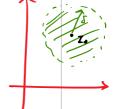
Lecture 1

Definition 1 (Some notation)

Given $z_0 \in \mathbb{C}$ and $\delta > 0$, the δ -neighbourhood of z_0 , denoted by $B_{\delta}(z_0)$ is the set

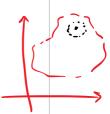
$$B_{\delta}(z_0):=\{z\in\mathbb{C}:|z-z_0|<\delta\}.$$



Definition 2 (Open sets)

A set $U \subset \mathbb{C}$ is said to be open if: for every $z_0 \in \mathbb{C}$, there exists some $\delta > 0$ such that

$$B_{\delta}(z_0) \subset U$$
.



Definition 3 (Path-connected sets)

A set $P \subset \mathbb{C}$ is said to be path-connected if any two points in P can be joined by a path in P. (A continuous function from [0,1] to *P*.)





1 Bs(Zo) are open

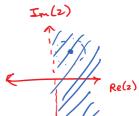
for any ZEC and SZO.



② C is open. B is open.

3) Strict right half plane IH is open

H = { z & C : Re(z) 70}



4) {z∈C: Re(z) ≥0} is NOT open.

Lecture 1

Definition 4 (Differentiable)

Let $\Omega \subset \mathbb{C}$ be open. Let

$$f:\Omega\to\mathbb{C}$$

be a function. Let $z_0 \in \Omega$. f is said to be differentiable at z_0 if

$$\lim_{z\to z_0}\frac{f(z)-f(z_0)}{z-z_0}$$

exists. In this case, it is denoted by $\underline{f'(z_0)}$.

$$f:(a,b) \rightarrow \mathbb{R}$$

 $f(x_0) := \lim_{x \to x_0} \frac{f(x_0) - f(x_0)}{x - x_0}$



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$$\Omega = C$$
, z , z^2 , z^2 , ...

exp, sin, ω , ...?

Non-lift: $|z|$, \overline{z} , ...

Lecture 1

Definition 5 (Holomorphic)

- **O** A function f is said to be holomorphic on an open set Ω if it is differentiable at every $z_0 \in \Omega$.
- ② A function f is said to be holomorphic at $\underline{z_0}$ if it is holomorphic on some neighbourhood of z_0 .

Remark 1

 \rightarrow A function may be differentiable at z_0 but not holomorphic at z_0 . For example, $\underline{f(z) = |z|^2}$ is differentiable only at 0. Thus, it is differentiable at 0 but holomorphic nowhere.

For sets, however, there is no difference.



Points:

H610.

⇒ Piff

6.1



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Notation

From this point on, Ω be always denote an open subset of $\mathbb C.$ Whenever I write some complex number z as $z = \underline{x} + \iota \underline{y}$, it will be assumed that $x, y \in \mathbb{R}$.

Similarly for $f(z) = u(z) + \iota v(z)$.

Let $f:\Omega\to\mathbb{C}$ be a function. We can decompose f as

$$c_{\mu} = \int_{z}^{z} R^{2} f(z) = u(z) + \iota v(z),$$

where $u,v:\underline{\Omega} o \mathbb{R}$ are real valued functions.

The idea now is to consider u and v as functions of two variables. We can do so by simply considering $u(x,y) = u(x + \iota y)$ and similarly for v. Now, if we know that f is holomorphic, then we have the following result.

$$\int u, v : \Omega \longrightarrow \mathbb{R} \left[\underbrace{MA 109, 11}_{ux, uy, va, vy \text{ mate sense}} \right]$$

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Lanchy- Riemann

Theorem 1 (CR equations)

Let $f: \Omega \to \mathbb{C}$ be differentiable at $\underline{\underline{a point}} \ z_0 \in \Omega$. Let $z_0 = x_0 + \iota y_0$.

Then, we have

$$\underline{\underline{u}}_{x}(x_{0}, y_{0}) = \underline{v}_{y}(x_{0}, y_{0}) \text{ and } \underline{\underline{u}}_{y}(x_{0}, y_{0}) = -\underline{v}_{x}(x_{0}, y_{0}).$$

Moreover, we have

Existence of u_x, u_y, v_x, v_y is part of the theorem.

Note the subscript is x for both in the above. Also note that all the equalities are only at the point z_0 . In particular, we are only assuming differentiability at z_0 .

f(2) = Z = x+iy to see what the agus shoul

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Converse? What is the converse? Is it true?

Nol

No. The converse is not true.

An example for you to check is

he converse? Is it true? Converse
$$N$$
 not true.

