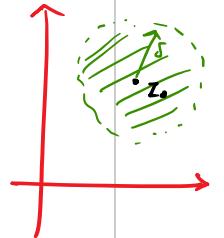


## Lecture 1

### Definition 1 (Some notation)

Given  $z_0 \in \mathbb{C}$  and  $\delta > 0$ , the  $\delta$ -neighbourhood of  $z_0$ , denoted by  $B_\delta(z_0)$  is the set

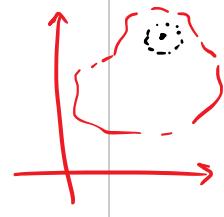
$$B_\delta(z_0) := \{z \in \mathbb{C} : |z - z_0| < \delta\}.$$



### Definition 2 (Open sets)

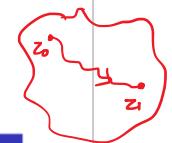
A set  $U \subset \mathbb{C}$  is said to be open if:  
for every  $z_0 \in U$ , there exists *some*  $\delta > 0$  such that

$$B_\delta(z_0) \subset U.$$



### Definition 3 (Path-connected sets)

A set  $P \subset \mathbb{C}$  is said to be path-connected if any two points in  $P$  can be joined by a path in  $P$ . (A continuous function from  $[0, 1]$  to  $P$ .)

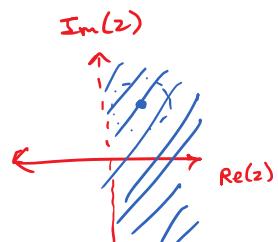


Examples. ①  $B_\delta(z_0)$  are open for any  $z_0 \in \mathbb{C}$  and  $\delta > 0$ .

②  $\mathbb{C}$  is open.  $\emptyset$  is open.

③ Strict right half plane  $H \subseteq \mathbb{C}$  is open

$$H := \{z \in \mathbb{C} : \operatorname{Re}(z) > 0\}.$$



④  $\{z \in \mathbb{C} : \operatorname{Re}(z) \geq 0\}$  is NOT open.

# Lecture 1

## Definition 4 (Differentiable)

Let  $\Omega \subset \mathbb{C}$  be open. Let

$$f : \Omega \rightarrow \mathbb{C}$$

be a function. Let  $z_0 \in \Omega$ .  $f$  is said to be *differentiable at  $z_0$*  if

$$\lim_{z \rightarrow z_0} \frac{f(z) - f(z_0)}{z - z_0}$$

exists. In this case, it is denoted by  $f'(z_0)$ .

$$f : (a, b) \rightarrow \mathbb{R}$$
$$f'(x_0) := \lim_{x \rightarrow x_0} \frac{f(x) - f(x_0)}{x - x_0}$$



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$$\Omega = \mathbb{C}, \quad z, z^2, \quad z^n, \dots$$

$$\exp, \quad \sin, \quad \cos, \quad \dots ?$$

$$\text{Non-diff:} \quad |z|, \quad \bar{z}, \dots$$

# Lecture 1

## Definition 5 (Holomorphic)

- ① A function  $f$  is said to be holomorphic on an open set  $\Omega$  if it is differentiable at every  $z_0 \in \Omega$ .
- ② A function  $f$  is said to be holomorphic at  $z_0$  if it is holomorphic on some neighbourhood of  $z_0$ .

## Remark 1

→ A function may be differentiable at  $z_0$  but not holomorphic at  $z_0$ .  
For example,  $f(z) = |z|^2$  is differentiable only at 0. Thus, it is differentiable at 0 but holomorphic nowhere.

For sets, however, there is no difference.



Points: Holo.  $\Rightarrow$  Diff but  $\Leftarrow$

## Notation

From this point on,  $\Omega$  be always denote an open subset of  $\mathbb{C}$ .

Whenever I write some complex number  $z$  as  $z = \underline{x} + \iota \underline{y}$ , it will be assumed that  $x, y \in \mathbb{R}$ .

Similarly for  $f(z) = \underline{u(z)} + \iota \underline{v(z)}$ .

## Lecture 2: CR Equations

$$\begin{array}{c} \mathbb{C} \longleftrightarrow \mathbb{R}^2 \\ z = x + iy \longleftrightarrow (x, y) \end{array}$$

Let  $f : \Omega \rightarrow \mathbb{C}$  be a function. We can decompose  $f$  as

$$\mathbb{C} \cong \mathbb{R}^2 \quad f(z) = u(z) + i v(z),$$

where  $u, v : \Omega \rightarrow \mathbb{R}$  are real valued functions.

The idea now is to consider  $u$  and  $v$  as functions of two variables. We can do so by simply considering  $u(x, y) = u(x + iy)$  and similarly for  $v$ . Now, if we know that  $f$  is holomorphic, then we have the following result.

$$\boxed{\begin{array}{c} u, v : \Omega \hookrightarrow \mathbb{R}^2 \rightarrow \mathbb{R} \\ u_x, u_y, v_x, v_y \text{ make sense.} \end{array}} \text{ MA 109, 111}$$

## Lecture 2: CR Equations

↳ Cauchy-Riemann

### Theorem 1 (CR equations)

Let  $f : \Omega \rightarrow \mathbb{C}$  be differentiable at a point  $z_0 \in \Omega$ . Let

$$z_0 = x_0 + iy_0.$$

Then, we have

$$\textcircled{1} \quad \underline{\underline{u_x}}(x_0, y_0) = \underline{\underline{v_y}}(x_0, y_0) \quad \text{and} \quad \underline{\underline{u_y}}(x_0, y_0) = -\underline{\underline{v_x}}(x_0, y_0).$$

Moreover, we have

$$\textcircled{2} \quad f'(z_0) = \underline{\underline{u_x}}(x_0, y_0) + i\underline{\underline{v_x}}(x_0, y_0).$$

$$f' = u_x + iv_x$$

Existence of  $u_x, u_y, v_x, v_y$  is part of the theorem.

Note the subscript is  $x$  for both in the above.

Also note that all the equalities are only at the point  $z_0$ . In particular, we are only assuming differentiability at  $z_0$ .

