Calibration results
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Camera-system parameters:
cam0 (/color):
type: <class 'aslam_cv.libaslam_cv_python.DistortedPinholeCameraGeometry'>
distortion: [ 0.1037592  -0.21034509 -0.00123532 -0.00129998] +- [0.00672523 0.01431332 0.00101919 0.00105175]
projection: [899.28054102 899.33120271 631.94678609 355.47058304] +- [5.08946586 5.02329142 3.27796929 3.07296251]
reprojection error: [0.000000, 0.000000] +- [0.129755, 0.098199]


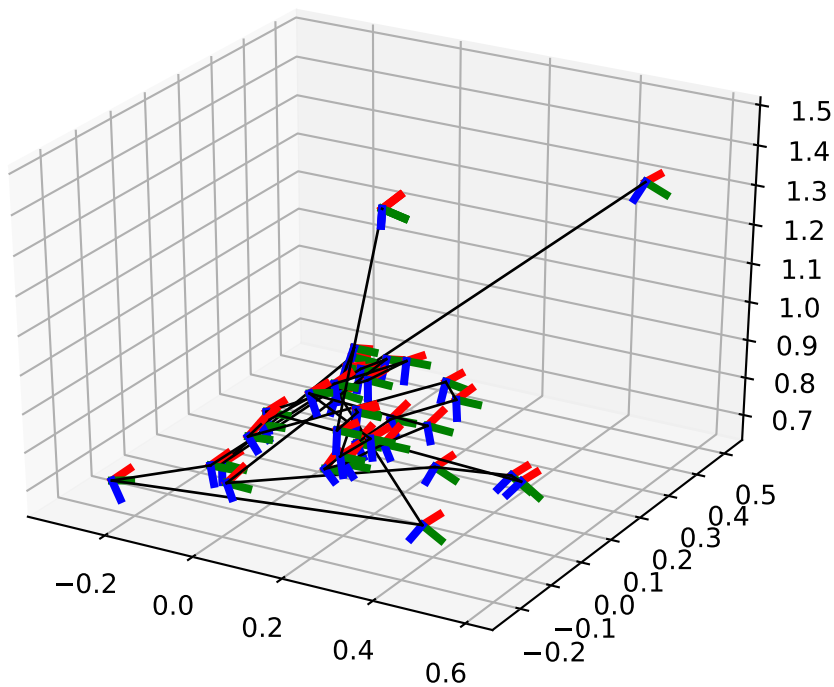Target configuration
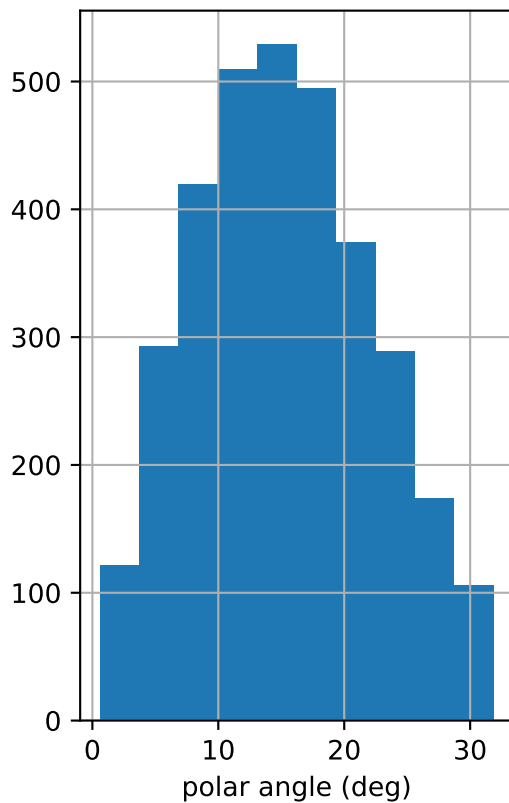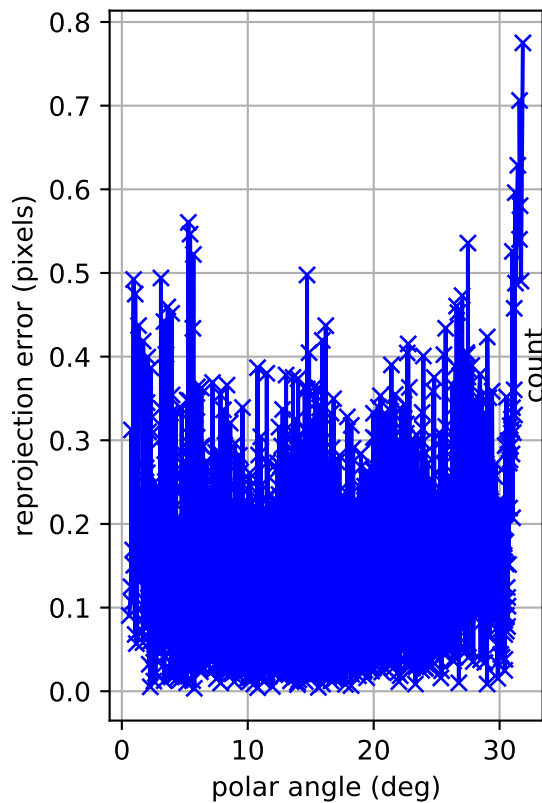====================

