Y-Bus Matr Real Part:							
	-0.4221	0	-0.4221	0	0	0	0 🗸
-0.4221	1.2663	-0.4221	0	-0.4221	0	0	0 🗸
0	-0.4221	1.2663	0	-0.4221	-0.4221	0	0 🗸
	0	0	0.8442	0	0	-0.4221	0 🗸
0 0	-0.4221	-0.4221	0	73.8936	0	0	-73.0494 🗹
0 0	0	-0.4221	0	0	0.9178	0	0 Ľ
-0.4957 0	0	0	-0.4221	0	0	0.8442	-0.4221 ∠
0 0	0	0	0	-73.0494	0	-0.4221	73.4715 🗹
0 0		0		0			
0.4957	0	0	O	O	-0.4937	O	0 -
Imaginary							
0	1.3766	0	1.3/66	0	0	0	0 k
1.3766	-4.1288	1.3766	0	1.3766	0	0	0 Ľ
0 0	-4.1288 1.3766		0			0	0 V
0 0 0 1.3766		-4.1288	0	1.3766	1.3766		0 L
0 0 0 1.3766 0	1.3766	-4.1288 0	0 -2.7526	1.3766	1.3766	0	0 L
0 0 0 1.3766 0 0	1.3766	-4.1288 0	0 -2.7526 0	1.3766	1.3766	0 1.3766 0	0 ✔ 0 ✔ 101.0258 ✔
0 0 0 1.3766 0 0	1.3766 0 1.3766	-4.1288 0 1.3766	0 -2.7526 0	1.3766 0 -103.7784	1.3766 0 0 -11.4223	0 1.3766 0	0 ✔ 0 ✔ 101.0258 ✔
0 0 0 1.3766 0 0 0	1.3766 0 1.3766 0	-4.1288 0 1.3766 1.3766	0 -2.7526 0 0 1.3766	1.3766 0 -103.7784 0	1.3766 0 0 -11.4223	0 1.3766 0 0 -2.7526	0 \(\nu \) 0 \(\nu \) 101.0258 \(\nu \) 0 \(\nu \)
0 0 0 1.3766 0 0 0 0 10.0460	1.3766 0 1.3766 0	-4.1288 0 1.3766 1.3766	0 -2.7526 0 0 1.3766	1.3766 0 -103.7784 0 0	1.3766 0 0 -11.4223	0 1.3766 0 0 -2.7526 1.3766	0 \(\vec{\vec{\vec{\vec{\vec{\vec{\vec{

=== Newton-Raphson Load Flow Solution ===

Jacobian Matrix at First Iteration:

Size: 14 x 14

Columns 1 through 11

4.1298	-1.3766	0	-1.3766	0	0	0	0 🗸
1.2663	0 -0.4221						
-1.3766	4.1298	0	-1.3766	-1.3766	0	0	0 🗸

-0.4221 0 -0.4221								
-0				0	^	1 2766	0	0 Ľ
0	0	0	2./532	U	U	-1.3/66	0	0 2
			0	102 7700	0	0	101 0050	0.1
				103.7790	U	U	-101.0258	0 🗸
-0		0 73			11 1006	0	0	10 0160 /
			0	0	11.4226	Ü	0	-10.0460 ∠
0		0						
	0		-1.3766	0	0	2.7532	-1.3766	0 🗸
0	-0.4221	0						
	0		0	-101.0258	0	-1.3766	102.4024	0 Ľ
0		-73.0494						
	0	0	0	0	-10.0460	0	0	10.0460 🗸
0	0	0						
	-1.2663	0.4221	0	0.4221	0	0	0	0 🖍
4.	1279	0 -1.	3766					
	0	0	-0.8442	0	0	0.4221	0	0 🗸
0	2.7519	0						
	0.4221	0.4221	0	-73.8936	0	0	73.0494	0 🗹
-1	.3766	0 103	3.7777					
	0	0.4221	0	0	-0.9178	0	0	0.4957 ≰
0	0	0						
	0	0	0.4221	0	0	-0.8442	0.4221	0 🗸
0	-1.3766	0						
	0	0	0	73.0494	0	0.4221	-73.4715	0 🗸
0	0	-101.0258						
Columns 12 through 14								

Iteration 1: Max mismatch = 0.246600
Iteration 2: Max mismatch = 0.065825
Iteration 3: Max mismatch = 0.001488
Converged in 4 iterations

=== Final Load Flow Results ===

Bus Voltage Angle P_gen Q_gen P_load Q_load No. (p.u.) (deg) (MW) (Mvar) (MW) (Mvar)

1	1.0000	0.00	0.00	0.00	0.00	0.00
2	0.9775	12.85	0.00	0.00	0.20	0.13
3	1.0000	23.34	25.00	0.00	0.34	0.21
4	0.9826	4.87	0.00	0.00	0.20	0.13
5	0.9759	15.30	0.00	0.00	0.82	0.51
6	1.0031	32.56	0.00	0.00	0.20	0.13
7	0.9735	9.94	0.00	0.00	0.54	0.34
8	0.9755	15.24	0.00	0.00	0.67	0.41
9	1.0000	33.88	25.00	0.00	1.97	1.22

=== Line Flow Results ===

From	n	To P_flow	Q_flow	S_flow
Bus	Bus	(MW)	(Mvar)	(MVA)
1	2	-27.95	15.64	32.03
2	3	-24.74	6.74	25.64
1	4	-10.60	6.40	12.38
4	7	-11.11	5.32	12.32
7	8	-11.98	4.00	12.63
2	5	-5.50	2.05	5.87
3	5	20.22	-1.13	20.25
3	6	-21.70	8.15	23.18
5	8	12.99	-2.49	13.23
6	9	-23.00	4.48	23.43

=== System Summary ===

Total Active Power Loss: 6.50 MW
Total Reactive Power Loss: 21.64 Mvar

Number of Iterations: 4

- $[\checkmark]$ Bus Voltage Magnitudes match ETAP values
- $[\checkmark]$ Bus Voltage Angles match ETAP values
- $[\checkmark]$ Active Power Generation/Load match ETAP
- $[\checkmark]$ Reactive Power Generation/Load match ETAP
- $[\ensuremath{\checkmark}]$ Apparent Power per bus verified
- $\left[oldsymbol{ \checkmark }
 ight]$ Active and Reactive Line Flows validated
- $[\checkmark]$ Total Active Power Loss within tolerance
- $[\checkmark]$ Total Reactive Power Loss within tolerance
- $[\checkmark]$ Convergence achieved within 4 iterations
- $[\checkmark]$ Results plotted with GUI and match report visuals
- $[{m {\it I}}]$ Final values confirmed with ETAP load flow report

=== Comparison with ETAP Results === ETAP Total Losses: 6.28 MW, 20.90 Mvar MATLAB Results: 6.50 MW, 21.64 Mvar

ETAP Iterations: 1
MATLAB Iterations: 4

=== Full-Screen Load Flow GUI Rendered ===

=== Updated GUI with Actual Power and Voltage Values Rendered === $\gt\gt$