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Theory (1)

1.1 Permutations

1.1.1 Derangements

Permutations of a set such that none of the elements appear in their original position.

$$D(n) = (n-1)(D(n-1) + D(n-2))$$

$$nD(n-1) + (-1)^n = \left\lfloor \frac{n!}{e} \right\rfloor$$

1.1.2 Burnside's lemma

Given a group G of symmetries and a set X , the number of elements of X up to symmetry equals

$$\frac{1}{|G|} \sum_{g \in G} |X^g|,$$

where X^g are the elements fixed by g ($g.x = x$).

If $f(n)$ counts "configurations" (of some sort) of length n , we can ignore rotational symmetry using $G = \mathbb{Z}_n$ to get

$$g(n) = \frac{1}{n} \sum_{k=0}^{n-1} f(\gcd(n, k)) = \frac{1}{n} \sum_{k|n} f(k) \phi(n/k).$$

1.1.3 Partition function

Number of ways of writing n as a sum of positive integers, disregarding the order of the summands.

$$p(0) = 1, \quad p(n) = \sum_{k \in \mathbb{Z} \setminus \{0\}} (-1)^{k+1} p(n - k(3k-1)/2)$$

$$p(n) \sim 0.145/n \cdot \exp(2.56\sqrt{n})$$

1.1.4 Stirling numbers of the first kind

Number of permutations on n items with k cycles.

$$c(n, k) = c(n-1, k-1) + (n-1)c(n-1, k), \quad c(0, 0) = 1$$

$$\sum_{k=0}^n c(n, k) x^k = x(x+1) \dots (x+n-1)$$

$$c(8, k) =$$

$$8, 0, 5040, 13068, 13132, 6769, 1960, 322, 28, 1$$

$$c(n, 2) =$$

$$0, 0, 1, 3, 11, 50, 274, 1764, 13068, 109584, \dots$$

1.1.5 Eulerian numbers

Number of permutations $\pi \in S_n$ in which exactly k elements are greater than the previous element. k j :s s.t. $\pi(j) > \pi(j+1)$, $k+1$ j :s s.t. $\pi(j) \geq j$, k j :s s.t. $\pi(j) > j$.

$$E(n, k) = (n-k)E(n-1, k-1) + (k+1)E(n-1, k)$$

$$E(n, k) = \sum_{j=0}^k (-1)^j \binom{n+1}{j} (k+1-j)^n$$

$$E(n, 0) = E(n, n-1) = 1$$

1.1.6 Bell numbers

Total number of partitions of n distinct elements.

$$B(n) = 1, 1, 2, 5, 15, 52, 203, 877, 4140, 21147, \dots$$

For p prime,

$$B(p^m + n) \equiv mB(n) + B(n+1) \pmod{p}$$

1.1.7 Stirling numbers of the second kind

Partitions of n distinct elements into exactly k groups.

$$S(n, k) = S(n-1, k-1) + kS(n-1, k)$$

$$S(n, 1) = S(n, n) = 1$$

$$S(n, k) = \frac{1}{k!} \sum_{j=0}^k (-1)^{k-j} \binom{k}{j} j^n$$

1.1.8 Labeled unrooted trees

on n vertices: n^{n-2}

on k existing trees of size n_i :

$$n_1 n_2 \dots n_k n^{k-2}$$

with degrees d_i :

$$(n-2)! / ((d_1-1)! \dots (d_n-1)!)$$

1.1.9 Catalan numbers

$$C_n = \frac{1}{n+1} \binom{2n}{n} = \binom{2n}{n} - \binom{2n}{n+1} = \frac{(2n)!}{(n+1)!n!}$$

$$C_0 = 1, \quad C_{n+1} = \frac{2(2n+1)}{n+2} C_n, \quad C_{n+1} = \sum C_i C_{n-i}$$

$$C_n = 1, 1, 2, 5, 14, 42, 132, 429, 1430, 4862, 16796, 58786, \dots$$

- sub-diagonal monotone paths in an $n \times n$ grid.
- strings with n pairs of parenthesis, correctly nested.
- binary trees with $n+1$ leaves (0 or 2 children).
- ordered trees with $n+1$ vertices.
- ways a convex polygon with $n+2$ sides can be cut into triangles by connecting vertices with straight lines.
- permutations of $[n]$ with no 3-term increasing subseq.

1.1.10 Pick Theorem

S = area of polygon, I = Number of integer points inside, B = Number of integer points on boundary

$$I + B/2 - 1 = S$$

1.1.11 Bézout's identity

For $a \neq 0, b \neq 0$, then $d = \gcd(a, b)$ is the smallest positive integer for which there are integer solutions to

$$ax + by = d$$

If (x, y) is one solution, then all solutions are given by

$$\left(x + \frac{kb}{\gcd(a, b)}, y - \frac{ka}{\gcd(a, b)}\right), \quad k \in \mathbb{Z}$$

1.1.12 Pythagorean Triples

The Pythagorean triples are uniquely generated by

$$a = k \cdot (m^2 - n^2), \quad b = k \cdot (2mn), \quad c = k \cdot (m^2 + n^2),$$

with $m > n > 0, k > 0, m \perp n$, and either m or n even.

1.1.13 Equations

$$ax^2 + bx + c = 0 \Rightarrow x = \frac{-b \pm \sqrt{b^2 - 4ac}}{2a}$$

The extremum is given by $x = -b/2a$.

$$\begin{aligned} ax + by = e \\ cx + dy = f \end{aligned} \Rightarrow \begin{aligned} x &= \frac{ed - bf}{ad - bc} \\ y &= \frac{af - ec}{ad - bc} \end{aligned}$$

In general, given an equation $Ax = b$, the solution to a variable x_i is given by

$$x_i = \frac{\det A'_i}{\det A}$$

where A'_i is A with the i 'th column replaced by b .

1.1.14 Triangles

Side lengths: a, b, c

$$\text{Semiperimeter: } p = \frac{a + b + c}{2}$$

$$\text{Area: } A = \sqrt{p(p-a)(p-b)(p-c)}$$

$$\text{Circumradius: } R = \frac{abc}{4A}$$

$$\text{Inradius: } r = \frac{A}{p}$$

Length of median (divides triangle into two equal-area triangles):

$$m_a = \frac{1}{2}\sqrt{2b^2 + 2c^2 - a^2}$$

Length of bisector (divides angles in two):

$$s_a = \sqrt{bc \left[1 - \left(\frac{a}{b+c} \right)^2 \right]}$$

Law of sines:

$$\frac{\sin \alpha}{a} = \frac{\sin \beta}{b} = \frac{\sin \gamma}{c} = \frac{1}{2R}$$

Law of cosines:

$$a^2 = b^2 + c^2 - 2bc \cos \alpha$$

Law of tangents:

$$\frac{a+b}{a-b} = \frac{\tan \frac{\alpha+\beta}{2}}{\tan \frac{\alpha-\beta}{2}}$$

1.1.15 Trigonometry

$$\sin(v+w) = \sin v \cos w + \cos v \sin w$$

$$\cos(v+w) = \cos v \cos w - \sin v \sin w$$

$$\tan(v+w) = \frac{\tan v + \tan w}{1 - \tan v \tan w}$$

$$\sin v + \sin w = 2 \sin \frac{v+w}{2} \cos \frac{v-w}{2}$$

$$\cos v + \cos w = 2 \cos \frac{v+w}{2} \cos \frac{v-w}{2}$$

$$(V+W) \tan(v-w)/2 = (V-W) \tan(v+w)/2$$

where V, W are lengths of sides opposite angles v, w .

$$a \cos x + b \sin x = r \cos(x - \phi)$$

$$a \sin x + b \cos x = r \sin(x + \phi)$$

where $r = \sqrt{a^2 + b^2}, \phi = \text{atan2}(b, a)$.

1.1.16 Quadrilaterals

With side lengths a, b, c, d , diagonals e, f , diagonals angle θ , area A and magic flux $F = b^2 + d^2 - a^2 - c^2$:

$$4A = 2ef \cdot \sin \theta = F \tan \theta = \sqrt{4e^2 f^2 - F^2}$$

For cyclic quadrilaterals the sum of opposite angles is 180° , $ef = ac + bd$, and $A = \sqrt{(p-a)(p-b)(p-c)(p-d)}$.

1.1.17 Sums

$$1^2 + 2^2 + 3^2 + \dots + n^2 = \frac{n(2n+1)(n+1)}{6}$$

$$1^3 + 2^3 + 3^3 + \dots + n^3 = \frac{n^2(n+1)^2}{4}$$

$$1^4 + 2^4 + 3^4 + \dots + n^4 = \frac{n(n+1)(2n+1)(3n^2+3n-1)}{30}$$

1.1.18 Derivatives/Integrals

$$\frac{d}{dx} \arcsin x = \frac{1}{\sqrt{1-x^2}} \quad \frac{d}{dx} \arccos x = -\frac{1}{\sqrt{1-x^2}}$$

$$\frac{d}{dx} \tan x = 1 + \tan^2 x \quad \frac{d}{dx} \arctan x = \frac{1}{1+x^2}$$

Binomial distribution

First success distribution

The number of trials needed to get the first success in independent yes/no experiments, each with probability p is $\text{Fs}(p)$, $0 \leq p \leq 1$.

$$p(k) = p(1-p)^{k-1}, k = 1, 2, \dots$$

$$\mu = \frac{1}{p}, \sigma^2 = \frac{1-p}{p^2}$$

Poisson distribution

The number of events occurring in a fixed period of time t if these events occur with a known average rate κ and independently of the time since the last event is $\text{Po}(\lambda)$, $\lambda = t\kappa$.

$$p(k) = e^{-\lambda} \frac{\lambda^k}{k!}, k = 0, 1, 2, \dots$$

$$\mu = \lambda, \sigma^2 = \lambda$$

1.1.19 Continuous distributions

Uniform distribution

Exponential distribution

The time between events in a Poisson process is $\text{Exp}(\lambda)$, $\lambda > 0$.

$$f(x) = \begin{cases} \lambda e^{-\lambda x} & x \geq 0 \\ 0 & x < 0 \end{cases}$$

$$\mu = \frac{1}{\lambda}, \sigma^2 = \frac{1}{\lambda^2}$$

Normal distribution

Most real random values with mean μ and variance σ^2 are well described by $\mathcal{N}(\mu, \sigma^2)$, $\sigma > 0$.

$$f(x) = \frac{1}{\sqrt{2\pi\sigma^2}} e^{-\frac{(x-\mu)^2}{2\sigma^2}}$$

If $X_1 \sim \mathcal{N}(\mu_1, \sigma_1^2)$ and $X_2 \sim \mathcal{N}(\mu_2, \sigma_2^2)$ then

$$aX_1 + bX_2 + c \sim \mathcal{N}(\mu_1 + \mu_2 + c, a^2\sigma_1^2 + b^2\sigma_2^2)$$

1.2 Graph

Number of Spanning Trees Create an $N \times N$ matrix `mat`, and for each edge $a \rightarrow b \in G$, do `mat[a][b]--`, `mat[b][b]++` (and `mat[b][a]--`, `mat[a][a]++` if G is undirected). Remove the i th row and column and take the determinant; this yields the number of directed spanning trees rooted at i (if G is undirected, remove any row/column).

Erdős–Gallai theorem A simple graph with node degrees $d_1 \geq \dots \geq d_n$ exists iff $d_1 + \dots + d_n$ is even and for every $k = 1 \dots n$,

$$\sum_{i=1}^k d_i \leq k(k-1) + \sum_{i=k+1}^n \min(d_i, k).$$

Mirsky's Theorem Max length chain is equal to min partitioning into antichains. Max chain is height of poset.

Dilworth's Theorem Min partition into chains is equal to max length antichain. From poset create bipartite graph. Any edge from $v_i - v_j$ implies $LV_i - RV_j$. Let A be the set of vertices such that neither LV_i nor RV_i are in vertex cover. A is an antichain of size n -max matching. To get min partition into chains, take a vertex from left side, keep taking vertices till a matching exist. Consider this as a chain. Its size is n - max matching.

Combinatorial (2)

2.1 DP Optimizations

Quadrangle Inequality. f satisfies it if

$$\forall a \leq b \leq c \leq d, f(a, d) - f(a, c) \geq f(b, d) - f(b, c).$$

PointsOnBoundary.h

Description: given a polygon A in order, returns count of points(integer) on boundary Integer \rightarrow permutation can use a lookup table.