Test  $f(z) = z$   
 $= x+iy$   
to see  
what the  
signs should  
be.

## Lecture 2: CR Equations

Converse? What is the converse? Is it true?

No. The converse is **not** true.

An example for you to check is

$$f(z) := \begin{cases} \frac{\bar{z}^2}{z} & z \neq 0, \\ 0 & z = 0. \end{cases}$$

CR equations hold at the point  $(x_0, y_0)$

$f$  is differentiable at  $z_0$ ?

Check that  $u$  and  $v$  satisfy the CR equations at  $(0, 0)$  but  $f$  is not differentiable at  $0 + 0i$ . (Page 23 of slides.)

## Lecture 2: CR Equations

We recall MA 105 now. | or + (1)

### Definition 6 (Total derivative)

If  $f : \Omega \rightarrow \mathbb{C}$  is a function, we may view it as a function

$$f : \Omega \xrightarrow{\epsilon^{\mathbb{R}^2}} \mathbb{R}^2.$$

Recall that  $f$  is said to be real differentiable at  $(x_0, y_0) \in \Omega \subset \mathbb{R}^2$  if there exists a  $2 \times 2$  real matrix  $A$  such that

$$\lim_{(h,k) \rightarrow (0,0)} \frac{\left\| f(x_0 + h, y_0 + k) - f(x_0, y_0) - A \begin{bmatrix} h \\ k \end{bmatrix} \right\|}{\|(h, k)\|} = 0.$$

The matrix  $A$  was called the *total derivative of  $f$  at  $(x_0, y_0)$* .

## Lecture 2: CR Equations

### Theorem 2

If  $f$  is (complex) differentiable at a point  $z_0 = x_0 + \iota y_0$ , then  $f$  is real differentiable at  $(x_0, y_0)$ .

Once again, this is only talking about differentiability at a point.

The converse is again not true.

Take the example  $f(z) = \bar{z}$ . Thus, we have seen two sufficient conditions for complex differentiability so far. Neither is individually sufficient. However, together, they are.

$$\begin{aligned} u(x, y) &= x \\ v(x, y) &= -y \end{aligned} \quad \left. \begin{array}{l} u_x = 1 \\ v_y = -1 \end{array} \right\}$$

## Lecture 2: CR Equations

$$\begin{aligned} CD &\Rightarrow CR + RD \\ CR \not\Rightarrow CD, \quad RD \not\Rightarrow CD \end{aligned}$$

### Theorem 3

Let  $f : \Omega \rightarrow \mathbb{C}$  be a function and let  $z_0 = x_0 + iy_0 \in \Omega$ . If the CR equations hold at the point  $(x_0, y_0)$  and if  $f$  is real differentiable at the point  $(x_0, y_0)$ , then  $f$  is complex differentiable at the point  $z_0$ .

$$(CR + RD) \Rightarrow CD$$

Recall from MA 109, 111:  
If  $f : \Omega \rightarrow \mathbb{R}^2$  is a function s.t.  
 $f = (u, v)$        $u_x, u_y, v_x, v_y$  are continuous on  $\Omega$ ,  
then  $f$  is real diff. on  $\Omega$ .

## Lecture 2: CR Equations

Note : if  $f: \Omega \rightarrow \mathbb{R}^2$ , then  $f_x, f_y, \text{etc.}$  are meaningless.

### Definition 7 (Harmonic functions)

Let  $u: \Omega \rightarrow \mathbb{R}$  be a twice continuously differentiable function.  $u$  is said to be *harmonic* if  $\underline{u_{xx}} + \underline{u_{yy}} = 0$ .

### Proposition 1

The real and imaginary parts of a holomorphic function are harmonic.

$$\begin{aligned} u_{xx} &= v_y & u_{yy} &= -v_x \\ u_{yy} &= v_{yy} & u_{yy} &= -v_{xy} \end{aligned} \quad \left. \begin{aligned} u_{xy} &= v_{yx} \\ u_{yy} &= v_{yy} \end{aligned} \right\} \text{but } v_{xy} = v_{yx} \quad \text{by assumption of } u, v \text{ being } C^2$$

Suppose  $u$  and  $v$  are harmonic on  $\Omega$ .  $v$  is said to be a harmonic conjugate of  $u$  if  $f = u + iv$  is holomorphic on  $\Omega$ .

If  $v$  is a harmonic conjugate of  $u$ , then  $-u$  is a harmonic conjugate of  $v$ .

Check the second last slide of this lecture to find the algorithm for finding a harmonic conjugate.

Harmonic Conjugate need not exist.

Example. Consider  $\Omega = \mathbb{R} - \{(0, 0)\}$  and

$u: \Omega \rightarrow \mathbb{R}$  defined as

$$u(x, y) = \frac{1}{2} \log(x^2 + y^2).$$

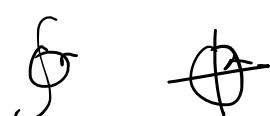
If  $u$  had a harmonic conjugate  $v$ , then

$$v_y(x, y) = \frac{x}{x^2 + y^2} \quad \text{and} \quad v_x(x, y) = -\frac{y}{x^2 + y^2}.$$

But  $\nabla v: \Omega \rightarrow \mathbb{R}$  s.t.

$$\nabla v = \left( \frac{-y}{x^2 + y^2}, \frac{x}{x^2 + y^2} \right).$$

(Proof?)



$\mathcal{G}$   $\oplus$

Claim 1. Arbitrary union of open sets is open.

Proof. Let  $\{U_i : i \in I\}$  be a collection of open sets.

$$\text{Define } U := \bigcup_{i \in I} U_i$$

$$= \{x : x \in U_i \text{ for some } i \in I\}.$$

IS:  $U$  is open.



Proof. Let  $x \in U$  be arbitrary.

Then,  $\exists i_0 \in I$  s.t.  $x \in U_{i_0}$ .

Since  $U_{i_0}$  is open,  $\exists \delta > 0$  s.t.

