

Language — C++

Classes — controller

elevator (elevator FSM + Door FSM + IR sensor)

memory (use std::vector?)

floor lights

Global vars — fire mode

current elevator floor

Maybe add graphics?

→ mouse over elevator when open to simulate
"people" walking in/out

→ states outputs in view

→ up down button

→ add 2 elevators?

→ SDL libs

Controller

States

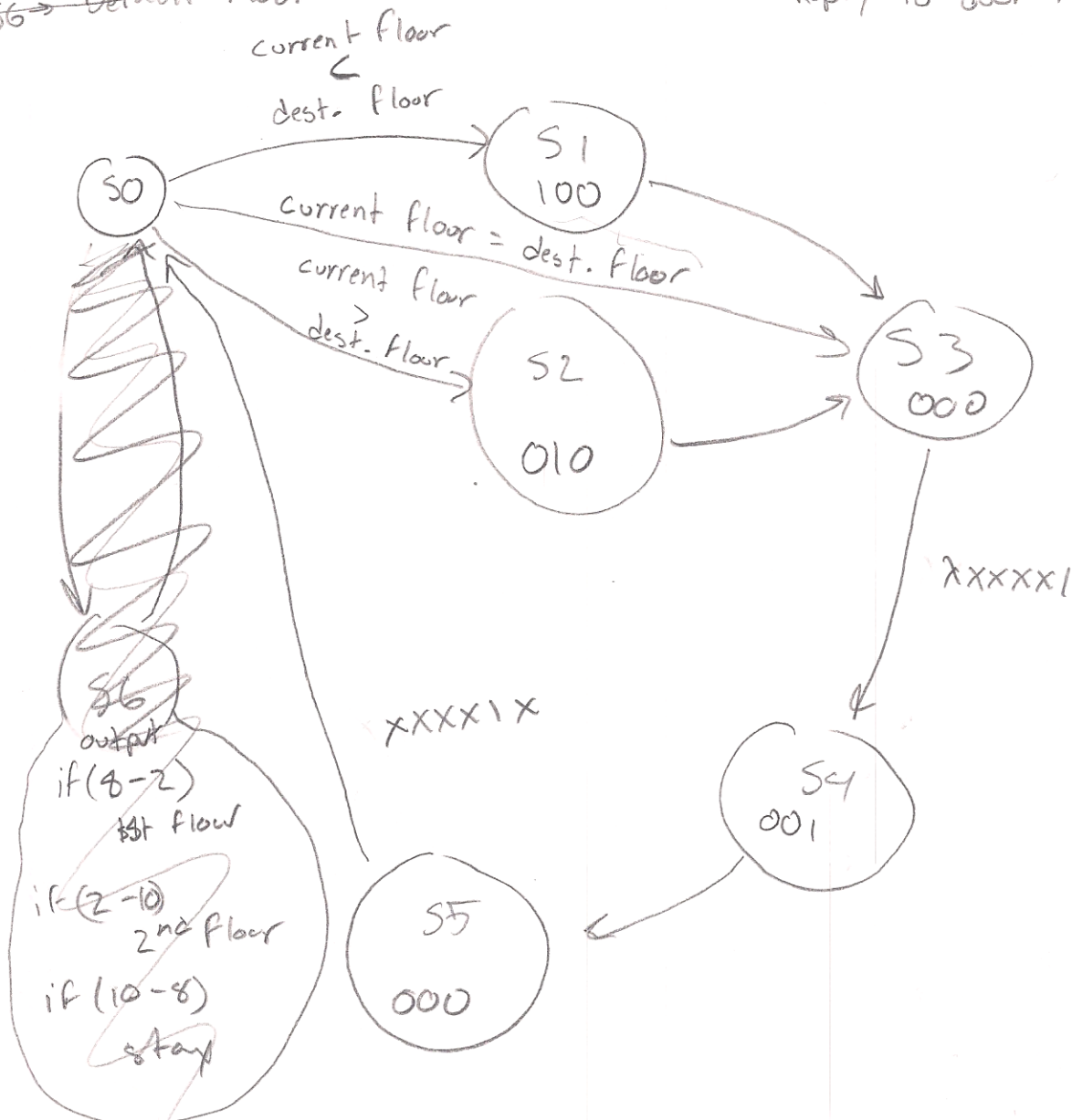
- S0 → Ask memory black box
- S1 → Elevator up -
- S2 → Elevator down -
- S3 → wait for latch -
- S4 → reply to door FSM -
- S5 → wait for door closed -
- S6 → Default floor

