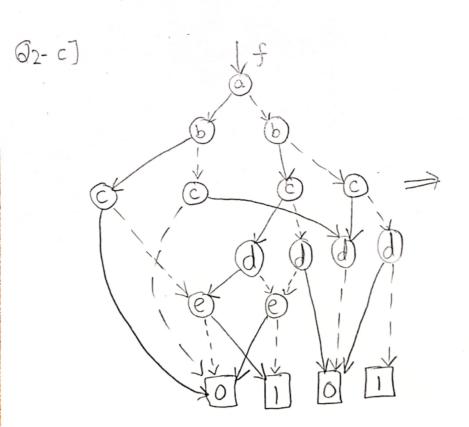
i) a,b,c,d,e (0,0,0,0,0) = 1 (0,0,0,0,0) = 1

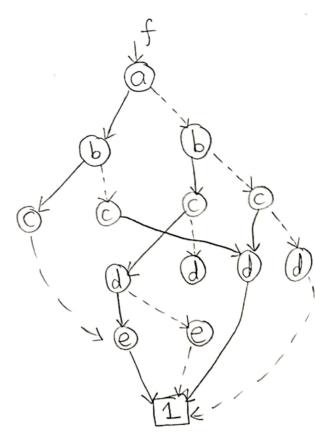
(ii) a, b, c, d, e $(1,0,1,0,1) \Rightarrow \# \text{ bubbles} = 3$  : f(1,0,1,0,1) = 0

(iii) a,b,c,d,e = # bubbles = 3 : f(0,1,0,1,0) = 0 (0,1,0,1,0)

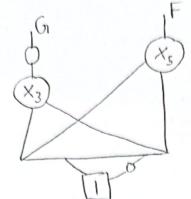
Q2-b] dist of {a,b,c,de} for f=0
0001X,0010X,01001,0101X,01101,01110,100XX,
1010X,110X0,111XX

Total # = 21





Q3.7 G



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-> Rule 1 is fine

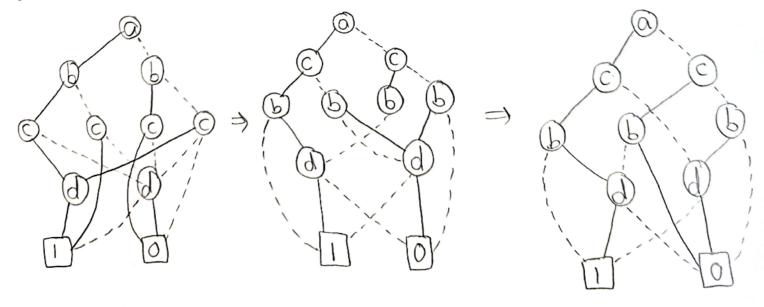
ITE (F, 0, G), since  $X_5 > X_3$ ITE  $(F, 0, G) \rightarrow \text{ITE}(\overline{G}, 0, \overline{F})$ 

-) Rule 3: If contains complement edge parameters:

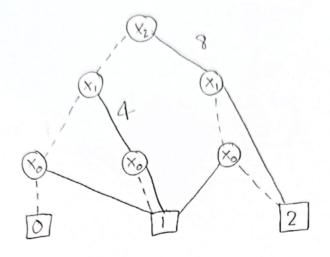
The first & second parameters can't be complement edges.

 $: ITE(\bar{G}, 0, \bar{F}) \longrightarrow ITE(\bar{G}, 1, \bar{F})$ 

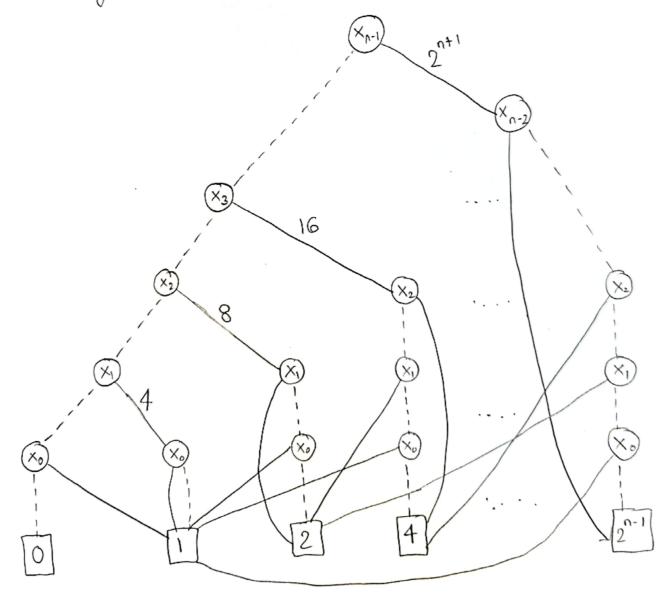
Q4·]



Q5.] a) For 3 bit vector  $x_2 x_1 x_0 (x)$   $x^2 = (4x_2 + 2x_1 + x_0) (4x_2 + 2x_1 + x_0)$   $x^2 = 16x_2^2 + 16x_1x_2 + 8x_0x_2 + 4x_0x_1 + 4x_1^2 + x_0^2$ & the corresponding \*BMD is



For a general n bit case



of s) b) Since we are interested in finding the square root (integral part), we need to think of a way to convert the \*BMD into a form which describes the truth table of the desired function.

MTBDD best serves this purpose as it models the function according to the truth table with word values.

So the algorithm: Y-) input value

- 1.) From the \*BMD of X2 in part 5(a), convert it to 11
- 2.) Convert the BMD to MTBDD
- 3.) Once we get the MTBDD, it's leaf nodes will. consist of square values.
- 4) Check Y for values on leaves.

  for in range (number of leaves):
- if (y > leaf (i))
  go to next leaf // i++

if (Y <= leaf(i))
go back to previous leaf
return square root of this leaf value

We can also use efficient searching algorithms on trees like BST to reduce the computational complexity