

## Calibration results

=====

### Camera-system parameters:

cam0 (/color):

type: <class 'aslam\_cv.libaslam\_cv\_python.DistortedPinholeCameraGeometry'>

distortion: [-0.078159 -0.00412511 -0.01086701 -0.00326966] +- [ 0.00521866 0.00471684 0.00101371 0.00082097]

projection: [ 343.02356912 341.27120373 307.52406916 224.31089037] +- [ 5.90745681 5.8008309 2.85298298 2.61397066]

reprojection error: [-0.000005, 0.000001] +- [1.794865, 1.748695]

## Target configuration

=====

Type: aprilgrid

Tags:

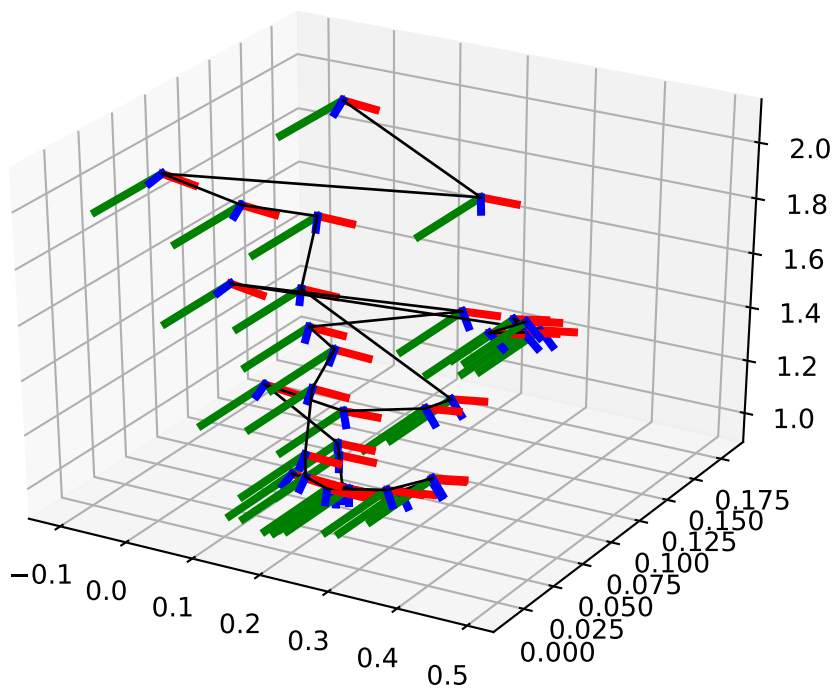
Rows: 6

Cols: 6

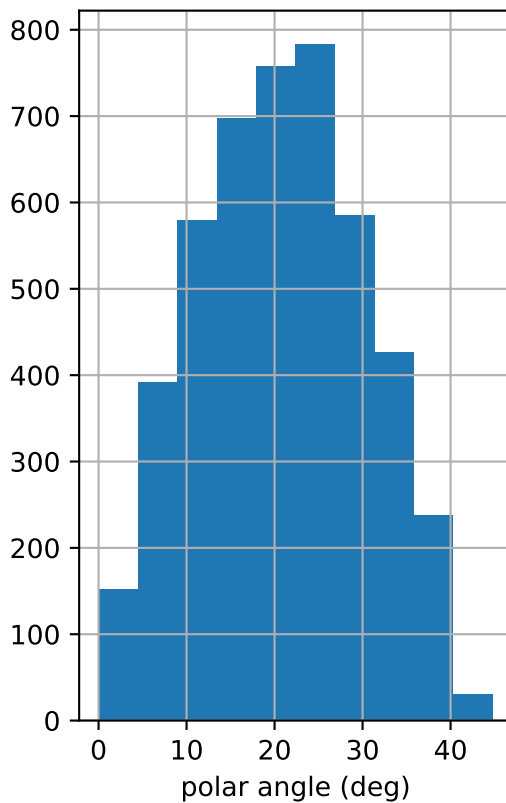
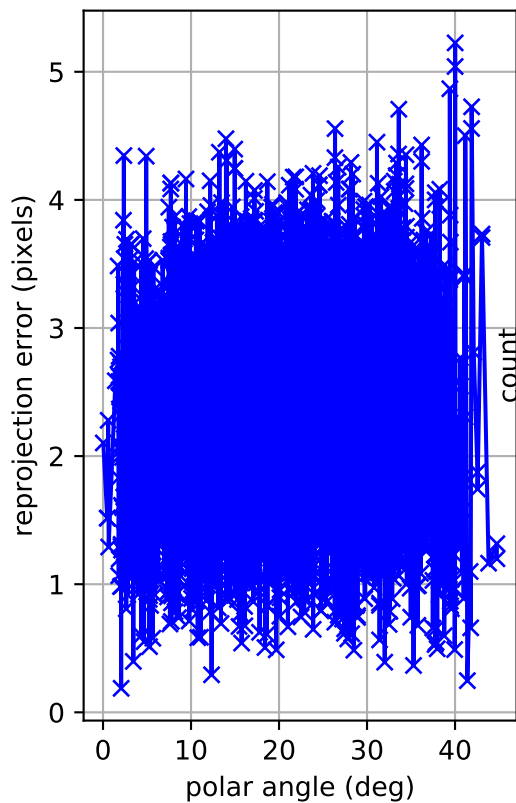
Size: 0.08 [m]