Inputs

- floor to go next (2 bits)
- ~~Elevator reached signal (1 bit)~~
- what floor the elevator (2 bits)
- door closed (1 bit)
- latch (1 bit)

Outputs

- Elevator up/down (2 bits)
- reply to door FSM (1 bit)



Elevator

States

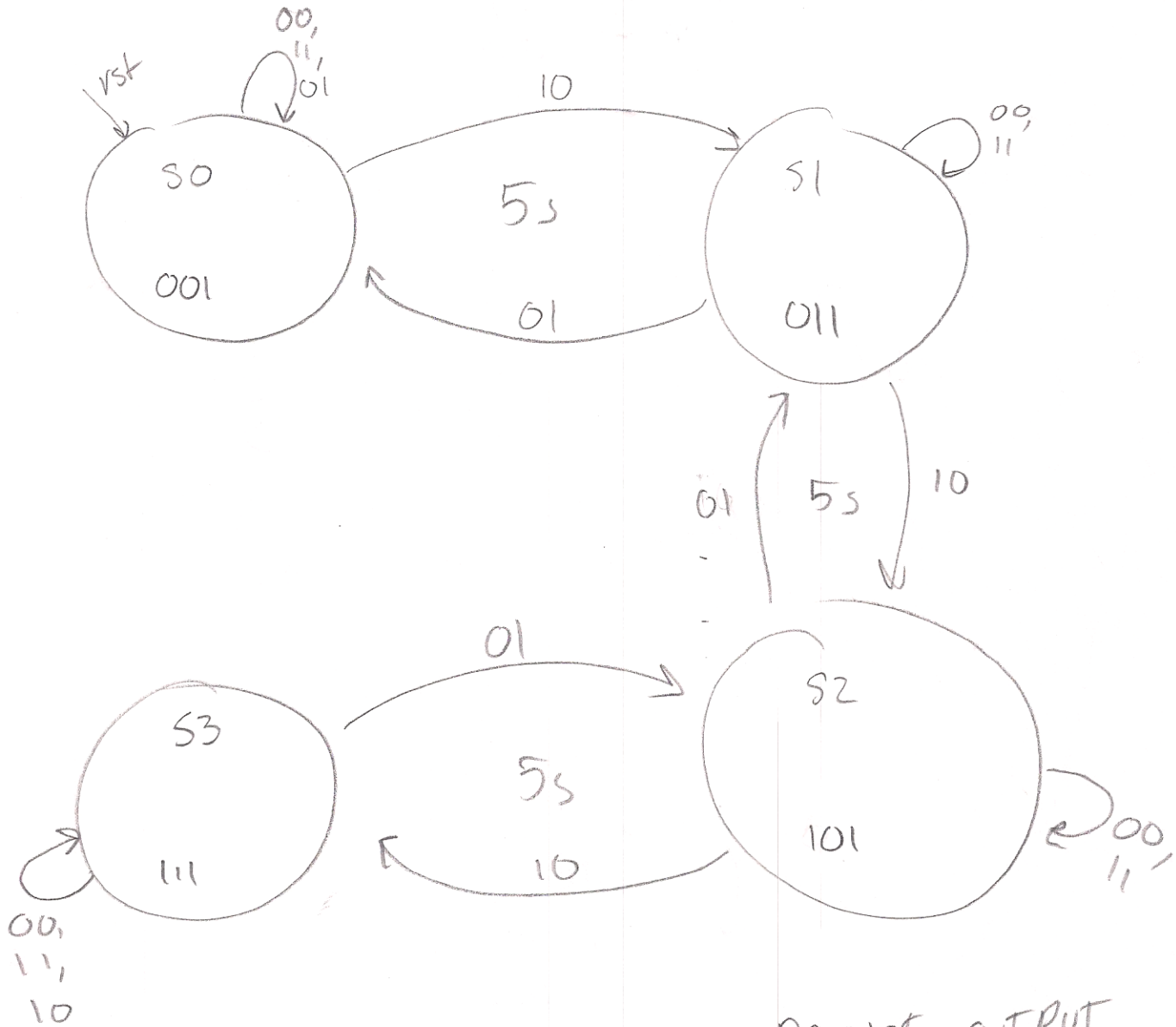
$S_0 \rightarrow 00 \rightarrow Gf$
 $S_1 \rightarrow 01 \rightarrow 1f$
 $S_2 \rightarrow 10 \rightarrow 2f$
 $S_3 \rightarrow 11 \rightarrow 3f$