Type: checkerboard
Rows
Count: 8
Distance: 0.03 [m]
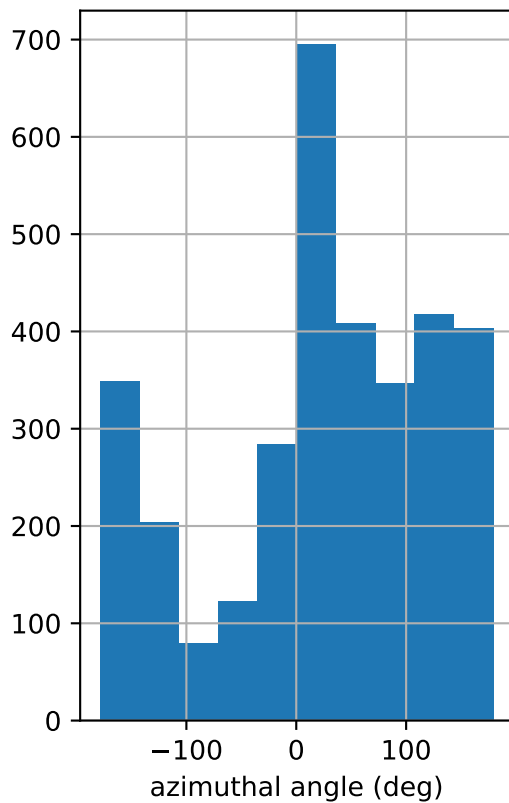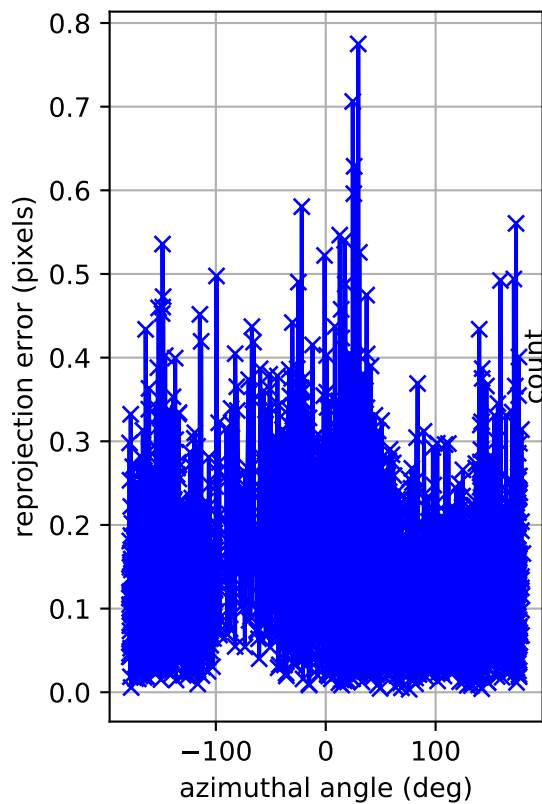Cols
Count: 11
Distance: 0.03 [m]
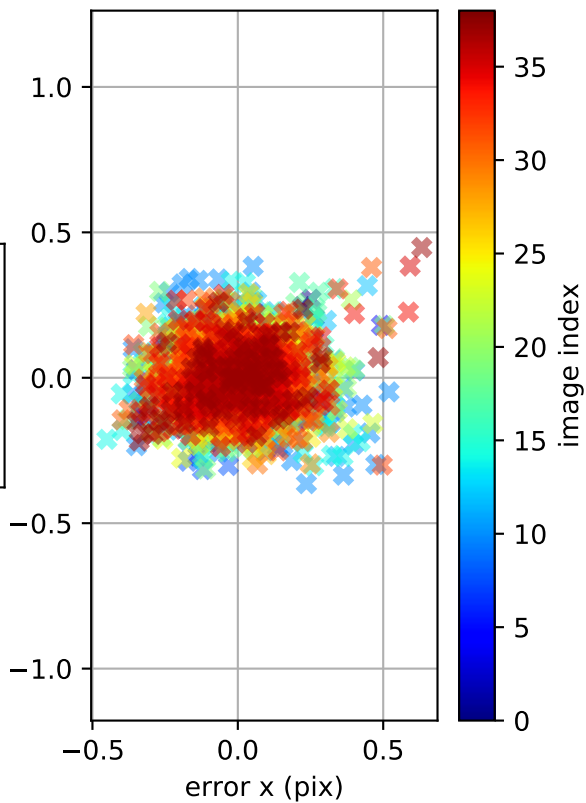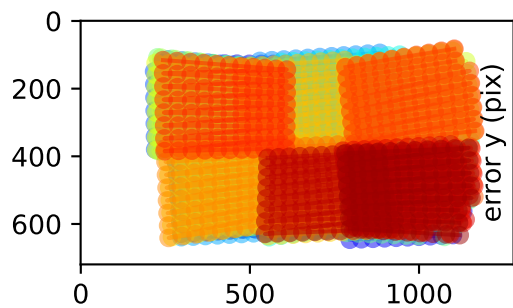
cam0: estimated poses

cam0: polar error

cam0: azimuthal error

cam0: reprojection errors

Location of removed outlier corners

cam0