Time: $\mathcal{O}(n)$

ad93fa, 6 lines

```
int boundary(vector<pair<int,int>>&A){
    int ats=A.size();
    for(int i=0;i<A.size();i++){
        int dx=(A[i].first-A[(i+1)%A.size()].first);
        int dy=(A[i].second-A[(i+1)%A.size()].second);
        ats+=abs(__gcd(dx,dy))-1;
    }
    return ats;
}
```

1D-1D.h

Description: Applicable if $dp_i = \min_{j>i}(dp_j + \text{cost}(i, j))$ s.t. $opt_i \leq opt_j$ when $i \leq j$ (which holds if quadrangle)

Time: $\mathcal{O}(n \log n)$

d76777, 17 lines

```
#define until first

#define opt second
ll dp[100000];ll cost(int i,int j){
    return dp[j]/*+cost to jump from i to j*/;
}void solve(int n){dp[n]=0;vector<PII>v;
v EB(n-1,n);
for(int i=n-1,ipos=0;i>=1;i--){
```

```
while(ipos+1<SZ(v)&&i<=v[ipos+1].until)ipos
    ++;
dp[i]=cost(i,v[ipos].opt);
while(v.back().until<i&&cost(v.back().until,
    i)<=cost(v.back().until,v.back().opt)){
v.pop_back();}
int l=1,r=min(i-1,v.back().until);
while(l<=r){int mid=(l+r)/2;
if(cost(mid,i)<=cost(mid,v.back().opt)){
l=mid+1;}else{r=mid-1;}}
if(l-1>=1)v.EB(l-1,i);}}
```

Dynamic-CHT.h

Description: Add lines $y = ax + b$ and query for min at given x Time: $O(\log n)$ per update/query.

5a79a4, 23 lines

```
struct Line{//gives minimum
mutable int k,m,p;//line kx+m
bool operator<(const Line&o)const
{return k<o.k;}bool operator<(int x)const
{return p<x;}};
struct LineContainer:multiset<Line,less<>>
{//(for doubles,use inf=1/.0,div(a,b)
//=a/b)static const int inf=LLONG_MAX;
int div(int a,int b){//floored division
return a/b-((a^b)<0&&a%b);}
bool isect(iterator x,iterator y){
if(y==end())return x->p=inf,0;
if(x->k==y->k)x->p=x->m>y->m?inf:-inf;else
x->p=div(y->m-x->m,x->k-y->k);
return x->p>=y->p;}void add(int k,int m){
auto z=insert({k,m,0}),y=z++,x=y;
while(isect(y,z))z=erase(z);
if(x!=begin()&&isect(--x,y))
isect(x,y=erase(y));while((y=x)!=begin()&&
(--x)->p>=y->p)isect(x,erase(y));}
int query(int x){assert(!empty());
auto l=*lower_bound(x);return l.k*x+l.m;
};}
```

Divide-and-Conquer.h

Description: Works when $dp_{k,i} = \min_{j < i} (dp_{k-1,j} + cost(j,i))$ and $opt_k(i) \leq opt_k(i+1)$. (This holds when quadrangle)

Usage: find $dp[1]$, then: for($i = 2$ to n) solve($i, 1, n, 1, n$)

Time: $O(kn \log n)$

1db0cf, 15 lines

```
ll dp[100][100]; // set correctly
ll cost(int i, int j); // cost to go from i
to j, 1-indexed.
void solve(int i, int l, int r, int optl,
    int optr) {
const ll inf = 1e18; // set correctly
if (l > r || optl > optr) return;
int mid = (l + r)/2; pair<ll, int> best =
    {inf, -1};
for (int j = optl; j <= min(mid, optr); j
    ++){
pair<ll,int> cand(dp[i - 1][j] + cost(j,
    mid), j);
if (best.second == -1) best = cand;
else best = min(best, cand);
}
dp[i][mid] = best.first;
solve(i, l, mid - 1, optl, best.second);
solve(i, mid + 1, r, best.second, optr);
}
```

KnuthDP.h

Description: When doing DP on intervals: $a[i][j] = \min_{i < k < j} (a[i][k] + a[k][j]) + f(i, j)$, where the (minimal) optimal k increases with both i and j , one can solve intervals in increasing order of length, and search $k = p[i][j]$ for $a[i][j]$ only between $p[i][j-1]$ and $p[i+1][j]$. This is known as Knuth DP. Sufficient criteria for this are if $f(b, c) \leq f(a, d)$ and $f(a, c) + f(b, d) \geq f(a, d) + f(b, c)$ for all $a \leq b \leq c \leq d$. Consider also: LineContainer (ch. Data structures), monotone queues, ternary search.

Time: $O(N^2)$

2556d3, 13 lines

```
const int N=1001;int dp[N][N];int opt[N][N];
int rec(){vector<int>pref(m);
for(int i=0;i<m;i++){pref[i]=A[i];
if(i)pref[i]+=pref[i-1];}
for(int i=0;i<m;i++){
opt[i][i]=i;dp[i][i]=0;}
for(int i=m-2;i>=0;i--){
for(int j=i+1;j<m;j++){int mn=mod*1000;
int cost;//COST[i,j]
for(int k=opt[i][j-1];k<=min(j-1,opt[i+1][j]
    ));k++){
if(mn>=dp[i][k]+dp[k+1][j]+cost){
```

```
opt[i][j]=k;mn=dp[i][k]+dp[k+1][j]+cost;}}
dp[i][j]=mn;}}return dp[0][m-1];}
```

Numerical (3)

3.1 Polynomials

PolyInterpolate.h

Description: Given n points $(x[i], y[i])$, computes an $n-1$ -degree polynomial p that passes through them: $p(x) = a[0] * x^0 + \dots + a[n-1] * x^{n-1}$. For numerical precision, pick $x[k] = c * \cos(k/(n-1) * \pi), k = 0 \dots n-1$.

Time: $O(n^2)$

a4f803, 8 lines

```
typedef vector<double>vd;
vd interpolate(vd x,vd y,int n){
vd res(n),temp(n);REP(k,0,n-1)REP(i,k+1,n)
y[i]=(y[i]-y[k])/(x[i]-x[k]);
double last=0;temp[0]=1;
REP(k,0,n)REP(i,0,n){res[i]+=y[k]*temp[i];
swap(last,temp[i]);temp[i]=last*x[k];}
return res;}
```

3.2 Matrices

IntDeterminant.h

Description: Calculates determinant using modular arithmetics. Modulos can also be removed to get a pure-integer version.

Time: $O(N^3)$

669167, 9 lines

```
const ll mod=12345;
ll det(vector<vector<ll>>&a){
int n=SZ(a);ll ans=1;REP(i,0,n){
REP(j,i+1,n){while(a[j][i]!=0){//gcd step
ll t=a[i][i]/a[j][i];if(t)REP(k,i,n)
a[i][k]=(a[i][k]-a[j][k]*t)%mod;
swap(a[i],a[j]);ans*=-1;}}
ans=ans*a[i][i]%mod;if(!ans)return 0;}
return(ans+mod)%mod;}
```

SolveLinear.h

Description: Solves $A * x = b$. If there are multiple solutions, an arbitrary one is returned. Returns rank, or -1 if no solutions. Data in A and b is lost.

Time: $O(n^2m)$

d6dca7, 20 lines

```

typedef vector<double>vd;
const double eps=1e-12;
int solveLinear(vector<vd>&A,vd&b,vd&x){
int n=SZ(A),m=SZ(x),rank=0,br,bc;
if(n)assert(SZ(A[0])==m);
VI col(m);iota(ALL(col),0);REP(i,0,n){
double v,bv=0;REP(r,i,n)REP(c,i,m)
if((v=fabs(A[r][c]))>bv)br=r,bc=c,bv=v;
if(bv<=eps){
REP(j,i,n)if(fabs(b[j])>eps)return-1;
break;}swap(A[i],A[br]);swap(b[i],b[br]);
swap(col[i],col[bc]);
REP(j,0,n)swap(A[j][i],A[j][bc]);
bv=1/A[i][i];REP(j,i+1,n){
double fac=A[j][i]*bv;b[j]-=fac*b[i];
REP(k,i+1,m)A[j][k]-=fac*A[i][k];}rank++;}
x.assign(m,0);for(int i=rank;i--){
b[i]/=A[i][i];x[col[i]]=b[i];
REP(j,0,i)b[j]-=A[j][i]*b[i];}
return rank;}//(multiple solutions if rank<m
)

```

SolveLinear2.h

Description: To get all uniquely determined values of x back from SolveLinear, make the following changes:

```

"SolveLinear.h" 5cad07, 5 lines
REP(j,0,n)if(j!=i)//instead of REP(j,i+1,n)
//...then at the end:
x.assign(m,undefined);REP(i,0,rank){
REP(j,rank,m)if(fabs(A[i][j])>eps)goto fail;
x[col[i]]=b[i]/A[i][i];fail::;}

```

SolveLinearBinary.h

Description: Solves $Ax = b$ over \mathbb{F}_2 . If there are multiple solutions, one is returned arbitrarily. Returns rank, or -1 if no solutions. Destroys A and b .

Time: $\mathcal{O}(n^2m)$

```

typedef bitset<1000>bs;
int solveLinear(vector<bs>&A,VI&b,bs&x,int m
){
int n=SZ(A),rank=0,br;assert(m<=SZ(x));
VI col(m);iota(ALL(col),0);REP(i,0,n){
for(br=i;br<n;++br)if(A[br].any())break;
if(br==n){REP(j,i,n)if(b[j])return-1;
break;}int bc=(int)A[br]._Find_next(i-1);

```

```

swap(A[i],A[br]);swap(b[i],b[br]);
swap(col[i],col[bc]);
REP(j,0,n)if(A[j][i]!=A[j][bc]){
A[j].flip(i);A[j].flip(bc);}
REP(j,i+1,n)if(A[j][i]){b[j]^=b[i];
A[j]^=A[i];}rank++;}x=bs();
for(int i=rank;i--){if(!b[i])continue;
x[col[i]]=1;REP(j,0,i)b[j]^=A[j][i];}
return rank;}//(multiple solutions if rank<m
)

```

MatrixInverse.h

Description: Invert matrix A . Returns rank; result is stored in A unless singular ($\text{rank} < n$). Can easily be extended to prime moduli; for prime powers, repeatedly set $A^{-1} = A^{-1}(2I - AA^{-1}) \pmod{p^k}$ where A^{-1} starts as the inverse of $A \pmod p$, and k is doubled in each step.

Time: $\mathcal{O}(n^3)$

```

int matInv(vector<vector<double>>&A){
int n=SZ(A);VI col(n);
vector<vector<double>>tmp(n,vector<double>(n
));
REP(i,0,n)tmp[i][i]=1,col[i]=i;REP(i,0,n){
int r=i,c=i;REP(j,i,n)REP(k,i,n)
if(fabs(A[j][k])>fabs(A[r][c]))r=j,c=k;
if(fabs(A[r][c])<1e-12)return i;
A[i].swap(A[r]);tmp[i].swap(tmp[r]);
REP(j,0,n)
{swap(A[j][i],A[j][c]),swap(tmp[j][i],tmp[j
][c]);}
swap(col[i],col[c]);double v=A[i][i];
REP(j,i+1,n){double f=A[j][i]/v;A[j][i]=0;
REP(k,i+1,n)A[j][k]-=f*A[i][k];
REP(k,0,n)tmp[j][k]-=f*tmp[i][k];}
REP(j,i+1,n)A[i][j]/=v;
REP(j,0,n)tmp[i][j]/=v;A[i][i]=1;}
for(int i=n-1;i>0;--i)REP(j,0,i){
double v=A[j][i];
REP(k,0,n)tmp[j][k]-=v*tmp[i][k];}
REP(i,0,n)REP(j,0,n)A[col[i]][col[j]]=tmp[i
][j];
return n;}

```

3.3 Fourier transforms

FastFourierTransform.h

Description: $\text{fft}(a)$ computes $\hat{f}(k) = \sum_x a[x] \exp(2\pi i \cdot kx/N)$ for all k . N must be a power of 2. Useful for convolution: $\text{conv}(a, b) = c$, where $c[x] = \sum a[i]b[x-i]$. For convolution of complex numbers or more than two vectors: FFT, multiply pointwise, divide by n , reverse($\text{start}+1, \text{end}$), FFT back. Rounding is safe if $(\sum a_i^2 + \sum b_i^2) \log_2 N < 9 \cdot 10^{14}$ (in practice 10^{16} ; higher for random inputs). Otherwise, use NTT/FFTMod.

Time: $\mathcal{O}(N \log N)$ with $N = |A| + |B|$ ($\sim 1s$ for $N = 2^{22}$)
be8bc4, 29 lines

```

typedef complex<double>C;
typedef vector<double>vd;
void fft(vector<C>&a){
int n=SZ(a),L=31-__builtin_clz(n);
static vector<complex<long double>>R(2,1);
static vector<C>rt(2,1);//(^10%faster if
double)
for(static int k=2;k<n;k*=2){
R.resize(n);rt.resize(n);
auto x=polar(1.0L,acos(-1.0L)/k);
REP(i,k,2*k)rt[i]=R[i]=i&1?R[i/2]*x:R[i/2];
}VI rev(n);
REP(i,0,n)rev[i]=(rev[i/2]|(i&1)<<L)/2;
REP(i,0,n)if(i<rev[i])swap(a[i],a[rev[i]]);
for(int k=1;k<n;k*=2)
for(int i=0;i<n;i+=2*k)REP(j,0,k){
//C z=rt[j+k]*a[i+j+k];//(25%faster if hand-
rolled)
a[i+j+k]=a[i+j]-z;a[i+j]+=z;}
vd conv(const vd&a,const vd&b){
if(a.empty()||b.empty())return{};
vd res(SZ(a)+SZ(b)-1);
int L=32-__builtin_clz(SZ(res)),n=1<<L;
vector<C>in(n),out(n);
copy(ALL(a),begin(in));
REP(i,0,SZ(b))in[i].imag(b[i]);fft(in);
for(C&x:in)x*=x;
REP(i,0,n)out[i]=in[-i&(n-1)]-conj(in[i]);
fft(out);
REP(i,0,SZ(res))res[i]=imag(out[i])/(4*n);
return res;}

```


FastFourierTransformMod.h

Description: Higher precision FFT, can be used for convolutions modulo arbitrary integers as long as $N \log_2 N \cdot \text{mod} < 8.6 \cdot 10^{14}$ (in practice 10^{16} or higher). Inputs must be in $[0, \text{mod})$.

