

Calibration results

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Camera-system parameters:

cam0 (/color):

type: <class 'aslam_cv.libaslam_cv_python.DistortedPinholeCameraGeometry'>

distortion: [-0.04894362 -0.0034989 -0.01261869 -0.00236945] +- [0.00916659 0.00270432 0.00141467 0.00088217]

projection: [240.13081429 239.9745491 307.9370975 207.34305884] +- [21.56968686 21.27430344 2.39248659 2.67214471]

reprojection error: [-0.000037, -0.000006] +- [1.812805, 1.798987]

Target configuration

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Type: aprilgrid

Tags:

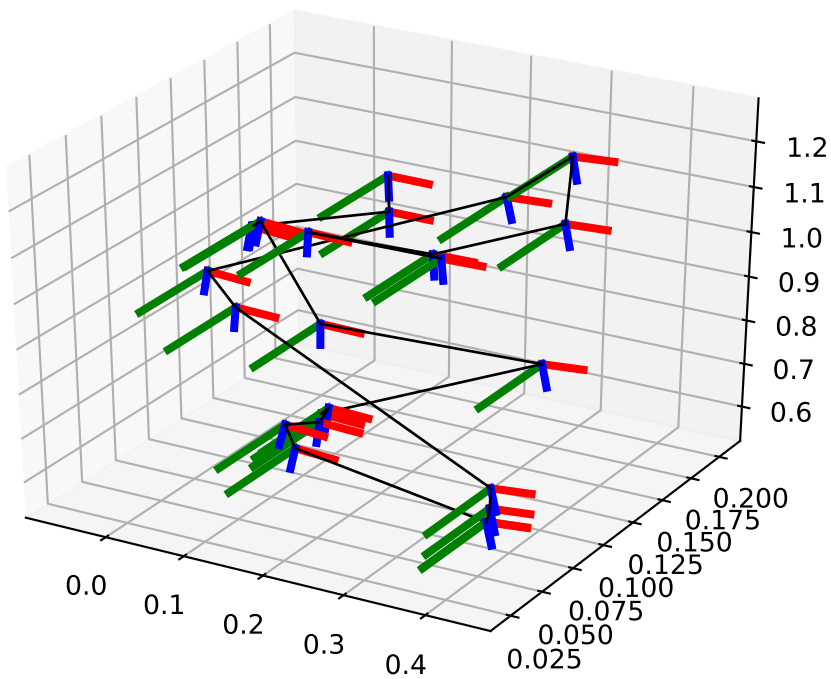
Rows: 6

Cols: 6

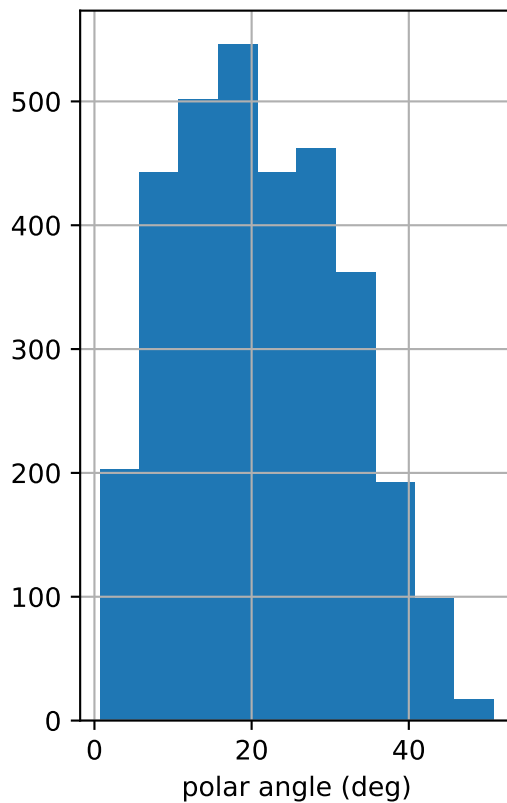
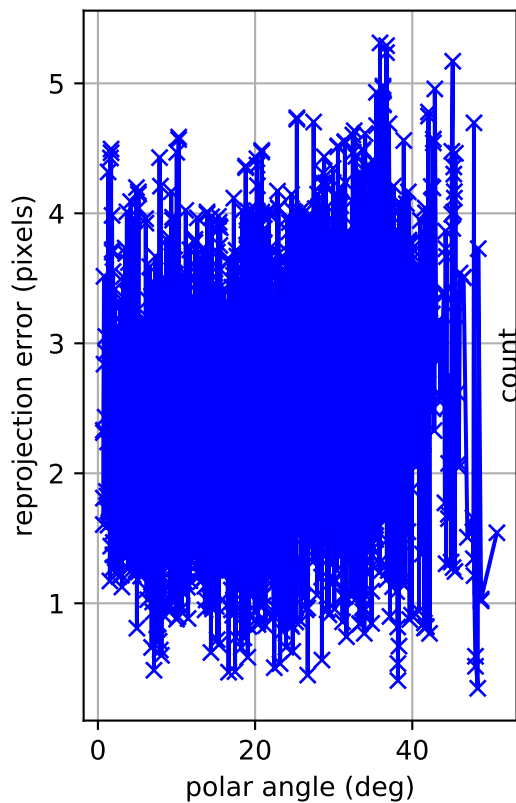
Size: 0.08 [m]