The point (x_0, y_0) to check is

$$f(z) := \begin{cases} \frac{\overline{z}^2}{z} & z \neq 0, \\ 0 & z = 0. \end{cases}$$

of the point (x_0, y_0) and $(x_0, y_0$

Check that u and v satisfy the CR equations at (0,0) but f is not differentiable at $0 + 0\iota$. (Page 23 of slides.)

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We recall MA 105 now.

Definition 6 (Total derivative)

If $f:\Omega\to\mathbb{C}$ is a function, we may view it as a function

$$f:\Omega o\mathbb{R}^2.$$

Recall that f is said to be real differentiable at $(x_0, y_0) \in \Omega \subset \mathbb{R}^2$ if there exits a 2×2 real matrix A such that

$$\lim_{(h,k)\to(0,0)} \frac{\left\| f(x_0+h,y_0+k) - f(x_0,y_0) - A\begin{bmatrix} h \\ k \end{bmatrix} \right\|}{\|(h,k)\|} = 0.$$

The matrix A was called the total derivative of f at (x_0, y_0) .

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Theorem 2

If f is (complex) differentiable at a point $z_0 = x_0 + \iota y_0$, then f is real differentiable at (x_0, y_0) .

Once again, this is only talking about differentiability at a point. The converse is again not true.

Take the example $f(z) = \bar{z}$. Thus, we have seen two sufficient conditions for complex differentiability so far. Neither is individually sufficient. However, together, they are.

Theorem 3

Let $f: \Omega \to \mathbb{C}$ be a function and let $z_0 = x_0 + \iota y_0 \in \Omega$. If the CR equations hold at the point (x_0, y_0) and if f is real differentiable at the point (x_0, y_0) , then f is complex differentiable at the point z_0 .

(CR + RD)
$$\Rightarrow$$
 CD

Recall from MA 109, III:

Jet $f: \mathcal{Q} \rightarrow \mathbb{R}^2$ is a function set:

 $f: (u,v)$

Un, Uy, v_x , v_y are continuous on \mathcal{Q}_1

then f is real diff. on \mathcal{Q}_2 .

f: s2 - R2, then fx, fy, etc. are meaningless.

Definition 7 (Harmonic functions)

Let $u:\Omega \to \mathbb{R}^p$ be a twice continuously differentiable function. uis said to be *harmonic* if $u_{xx} + u_{yy} = 0$.

Proposition 1

The real and imaginary parts of a holomorphic function are (Ux = Vy (Uy = - Vx (Uy = - Vxy)

conjugate of u if $f = u + \iota v$ is holomorphic on Ω .

If v is a harmonic conjugate of u, then -u is a harmonic conjugate of v.

Check the second last slide of this lecture to find the algorithm for finding a harmonic conjugate.

Harmonie Conjugate need not exist.

Example. Consider S2 = 12 - 510, 033 and U: SZ - R defined as $u(x, y) = \frac{1}{2} \log (x^2 + y^2).$

> u had a harmonic conjugate v, then $\nabla_{\mathbf{y}}(x,y) = \frac{\mathbf{x}}{\mathbf{x}^2 + \mathbf{y}^2}$ and $\nabla_{\mathbf{x}}(x,y) = -\frac{\mathbf{y}}{\mathbf{x}^2 + \mathbf{y}^2}$.

But 7 v: 12 - R s.t. $\nabla v = \left(\frac{-y}{y^2 + y^2}, \frac{x}{x^2 + y^2} \right).$



Claim 1. Arbitrary union of open sets is open.

Proof. Let $\{U_i: i \in I\}$ be a collection of open sets.

Define $U:=\bigcup_{i \in I} U_i$ $= \{x: x \in U_i \text{ for some } i \in I\}$.

IS: U is open.

Proof

Let $z \in U$ be arbitrary.

Then, $\exists i_0 \in U$ s.t. $z \in U_{i_0}$.

Since U_{i_0} is open, $\exists \delta > 0$ s.t.

 $B_{\delta}(x) \subseteq U_{i_{\bullet}}$

But Vio \subseteq U. Thur, $B_5(a) \subseteq U$.

Thus, U is open. 13

Claim? Finite intersection of open sets is open.

Boof. It suffice to prove that intersection of two open sets is open.

A, ..., An - open

(A, nAz), Az, ..., An - open

A, nAz nAz, ..., An - open

W

Kin ... n An -sopon

let Us and Us be open and n ∈ U, nUz.