Time: $\mathcal{O}(N \log N)$, where $N = |A| + |B|$ (twice as slow as NTT or FFT)

"FastFourierTransform.h"

860295, 16 lines

```
typedef vector<ll>vl;
template<int M>vl convMod(const vl&a,const vl&b){
    if(a.empty()||b.empty())return{};
    vl res(SZ(a)+SZ(b)-1);
    int B=32-__builtin_clz(SZ(res)),n=1<<B,cut=
        int(sqrt(M));
    vector<C>L(n),R(n),outs(n),outl(n);
    REP(i,0,SZ(a))L[i]=C((int)a[i]/cut,(int)a[i]
        %cut);
    REP(i,0,SZ(b))R[i]=C((int)b[i]/cut,(int)b[i]
        %cut);
    fft(L),fft(R);REP(i,0,n){int j=-i&(n-1);
    outl[j]=(L[i]+conj(L[j]))*R[i]/(2.0*n);
    outs[j]=(L[i]-conj(L[j]))*R[i]/(2.0*n)/1i;
    }fft(outl),fft(outs);REP(i,0,SZ(res)){
    ll av=ll(real(outl[i])+.5),cv=ll(imag(outs[i]
        )+.5);
    ll bv=ll(imag(outl[i])+.5)+ll(real(outs[i])
        +.5);
    res[i]=(av%M*cut+bv)%M*cut+cv)%M;
    return res;}
```

NumberTheoreticTransform.h

Description: ntt(a) computes $\hat{f}(k) = \sum_x a[x]g^{xk}$ for all k , where $g = \text{root}^{(\text{mod}-1)/N}$. N must be a power of 2. Useful for convolution modulo specific nice primes of the form $2^a b + 1$, where the convolution result has size at most 2^a . For arbitrary modulo, see FFTMod. $\text{conv}(a, b) = c$, where $c[x] = \sum a[i]b[x-i]$. For manual convolution: NTT the inputs, multiply pointwise, divide by n , reverse(start+1, end), NTT back. Inputs must be in $[0, \text{mod})$.

Time: $\mathcal{O}(N \log N)$

"../number-theory/ModPow.h"

14d0bb, 27 lines

```
const ll mod=(119<<23)+1,root=62;//
    =998244353
//For p<2^30 there is also e.g
    .5<<25,7<<26,479<<21
//and 483<<21(same root).The last two are>10
    ^9.
typedef vector<ll>vl;void ntt(vl&a){
    int n=SZ(a),L=31-__builtin_clz(n);
    static vl rt(2,1);
    for(static int k=2,s=2;k<n;k*=2,s++){
        rt.resize(n);
        ll z[]={1,modpow(root,mod>>s)};
        REP(i,k,2*k)rt[i]=rt[i/2]*z[i&1]%mod;
        VI rev(n);
        REP(i,0,n)rev[i]=(rev[i/2]|(i&1)<<L)/2;
        REP(i,0,n)if(i<rev[i])swap(a[i],a[rev[i]]);
        for(int k=1;k<n;k*=2)
            for(int i=0;i<n;i+=2*k)REP(j,0,k){
                ll z=rt[j+k]*a[i+j+k]%mod,&ai=a[i+j];
                a[i+j+k]=ai-z+(z>ai?mod:0);
                ai+=(ai+z>mod?z-mod:z);
            }
        vl conv(const vl&a,const vl&b){
            if(a.empty()||b.empty())return{};
            int s=SZ(a)+SZ(b)-1,B=32-__builtin_clz(s),n
                =1<<B;
            int inv=modpow(n,mod-2);
            vl L(a),R(b),out(n);
            L.resize(n),R.resize(n);ntt(L),ntt(R);
            REP(i,0,n)out[-i&(n-1)]=(ll)L[i]*R[i]%mod*
                inv%mod;
            ntt(out);
            return{out.begin(),out.begin()+s};}
```

FastSubsetTransform.h

Description: Transform to a basis with fast convolutions of the form $c[z] = \sum_{z=x \oplus y} a[x] \cdot b[y]$, where \oplus is one of AND, OR, XOR. The size of a must be a power of two.

Time: $\mathcal{O}(N \log N)$

d5806e, 11 lines

```
void FST(VI&a,bool inv){
    for(int n=SZ(a),step=1;step<n;step*=2){
        for(int i=0;i<n;i+=2*step)REP(j,i,i+step){
            int&u=a[j],&v=a[j+step];tie(u,v)=
            inv?PII(v-u,u):PII(v,u+v);//AND
            //inv?PII(v,u-v):PII(u+v,u);//OR
            //PII(u+v,u-v);//XOR
```

```
//if(inv)for(int&x:a)x/=SZ(a);//XOR only
VI conv(VI a,VI b){FST(a,0);FST(b,0);
REP(i,0,SZ(a))a[i]*=b[i];
FST(a,1);return a;}
```

WalshHadamard.h

Description: $C_k = \sum_{i \otimes j = k} A_i B_j$

Usage: Apply the transform, point multiply and invert

Time: $\mathcal{O}(N \log N)$

905e71, 7 lines

```
void WalshHadamard(poly &P, bool invert) {
    for (int len = 1; 2 * len <= SZ(P); len
        <= 1) {
        for (int i = 0; i < SZ(P); i += 2 * len)
            {
                REP(j, 0, len) {
                    auto u = P[i + j], v = P[i + len + j];
                    P[i + j] = u + v, P[i + len + j] = u
                        - v;
                }
            } // XOR
        if (invert) for (auto &x : P) x /= SZ(P);
    }
```

Number theory (4)

4.1 Modular arithmetic

ModPow.h

fe1717, 4 lines

```
int power(long long x,unsigned int y,int p){
    int res=1;x=x%p;if(x==0)return 0;
    while(y>0){if(y&1)res=(res*x)%p;
    y=y>>1;x=(x*x)%p;}return res;}
```

NCR.h

Description: Calculates ncr for large N and prime Mod

8f060e, 11 lines

```
#define MAX_N_FACT(int)3e5+5
```

```
vector<long long>factorial(MAX_N_FACT,1),
    inverse_factorial(MAX_N_FACT,1),inv(
    MAX_N_FACT,1);
void prec_factorials(){
    for(int i=2;i<MAX_N_FACT;i++){
        factorial[i]=factorial[i-1]*i%mod;
        inv[i]=(mod-(mod/i)*inv[mod%i]%mod);
```

```
inverse_factorial[i]=(inv[i]*
    inverse_factorial[i-1])%mod;
}}long long ncr(int n,int k){
return factorial[n]*inverse_factorial[k]%mod
    *inverse_factorial[n-k]%mod;
}
```

ModLog.h

Description: Returns the smallest $x > 0$ s.t. $a^x = b \pmod{m}$, or -1 if no such x exists. $\text{modLog}(a,1,m)$ can be used to calculate the order of a .

Time: $\mathcal{O}(\sqrt{m})$

0ff368, 8 lines

```
ll modLog(ll a,ll b,ll m){
ll n=(ll)sqrt(m)+1,e=1,f=1,j=1;
unordered_map<ll,ll>A;
while(j<=n&&(e=f*e*a%m)!=b%m)A[e*b%m]=j++;
if(e==b%m)return j;
if(__gcd(m,e)==__gcd(m,b))
REP(i,2,n+2)if(A.count(e=e*f%m))
return n*i-A[e];return -1;}
```

primRoot.h

Description: Calculates ncr for large N and prime Mod

4ca525, 9 lines

```
int PrimRoot(int p,int x){
//finds primitive root of prime p greater
    than x(If it doesnt exist,returns 0)
vector<int>v;int t=p-1;REP(i,2,t+1){
if(i*i>t)break;if(t%i==0){v.pb((p-1)/i);
while(t%i==0){t/=i;}}}
if(t>1)v.pb((p-1)/t);REP(i,x+1,p){
ll flag=0;REP(j,0,((ll)v.size())){
if(powM(i,v[j],p)==1){flag=1;break;}}
if(flag==0){return i;}}return 0;}
```

ModSqrt.h

Description: Tonelli-Shanks algorithm for modular square roots. Finds x s.t. $x^2 = a \pmod{p}$ ($-x$ gives the other solution).

Time: $\mathcal{O}(\log^2 p)$ worst case, $\mathcal{O}(\log p)$ for most p

"ModPow.h"

19a793, 14 lines

```
ll sqrt(ll a,ll p){a%=p;if(a<0)a+=p;
if(a==0)return 0;
assert(modpow(a,(p-1)/2,p)==1);//else no
    solution
if(p%4==3)return modpow(a,(p+1)/4,p);
```

```
//a^(n+3)/8 or 2^(n+3)/8*2^(n-1)/4 works if
    p%8==5
ll s=p-1,n=2;int r=0,m;while(s%2==0)
    ++r,s/=2;
while(modpow(n,(p-1)/2,p)!=p-1)++n;
ll x=modpow(a,(s+1)/2,p);
ll b=modpow(a,s,p),g=modpow(n,s,p);
for(;;r=m){ll t=b;for(m=0;m<r&&t!=1;++m)
    t=t*t%p;if(m==0)return x;
ll gs=modpow(g,1LL<<(r-m-1),p);
g=gs*gs%p;x=x*gs%p;b=b*g%p;}}
```

4.2 Primality

MillerRabin.h

Description: Deterministic Miller-Rabin primality test. Guaranteed to work for numbers up to $7 \cdot 10^{18}$; for larger numbers, use Python and extend A randomly.

Time: 7 times the complexity of $a^b \pmod{c}$.

"ModMuLLL.h"

60dcd1, 9 lines

```
bool isPrime(ull n){
if(n<2||n%64!=1)return(n|1)==3;
ull A[]={2, 325, 9375, 28178, 450775,
    9780504, 1795265022},
s=__builtin_ctzll(n-1),d=n>>s;
for(ull a:A){//^count trailing zeroes
ull p=modpow(a%n,d,n),i=s;
while(p!=1&&p!=n-1&&a%n&&i-- )
p=modmul(p,p,n);if(p!=n-1&&i!=s)return 0;
return 1;}
```

Factor.h

Description: Pollard-rho randomized factorization algorithm. Returns prime factors of a number, in arbitrary order (e.g. $2299 \rightarrow \{11, 19, 11\}$).

Time: $\mathcal{O}(n^{1/4})$, less for numbers with small factors.

"ModMuLLL.h", "MillerRabin.h"

65f857, 11 lines

```
ull pollard(ull n){
auto f=[n](ull x){return modmul(x,x,n)+1;};
ull x=0,y=0,t=30,prd=2,i=1,q;
while(t++<40||__gcd(prd,n)==1){
if(x==y)x=++i,y=f(x);
if((q=modmul(prd,max(x,y)-min(x,y),n)))prd=q;
};
x=f(x),y=f(f(y));return __gcd(prd,n);}
vector<ull>factor(ull n){if(n==1)return{};
if(isPrime(n))return{n};ull x=pollard(n);
```

```
auto l=factor(x),r=factor(n/x);
l.insert(l.end(),ALL(r));return l;}
```

4.3 Divisibility

euclid.h

Description: Finds two integers x and y , such that $ax + by = \text{gcd}(a, b)$. If you just need gcd, use the built in `__gcd` instead. If a and b are coprime, then x is the inverse of $a \pmod{b}$.

33ba8f, 3 lines

```
ll euclid(ll a,ll b,ll&x,ll&y){
if(!b)return x=1,y=0,a;
ll d=euclid(b,a%b,y,x);return y-=a/b*x,d;}
```

diphontine.h

Description: Diphantine Equation.

Time: $\log(1)$

5059d0, 12 lines

```
int gcd(int a, int b, int &x, int &y) {
if (b == 0) {x = 1;y = 0;return a;}
int x1, y1;
int d = gcd(b, a % b, x1, y1);x = y1;
y = x1 - y1 * (a / b);return d;}
bool find_any_solution(int a, int b, int c,
int &x0, int &y0, int &g) {
g = gcd(abs(a), abs(b), x0, y0);
if (c % g) {
return false;}
x0 *= c / g;y0 *= c / g;
if (a < 0) x0 = -x0;if (b < 0) y0 = -y0;
return true;}
```

CRT.h

Description: Chinese Remainder Theorem.

`crt(a, m, b, n)` computes x such that $x \equiv a \pmod{m}$, $x \equiv b \pmod{n}$. If $|a| < m$ and $|b| < n$, x will obey $0 \leq x < \text{lcm}(m, n)$. Assumes $mn < 2^{62}$.