Input

$00 \rightarrow$
 $01 \rightarrow wait$
 $10 \rightarrow Gdown$
 $11 \rightarrow Gup$
 $11 \rightarrow dont care$

Output

Current floor (2 bits)
start door FSM (1 bit)



DO NOT OUTPUT
FO FLOOR FSM
GO THROUGH CONTROLLER

Door FSM

SOIC

States

S0 → door closed

S1 → latching (1s) / output sound

S2 → open door

S3 → wait for IR sensor

S4 → close door

Inputs

start door FSM (1bit)

controller open door (1bit)

IR sensor end (1bit)

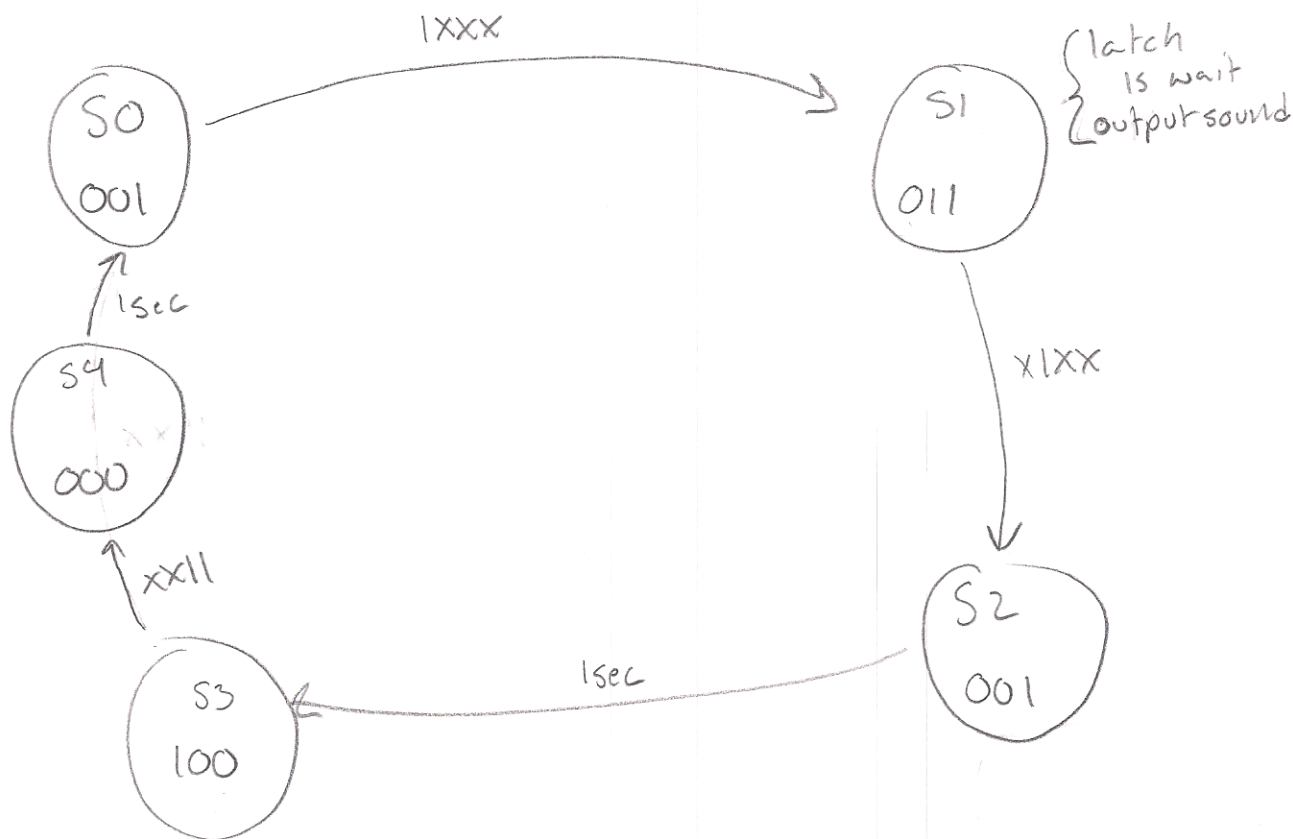
(combine!) Door close (IR sensor) (1bit)