Let Us and Us be open and $2c \in U_1 \cap U_2$. $3\delta_2 > 0$ s.t. $B\delta_1(x) \subseteq U_1$ and $B\delta_2(x) \subseteq U_2$. Pick S := min(S1, S2) 70. Then, $B_{\delta}(n) \subset B_{\delta_{1}}(n) \subset U_{1}$ and $B_{\delta}(n) \subseteq B_{\delta_2}(n) \subseteq U_2.$ $\beta \delta(n) \subseteq (U_1 \cap U_2).$ a

"Pual" stadements for closed sets.

U1, U2 - soper You can say: U, U U2 and U, OU2 are open U1, V2,..., Un →open ⇒ U1 v ··· v Un & v1 n···n Un are open. $U_1, U_2, U_3, \dots \rightarrow \text{open} \Rightarrow \bigcup_{i=1}^{\infty} U_i$ is open but $\bigcap_{i=1}^{\infty} U_i$ may

 $C - \left(\bigcup_{i \in I} U_i\right) = \bigcap_{i \in I} \left(C - U_i\right) \left[\bigcup_{i := B_{V_i}(o)} \bigcup_{i \in I} B_{V_i}(o)\right]$ $Closed \iff Compkenent is open. i \in N \qquad for all indications open. open.$

Recap Page 13

Lecture 3: Power Series

Definition 8 (Convergence of series)

A series of the form

$$\longrightarrow \sum_{n=0}^{\infty} a_n$$

of complex numbers is said to converge if the sequence of partial sums

$$s_n = \sum_{k=0}^n a_k$$

converges (to a finite complex number).

The sequence of partial sums is just the following sequence:

$$\underline{a_0}, a_0 + a_1, \underline{a_0} + a_1 + \underline{a_2}, \dots$$

"Divergent" is simply used to mean "not convergent."

Check that $\sum (-1)^n$ and $\sum n$ both diverge.

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Lecture 3: Power Series

Definition 9 (limsup)

Given a sequence (x_n) of real numbers, we may define a new sequence (y_n) as

$$y_n=\sup\{x_m:m\geq n\}.$$

The limit of this sequence always exists and we define

$$\limsup_{n\to\infty} x_n = \lim_{n\to\infty} y_n.$$

Remark 2

Each y_n might be ∞ . That is allowed.

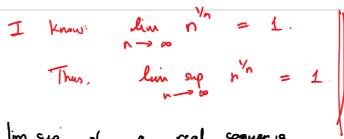
The limsup might be $\pm \infty$. This is also allowed.

Each y_n might be ∞ . That is allowed.

The limsup might be $\pm \infty$. This is also allowed.

If $\lim x_n$ itself exists, then it equals the $\lim \sup$ as well.

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Lecture 3: Power Series

We will be interested in discussing radius of convergence of *power* series. We all know what that is. It is a series of the form

$$\sum_{n=0}^{\infty} a_n (z-z_0)^n \qquad (*)$$

where $z_0 \in \mathbb{C}$ and each $a_n \in \mathbb{C}$.

What is the radius of convergence, though? (The definition, that is.)

Theorem 4 (Radius of convergence)

Given any power series as (*), there exists $R \in [0, \infty]$ such that

- (*) converges for any z with $|z-z_0| < R$, and
- (*) diverges for any z with $|z-z_0|>R$.

cirle,

This R is called the radius of convergence.

Note the brackets.

La may converge

for Some

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may divege

 $\sum_{n=1}^{\infty} \frac{z^n}{n} \sim \Re(z) = 1$ at -1: con verges at 1: diverges for all th |z| = 1

Lecture 3: Power Series

We would now like to be able to calculate the radius of convergence.

Theorem 5 (Root test)

Let (*) be as earlier. Define

$$\alpha = \limsup_{n \to \infty} \sqrt[n]{|a_n|}.$$

ALWAYS WORKS.

Then, $R = \alpha^{-1}$ is the radius of convergence.

This test always works. We had no assumptions of any kind on (*). Note that $^{-1}$.

If $\alpha=0$, then $R=\infty$ and vice-versa.

then
$$K = \infty$$
 and vice-versa.

$$\sum_{n=1}^{\infty} \sum_{n=1}^{\infty} \sum_{n=1}^{\infty$$

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Note: limit rules of t, o, () do not apply to limsup.

limsup (an +bn) < limsup (an) + limsup(bn)

 k_{NOW} $k_{N\rightarrow \infty}$ $k_{N\rightarrow \infty}$ $k_{N\rightarrow \infty}$ $k_{N\rightarrow \infty}$ $k_{N\rightarrow \infty}$ $k_{N\rightarrow \infty}$ $k_{N\rightarrow \infty}$

 $\lim_{N \to \infty} \left(\frac{1}{N} \right)^{\gamma_N} = \frac{1}{N} = \frac{1}{N} = \frac{1}{N} = \frac{1}{N}$

Lecture 3: Power Series

We have another test. This is simpler (to calculate) but mightn't always work.