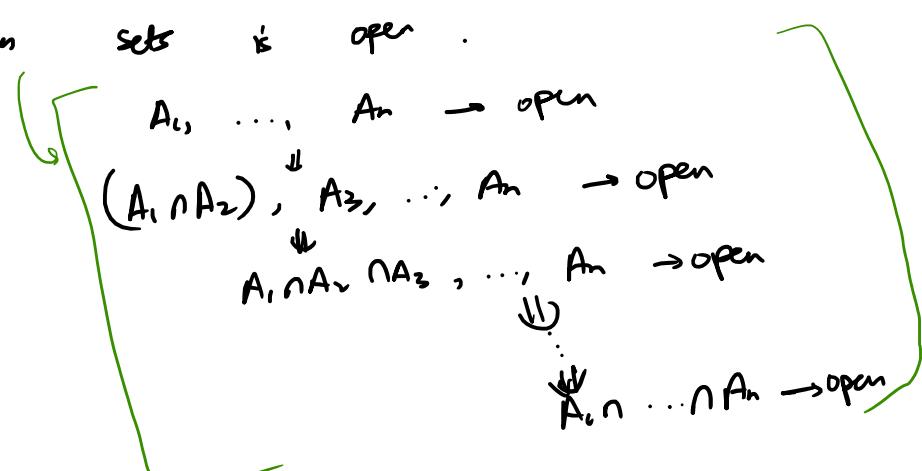
$$B_\delta(x) \subset U_{i_0}.$$

But  $U_{i_0} \subseteq U$ . Thus,  $B_\delta(x) \subseteq U$ .

Thus,  $U$  is open.  $\blacksquare$

Claim 2. Finite intersection of open sets is open.

Proof. It suffices to prove that intersection of two open sets is open.



Let  $U_1$  and  $U_2$  be open and  $x \in U_1 \cap U_2$ .

Let  $U_1$  and  $U_2$  be open and  $x \in U_1 \cap U_2$ .

$$\left. \begin{array}{l} \exists \delta_1 > 0 \text{ s.t. } B_{\delta_1}(x) \subseteq U_1 \text{ and} \\ \exists \delta_2 > 0 \text{ s.t. } B_{\delta_2}(x) \subseteq U_2. \end{array} \right\} \because U_1 \text{ & } U_2 \text{ are open}$$

Pick  $\delta := \min(\delta_1, \delta_2) > 0$ .

Then,  $B_\delta(x) \subseteq B_{\delta_1}(x) \subseteq U_1$  and

$$B_\delta(x) \subseteq B_{\delta_2}(x) \subseteq U_2.$$

$$\therefore B_\delta(x) \subseteq (U_1 \cap U_2).$$

□

"Dual" statements for closed sets.

$U_1, U_2 \rightarrow \text{open}$  you can say:  $U_1 \cup U_2$  and  $U_1 \cap U_2$  are open

$U_1, U_2, \dots, U_n \rightarrow \text{open} \Rightarrow U_1 \cup \dots \cup U_n$  &  $U_1 \cap \dots \cap U_n$  are open.

$U_1, U_2, U_3, \dots \rightarrow \text{open} \Rightarrow \bigcup_{i=1}^{\infty} U_i$  is open but  $\bigcap_{i=1}^{\infty} U_i$  may not be.

$$C - \left( \bigcup_{i \in I} U_i \right) = \bigcap_{i \in I} (C - U_i)$$

closed  $\Leftrightarrow$  complement is open.

$$U_i := B_{r_i}(o).$$

$$\bigcap_{i \in I} U_i = \{o\}$$

↑  
not  
open.



## Tutorial 2

14 August 2021 11:55

### Lecture 3: Power Series

#### Definition 8 (Convergence of series)

A series of the form

$$\rightarrow \sum_{n=0}^{\infty} a_n \quad \begin{matrix} (a_n)_{n \geq 0} \rightarrow \text{sequence} \\ \text{in } \mathbb{C} \end{matrix}$$

of complex numbers is said to converge if the sequence of partial sums

$$s_n = \sum_{k=0}^n a_k$$

converges (to a finite complex number).

The sequence of partial sums is just the following sequence:

$$a_0, \underline{a_0 + a_1}, \underline{a_0 + a_1 + a_2}, \dots$$

"Divergent" is simply used to mean "not convergent."

Check that  $\sum (-1)^n$  and  $\sum n$  both diverge.

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Similarly  
 $\sum_{k=0}^n k = \frac{n(n+1)}{2}$  diverges  
 $1+2+3+4+\dots$  diverges

$$a_n = (-1)^n \quad \text{for } n \geq 0$$

partial sums  
 $1 - 1 + 1 - 1 + 1 - 1 + \dots$   
 $1, 0, 1, 0, 1, 0, 1, 0, \dots$   
Diverges

### Lecture 3: Power Series

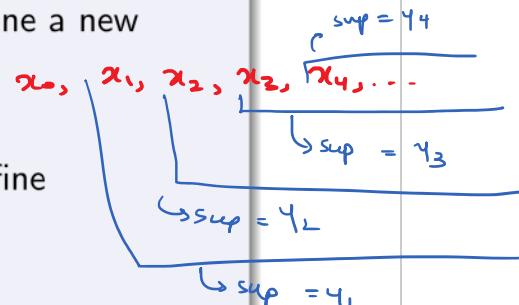
#### Definition 9 (limsup)

Given a sequence  $(x_n)$  of real numbers, we may define a new sequence  $(y_n)$  as

$$y_n = \underline{\sup \{x_m : m \geq n\}}.$$

The limit of this sequence always exists and we define

$$\limsup_{n \rightarrow \infty} x_n = \lim_{n \rightarrow \infty} y_n.$$



#### Remark 2

Each  $y_n$  might be  $\infty$ . That is allowed.

The limsup might be  $\pm\infty$ . This is also allowed.

Each  $y_n$  might be  $\infty$ . That is allowed.

The limsup might be  $\pm\infty$ . This is also allowed.

If  $\lim_{n \rightarrow \infty} x_n$  itself exists, then it equals the lim sup as well.

I know:  $\lim_{n \rightarrow \infty} n^{y_n} = 1$ .