Outputs

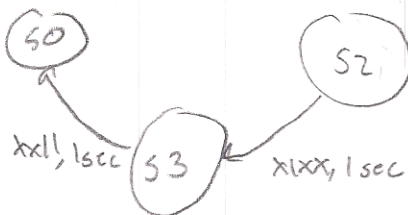
IR sensor start (1bit)

sound (1bit)

door closed (1bit)



Combine S2, S3, S4 to



IR sensor

states

S0 → Ist (IR sensor off)

S1 → Person walking through

S2 → No person walking through

S3 → Close door

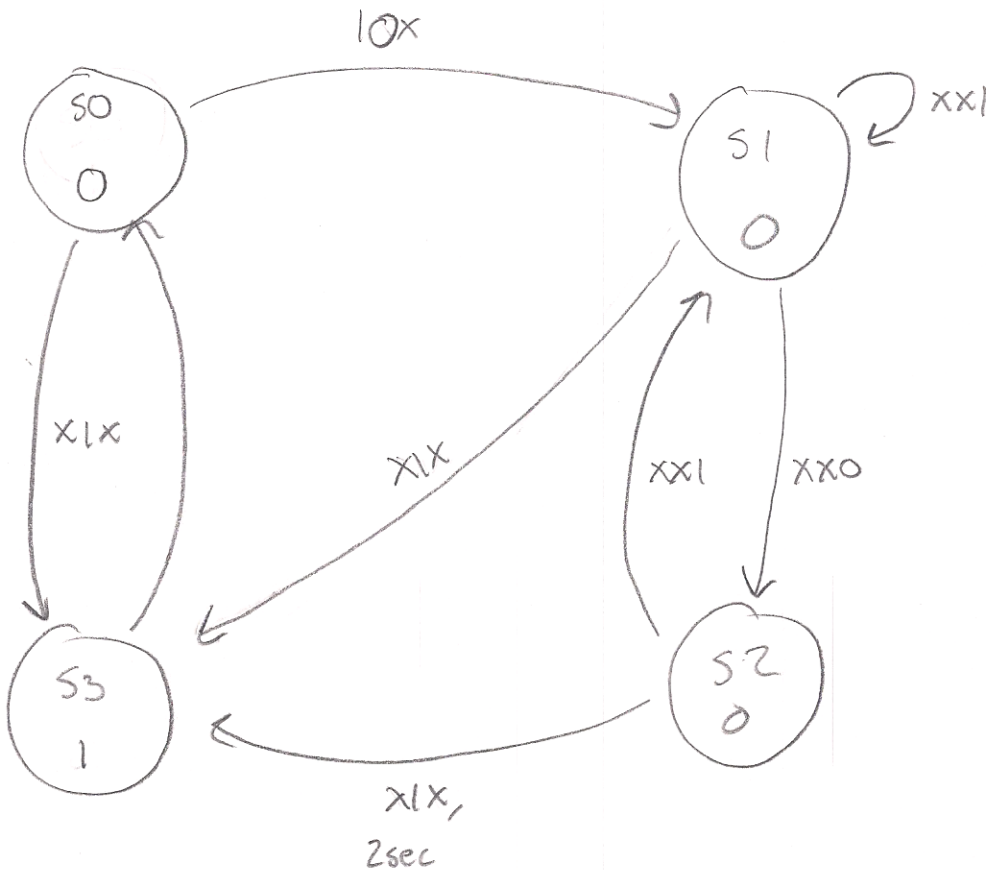
Inputs

start IR
fire state