Time: $\log(n)$

"euclid.h"

04d93a, 5 lines

```
ll crt(ll a,ll m,ll b,ll n){
if(n>m)swap(a,b),swap(m,n);
ll x,y,g=euclid(m,n,x,y);
assert((a-b)%g==0);//else no solution
x=(b-a)%n*x%n/g*m+a;return x<0?x+m*n/g:x;}
```


phiFunction.h

Description: Euler's ϕ function is defined as $\phi(n) := \#$ of positive integers $\leq n$ that are coprime with n . $\phi(1) = 1$, p prime $\Rightarrow \phi(p^k) = (p-1)p^{k-1}$, m, n coprime $\Rightarrow \phi(mn) = \phi(m)\phi(n)$. If $n = p_1^{k_1} p_2^{k_2} \dots p_r^{k_r}$, then $\phi(n) = (p_1-1)p_1^{k_1-1} \dots (p_r-1)p_r^{k_r-1}$. $\phi(n) = n \cdot \prod_{p|n} (1 - 1/p)$.

$\sum_{d|n} \phi(d) = n$, $\sum_{1 \leq k \leq n, \gcd(k,n)=1} k = n\phi(n)/2, n > 1$

Euler's thm: a, n coprime $\Rightarrow a^{\phi(n)} \equiv 1 \pmod{n}$.

Fermat's little thm: p prime $\Rightarrow a^{p-1} \equiv 1 \pmod{p} \forall a$.

e4742a, 5 lines

```
const int LIM=5000000;int phi[LIM];
void calculatePhi(){
REP(i,0,LIM)phi[i]=i&1?i/2;
for(int i=3;i<LIM;i+=2)if(phi[i]==i)
for(int j=i;j<LIM;j+=i)phi[j]-=phi[j]/i;}
```

Data structures (5)

HashMap.h

Description: Hash map with mostly the same API as unordered_map, but ~3x faster. Uses 1.5x memory. Initial capacity must be a power of 2 (if provided).

16355a, 9 lines

```
#include<bits/extc++.h>
//To use most bits rather than just the
lowest ones:
#include<bits/extc++.h>
//To use most bits rather than just the
lowest ones:
struct chash{//large odd number for C
const uint64_t C=11(4e18*acos(0))|71;
ll operator()(ll x)const{
return__builtin_bswap64(x*C);}
};
__gnu_pbds::gp_hash_table<ll,int,chash>h({},
{}, {}, {}, {1<<16});
```

Trie.h

Description: krishna

Time: $\mathcal{O}(\log N)$

1cba01, 13 lines

```
const int NX=int(1e6)+int(5e5);int arr[NX
][26];
int root;int lastocc;void Trie(){
root=0,lastocc=0;
memset(arr,0,sizeof(int)*NX*26);}
```

```
void insert(const string&x){
int curptr=root;for(auto ch:x){
if(arr[curptr][ch-'a']==0)
arr[curptr][ch-'a']+=lastocc;
curptr=arr[curptr][ch-'a'];}}
int search(const string&x){
int curptr=root;for(auto ch:x){
if(arr[curptr][ch-'a']==0)return 0;else
curptr=arr[curptr][ch-'a'];}return 1;}
```

Treap.h

Description: A short self-balancing tree. It acts as a sequential container with log-time splits/joins, and is easy to augment with additional data.

Time: $\mathcal{O}(\log N)$

998917, 59 lines

```
mt19937 gen(time(0));
uniform_int_distribution<int>rng;
typedef struct node{
int prior,size,val,sum,lazy;
//value in array,info of segtree,lazy update
struct node*l,*r;}node;typedef node*pnode;
int sz(pnode t){return t?t->size:0;}
void upd_sz(pnode t){
if(t)t->size=sz(t->l)+1+sz(t->r);}
void lazy(pnode t){if(!t||!t->lazy)return;
t->val+=t->lazy;//operation of lazy
t->sum+=t->lazy*sz(t);
if(t->l)t->l->lazy+=t->lazy;//propagate lazy
if(t->r)t->r->lazy+=t->lazy;t->lazy=0;}
void reset(pnode t){
if(t)t->sum=t->val;}//lazy already
propagated}
void combine(pnode&t,pnode l,pnode r){//
combine segtree ranges
if(!l||!r)return void(t=l?l:r);
t->sum=l->sum+r->sum;}
void operation(pnode t){//operation of
segtree
if(!t)return;
reset(t);//node represents single element of
array
lazy(t->l);lazy(t->r);//imp:propagate lazy
before combining l,r
combine(t,t->l,t);combine(t,t,t->r);}
```

```
void split(pnode t,pnode&l,pnode&r,int pos,
int add=0){
if(!t)return void(l=r=NULL);
lazy(t);int curr_pos=add+sz(t->l);
if(curr_pos<=pos)//element at pos goes to"l"
split(t->r,t->r,r,pos,curr_pos+1),l=t;
else split(t->l,l,t->l,pos,add),r=t;
upd_sz(t);operation(t);}
void merge(pnode&t,pnode l,pnode r){//result
//left/right array
lazy(l);lazy(r);if(!l||!r)t=l?l:r;
else if(l->prior>r->prior)merge(l->r,l->r,r),
t=l;
else merge(r->l,l,r->l),t=r;
upd_sz(t);operation(t);}
pnode init(int val){
pnode ret=(pnode)malloc(sizeof(node));
ret->prior=rng(gen);ret->size=1;
ret->val=val;ret->sum=val;ret->lazy=0;
return ret;}
int range_query(pnode t,int l,int r){//[l,r]
pnode L,mid,R;
split(t,L,mid,l-1);split(mid,t,R,r-l);//note
:r-l!!
int ans=t->sum;
merge(mid,L,t);merge(t,mid,R);return ans;}
void range_update(pnode t,int l,int r,int
val){//[l,r]
pnode L,mid,R;
split(t,L,mid,l-1);split(mid,t,R,r-l);//note
:r-l!!
t->lazy+=val;//lazy_update
merge(mid,L,t);merge(t,mid,R);}
void reverse(pnode t,int l,int r){
pnode t1=NULL,t2=NULL,t3=NULL;
split(t,t1,t2,l-1);split(t2,t2,t3,r-l);
assert(t2);t2->rev^=true;
merge(t,t1,t2);merge(t,t,t3);}
void output(pnode t){if(!t)return;
output(t->l);cout<<t->val<<" ";
output(t->r);}pnode Treap=NULL;
```

TreapBST.h

Description: A short self-balancing tree. It acts as a sequential container with log-time splits/joins, and is easy to augment with additional data.

Time: $\mathcal{O}(\log N)$

f9c99d, 22 lines

```

struct node{int val,prior,size;node*l,*r;};
typedef node*pnode;int sz(pnode t){return t?
    t->size:0;}
void upd_sz(pnode t){if(t)t->size=sz(t->l)
    +1+sz(t->r);}
void split(pnode t,pnode&l,pnode&r,int key){
    if(!t)l=r=NULL;
    else if(t->val<=key)split(t->r,t->r,r,key),l
        =t;//key in l
    else split(t->l,l,t->l,key),r=t;upd_sz(t);
}void merge(pnode&t,pnode l,pnode r){if(!l
    ||!r)t=l?l:r;
    else if(l->prior>r->prior)merge(l->r,l->r,r),
        t=l;
    else merge(r->l,l,r->l),t=r;upd_sz(t);
}void insert(pnode&t,pnode it){if(!t)t=it;
    else if(it->prior>t->prior)split(t,it->l,it
        ->r,it->val),t=it;
    else insert(t->val<it->val?t->r:t->l,it);
        upd_sz(t);
}void erase(pnode&t,int key){if(!t)return;
    else if(t->val==key){pnode x=t;merge(t,t->l,
        t->r);free(x);}
    else erase(t->val<key?t->r:t->l,key);upd_sz(
        t);
}void unite(pnode&t,pnode l,pnode r){
    if(!l||!r)return void(t=l?l:r);pnode lt,rt;
    if(l->prior<r->prior)swap(l,r);split(r,lt,rt
        ,l->val);
    unite(l->l,l->l,lt);unite(l->r,l->r,rt);t=l;
        upd_sz(t);
}pnode init(int val){pnode ret=(pnode)malloc
    (sizeof(node));
    ret->val=val;ret->size=1;ret->prior=rand();
        ret->l=ret->r=NULL;
    return ret;}insert(init(x),head);

```

UnionFindRollback.h

Description: Disjoint-set data structure with undo. If undo is not needed, skip st, time() and rollback().

Usage: int t = uf.time(); ...;
uf.rollback(t);

Time: $\mathcal{O}(\log(N))$

f79afc, 14 lines

```

struct RollbackUF{VI e;vector<PII>st;

```

```

RollbackUF(int n):e(n,-1){}
int size(int x){return e[find(x)];}
int find(int x){return e[x]<0?x:find(e[x]);}
int time(){return SZ(st);}
void rollback(int t){
    for(int i=time();i-->t;)
        e[st[i].first]=st[i].second;st.resize(t);}
bool join(int a,int b){
    a=find(a),b=find(b);if(a==b)return false;
    if(e[a]>e[b])swap(a,b);
    st.push_back({a,e[a]});
    st.push_back({b,e[b]});e[a]+=e[b];e[b]=a;
    return true;};}

```

5.1 Range DS

SegmentTree.h

Description: Zero-indexed max-tree. Bounds are inclusive to the left and exclusive to the right. Can be changed by modifying T, f and unit.

Time: $\mathcal{O}(\log N)$

d11ec5, 12 lines

```

template<typename T>struct segTree{T unit;
    T(*f)(T obj1,T obj2);vector<T>s;int n;
    segTree(int n,T(*c)(T obj1,T obj2),T def):s
        (2*n,def),n(n),f(c),unit(def){}
    void update(int pos,T val){
        for(s[pos+=n]=val;pos/=2;)
            s[pos]=f(s[pos*2],s[pos*2+1]);}
    T query(int b,int e){//query[b,e]e++;
        T ra=unit,rb=unit;
        for(b+=n,e+=n;b<e;b/=2,e/=2){
            if(b%2)ra=f(ra,s[b++]);
            if(e%2)rb=f(s[--e],rb);}
        return f(ra,rb);};}

```

LazySegmentTree.h

Description: Segment tree with ability to add or set values of large intervals, and compute max of intervals. Can be changed to other things. Use with a bump allocator for better performance, and SmallPtr or implicit indices to save memory.

Usage: Node* tr = new Node(v, 0, SZ(v));

Time: $\mathcal{O}(\log N)$.

c9356c, 30 lines

```

int ST[4*N],lazy[4*N],A[N];
#define lc(x<<1)

```

```

#define rc(x<<1)|1
void push(int x,int l,int r){
    ST[x]+=lazy[x];//Operation of lazy
    if(l==r-1)lazy[x]=0;if(!lazy[x])return;
    lazy[lc]+=lazy[x];
    lazy[rc]+=lazy[x];lazy[x]=0;//Propagate Lazy
}void up(int x){//Operation of Segtree
    ST[x]=min(ST[lc],ST[rc]);
}void build(int l=0,int r=N,int x=1){
    lazy[x]=0;//clear lazy
    if(l==r-1)return void(ST[x]=A[l]);
    int m=(l+r)/2;
    build(l,m,lc);build(m,r,rc);up(x);
}void update(int L,int R,int add,int l=0,int
    r=N,int x=1){
    push(x,l,r);int m=(l+r)/2;
    if(l>=R||r<=L)return;if(l>=L&&r<=R){
        lazy[x]+=add;//operation of lazy update
        return push(x,l,r);
    }update(L,R,add,l,m,lc);
    update(L,R,add,m,r,rc);up(x);
}int query(int L,int R,int l=0,int r=N,int x
    =1){
    push(x,l,r);int m=(l+r)/2;
    if(l>=R||r<=L)return INF;//nothing here
    if(l>=L&&r<=R)return ST[x];
    int la=query(L,R,l,m,lc);
    int ra=query(L,R,m,r,rc);
    return min(la,ra);//operation of segtree}

```

PersistentSegmentTree.h

Description: Segment tree with ability to add or set values of large intervals, and compute max of intervals. Can be changed to other things. Use with a bump allocator for better performance, and SmallPtr or implicit indices to save memory.

Usage: Node* tr = new Node(v, 0, SZ(v));

Time: $\mathcal{O}(\log N)$.