Thus,  $\limsup_{n \rightarrow \infty} n^{y_n} = 1$ .

$\limsup$  of a real sequence always exists!

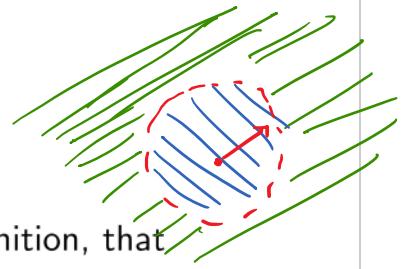
$\lim_{n \rightarrow \infty} \frac{\sin(n)}{n} = 0$

$\limsup_{n \rightarrow \infty} \frac{\sin(n)}{n} = 0$

## Lecture 3: Power Series

We will be interested in discussing radius of convergence of power series. We all know what that is. It is a series of the form

$$\sum_{n=0}^{\infty} a_n(z - z_0)^n \quad (*)$$



where  $z_0 \in \mathbb{C}$  and each  $a_n \in \mathbb{C}$ .

What is the radius of convergence, though? (The definition, that is.)

### Theorem 4 (Radius of convergence)

Given any power series as  $(*)$ , there exists  $R \in [0, \infty]$  such that

- ①  $(*)$  converges for any  $z$  with  $|z - z_0| < R$ , and
- ②  $(*)$  diverges for any  $z$  with  $|z - z_0| > R$ . *absolutely*

This  $R$  is called the radius of convergence.

Note the brackets.

$$\sum_{n=1}^{\infty} \frac{z^n}{n} \rightarrow R_oC = 1$$

at  $-1$ : converges  
at  $1$ : diverges

$$\sum z^n \sim R_oC = 1$$

diverges for all  $z$  with  $|z| = 1$

## Lecture 3: Power Series

We would now like to be able to calculate the radius of convergence.

### Theorem 5 (Root test)

Let  $(*)$  be as earlier. Define

$$\alpha = \limsup_{n \rightarrow \infty} \sqrt[n]{|a_n|}.$$

ALWAYS WORKS.

Then,  $R = \alpha^{-1}$  is the radius of convergence.

This test *always works*. We had no assumptions of any kind on  $(*)$ .

Note that  $\alpha^{-1}$ .

If  $\alpha = 0$ , then  $R = \infty$  and vice-versa.

$$\sum_{n=1}^{\infty} \frac{z^n}{n} \quad \alpha = \limsup \left( \frac{1}{n} \right)^{\frac{1}{n}} =$$

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Note: limit rules of  $+$ ,  $\cdot$ ,  $(\cdot)^{-1}$   
do not apply to  $\limsup$ .

we know  $\lim_{n \rightarrow \infty} n^{y_n} = 1$   
 $\therefore \lim_{n \rightarrow \infty} \left( \frac{1}{n} \right)^{y_n} = \frac{1}{1} = 1 \quad \therefore \limsup \left( \frac{1}{n} \right)^{y_n} = 1$

$$\limsup (a_n + b_n) \leq \limsup (a_n) + \limsup (b_n)$$

## Lecture 3: Power Series

We have another test. This is simpler (to calculate) but mightn't always work.

### Theorem 6 (Ratio test)

Let  $(*)$  be as earlier.

Assume that the limit

$$R = \lim_{n \rightarrow \infty} \left| \frac{a_n}{a_{n+1}} \right|$$

can apply to

$$\sum \frac{z^n}{n}$$

$$\text{or } \sum_{n=0}^{\infty} \frac{z^n}{n!}$$

$$\frac{\left( \frac{1}{n!} \right)}{\left( \frac{1}{(n+1)!} \right)}$$

$$= n+1 \rightarrow \infty$$

exists. (Possibly as  $\infty$ .)

Then,  $R$  is the radius of convergence.

Note that here we assume that the limit does exist. This may not always be true.

Note that I'm not taking any inverse here but also note the way the ratio is taken. We have  $a_n/a_{n+1}$ .

Note that I'm not taking any inverse here but also note the way the ratio is taken. We have  $a_n/a_{n+1}$ .

Take  $f(z) = \sum_{n=1}^{\infty} \frac{z^n}{n^2}$ . Then,  $f'(z) = \sum_{n=1}^{\infty} \frac{z^{n-1}}{n}$ .

$\hookrightarrow R=C=1$

$\downarrow$  converges at  $z=1$

$\downarrow$  does not converge at  $z=1$ .

## Lecture 3: Power Series

Differentiability of power series is what one should expect.

### Theorem 7 (Differentiability)

Let  $\sum_{n=0}^{\infty} a_n z^n$  be a power series with radius of convergence  $R > 0$ . On the open disc of radius  $R$ , let  $f(z)$  denote this sum.

Then, on this disc, we have

$$f'(z) = \sum_{n=1}^{\infty} n a_n z^{n-1}.$$

Boundary: NO CONVERGENCE.

Note that this is again a power series with the same radius of convergence. Thus, we may repeat the process indefinitely. In other words, power series are infinite differentiable.

$$\limsup (a_n)^{\frac{1}{n}} = \limsup n^{\frac{1}{n}} |a_n|^{\frac{1}{n}}$$

Digression. Let  $(x_n)_{n \geq 0}$  be a real sequence.

Consider

$$E := \left\{ \text{limits of all possible convergent subsequences} \right\} \subseteq \mathbb{R} \cup \{\pm\infty\}.$$

$$\text{Then, } \limsup_{n \rightarrow \infty} x_n = \sup E.$$

## Lecture 4: Exponential function

I shall just recall the facts from the lecture.

### Definition 10 (Exponential function)

The power series

$$\sum_{n=0}^{\infty} \frac{z^n}{n!}$$

converges on all of  $\mathbb{C}$ . This sum is denoted by  $\exp(z)$ .

### Theorem 8 (Facts)

- ①  $\exp'(z) = \exp(z)$ , ✓
- ②  $\exp'(bz) = b \exp(bz)$ , for  $b \in \mathbb{C}$ , ✓
- ③  $\exp(z) \cdot \exp(-z) = 1$  for all  $z \in \mathbb{C}$ , ✓
- ④  $\exp(z)$  is always nonzero.