IR on

SFI

output

Door close



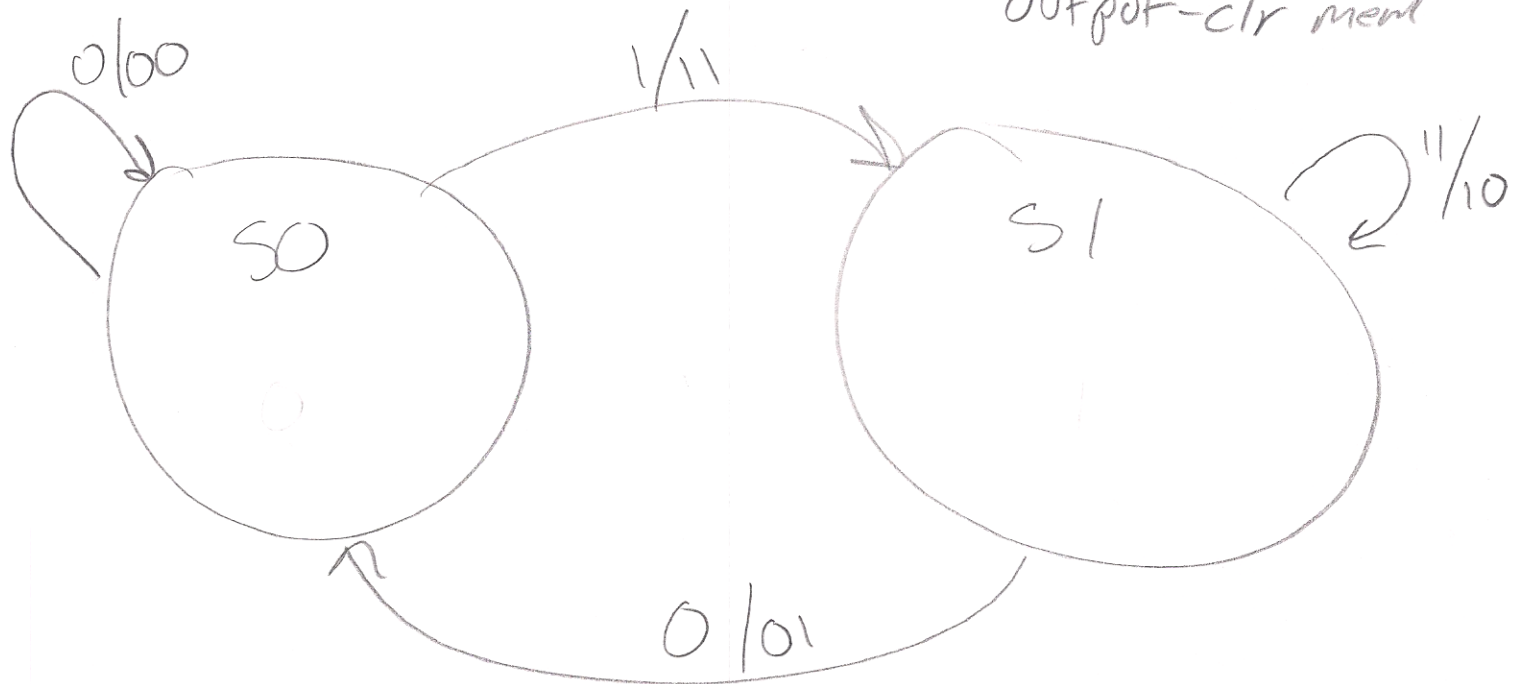
FIRE

Input - Fire key inserted

Output -

In Panic mode

output - clr mem



If key was disconnected ^{after being 1} (Input 0) reset memory and go to default

S0 → Not in fire mode

S1 → In fire mode

Controller (FIRE)

S0 → paused state (rst state)