6aa2ac, 26 lines

```

struct Vertex{Vertex*l,*r;int sum;
    Vertex(int val):l(nullptr),r(nullptr),sum(
        val){}
    Vertex(Vertex*l,Vertex*r):l(l),r(r),sum(0){
        if(l)sum+=l->sum;if(r)sum+=r->sum;}};
    Vertex*build(int a[],int tl,int tr){

```

```

if(tl==tr) return new Vertex(a[tl]);
int tm=(tl+tr)/2;
return new Vertex(build(a,tl,tm),build(a,tm
+1,tr));
}
int get_sum(Vertex*v,int tl,int tr,int l,int
r){
if(l>r) return 0;if(l==tl&&tr==r)
return v->sum;int tm=(tl+tr)/2;
return get_sum(v->l,tl,tm,l,min(r,tm))+
get_sum(v->r,tm+1,tr,max(l,tm+1),r);
}
Vertex*update(Vertex*v,int tl,int tr,int pos
,int new_val){
if(tl==tr) return new Vertex(new_val);
int tm=(tl+tr)/2;if(pos<=tm)
return new Vertex(update(v->l,tl,tm,pos,
new_val),v->r);
else
return new Vertex(v->l,update(v->r,tm+1,tr,
pos,new_val));
}int tl=0,tr=MAX_VALUE+1;
std::vector<Vertex*>roots;
roots.push_back(build(tl,tr));
for(int i=0;i<a.size();i++){
roots.push_back(update(roots.back(),tl,tr,i,
a[i]));
}

```

FenwickTree.h

Description: Computes partial sums $a[0] + a[1] + \dots + a[\text{pos} - 1]$, and updates single elements $a[i]$, taking the difference between the old and new value.

Time: Both operations are $\mathcal{O}(\log N)$.

367d01, 8 lines

```

struct FT{vector<ll>s;
FT()=default;FT(int n):s(n){}
void update(int pos,ll dif){a[pos]+=dif
for(;pos<SZ(s);pos|=pos+1)s[pos]+=dif;}
ll query(int pos){sum of values in[0,pos]
ll res=0;
for(;pos>0;pos&=pos-1)res+=s[pos-1];
return res;}};

```

RMQ.h

Description: Range Minimum Queries on an array. Returns $\min(V[a], V[a + 1], \dots, V[b - 1])$ in constant time.

Usage: RMQ rmq(values);
rmq.query(inclusive, exclusive);

Time: $\mathcal{O}(|V| \log |V| + Q)$

9a1bbf, 11 lines

```

template<class T>
struct RMQ{vector<vector<T>>jmp;
RMQ(const vector<T>&V):jmp(1,V){
for(int pw=1,k=1;pw*2<=SZ(V);pw*=2,++k){
jmp.emplace_back(SZ(V)-pw*2+1);
REP(j,0,SZ(jmp[k]))
jmp[k][j]=min(jmp[k-1][j],jmp[k-1][j+pw]);}}
T query(int a,int b){
assert(a<b);or return inf if a==b
int dep=31-__builtin_clz(b-a);
return min(jmp[dep][a],jmp[dep][b-(1<<dep)])
};};

```

MoQueries.h

Description: Answer interval or tree path queries by finding an approximate TSP through the queries, and moving from one query to the next by adding/removing points at the ends. If values are on tree edges, change step to add/remove the edge (a, c) and remove the initial add call (but keep in).

Time: $\mathcal{O}(N\sqrt{Q})$

3015c5, 35 lines

```

void add(int ind,int end){...}add a[ind] (
end=0 or 1)
void del(int ind,int end){...}remove a[ind
]
int calc(){...}compute current answer
VI mo(vector<PII>Q){
int L=0,R=0,blk=350;//~N/sqrt(Q)
VI s(SZ(Q)),res=s;
#define K(x)PII(x.first/blk,x.second^(x.
first/blk&1))
iota(ALL(s),0);
sort(ALL(s), [&](int s,int t){return K(Q[s])<
K(Q[t]);});
for(int qi:s){PII q=Q[qi];
while(L>q.first)add(--L,0);
while(R<q.second)add(R++,1);
while(L<q.first)del(L++,0);
while(R>q.second)del(--R,1);
res[qi]=calc();}return res;}

```

```

VI moTree(vector<array<int,2>>Q,vector<VI>&
ed,int root=0){
int N=SZ(ed),pos[2]={},blk=350;//~N/sqrt(Q)
VI s(SZ(Q)),res=s,I(N),L(N),R(N),in(N),par(N
);
add(0,0),in[0]=1;
auto dfs=[&](int x,int p,int dep,auto&f)->
void{
par[x]=p;L[x]=N;if(dep)I[x]=N++;
for(int y:ed[x])if(y!=p)f(y,x,!dep,f);
if(!dep)I[x]=N++;R[x]=N;};
dfs(root,-1,0,dfs);
#define K(x)PII(I[x[0]]/blk,I[x[1]]^(I[x
[0]]/blk&1))
iota(ALL(s),0);
sort(ALL(s), [&](int s,int t){return K(Q[s])<
K(Q[t]);});
for(int qi:s)REP(end,0,2){
int&a=pos[end],b=Q[qi][end],i=0;
#define step(c){if(in[c]){del(a,end);in[a
]=0;}}\
else{add(c,end);in[c]=1;}a=c;}
while(!(L[b]<=L[a]&&R[a]<=R[b]))
I[i++]=b,b=par[b];while(a!=b)step(par[a]);
while(i--)step(I[i]);
if(end)res[qi]=calc();}return res;}

```

MoWithUpdates.h

Description: Supports point updates at position

Time: $\mathcal{O}(n^{5/3})$ when block = $n^{2/3}$

303d07, 14 lines

```

struct Query { int l, r, id, t; }
struct Update { int pos, pre, now; };
void MoWithUpdates(vector<Query> qs, vector<
Update> upd) {
int BLK; // set block size
sort(qs.begin(), qs.end(), [&](Query a,
Query b) {
return {a.l/BLK, a.r/BLK, a.t} < {b.l/
BLK, b.r/BLK, b.t};});
for (auto q : qs) {
while (t < q.t) ++t, apply(upd[t].pos,
upd[t].now);
while (t > q.t) apply(upd[t].pos, upd[t
].pre), --t;
while (l > q.l) add(--l);

```



```

while (l < q.l) remove(l++);
while (r < q.r) add(++r);
while (r > q.r) remove(r--);
ans[q.id] = get();}

```

Strings (6)

6.1 String Matching

KMP.h

Description: pi[x] computes the length of the longest prefix of s that ends at x, other than s[0...x] itself (abacaba -> 0010123). Can be used to find all occurrences of a string.

Time: $\mathcal{O}(n)$

e21281, 9 lines

```

VI pi(const string&s){VI p(SZ(s));
REP(i,1,SZ(s)){int g=p[i-1];
while(g&& s[i]!=s[g])g=p[g-1];
p[i]=g+(s[i]==s[g]);}return p;}
VI match(const string&s,const string&pat){
VI p=pi(pat+'\0'+s),res;
REP(i,SZ(p)-SZ(s),SZ(p)){
if(p[i]==SZ(pat))res.push_back(i-2*SZ(pat));
}
return res;}

```

Zfunc.h

Description: z[x] computes the length of the longest common prefix of s[i:] and s, except z[0] = 0. (abacaba -> 0010301)

Time: $\mathcal{O}(n)$

a706e2, 6 lines

```

VI Z(string S){VI z(SZ(S));int l=-1,r=-1;
REP(i,1,SZ(S)){
z[i]=i>=r?0:min(r-i,z[i-l]);
while(i+z[i]<SZ(S)&&S[i+z[i]]==S[z[i]])
z[i]++;if(i+z[i]>r)l=i,r=i+z[i];}
return z;}

```

AhoCorasick.h

Description: Aho-Corasick automaton

Time: construction $\mathcal{O}(26N)$, where $N = \text{sum patterns}$

102538, 44 lines

```

struct ahocorasick{
vector<vector<int>>next;
vector<int>fail,out,finish,cnt;
vector<string>words;

```

```

/*if there are repeated words and it is
necessary to show them 'finish' has to be
vector<vector<int>> fail stores the
suffix links finish stores index of word
which ends at that index(if any) cnt
stores the number of words ending at i
out stores the index in trie of that
suffix link where some word ends*/

```

```

ahocorasick(){
next.push_back(vector<int>(26));
finish.push_back(0);cnt.push_back(0);}
void insert(string&s){int u=0;
for(int i=0;i<s.size();++i){
int c=s[i]-'a';if(!next[u][c]){
next[u][c]=next.size();
next.push_back(vector<int>(26));
finish.push_back(-1);cnt.push_back(0);}
u=next[u][c];}
finish[u]=words.size();++cnt[u];
words.push_back(s);}
int get_fail(int pfail,int c){
while(!next[pfail][c]&& pfail!=0)
pfail=fail[pfail];return next[pfail][c];}
void update_out(int u){out[u]=fail[u];
while(finish[out[u]]!=-1)
out[u]=fail[out[u]];}void buildf(){
queue<int>q;fail.assign(next.size(),0);
out.assign(next.size(),0);
for(int i=0;i<26;++i)if(next[0][i])
q.push(next[0][i]);while(q.size()){
int u=q.front();q.pop();
for(int i=0;i<26;++i){int v=next[u][i];
if(v){fail[v]=get_fail(fail[u],i);
cnt[v]+=cnt[fail[v]];q.push(v);
//update_out is similar to while loop in
match functions
//since it goes through all strings while
end at that node
//so comment if unnecessary
update_out(v);}}}int match(string&s){
int cur=0,matches=0;
for(int i=0;i<s.size();++i){
int c=s[i]-'a';if(next[cur][c])
cur=next[cur][c];else
cur=get_fail(fail[cur],c);
matches+=cnt[cur];int t=cur;while(t!=0){

```

```

if(finish[t]!=-1){
cout<<words[finish[t]]<<endl;}}t=out[t];}
return matches;}};

```

Hashing.h

Description: Self-explanatory methods for string hashing.

91d0ec, 18 lines

```

/*Arithmetic mod 2^64-1.2x slower than mod 2
^64 and more code,but works on evil test
data(e.g.Thue-Morse,where ABBA...and
BAAB...of length 2^10 hash the same mod
2^64).typedef ull H;"instead if you
think test data is random,or work mod 10
^9+7 if the Birthday paradox is not a
problem.*
typedef uint64_t ull;struct H{
ull x;H(ull x=0):x(x){}
H operator+(H o){return x+o.x+(x+o.x<x);}
H operator-(H o){return *this+~o.x;}
H operator*(H o){auto m=(__uint128_t)x*o.x;
return H((ull)m)+(ull)(m>>64);}
ull get()const{return x+!~x;}
bool operator==(H o)const{return get()==o.
get();}
bool operator<(H o)const{return get()<o.get
();}
};
static const H C=(1ll)1e11+3;//(order~3e9;
random also ok)
struct HashInterval{vector<H>ha,pw;
HashInterval(string&str):ha(sz(str)+1),pw(ha
){
pw[0]=1;rep(i,0,sz(str))
ha[i+1]=ha[i]*C+str[i],pw[i+1]=pw[i]*C;}
H hashInterval(int a,int b){//hash[a,b]
return ha[b]-ha[a]*pw[b-a];}};

```

MinRotation.h

Description: Finds the lexicographically smallest rotation of a string.

Usage: rotate(v.begin(), v.begin()+minRotation(v), v.end());

Time: $\mathcal{O}(N)$

43e521, 4 lines

```

int minRotation(string s){
int a=0,N=SZ(s);s+=s;REP(b,0,N)REP(k,0,N){

```

```
if(a+k==b||s[a+k]<s[b+k]){b+=max(0,k-1);
    break;}
if(s[a+k]>s[b+k]){a=b;break;}}return a;}
```

6.2 Palindromes

Manacher.h

Description: For each position in a string, computes $p[0][i]$ = half length of longest even palindrome around pos i , $p[1][i]$ = longest odd (half rounded down).

Time: $\mathcal{O}(N)$

1deebd, 9 lines

```
array<VI,2>manacher(const string&s){
    int n=SZ(s);array<VI,2>p={VI(n+1),VI(n)};
    REP(z,0,2)for(int i=0,l=0,r=0;i<n;i++){
        int t=r-i+!z;
        if(i<r)p[z][i]=min(t,p[z][l+t]);
        int L=i-p[z][i],R=i+p[z][i]-!z;
        while(L>=1&&R+1<n&&s[L-1]==s[R+1])
            p[z][i]++,L--,R++;if(R>r)l=L,r=R;
        return p;}
```

6.3 Suffix DS

SuffixArray.h

Description: Builds suffix array for a string. $sa[i]$ is the starting index of the suffix which is i 'th in the sorted suffix array. The returned vector is of size $n+1$, and $sa[0] = n$. The lcp array contains longest common prefixes for neighbouring strings in the suffix array: $lcp[i] = lcp(sa[i], sa[i-1])$, $lcp[0] = 0$. The input string must not contain any zero bytes.