## Lecture 4: Exponential function

Now, we some “converse” facts.

### Theorem 9 (Characterisations)

- ① If  $f'(z) = bf(z)$ , then  $f(z) = a \exp(bz)$  for some  $a, b \in \mathbb{C}$ ,
- ② If  $f' = f$  and  $f(0) = 1$ , then  $f(z) = \exp(z)$ .

### Theorem 10 (Final fact)

Let  $z, w \in \mathbb{C}$ , then

$$\exp(z + w) = \exp(z) \cdot \exp(w).$$

*$\exp : \mathbb{C} \longrightarrow \mathbb{C}^\times$  is a group homomorphism.  
+                    .       $\mathbb{C}^{\text{tors}}$*

## Lecture 4: Exponential function

### Definition 11 (Domain)

A subset  $\Omega \subset \mathbb{C}$  is said to be a *domain* if it is open and path-connected.

We had one very nice result on the zeroes of analytic functions.

### → Theorem 11 (Zeroes are isolated)

Let  $\Omega$  be a **domain** and  $f : \Omega \rightarrow \mathbb{C}$  be a non-constant analytic function. Let  $z_0 \in \Omega$  be such that  $f(z_0) = 0$ . Then, there exists  $\delta > 0$  such that  $f$  has no other zero in  $B_\delta(z_0)$ .



The above is saying that around every zero of  $f$ , we can draw a (sufficiently small) circle such that  $f$  has no other zero in that disc. This is the same as saying that the set of zeroes is *discrete*.

# Logarithm

We discuss logarithm a bit.

## Definition 14 (Branch of the logarithm)

Let  $\Omega \subset \mathbb{C}$  be a **domain**. Let  $f : \Omega \rightarrow \mathbb{C}$  be a continuous function such that

$$\exp(f(z)) = z, \quad \text{for all } z \in \Omega.$$

Then,  $f$  is called a *branch of the logarithm*.

## Theorem 21 (Uniqueness of branches)

Assume that  $f, g : \Omega \rightarrow \mathbb{C}$  are two branches of the logarithm.

Then,  $f - g$  is a constant function. Moreover, this constant is an integer multiple of  $2\pi i$ .

The last theorem also assumed that  $\Omega$  is a **domain**.

Branch of log may not exist on a given domain.

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No branch on  $\mathbb{C}$ . Also, there is no branch on  $\mathbb{C}^*$ .

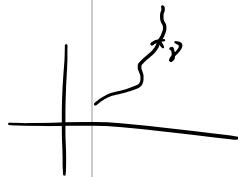
## Lecture 5: Integration

### Definition 12

Let  $f : [a, b] \xrightarrow{\text{C}} \mathbb{C}$  be a piecewise continuous function. Writing  $f = u + \iota v$  as usual, we define

$$\int_a^b f(t) dt := \underbrace{\int_a^b u(t) dt}_{\hookrightarrow \text{continuous}} + \iota \underbrace{\int_a^b v(t) dt}_{\text{piece wise diff.}}$$

This is naturally what one would have wanted to define. Now, we define integration over a *contour*. (What is a contour?)



### Definition 13

Let  $f : \Omega \rightarrow \mathbb{C}$  be a continuous function. Let  $\gamma : [a, b] \rightarrow \Omega$  be a contour. We define

$$\int_{\gamma} f(z) dz := \int_a^b f(\gamma(t)) \gamma'(t) dt.$$

## Lecture 5: Integration

We have a useful inequality called the **ML** inequality.

### Theorem 12 (**ML** Inequality)

Let  $\gamma$  be a contour of length  $L$  and  $f$  be a continuous function defined on the image of  $\gamma$ .

Suppose that

$$\underline{|f(\gamma(t))|} \leq M, \quad \text{for all } t \in [a, b].$$

Then, we have

$$\left| \int_{\gamma} f(z) dz \right| \leq ML.$$

"Real analogue : If  $f : [a, b] \rightarrow \mathbb{R}$  is bounded by  $M$ , then

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$$\int_a^b f \leq M(b-a).$$

## Lecture 5: Integration

"**FTC**"

### Theorem 13 (Primitives and integrals)

Suppose  $f : \Omega \rightarrow \mathbb{C}$  has a primitive on  $\Omega$ . That is, there exists a function  $F : \Omega \rightarrow \mathbb{C}$  such that  $F' = f$ . (The complex derivative.)  
h.o.t. Then, we have

$$\int_{\gamma} f(z) dz = F(\gamma(b)) - F(\gamma(a)).$$

If  $\gamma$  is closed, that is, if  $\gamma(b) = \gamma(a)$ , then

$$\gamma(a) = \gamma(b)$$

$$\int_{\gamma} f(z) dz = 0.$$

Primitive on  $\Omega$



Integral over closed curves in  $\Omega$  in 0.

Note:  $\Omega$  need not contain interior of  $\gamma$ . Thus, we can conclude  
Existence of a primitive is a strong condition, by the way. A holomorphic function need not have a primitive on all of  $\Omega$ .

$$\int_{\gamma} \frac{1}{z^2} dz = 0 \text{ on the unit circle.}$$

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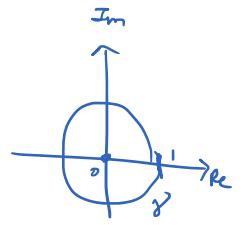
Consider  $\Omega = \mathbb{C} - \{z_0\}$ .

Let  $f: \Omega \rightarrow \mathbb{C}$  be  $f(z) := \frac{1}{z}$ .

Then,  $f$  has no primitive on  $\Omega$ .

Proof. Let  $\gamma(t) := e^{2\pi i t}$ ,  $t \in [0, 1]$ .

$$\begin{aligned} \text{Then, } \int_{\gamma} f &= \int_0^1 f(\gamma(t))\gamma'(t)dt = \int_0^1 (e^{-2\pi i t})(2\pi i)(e^{2\pi i t})dt \\ &= (2\pi i) \int_0^1 dt = 2\pi i \neq 0 \end{aligned}$$



## Lecture 5: Integration

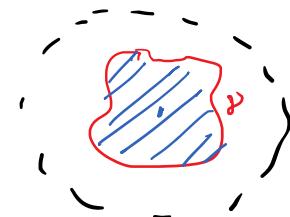
Now, we come to Cauchy's theorem.