Spacing 0.00832 [m]

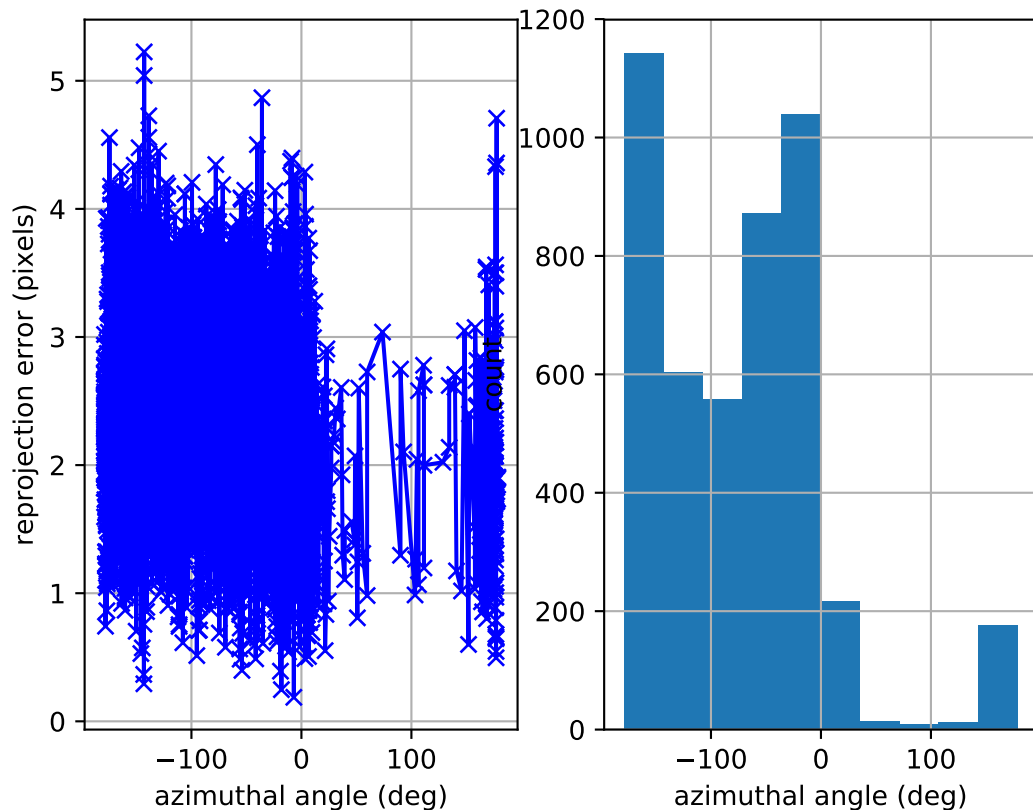
cam0: estimated poses



cam0: polar error



cam0: azimuthal error



cam0: reprojection errors