S1 → Go up

S2 → Go down

S3 → wait for latch

S4 → wait for door open button

S5 → wait for door closed button

same inputs as
controller

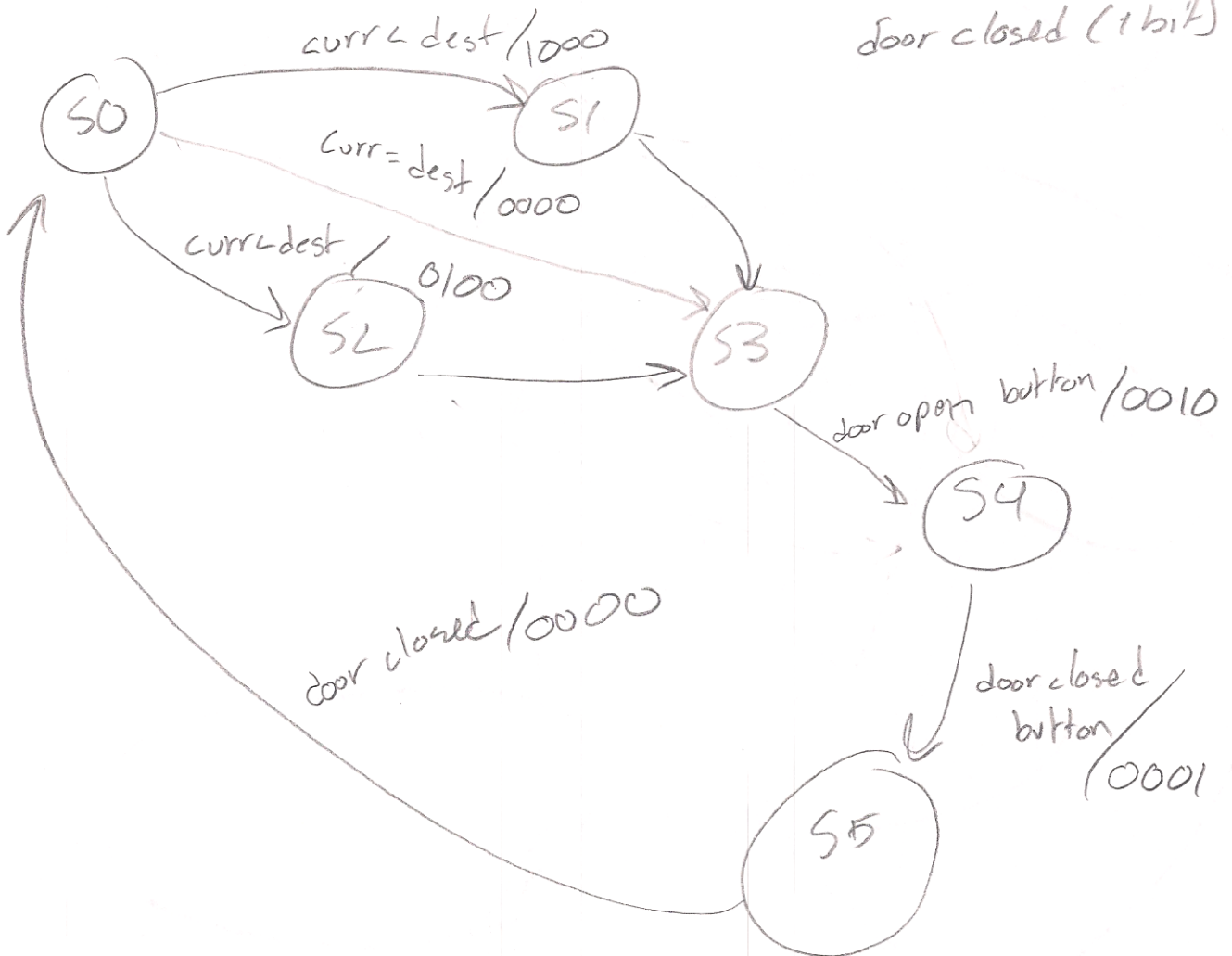
+ door open

outputs

elevator up/down (2 bits)

door open (1 bit)

door closed (1 bit)



Door FSM (FIRE)

S0 → door closed

S1 → latch/sound

S2 → ~~door open~~
open door

S3 → ~~door closed~~
close door

Input

start (1bit)

open door (1bit)