### Theorem 14 (Cauchy's Theorem)

Let  $\gamma$  be a simple, closed contour and let  $f$  be a holomorphic function defined on an open set  $\Omega$  containing  $\gamma$  as well as its interior. Then,

$$\longrightarrow \int_{\gamma} f(z)dz = 0.$$

If  $\Omega$  is simply-connected, then the interior condition is automatically met. This gives us the next result.



## Lecture 5: Integration

### Theorem 15 (“General” Cauchy Theorem)

Let  $\Omega$  be a simply-connected domain. Let  $\gamma : [a, b] \rightarrow \mathbb{C}$  be a simple, closed contour and  $f : \Omega \rightarrow \mathbb{C}$  holomorphic. Then,

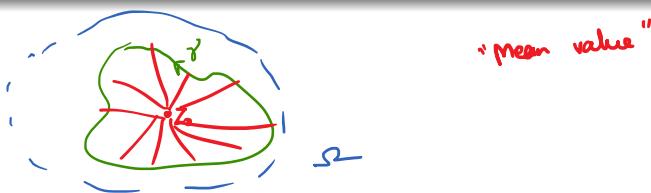
$$\int_{\gamma} f(z) dz = 0.$$

## Lecture 6: CIF and Consequences

### Theorem 16 (Cauchy Integral Formula)

Let  $f$  be holomorphic everywhere on an open set  $\Omega$ . Let  $\gamma$  be a simple closed curve in  $\Omega$ , oriented positively. If  $z_0$  is interior to  $\gamma$  and  $\Omega$  contains the interior of  $\gamma$ , then

$$f(z_0) = \frac{1}{2\pi\iota} \int_{\gamma} \frac{f(z)}{z - z_0} dz.$$



## Lecture 6: CIF and Consequences

We then saw a consequence of CIF which I state as a theorem below.

### Theorem 17 (Holomorphic $\Rightarrow$ Analytic)

Let  $\Omega \subset \mathbb{C}$  be open and  $f : \Omega \rightarrow \mathbb{C}$  be holomorphic. Pick any  $z_0 \in \Omega$ . Let  $R > 0$  be the largest such that  $B_R(z_0) \subset \Omega$ . (The case  $R = \infty$  is allowed. That just means  $\Omega = \mathbb{C}$ .) Then, on the disc  $B_R(z_0)$ , we may write  $f(z)$  as

$$f(z) = \sum_{n=0}^{\infty} a_n (z - z_0)^n,$$

where each  $a_n$  is given by

$$a_n = \frac{1}{2\pi\iota} \int_{|w-z_0|=r} \frac{f(w)}{(w - z_0)^{n+1}} dw.$$



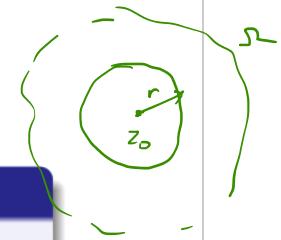
## Lecture 6: CIF and Consequences

The above also gives us (what I call) the “generalised” Cauchy Integral Formula.

Theorem 18 (“Generalised” CIF)

$$\int_{|w-z_0|=r} \frac{f(w)}{(w-z_0)^{n+1}} dw = \frac{2\pi\iota}{n!} f^{(n)}(z_0),$$

where  $f$  is a function which is holomorphic on an open disc  $B_R(z_0)$  and  $r < R$ .



Remark 3

Note that, as usual, we require  $f$  to be holomorphic within the circle as well.

Just keep the "Generalised CIF" in mind, in case all these various theorems are too confusing! It will let you derive everything else quite simply!

In fact, the simplest thing is Cauchy's residue theorem which is the best generalisation of all these results, which we'll see later in the course and everything else becomes a very direct corollary of it.

## Lecture 7: CIF and Consequences

### Theorem 19 (Cauchy's estimate)

Suppose that  $f$  is holomorphic on  $|z - z_0| < R$  and bounded by  $M > 0$  on this disc. Then,

$$|f^{(n)}(z_0)| \leq \frac{n!M}{R^n}.$$

An easy application of this give us:

### Theorem 20 (Liouville's Theorem)

Let  $f : \mathbb{C} \rightarrow \mathbb{C}$  be holomorphic. If  $f$  is bounded, then  $f$  is constant!

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## Logarithm

from last tutorial

The previous theorem talked about uniqueness of branches (up to a constant) assuming the existence of such a branch. Now, we see when a branch is actually possible. *Short: Simply connected domain without 0 has a log.*

### Theorem 22 (Existence of a branch)

Let  $\Omega$  be a **simply-connected** domain in  $\mathbb{C}$ . Assume that  $1 \in \Omega$  and  $0 \notin \Omega$ .

There exists a unique function  $F : \Omega \rightarrow \mathbb{C}$  such that

- ①  $F(1) = 0$ , ✓
- ②  $F'(z) = 1/z$ , ✓
- ③  $\exp(F(z)) = z$  for all  $z \in \Omega$ ,
- ④  $F(r) = \log(r)$  for all  $r \in \Omega \cap \mathbb{R}^+$ .

*F is a branch of log*

The log in the last point is the usual log for real numbers as seen in 105. The above  $F$  is then denoted by  $\log$ .