Time: $\mathcal{O}(n \log n)$

3e14f8, 18 lines

```
struct SuffixArray{VI sa,lcp;
    SuffixArray(string&s,int lim=256){//or
        basic_string<int>
        int n=SZ(s)+1,k=0,a,b;
        VI x(ALL(s)+1),y(n),ws(max(n,lim)),rank(n);
        sa=lcp=y,iota(ALL(sa),0);
        for(int j=0,p=0;p<n;j=max(1,j*2),lim=p){
            p=j,iota(ALL(y),n-j);
            REP(i,0,n)if(sa[i]>=j)y[p++]=sa[i]-j;
            fill(ALL(ws),0);REP(i,0,n)ws[x[i]]++;
            REP(i,1,lim)ws[i]+=ws[i-1];
            for(int i=n;i--;)sa[--ws[x[y[i]]]]=y[i];
            swap(x,y),p=1,x[sa[0]]=0;
            REP(i,1,n)a=sa[i-1],b=sa[i],x[b]=
```

```
(y[a]==y[b]&&y[a+j]==y[b+j])?p-1:p++;}
    REP(i,1,n)rank[sa[i]]=i;
    for(int i=0,j;i<n-1;lcp[rank[i++]]=k)
        for(k&&k--,j=sa[rank[i]-1];
            s[i+k]==s[j+k];k++);};}
```

SuffixAutomaton.h

Description: Each path in the automaton is a substring (if it ends in a terminal node, it is a suffix) And no. of occurrences = no. of ways to reach a terminal node. Or keep reverse edges of suffix links(all prefixes for that substring), then no. of ways to reach a root.

Time: $\mathcal{O}(\text{len})$ map accesses, map can be at most of size alphabet, can also use unordered_map

37fe84, 22 lines

```
struct SuffixAutomaton{
    vector<map<char,int>>edges;
    VI link,length;//length[i]:longest string in
        i-th class
    int last;//index of equivalence class of
        whole string
    SuffixAutomaton(string s):edges{},link{-1},
        length{0},last(0){
        edges.emplace_back();REP(i,0,SZ(s)){
            edges.emplace_back();
            length.push_back(i+1);link.push_back(0);
            int r=SZ(edges)-1,p=last;
            while(p>=0&&edges[p].find(s[i])==edges[p].
                end()){
                edges[p][s[i]]=r,p=link[p];}if(p!=-1){
                const int q=edges[p][s[i]];
                if(length[p]+1==length[q])link[r]=q;else{
                    edges.push_back(edges[q]);
                    length.push_back(length[p]+1);
                    link.push_back(link[q]);
                    const int qq=SZ(edges)-1;
                    link[q]=link[r]=qq;
                    for(;p>=0&&edges[p][s[i]]==q;p=link[p])
                        edges[p][s[i]]=qq;}}last=r;}VI terminals;
            for(int p=last;p>0;p=link[p])
                terminals.push_back(p);};}
```

Graph (7)

BellmanFord.h

Description: Unreachable nodes get dist = inf; nodes reachable through negative-weight cycles get dist = -inf. Assumes $V^2 \max |w_i| < \sim 2^{63}$.

Time: $\mathcal{O}(VE)$

11ca03, 16 lines

```
const ll inf=LLONG_MAX;
struct Ed{int a,b,w,s(){return a<b?a:-a;}};
struct Node{ll dist=inf;int prev=-1;};
void bellmanFord(vector<Node>&nodes,vector<
    Ed>&eds,int s){
    nodes[s].dist=0;
    sort(ALL(eds),[](Ed a,Ed b){return a.s()<b.s
        ();});
    int lim=SZ(nodes)/2+2;
    REP(i,0,lim)for(Ed ed:eds){
        Node cur=nodes[ed.a],&dest=nodes[ed.b];
        if(abs(cur.dist)==inf)continue;
        ll d=cur.dist+ed.w;if(d<dest.dist){
            dest.prev=ed.a;
            dest.dist=(i<lim-1?d:-inf);}}
    REP(i,0,lim)for(Ed e:eds){
        if(nodes[e.a].dist==inf)
            nodes[e.b].dist=-inf;}}
```

FloydWarshall.h

Description: Input is an distance matrix m , where $m[i][j] = \text{inf}$ if i and j are not adjacent. As output, $m[i][j]$ is set to the shortest distance between i and j , inf if no path, or $-\text{inf}$ if the path goes through a negative-weight cycle.

Time: $\mathcal{O}(N^3)$

0ff4bf, 10 lines

```
const ll inf=1LL<<62;
void floydWarshall(vector<vector<ll>>&m){
    int n=SZ(m);
    REP(i,0,n)m[i][i]=min(m[i][i],0LL);
    REP(k,0,n)REP(i,0,n)REP(j,0,n)
        if(m[i][k]!=inf&&m[k][j]!=inf){
            auto newDist=max(m[i][k]+m[k][j],-inf);
            m[i][j]=min(m[i][j],newDist);}
    REP(k,0,n)if(m[k][k]<0)REP(i,0,n)REP(j,0,n)
        if(m[i][k]!=inf&&m[k][j]!=inf)m[i][j]=-inf;}
```

7.1 Network flow

Dinic.h

Description: Flow algorithm with complexity $O(VE \log U)$ where $U = \max |cap|$. $O(\min(E^{1/2}, V^{2/3})E)$ if $U = 1$; $O(\sqrt{V}E)$ for bipartite matching.

abfd54, 25 lines

```
struct Dinic{struct Edge{
int to,rev;ll c,oc;
ll flow(){return max(oc-c,0LL);};//if you
    need flows
};VI lvl,ptr,q;vector<vector<Edge>>adj;
Dinic(int n):lvl(n),ptr(n),q(n),adj(n){}
void addEdge(int a,int b,ll c,ll rcap=0){
adj[a].push_back({b,SZ(adj[b]),c,c});
adj[b].push_back({a,SZ(adj[a])-1,rcap,rcap});
};
ll dfs(int v,int t,ll f){
if(v==t||!f)return f;
for(int&i=ptr[v];i<SZ(adj[v]);i++){
Edge&e=adj[v][i];if(lvl[e.to]==lvl[v]+1)
if(ll p=dfs(e.to,t,min(f,e.c))){
e.c-=p,adj[e.to][e.rev].c+=p;return p;}}
return 0;}ll calc(int s,int t){
ll flow=0;q[0]=s;
REP(L,0,31)do{//'int L=30'maybe faster for
    random data
lvl=ptr=VI(SZ(q));int qi=0,qe=lvl[s]=1;
while(qi<qe&&!lvl[t]){int v=q[qi++];
for(Edge e:adj[v])
if(!lvl[e.to]&&e.c>(30-L))
q[qe++]=e.to,lvl[e.to]=lvl[v]+1;}
while(ll p=dfs(s,t,LLONG_MAX))flow+=p;
}while(lvl[t]);return flow;}
bool leftOfMinCut(int a){return lvl[a]!=0;}}
```

MCMF-SPFA.h

Description: Multiedges and negative costs allowed.

Time: Approximately $O(V^2E^2)$

19b593, 35 lines

```
template<typename FLOW,typename COST>struct
MCMF{
const COST INFC=1e9,EPSC=0;
const FLOW INFF=1e9,EPSC=0;struct Edge{
int from,to;FLOW flow,cap;COST cost;};
int nodes,src,dest,m=0;
vector<vector<int>>adj;vector<Edge>edges;
void add(int u,int v,FLOW cap,COST cost){
edges.EB(u,v,0,cap,cost);adj[u].PB(m++);
```

```
edges.EB(v,u,0,0,-cost);adj[v].PB(m++);}
vector<COST>dis;vector<bool>inQ;VI par;
pair<FLOW,COST>SPFA(){
fill(ALL(dis),INFC);fill(ALL(inQ),false);
queue<int>Q;
Q.push(src),dis[src]=0,inQ[src]=true;
while(!Q.empty()){int u=Q.front();Q.pop();
inQ[u]=false;for(int i:adj[u]){
auto&e=edges[i];if(e.cap-e.flow>EPSC
&&dis[e.to]-(dis[u]+e.cost)>EPSC){
dis[e.to]=dis[u]+e.cost;par[e.to]=i;
if(!inQ[e.to]){Q.push(e.to),inQ[e.to]=true;}}}}
if(dis[dest]+EPSC>INFC)return{0,0};
FLOW aug=INFF;
for(int u=dest;u!=src;u=edges[par[u]].from){
aug=min(aug,edges[par[u]].cap-edges[par[u]].
    flow);}
for(int u=dest;u!=src;u=edges[par[u]].from){
edges[par[u]].flow+=aug;
edges[par[u]^1].flow-=aug;}
return{aug,aug*dis[dest]};}
MCMF(int n,int s,int t)
:nodes(n),src(s),dest(t),adj(n),dis(n),inQ(n)
    ,par(n){}
pair<FLOW,COST>mincostmaxflow(){
pair<FLOW,COST>ans(0,0);while(true){
auto cur=SPFA();if(cur.first<=EPSC)break;
ans.first+=cur.first;
ans.second+=cur.second;}return ans;}}
```

MinCostMaxFlow.h

Description: Min-cost max-flow. $cap[i][j] \neq cap[j][i]$ is allowed; double edges are not. If costs can be negative, call setpi before maxflow, but note that negative cost cycles are not supported. To obtain the actual flow, look at positive values only.

Time: Approximately $O(E^2)$

0c0fa5, 50 lines

```
//#include<bits/extc++.h>
const ll INF=numeric_limits<ll>::max()/4;
typedef vector<ll>VL;struct MCMF{
int N;vector<VI>ed,red;VI seen;VL dist,pi;
vector<VL>cap,flow,cost;vector<PII>par;
MCMF(int N):
```

```
N(N),ed(N),red(N),cap(N,VL(N)),flow(cap),
    cost(cap),
seen(N),dist(N),pi(N),par(N){}
void addEdge(int from,int to,ll cap,ll cost)
{
this->cap[from][to]=cap;
this->cost[from][to]=cost;
ed[from].push_back(to);
red[to].push_back(from);}void path(int s){
fill(ALL(seen),0);fill(ALL(dist),INF);
dist[s]=0;ll di;
__gnu_pbds::priority_queue<pair<ll,int>>q;
vector<decltype(q)::point_iterator>its(N);
q.push({0,s});
auto relax=[&](int i,ll cap,ll cost,int dir)
{
ll val=di-pi[i]+cost;if(cap&&val<dist[i]){
dist[i]=val;par[i]={s,dir};
if(its[i]==q.end())its[i]=q.push({-dist[i],i
    });}
else q.modify(its[i],{-dist[i],i});}
while(!q.empty()){
s=q.top().second;q.pop();
seen[s]=1;di=dist[s]+pi[s];
for(int i:ed[s])if(!seen[i])
relax(i,cap[s][i]-flow[s][i],cost[s][i],1);
for(int i:red[s])if(!seen[i])
relax(i,flow[i][s],-cost[i][s],0);
REP(i,0,N)pi[i]=min(pi[i]+dist[i],INF);}
pair<ll,ll>maxflow(int s,int t){
ll totflow=0,totcost=0;
while(path(s),seen[t]){ll fl=INF;
for(int p,r,x=t;tie(p,r)=par[x],x!=s;x=p)
fl=min(fl,r?cap[p][x]-flow[p][x]:flow[x][p]);
totflow+=fl;
for(int p,r,x=t;tie(p,r)=par[x],x!=s;x=p)
if(r)flow[p][x]+=fl;else flow[x][p]-=fl;}
REP(i,0,N)REP(j,0,N)totcost+=cost[i][j]*flow
    [i][j];
return{totflow,totcost};}
//If some costs can be negative,call this
    before maxflow:
void setpi(int s){//(otherwise,leave this
    out)
fill(ALL(pi),INF);pi[s]=0;
```

```
int it=N,ch=1;ll v;while(ch--&&it--)
REP(i,0,N)if(pi[i]!=INF)
for(int to:ed[i])if(cap[i][to])
if((v=pi[i]+cost[i][to])<pi[to])
pi[to]=v,ch=1;
assert(it>=0);//negative cost cycle};
```

GlobalMinCut.h

Description: Find a global minimum cut in an undirected graph, as represented by an adjacency matrix.

Time: $\mathcal{O}(V^3)$

1d69cc, 14 lines

```
pair<int,VI>globalMinCut(vector<VI>mat){
pair<int,VI>best={INT_MAX,{}};
int n=SZ(mat);vector<VI>co(n);
REP(i,0,n)co[i]={i};REP(ph,1,n){
VI w=mat[0];size_t s=0,t=0;
REP(it,0,n-ph){//O(V^2)->O(E log V)with prio
.queue
w[t]=INT_MIN;
s=t,t=max_element(ALL(w))-w.begin();
REP(i,0,n)w[i]+=mat[t][i];}
best=min(best,{w[t]-mat[t][t],co[t]});
co[s].insert(co[s].end(),ALL(co[t]));
REP(i,0,n)mat[s][i]+=mat[t][i];
REP(i,0,n)mat[i][s]=mat[s][i];
mat[0][t]=INT_MIN;}return best;}
```

7.2 Matching

WeightedMatching.h

Description: Given a weighted bipartite graph, matches every node on the left with a node on the right such that no nodes are in two matchings and the sum of the edge weights is minimal. Takes $\text{cost}[N][M]$, where $\text{cost}[i][j]$ = cost for $L[i]$ to be matched with $R[j]$ and returns (min cost, match), where $L[i]$ is matched with $R[\text{match}[i]]$. Negate costs for max cost.