Theorem 6 (Ratio test)

Let (*) be as earlier.

Assume that the limit

$$R = \lim_{n \to \infty} \left| \frac{a_n}{a_{n+1}} \right| \qquad \text{an apply to}$$

$$\geq \frac{2^{\nu}}{n}$$

exists. (Possibly as ∞ .)

Then, R is the radius of convergence.

 $\frac{1}{2^{n}}$ $\frac{1}{(n+1)!}$ $\frac{1}{(n+1)!}$

Note that here we assume that the limit does exist. This may not always be true.

Note that I'm not taking any inverse here but also note the way the ratio is taken. We have a_n/a_{n+1} .

Note that I'm not taking any inverse here but also note the way the ratio is taken. We have a_n/a_{n+1} .

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 $f(2) = \sum_{n=1}^{\infty} \frac{z^n}{n^2} \cdot \text{ Then, } f'(2) = \sum_{n=1}^{\infty} \frac{z^{n-1}}{n}$ $G_{R} \cdot C = 1$ $G_{R} \cdot C = 1$ Take

Lecture 3: Power Series

Differentiability of power series is what one should expect.

Theorem 7 (Differentiability)

Let $\sum_{n=0}^{\infty} a_n z^n$ be a power series with radius of convergence R > 0. On the open disc of radius R, let f(z) denote this sum. Then, on this disc, we have

$$f'(z) = \sum_{n=1}^{\infty} n \underbrace{a_n z^{n-1}}_{\underline{\underline{a_n}}}.$$

Note that this is again a power series with the same radius of convergence. Thus, we may repeat the process indefinitely. In other words, power series are infinite differentiable.

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(Yn) nzo Le a real Consider E := { limite of all possible convergent subsequences} & IRU(±003).

Then, lim sup xn = sup E.

Lecture 4: Exponential function

I shall just recall the facts from the lecture.

Definition 10 (Exponential function)

The power series

oitor

$$\sum_{n=0}^{\infty} \frac{z^n}{n!}$$

converges on all of \mathbb{C} . This sum is denoted by $\exp(z)$.

Theorem 8 (Facts)

- $\exp(z) \cdot \exp(-z) = 1$ for all $z \in \mathbb{C}$.
- \bigcirc exp(z) is always nonzero.

Lecture 4: Exponential function

Now, we some "converse" facts.

Theorem 9 (Characterisations)

- If f'(z) = bf(z), then $f(z) = a \exp(bz)$ for some $a, b \in \mathbb{C}$,
- ② If f' = f and f(0) = 1, then $f(z) = \exp(z)$.

Theorem 10 (Final fact)

Let $z, w \in \mathbb{C}$, then

$$\exp(z+w)=\exp(z)\cdot\exp(w).$$

exp: C --- Cx is a group homomorphism. (190)

Lecture 4: Exponential function

Definition 11 (Domain)

A subset $\Omega\subset\mathbb{C}$ is said to be a *domain* if it is open and path-connected.

We had one very nice result on the zeroes of a analytic functions.

Theorem 11 (Zeroes are isolated)

Let Ω be a domain and $f:\Omega\to\mathbb{C}$ be a non-constant analytic function. Let $z_0 \in \Omega$ be such that $f(z_0) = 0$. Then, there exists $\delta > 0$ such that f has no other zero in $B_{\delta}(z_0)$.



The above is saying that around every zero of f, we can draw a (sufficiently small) circle such that f has no other zero in that disc. This is the same as saying that the set of zeroes is discrete.

Logarithm

We discuss logarithm a bit.

Definition 14 (Branch of the logarithm)

Let $\Omega \subset \mathbb{C}$ be a domain. Let $f : \Omega \to \mathbb{C}$ be a continuous function such that

$$\exp(f(z)) = z$$
, for all $z \in \Omega$.

Then, f is called a branch of the logarithm.

Theorem 21 (Uniqueness of branches)

Assume that $f, g: \Omega \to \mathbb{C}$ are two branches of the logarithm. Then, f - g is a constant function. Moreover, this constant is an integer multiple of $2\pi\iota$.

The last theorem also assumed that Ω is a domain.

given domain. Branch of 109 may not exit Aryaman Maithani

CY. on C. branch As, there no branch on