Spacing 0.00832 [m]

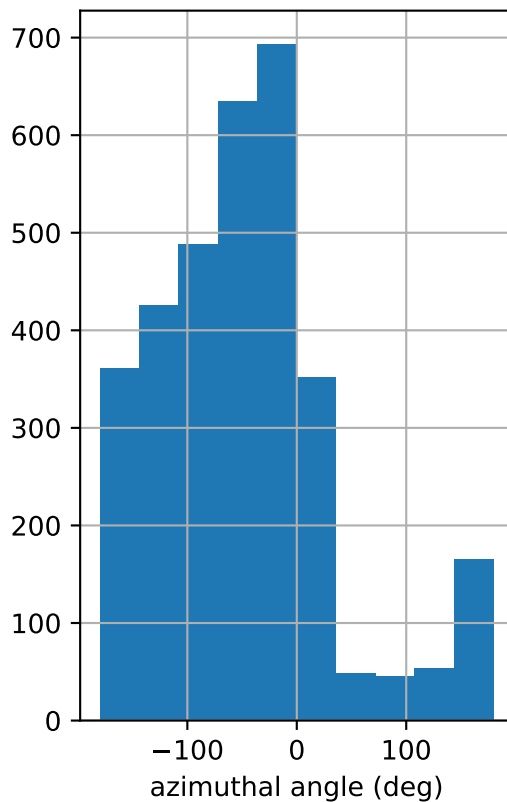
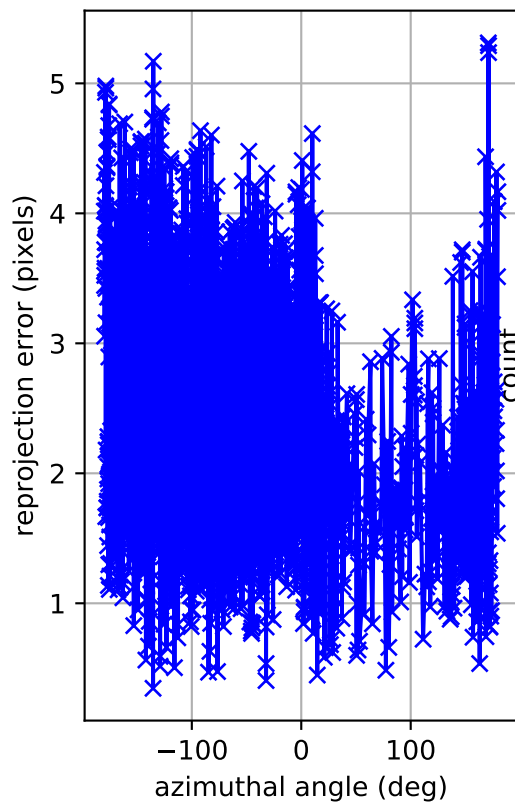
cam0: estimated poses



cam0: polar error



cam0: azimuthal error



cam0: reprojection errors

