# MA 105 : Calculus Integration with tagged partitions

Aryaman Maithani

**IIT** Bombay

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#### Introduction

In these slides, I will give an alternate definition of Riemann integrals which does not involve lower and upper sums but rather, relies on something knows as *tags*.

As one would expect, this definition is indeed equivalent to the one that you did in class. As usual, if you see someone claiming that two definitions are equivalent, you must demand a proof.

I shall, however, leave the burden of proof to you.

## Integration: some objects

Consider a closed and bounded interval I = [a, b].

A partition of I is a finite, ordered set of points  $a = x_0 < x_1 < x_2 < \cdots < x_n = b$ , and is usually denoted by  $\mathcal{P}$ .

The points in a partition are used to divide the interval I into non-overlapping subintervals,  $[x_0, x_1], \ldots, [x_{n-1}, x_n]$ .

If a point  $t_i$  is selected from each subinterval  $[x_i, x_{i+1}]$  then we call the partition to be tagged. It will be denoted by  $\dot{\mathcal{P}}$ . Tags can be selected in any way.

$$\mathcal{P} = (x_0 < x_1 < \dots < x_n) \text{ and } \dot{\mathcal{P}} = \{([x_i, x_{i+1}], t_i) : i = 0, \dots, n-1\}.$$

We define the norm of a partition  $\mathcal{P}$  to be the number

$$\|\mathcal{P}\| := \max\{x_1 - x_0, x_2 - x_1, \dots, x_n - x_{n-1}\}.$$

For a tagged partition  $\dot{P}$ , we define  $\|\dot{P}\| = \|P\|$ .

#### Riemann Sum

If  $f:[a,b]\to\mathbb{R}$  is a function, the Riemann sum of f corresponding to a tagged partition  $\dot{\mathcal{P}}$  of [a,b] is the number

$$S(f,\dot{P}) := \sum_{i=0}^{n-1} f(t_i) (x_{i+1} - x_i).$$

### Integration: Definition

A function  $f:[a,b]\to\mathbb{R}$  is said to be Riemann integrable over [a,b] if there exists a number  $L\in\mathbb{R}$  such that for every  $\epsilon>0$  there exists  $\delta>0$  such that if  $\dot{\mathcal{P}}$  is any tagged partition of [a,b] with  $\|\dot{\mathcal{P}}\|<\delta$ , then

$$|S(f,\dot{P})-L|<\epsilon.$$

The number L, in this case, will be called the Riemann integral of f over [a, b]. We denote it as

$$\int_{a}^{b} f$$
 or  $\int_{a}^{b} f(x) dx$ .