# Lost Hope

Objective detection with the Arduino Nano 33 BLE w/ OV7675 camera



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## Introduction

 The goal of the project was to train the model (Arduino Nano 33 ble) to detect a specific target using the Arduino camera.

 The group chose the target "banana" and trained the model to detect a banana when presented to the camera.

- Online images of bananas and real bananas were used to test the accuracy of model.

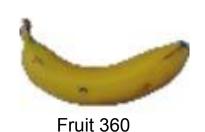




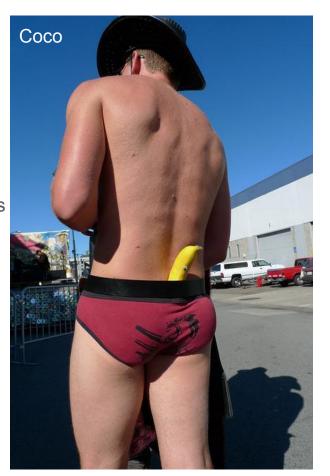


## **Data Collection**

- Fruits 360 Dataset (318 banana images)
- Coco 2017 Dataset (1618 banana / 39,347 not banana images)
- Custom Dataset (27,283 banana images)
  - Recorded ~6min video of bananas in various environments
  - Resized to 96x96 pixels
  - Split into individual frames
- Total Banana: 29,219
- Total Not Banana: 30,347





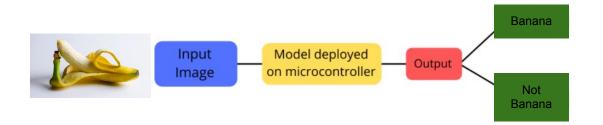


## **Training**

- mlcommons training script (visual wake words)
  - Mobile net v1
  - Google Colab
- Training/Validation



epoch	loss	accuracy	val_loss	val_accuracy
15/100	0.0297	0.9954	0.6286	0.7919
100/100	0.0040	0.9999	2.5840	0.7280



#### Microcontroller

- Code based off of Harvard TinyML Person Detector Code
- Works with RGB and Grayscale
- Image is sent 5 times per second
- Model is run ~once a second

	Bit[7:2]:	Reserved	
	Bit[1]:	RGB444 enable, effective only when COM15[4] is it	
		0: Disable	
RGB444		1: Enable /	
	Bit[0]:	RGB444 word format	
	5000	0: xR GB	
		1: RG Bx	
DOM	December		



# Video



#### Conclusion

- Issues
  - Hard to find starting point
  - TensorFlowLite version was outdated
  - More data needed (model was overfitting)
  - Timing the upload with the reset button
- Improvement ideas
  - More training data
  - Better accuracy with color (bananas are yellow)
  - More fruit models
- Real world use cases
  - Groceries Notifier
  - Ripeness Detection (for grocery store restocking)



## Questions?



How many Banana did you see in our slides?

No bananas were harmed during the completion of this project.