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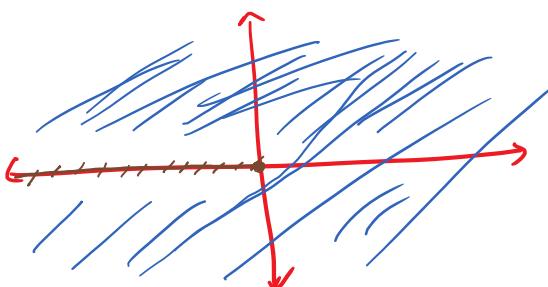
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Special example:  $\Omega = \mathbb{C} \setminus \mathbb{R}_{\leq 0}$   
 $= \mathbb{C} \setminus (-\infty, 0]$



## Lecture 8: Singularities

### Definition 15 (Singularities)

Let  $f : \Omega \rightarrow \mathbb{C}$  be a function. A point  $z_0 \in \mathbb{C}$  is said to be a singularity of  $f$  if  $\frac{\sin(z)}{z}$  at  $z_0$  "bad"

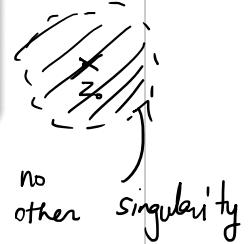
- ①  $z_0 \notin \Omega$ , i.e.,  $f$  is not defined at  $z_0$ , or
- ②  $z_0 \in \Omega$  and  $f$  is not holomorphic at  $z_0$ .

### Definition 16 (Isolated singularity)

A singularity  $z_0 \in \mathbb{C}$  is said to be *isolated* if there exists some  $\delta > 0$  such that  $f$  is holomorphic on  $B_\delta(z_0) \setminus \{z_0\}$ .

The above is saying that " $f$  is holomorphic on some *punctured disc* around  $z_0$ ."

Compare this "isolation" with what we saw earlier when we said that "zeroes are isolated."



## Lecture 8: Singularities

### Definition 17 (Non-isolated singularity)

A singularity which is not an isolated singularity is called a non-isolated singularity.

*The floor is made of floor.*

Note that if  $f$  has only finitely many singularities, then all the singularities are isolated.  $\leftarrow$  only one of interest

We classify isolated singularities into three types:

- ① Removable singularities,
- ② Poles,
- ③ Essential singularities.

will see an example today  
of non-isolated.

$$\frac{1}{\sin(\frac{1}{z})}$$

singularities

$$\{0\} \cup \left\{\frac{\pi}{n}, \frac{\pm 1}{2\pi}, \pm \frac{1}{3\pi}, \dots\right\}$$

### Remark 4

The above classification is only for isolated singularities.

## Lecture 8: Singularities

### Definition 18 (Removable singularity)

If an isolated singularity can be removed by defining the function by assigning a certain value at that point, we say that the singularity is removable.

$f(z) := \text{(e)define}$

These are characterised by the following theorem.

(RRST)

### Theorem 23 (Riemann's Removable Singularity Theorem)

An isolated singularity  $\uparrow$   $z_0$  is a removable singularity of  $f$  iff  $\lim_{z \rightarrow z_0} f(z)$  exists.

In the above, we mean that it exists as a (finite) complex number.

Moreover, in such a case, (re)defining  $f(z_0)$  as this limit makes  $f$  holomorphic.

$$f(z) = \frac{\sin z}{z}$$

defined on  $\mathbb{C} \setminus \{0\}$  has 0 as a removable singularity.

## Lecture 8: Singularities

### Definition 19 (Pole)

An isolated singularity  $z_0$  is said to be a pole if  $|f(z)| \rightarrow \infty$  as  $z \rightarrow z_0$ .

(No matter how you approach it.)

O is not  
a pole  
for  $f(z) = e^{1/z}$ .  
 $z \rightarrow 0$   
along negative  
real axis.

### Theorem 24

An isolated singularity  $z_0$  is a pole of  $f$  iff  $\lim_{z \rightarrow z_0} \frac{1}{f(z)} = 0$ .

### Theorem 25 (Order of a pole)

If  $z_0$  is a pole of  $f$ , then there exists an integer  $m > 0$  such that

$$f(z) = (z - z_0)^{-m} f_1(z)$$

on a punctured neighbourhood of  $z_0$ , for some function  $f_1$  which is holomorphic on the complete neighbourhood. The smallest such integer  $m$  is called the *order* of the pole.

If the order is 1, then  $z_0$  is said to be *simple* pole.

$$\begin{aligned} f(z) &= \frac{f_1(z)}{(z - z_0)^m} \\ &= f_1(z) \frac{(z - z_0)^{-m}}{(z - z_0)^m} \end{aligned}$$

$$f(z) = \frac{f_1(z)}{z - z_0}.$$

## Lecture 8: Singularities

### Definition 20 (Essential singularity)

An isolated singularity is called an essential singularity if it is neither a removable singularity nor a pole.

### Theorem 26 (Casorati-Weierstrass Theorem)

If  $z_0$  is an isolated singularity, then it is essential iff the values of  $f$  come arbitrarily close to every complex number in a neighborhood of  $z_0$ .

$$z_0 : \exists \delta > 0$$

Recall: A  $\subseteq \mathbb{C}$  is DENSE in  $\mathbb{C}$  if for every  $w \in \mathbb{C}$ ,  $\exists$  a sequence  $(a_n)_n$  in  $A$  s.t.  $a_n \rightarrow w$ .

$f(z)$  is DENSE in  $\mathbb{C}$ .



Thus, by looking at  $\lim_{z \rightarrow z_0} f(z)$  and  $\lim_{z \rightarrow z_0} 1/f(z)$ , we can completely deduce

TEST for an isolated singularity  $z_0$ :

→ ① Compute  $\lim_{z \rightarrow z_0} f(z)$ .

If this is a finite complex number, then  $\rightarrow$  removable.

→ ② Else: Compute  $\lim_{z \rightarrow z_0} \frac{1}{f(z)}$ .

If this is 0, then  $\rightarrow$  pole.

→ ③ Else : essential.