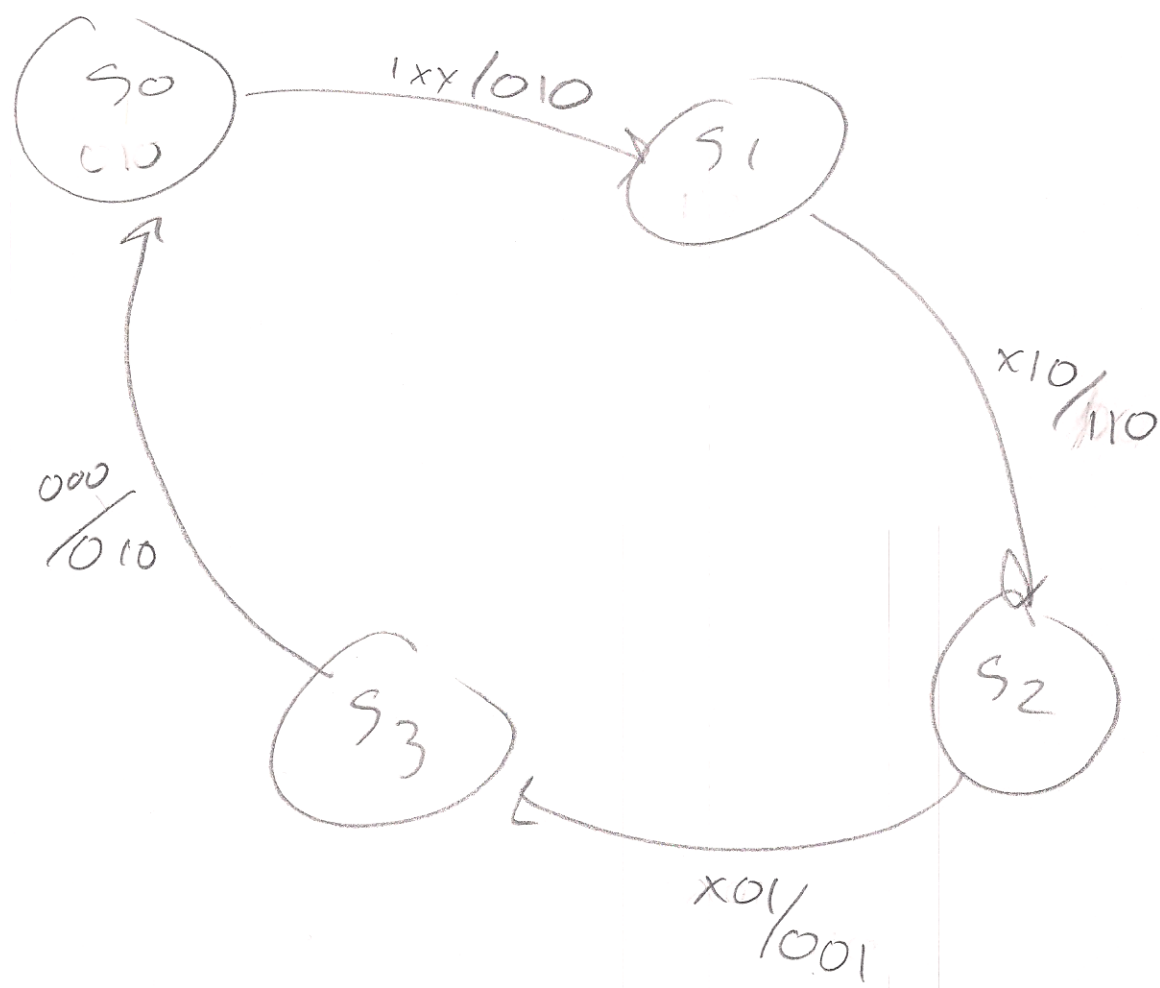
close door (1bit)

Outputs

sound

door closed

door open



MEMORY - NO FSM (black box)



clear mem - 1 bit
Input \Rightarrow Current floor - 2 bits
direction - 1 bit

output \Rightarrow Next floor to stop at

Input \Rightarrow buttons from each floor

IT'S A QUEUE

FIRST IN - FIRST OUT (FIFO)

\rightarrow if no next floor then

if ($8_{pin} = 2_{pin}$)
1st floor

if ($2_{pin} = 10_{pin}$)
2nd floor

if ($10_{pin} = 8_{pin}$)
stay at current floor

FLOOR LIGHTS - NO FSM (black box)

FSM seems to difficult

UP				DOWN			
X	X	X	X	X	X	X	X
6	1	2	3	6	1	2	3

Floor 6

up on \rightarrow x20 bitor 10000000

~~down on \rightarrow x20 bitor~~ cant go down

up off \rightarrow x20 bitand 0111,1111

Floor 1

up on \rightarrow x20 bitor 01000000

down on \rightarrow x20 bitor 0000,0100

up off \rightarrow x20 bitand 1011,1111

down off \rightarrow x20 bitand 1111,1011

12 operations

Inputs

up/down (from controller)

current floor (from elevator)

pass function object

that takes

parameter of

x20 and returns

the bitset operation

???