Time: $\mathcal{O}(N^2M)$

b7cb2b, 20 lines

```
pair<int,VI>hungarian(const vector<VI>&a){
if(a.empty())return{0,{}};
int n=SZ(a)+1,m=SZ(a[0])+1;
VI u(n),v(m),p(m),ans(n-1);REP(i,1,n){
p[0]=i;int j0=0;//add "dummy" worker 0
VI dist(m,INT_MAX),pre(m,-1);
vector<bool>done(m+1);do//dijkstra
done[j0]=true;
int i0=p[j0],j1,delta=INT_MAX;
```

```
REP(j,1,m)if(!done[j]){
auto cur=a[i0-1][j-1]-u[i0]-v[j];
if(cur<dist[j])dist[j]=cur,pre[j]=j0;
if(dist[j]<delta)delta=dist[j],j1=j;}
REP(j,0,m){
if(done[j])u[p[j]]+=delta,v[j]-=delta;
else dist[j]-=delta;j0=j1;}while(p[j0]);
while(j0){//update alternating path
int j1=pre[j0];p[j0]=p[j1],j0=j1;}
REP(j,1,m)if(p[j])ans[p[j]-1]=j-1;
return{-v[0],ans};//min cost}
```

7.3 DFS algorithms

SCC.h

Description: Finds strongly connected components in a directed graph. If vertices u, v belong to the same component, we can reach u from v and vice versa.

Usage: `scc(graph, [&](VI& v) { ... })` visits all components in reverse topological order. `comp[i]` holds the component index of a node (a component only has edges to components with lower index). `ncomps` will contain the number of components.

Time: $\mathcal{O}(E + V)$

c6a3ff, 14 lines

```
VI val,comp,z,cont;int Time,ncomps;
template<class G,class F>int dfs(int j,G&g,F
&f){
int low=val[j]++Time,x;z.push_back(j);
for(auto e:g[j])if(comp[e]<0)
low=min(low,val[e]?dfs(e,g,f));
if(low==val[j]){
do{x=z.back();z.pop_back();
comp[x]=ncomps;cont.push_back(x);
}while(x!=j);
f(cont);cont.clear();ncomps++;}
return val[j]=low;}
template<class G,class F>void scc(G&g,F f){
int n=SZ(g);val.assign(n,0);comp.assign(n,
-1);
Time=ncomps=0;REP(i,0,n)if(comp[i]<0)dfs(i,g
,f);}
```

BiconnectedComponents.h

Description: Finds all biconnected components in an undirected graph, and runs a callback for the edges in each. In a biconnected component there are at least two distinct paths between any two nodes. Note that a node can be in several components. An edge which is not in a component is a bridge, i.e., not part of any cycle.

Usage: `int eid = 0; ed.resize(N);`
for each edge (a,b) {
`ed[a].emplace_back(b, eid);`
`ed[b].emplace_back(a, eid++);` }
`bicomps([&](const VI& edgelist) {...});`

Time: $\mathcal{O}(E + V)$

69fe6f, 18 lines

```
VI num,st;vector<vector<PII>>ed;int Time;
template<class F>
int dfs(int at,int par,F&f){
int me=num[at]++Time,e,y,top=me;
for(auto pa:ed[at])if(pa.second!=par){
tie(y,e)=pa;if(num[y]){
top=min(top,num[y]);
if(num[y]<me)st.push_back(e);}else{
int si=SZ(st);int up=dfs(y,e,f);
top=min(top,up);if(up==me){
st.push_back(e);
f(VI(st.begin()+si,st.end()));
st.resize(si);}
else if(up<me)st.push_back(e);
else/*e is a bridge*/}}return top;}
template<class F>void bicomps(F f){
num.assign(SZ(ed),0);
REP(i,0,SZ(ed))if(!num[i])dfs(i,-1,f);}
```

2sat.h

Description: Valid Assignment

Usage: `TwoSat ts(number of boolean variables);`
`ts.either(0, ~3);` // Var 0 is true or var 3 is false
`ts.setValue(2);` // Var 2 is true
`ts.atMostOne({0,~1,2});` // ≤ 1 of vars 0, ~1 and 2 are true
`ts.solve();` // Returns true iff it is solvable
`ts.values[0..N-1]` holds the assigned values to the vars

Time: $\mathcal{O}(N + E)$, where N is the number of boolean variables, and E is the number of clauses.

f77183, 34 lines

```
struct two_sat{
int n;VVI g,gr;//gr is the reversed graph
VI comp,topo,ans,vis;//comp[v]ID of the SCC
containing node v
two_sat(){two_sat(int n){init(_n);}
void init(int n){n=n;g.assign(2*n,VI());
gr.assign(2*n,VI());comp.resize(2*n);
vis.resize(2*n);ans.resize(2*n);}
void add(int u,int v){
g[u].PB(v);gr[v].PB(u);}
/*For the following three functions int x,
bool val;if val is true,we take the
variable to be x.Otherwise we take it to
be x's complement. At least one of them
is true*/
void add_or(int i,bool f,int j,bool g){
add(i+(f?n:0),j+(g?0:n));add(j+(g?n:0),i+(f
?0:n));}
//Only one of them is true
void add_xor(int i,bool f,int j,bool g){
add_or(i,f,j,g);add_or(i,!f,j,!g);}
//Both of them have the same value
void add_and(int i,bool f,int j,bool g){
add_xor(i,!f,j,g);}
//Topological sort
void dfs(int u){vis[u]=1;
for(auto&v:g[u])if(!vis[v])dfs(v);topo.PB(u)
;}
//Extracting strongly connected components
void scc(int u,int id){
vis[u]=1;comp[u]=id;
for(auto&v:gr[u])if(!vis[v])scc(v,id);}
//Returns true if the given proposition is
satisfiable and constructs a valid
assignment
bool satisfiable(){fill(ALL(vis),0);
FOR(i,0,2*n)if(!vis[i])dfs(i);
fill(ALL(vis),0);reverse(ALL(topo));
int id=0;for(auto&v:topo)
if(!vis[v])scc(v,id++);
//Constructing the answerFOR(i,0,n){
if(comp[i]==comp[i+n])return false;
ans[i]=(comp[i]>comp[i+n]?1:0);}
return true;}};
```

7.4 Coloring

EdgeColoring.h

Description: Given a simple, undirected graph with max degree D , computes a $(D + 1)$ -coloring of the edges such that no neighboring edges share a color. (D -coloring is NP-hard, but can be done for bipartite graphs by repeated matchings of max-degree nodes.)

Time: $\mathcal{O}(NM)$

8618ee, 23 lines

```
VI edgeColoring(int N,vector<PII>eds){
VI cc(N+1),ret(SZ(eds)),fan(N),free(N),loc;
for(PII e:eds)++cc[e.first],++cc[e.second];
int u,v,ncols=*max_element(ALL(cc))+1;
vector<VI>adj(N,VI(ncols,-1));
for(PII e:eds){tie(u,v)=e;fan[0]=v;
loc.assign(ncols,0);
int at=u,end=u,d,c=free[u],ind=0,i=0;
while(d=free[v],!loc[d]&&(v=adj[u][d])!=-1)
loc[d]=++ind,cc[ind]=d,fan[ind]=v;
cc[loc[d]]=c;
for(int cd=d;at!=-1;cd^=c^d,at=adj[at][cd])
swap(adj[at][cd],adj[end=at][cd^c^d]);
while(adj[fan[i]][d]!=-1){
int left=fan[i],right=fan[++i],e=cc[i];
adj[u][e]=left;adj[left][e]=u;
adj[right][e]=-1;free[right]=e;}
adj[u][d]=fan[i];adj[fan[i]][d]=u;
for(int y:{fan[0],u,end})
for(int&z=free[y]=0;adj[y][z]!=-1;z++);}
REP(i,0,SZ(eds))
for(tie(u,v)=eds[i];adj[u][ret[i]]!=v;++ret
[i]);
return ret;}
```

BipartiteGraphColoring.h

Description: change max-values of m and n according to problem. v is vector of edges and cv is the color of corresponding edge. solve returns the maximum number of colors used. call the solve function to get the colors from 1 to d in $\mathcal{O}(n*m)$. Space occupied by `deg` is $2*(\text{max nodes possible on 1 side})$. Space occupied by `has` is $2*2*(\text{max nodes possible on 1 side})*(\text{max colors possible})$. Space occupied by `deg` is $(\text{max edges possible})$.

8c04bb, 26 lines

```
struct edge_color{int deg[2][MAXN];
```

```
II has[2][MAXN][MAXN];int color[MAXM];
int c[2];void clear(int n){
for(int t=0;t<2;t++){
for(int i=0;i<=n;i++){deg[t][i]=0;
for(int j=0;j<=n;j++){
has[t][i][j]=II(0,0);}}}}
void dfs(int x,int p){
auto i=has[p][x][c[!p]];
if(has[!p][i.first][c[p]].second)dfs(i.first
,!p);
else has[!p][i.first][c[!p]]=II(0,0);
has[p][x][c[p]]=i;
has[!p][i.first][c[p]]=II(x,i.second);
color[i.second]=c[p];}
int solve(vector<II>v,vector<int>&cv){
int m=SZ(v);int ans=0;
for(int i=1;i<=m;i++){int x[2];
x[0]=v[i-1].first;x[1]=v[i-1].second;
for(int d=0;d<2;d++){deg[d][x[d]]+=1;
ans=max(ans,deg[d][x[d]]);
for(c[d]=1;has[d][x[d]][c[d]].second;c[d]++)
;
}if(c[0]!=c[1])dfs(x[1],1);
for(int d=0;d<2;d++)has[d][x[d]][c[0]]=II(x
[!d],i);
color[i]=c[0];}cv.resize(m);
for(int i=1;i<=m;i++){cv[i-1]=color[i];
color[i]=0;}return ans;}};
```

7.5 Trees

BinaryLifting.h

Description: Assumes the root node points to itself.

Time: construction $\mathcal{O}(N \log N)$, queries $\mathcal{O}(\log N)$

c4e44c, 16 lines

```
vector<VI>treeJump(VI&P){int on=1,d=1;
while(on<SZ(P))on*=2,d++;
vector<VI>jmp(d,P);
REP(i,1,d)REP(j,0,SZ(P))
jmp[i][j]=jmp[i-1][jmp[i-1][j]];
return jmp;}
int jmp(vector<VI>&tbl,int nod,int steps){
REP(i,0,SZ(tbl))
if(steps&(1<<i))nod=tbl[i][nod];
return nod;}
```



```
int lca(vector<VI>&tbl,VI&depth,int a,int b)
{
    if(depth[a]<depth[b])swap(a,b);
    a=jmp(tbl,a,depth[a]-depth[b]);
    if(a==b)return a;for(int i=SZ(tbl);i--;){
        int c=tbl[i][a],d=tbl[i][b];
        if(c!=d)a=c,b=d;}return tbl[0][a];}
```

LCA.h

Description: Data structure for computing lowest common ancestors in a tree (with 0 as root). C should be an adjacency list of the tree, either directed or undirected.

Time: $\mathcal{O}(N \log N + Q)$

"/data-structures/RMQ.h" cbd116, 11 lines

```
struct LCA{int T=0;VI time,path,ret;
RMQ<int>rmq;
LCA(vector<VI>&C):time(SZ(C)),rmq((dfs(C,0,-1),ret)){}
void dfs(vector<VI>&C,int v,int par){
    time[v]=T++;for(int y:C[v])if(y!=par){
        path.push_back(v),ret.push_back(time[v]);
        dfs(C,y,v);}int lca(int a,int b){
        if(a==b)return a;
        tie(a,b)=minmax(time[a],time[b]);
        return path[rmq.query(a,b)];};
//dist(a,b){ret depth[a]+depth[b]-2*depth[
    lca(a,b)];}
```

CompressTree.h

Description: Assumes the root node points to itself.

Time: construction $\mathcal{O}(N \log N)$, queries $\mathcal{O}(\log N)$

0292cd, 13 lines

```
bool cmp(int u,int v){return arr[u]<arr[v];}
int create_tree(){//return root of tree
set<int>S;//get distinct nodesFord
REP(i,k)S.insert(Q[i]);k=0;for(auto it:S)Q[k++] = it;
sort(Q,Q+k,cmp);int kk=k;//distinct initial nodes
//add lca of adjacent pairs
for(int i=0;i<kk-1;i++){int x=lca(Q[i],Q[i+1]);
if(S.count(x))continue;Q[k++] = x;S.insert(x);
}sort(Q,Q+k,cmp);stack<int>s;s.push(Q[0]);
for(int i=1;i<k;i++){
while(!anc(s.top(),Q[i]))s.pop();
```

```
tree[s.top()].PB(Q[i]);tree[Q[i]].PB(s.top());
s.push(Q[i]);}return Q[0];}
```

HLD.h

Description: Decomposes a tree into vertex disjoint heavy paths and light edges such that the path from any leaf to the root contains at most $\log(n)$ light edges. Code does additive modifications and max queries, but can support commutative segtree modifications/queries on paths and subtrees. Takes as input the full adjacency list. VALS.EDGES being true means that values are stored in the edges, as opposed to the nodes. All values initialized to the segtree default. Root must be 0.