## Lecture 9: Laurent Series

### Theorem 27 (Modified CIF)

Suppose that  $z_0$  is an isolated singularity of  $f$ . Consider an annulus of the form

$$A = \{z : r < |z - z_0| < R\},$$

where  $0 \leq r < R \leq \infty$ . Assume that  $f$  is holomorphic on this open annulus  $A$ . Then, CIF takes the form

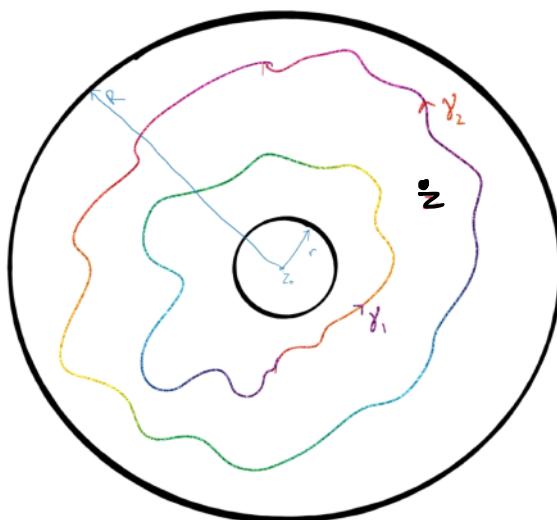
$$f(z) = \frac{1}{2\pi\iota} \int_{|w-z_0|=R'} \frac{f(w)}{w-z} dw - \frac{1}{2\pi\iota} \int_{|w-z_0|=r'} \frac{f(w)}{w-z} dw,$$

where  $r < r' < |z| < R' < R$ .

Just like how the usual CIF gave us the power series, this CIF gives us the Laurent series.

## Lecture 9: Laurent Series

Allowing deformations and assuming  $0 < r < R < \infty$ , here's the general picture to keep in mind:



Assume  $f$   
is holomorphic  
on  $A$ .

$A$

Pick  $z \in A$ .

Pick  $\gamma_1$  and  
 $\gamma_2$  as shown.

$$f(z) = \frac{1}{2\pi i} \left( \int_{\gamma_2} - \int_{\gamma_1} \right) \frac{f(w)}{w - z} dw.$$

## Lecture 9: Laurent Series

### Theorem 28 (Laurent Series)

With the same setup as earlier, for  $z \in A$ , we can write  $f(z)$  as

$$f(z) = \sum_{n=-\infty}^{\infty} a_n (z - z_0)^n,$$

is NOT assumed  
to be an  $\infty$ .  
sing.

where each  $a_n$  is given, as before, by

$$a_n = \frac{1}{2\pi\iota} \int_{|w-z_0|=r_0} \frac{f(w)}{(w - z_0)^{n+1}} dw,$$

where  $r < r_0 < R$ .

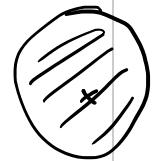
Note that the above is valid for  $n < 0$  as well.

$$a_{-1} = \frac{1}{2\pi\iota} \int_{|w-z_0|=r_0} f(w) dw$$

## Lecture 9: Laurent Series

### Definition 21 (Laurent series expansion at $z_0$ )

If  $z_0$  is an isolated singularity of  $f$ , then  $f$  is holomorphic in an annulus  $\{z : 0 < |z - z_0| < r\}$  for some  $r > 0$ . The Laurent series expansion on this annulus is called the Laurent series expansion at  $\underline{z_0}$ .



### Definition 22 (Principal part)

Let  $\sum_{n=-\infty}^{\infty} a_n(z - z_0)^n$  be the Laurent series expansion *at*  $z_0$ . Its principal part is

$$\sum_{n=-\infty}^{-1} a_n(z - z_0)^n.$$

## Lecture 9: Laurent Series

The most interesting coefficient of the principal part is the  $-1^{\text{st}}$  one. When we integrate a Laurent series along a circle centered at  $z_0$  (which contains no other singularity), only  $a_{-1}$  remains (with a factor of  $2\pi\iota$ ). This is given by

$$a_{-1} = \frac{1}{2\pi\iota} \int_{|z-z_0|=r_0} f(w) dw.$$

This is what is usually called the *residue* and written as

$$a_{-1} = \text{Res}(f; z_0).$$

## Lecture 9: Laurent Series

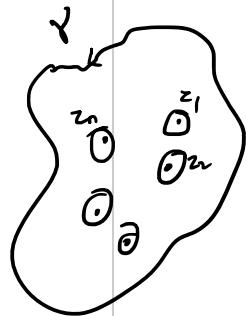
With residues, calculation of integrals becomes easier.

### Theorem 29 (Cauchy's Residue Theorem)

Suppose  $f$  is given and has finitely many singularities  $z_1, \dots, z_n$  within a **simple** closed contour  $\gamma$ . Then, we have

$$\int_{\gamma} f(z) dz = 2\pi i \sum_{i=1}^n \text{Res}(f; z_i).$$

(oriented positively)



Note that the above is implicitly implying that  $f$  is holomorphic at all other points within  $\gamma$ .

## Lecture 9: Laurent Series

Recall that given an isolated singularity, we can expand the function as a Laurent series *around* that point on a punctured neighbourhood. We had defined the principal part of this series to be the part containing the negative powers of  $z - z_0$ . We now see how they are related to the nature of the isolated singularity.

$$\sum_{n=-\infty}^{-1} a_n(z-z_0)^n$$

### Theorem 30 (Isolated singularities and their principal parts)

The isolated singularity  $z_0$  is

By "term", we mean "nonzero" term.

- ① removable iff the principal part has no terms,
- ② a pole iff the principal part has finitely many (and at least one) terms, and
- ③ essential iff the principal part has infinitely many terms.

In particular, the residue at a removable singularity is 0.

$$a_{-1} = 0$$

## Lecture 9: Laurent Series

Now, we see how one can calculate residue at a pole.

By the previous theorem, we know that  $f$  can be written as

$$f(z) = \frac{a_{-m}}{(z - z_0)^m} + \cdots + \frac{a_{-1}}{z - z_0} + a_0 + a_1(z - z_0) + \cdots,$$

for some integer  $m > 0$ .

$$a_{-m} \neq 0, \quad m \geq 1$$

Thus,

$$g(z) = (z - z_0)^m f(z) = a_{-m} + \cdots + a_{-1} (z - z_0)^{m-1} + a_0 (z - z_0)^m + \cdots$$

is holomorphic at  $z_0$  (after redefining; note that  $z_0$  is a removable singularity for  $g$ ) and

$$a_{-1} = \frac{1}{(m-1)!} g^{(m-1)}(z_0).$$