Time: $\mathcal{O}((\log N)^2)$

c4840c, 17 lines

```
VI sz,sc,hd,en,ex,par,dep;
seg_tree_lazy<node,update>st(1,{0,0},{0,0});
int timer=-1;
void hld(int u,int p,int ch,int d){
    hd[u]=ch;en[u]=++timer;par[u]=p;dep[u]=d;
    if(sc[u]!=-1)hld(sc[u],u,ch,d+1);
    for(auto e:g[u]){int v=U[e]^V[e]^u;
        if(v==p||v==sc[u])continue;
        hld(v,u,v,d+1);}ex[u]=timer;
    int path(int x,int y){int ma=(int)-1e9;
    while(hd[x]!=hd[y]){
        if(dep[hd[x]]<dep[hd[y]])swap(x,y);
        ma=max(st.query(en[hd[x]],en[x]).sum,ma);
        x=par[hd[x]];}//hd[x]->x upar wali line
        if(dep[x]<dep[y])swap(x,y);
        ma=max(ma,st.query(en[y],en[x]).sum);//y->x
    return ma;}
```

CentriodDecomposition.h

Description: Assumes the root node points to itself.

Time: construction $\mathcal{O}(N \log N)$, queries $\mathcal{O}(\log N)$

f8ca72, 11 lines

```
VI U,V,W,isDel;int dp[n][log2(n)+1];
//(avoid deleted edges)in all 3 DFS
void decompose(int root,int p){
    dfs_sz(root,-1);//calc sizes of subtrees
    int c=get_centroid(root,-1,sz[root]);//if sz
        [v]*2>sz[root]return get_centroid(v)else
        return u
    if(p==-1)p=root;
    //Add edge btwn p and c here
```

```
dfs(c);//to compute functions
for(auto e:g[root]){if(isDel[e])continue;
isDel[e]=1;int v=U[e]^V[e]^u;
decompose(v,root);}}
```

Geometry (8)

8.1 Geometric primitives

Point.h

Description: Class to handle points in the plane. T can be e.g. double or long long. (Avoid int.)

47ec0a, 25 lines

```
template<class T>int sgn(T x){return(x>0)-(x<0);}
template<class T>struct Point{
    typedef Point P;T x,y;
    explicit Point(T x=0,T y=0):x(x),y(y){}
    bool operator<(P p)const{return tie(x,y)<tie(p.x,p.y);}
    bool operator==(P p)const{return tie(x,y)==tie(p.x,p.y);}
    P operator+(P p)const{return P(x+p.x,y+p.y);}
    P operator-(P p)const{return P(x-p.x,y-p.y);}
    P operator*(T d)const{return P(x*d,y*d);}
    P operator/(T d)const{return P(x/d,y/d);}
    T dot(P p)const{return x*p.x+y*p.y;}
    T cross(P p)const{return x*p.y-y*p.x;}
    T cross(P a,P b)const{return(a-*this).cross(b-*this);}
    T dist2()const{return x*x+y*y;}
    double dist()const{return sqrt((double)dist2());}
    //angle to x-axis in interval[-pi,pi]
    double angle()const{return atan2(y,x);}
    P unit()const{return*this/dist();} //makes dist()=1
    P perp()const{return P(-y,x);} //rotates+90 degrees
    P normal()const{return perp().unit();}
    //returns point rotated'a' radians ccw around the origin
    P rotate(double a)const{
```

```

return P(x*cos(a)-y*sin(a),x*sin(a)+y*cos(a));
}
friend ostream&operator<<(ostream&os,P p){
return os<<"("<<p.x<<"", "<<p.y<<"");};

```

lineDistance.h

Description:

Returns the signed distance between point p and the line containing points a and b . Positive value on left side and negative on right as seen from a towards b . $a==b$ gives nan. P is supposed to be $\text{Point}<T>$ or $\text{Point3D}<T>$ where T is e.g. double or long long. It uses products in intermediate steps so watch out for overflow if using int or long long. Using Point3D will always give a non-negative distance. For Point3D , call `.dist` on the result of the cross product.

"Point.h" f6bf6b, 4 lines

```

template<class P>
double lineDist(const P&a,const P&b,const P&
p){
return(double)(b-a).cross(p-a)/(b-a).dist();
}

```

SegmentDistance.h

Description:

Returns the shortest distance between point p and the line segment from point s to e .

Usage: $\text{Point}<\text{double}>$ $a, b(2,2), p(1,1);$
 $\text{bool onSegment} = \text{segDist}(a,b,p) < 1e-10;$

"Point.h" 5c88f4, 5 lines

```

typedef Point<double>P;
double segDist(P&s,P&e,P&p){
if(s==e)return(p-s).dist();
auto d=(e-s).dist2(),t=min(d,max(.0,(p-s).
dot(e-s)));
return((p-s)*d-(e-s)*t).dist()/d;}

```

SegmentIntersection.h

Description:

If a unique intersection point between the line segments going from s_1 to e_1 and from s_2 to e_2 exists then it is returned. If no intersection point exists an empty vector is returned. If infinitely many exist a vector with 2 elements is returned, containing the endpoints of the common line segment. The wrong position will be returned if P is $\text{Point}<\text{ll}>$ and the intersection point does not have integer coordinates. Products of three coordinates are used in intermediate steps so watch out for overflow if using int or long long.

Usage: $\text{vector}<P>$ $\text{inter} = \text{segInter}(s_1,e_1,s_2,e_2);$
 $\text{if}(\text{SZ}(\text{inter})==1)$
 $\text{cout} << \text{"segments intersect at " } << \text{inter}[0] << \text{endl};$

"Point.h", "OnSegment.h" 36c2d7, 11 lines

```

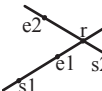
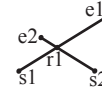
template<class P>vector<P>segInter(P a,P b,P
c,P d){
auto oa=c.cross(d,a),ob=c.cross(d,b),
oc=a.cross(b,c),od=a.cross(b,d);
//Checks if intersection is single non-
endpoint point.
if(sgn(oa)*sgn(ob)<0&&sgn(oc)*sgn(od)<0)
return{(a*ob-b*oa)/(ob-oa)};set<P>s;
if(onSegment(c,d,a))s.insert(a);
if(onSegment(c,d,b))s.insert(b);
if(onSegment(a,b,c))s.insert(c);
if(onSegment(a,b,d))s.insert(d);
return{ALL(s)};};

```

lineIntersection.h

Description:

If a unique intersection point of the lines going through s_1,e_1 and s_2,e_2 exists $\{1, \text{point}\}$ is returned. If no intersection point exists $\{0, (0,0)\}$ is returned and if infinitely many exist $\{-1, (0,0)\}$ is returned. The wrong position will be returned if P is $\text{Point}<\text{ll}>$ and the intersection point does not have integer coordinates. Products of three coordinates are used in intermediate steps so watch out for overflow if using int or ll.



Usage: $\text{auto res} = \text{lineInter}(s_1,e_1,s_2,e_2);$
 $\text{if}(\text{res.first} == 1)$
 $\text{cout} << \text{"intersection point at " } << \text{res.second} << \text{endl};$

"Point.h" a01f81, 7 lines

```

template<class P>
pair<int,P>lineInter(P s1,P e1,P s2,P e2){
auto d=(e1-s1).cross(e2-s2);
if(d==0)//if parallel
return{-(s1.cross(e1,s2)==0),P(0,0)};
auto p=s2.cross(e1,e2),q=s2.cross(e2,s1);
return{1,(s1*p+e1*q)/d};}

```

sideOf.h

Description: Returns where p is as seen from s towards e . $1/0/-1 \Leftrightarrow \text{left/on line/right}$. If the optional argument eps is given 0 is returned if p is within distance eps from the line. P is supposed to be $\text{Point}<T>$ where T is e.g. double or long long. It uses products in intermediate steps so watch out for overflow if using int or long long.

Usage: $\text{bool left} = \text{sideOf}(p_1,p_2,q)==1;$

"Point.h" 3af81c, 3 lines

```

template<class P>
int sideOf(P s,P e,P p){return sgn(s.cross(e
,p));}
template<class P>
int sideOf(const P&s,const P&e,const P&p,
double eps){
auto a=(e-s).cross(p-s);
double l=(e-s).dist()*eps;
return(a>l)-(a<-l);}

```

OnSegment.h

Description: Returns true iff p lies on the line segment from s to e . Use $(\text{segDist}(s,e,p) \leq \text{epsilon})$ instead when using $\text{Point}<\text{double}>$.

"Point.h" c597e8, 3 lines

```

template<class P>bool onSegment(P s,P e,P p)
{
return p.cross(s,e)==0&&(s-p).dot(e-p)<=0;
}

```


linearTransformation.h

Description:

Apply the linear transformation (translation, rotation and scaling) which takes line p0-p1 to line q0-q1 to point r.

"Point.h"

03a306, 6 lines

```
typedef Point<double>P;
P linearTransformation(const P&p0,const P&p1
,
const P&q0,const P&q1,const P&r){
P dp=p1-p0,dq=q1-q0,num(dp.cross(dq),dp.dot(
dq));
return q0+P((r-p0).cross(num),(r-p0).dot(num
))/dp.dist2();
}
```

LineProjectionReflection.h

Description: Projects point p onto line ab. Set refl=true to get reflection of point p across line ab insted. The wrong point will be returned if P is an integer point and the desired point doesn't have integer coordinates. Products of three coordinates are used in intermediate steps so watch out for overflow.

"Point.h"

b5562d, 5 lines

```
template<class P>
P lineProj(P a,P b,P p,bool refl=false){
P v=b-a;
return p-v.perp()*(1+refl)*v.cross(p-a)/v.
dist2();
}
```

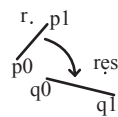
Angle.h

Description: A class for ordering angles (as represented by int points and a number of rotations around the origin). Useful for rotational sweeping. Sometimes also represents points or vectors.

Usage: vector<Angle> v = {w[0], w[0].t360()...}; // sorted
int j = 0; REP(i,0,n) { while (v[j] < v[i].t180()) ++j; }
// sweeps j such that (j-i) represents the number of positively oriented triangles with vertices at 0 and i

0f0602, 24 lines

```
struct Angle{int x,y,int t;
Angle(int x,int y,int t=0):x(x),y(y),t(t){}
```



```
Angle operator-(Angle b){return{x-b.x,y
-b.y,t};}
int half()const{assert(x||y);
return y<0||(y==0&&x<0);}
Angle t90()const{return{-y,x,t+(half()&&x
>=0)};}
Angle t180()const{return{-x,-y,t+half()};}
Angle t360()const{return{x,y,t+1}};};
bool operator<(Angle a,Angle b){
//add a.dist2()and b.dist2()to also compare
distances
return make_tuple(a.t,a.half(),a.y*(ll)b.x)<
make_tuple(b.t,b.half(),a.x*(ll)b.y);}
//Given two points,this calculates the
smallest angle between
//them,i.e.,the angle that covers the
defined line segment.
pair<Angle,Angle>segmentAngles(Angle a,Angle
b){
if(b<a)swap(a,b);return(b<a.t180()?
make_pair(a,b):make_pair(b,a.t360()));}
Angle operator+(Angle a,Angle b){//point a+
vector b
Angle r(a.x+b.x,a.y+b.y,a.t);
if(a.t180()<r)r.t--;
return r.t180()<a?r.t360():r;}
Angle angleDiff(Angle a,Angle b){//angle b-
angle a
int tu=b.t-a.t;a.t=b.t;
return{a.x*b.x+a.y*b.y,a.x*b.y-a.y*b.x,tu-(b
<a)};}
```

8.2 Circles

CircleIntersection.h

Description: Computes the pair of points at which two circles intersect. Returns false in case of no intersection.

"Point.h"

84d6d3, 9 lines

```
typedef Point<double>P;
bool circleInter(P a,P b,double r1,double r2
,pair<P,P>*out){
if(a==b){assert(r1!=r2);return false;}
P vec=b-a;
double d2=vec.dist2(),sum=r1+r2,dif=r1-r2,
p=(d2+r1*r1-r2*r2)/(d2*2),h2=r1*r1-p*p*d2;
if(sum*sum<d2||dif*dif>d2)return false;
```

```
P mid=a+vec*p,per=vec.perp()*sqrt(fmax(0,h2)
/d2);
*out={mid+per,mid-per};return true;}
```

CircleTangents.h

Description: Finds the external tangents of two circles, or internal if r2 is negated. Can return 0, 1, or 2 tangents – 0 if one circle contains the other (or overlaps it, in the internal case, or if the circles are the same); 1 if the circles are tangent to each other (in which case .first = .second and the tangent line is perpendicular to the line between the centers). .first and .second give the tangency points at circle 1 and 2 respectively. To find the tangents of a circle with a point set r2 to 0.

"Point.h"

b0153d, 10 lines

```
template<class P>
vector<pair<P,P>>tangents(P c1,double r1,P
c2,double r2){
P d=c2-c1;
double dr=r1-r2,d2=d.dist2(),h2=d2-dr*dr;
if(d2==0||h2<0)return{};
vector<pair<P,P>>out;
for(double sign:{-1,1}){
P v=(d*dr+d.perp()*sqrt(h2)*sign)/d2;
out.push_back({c1+v*r1,c2+v*r2});}
if(h2==0)out.pop_back();return out;}
```

CircleLine.h

Description: Finds the intersection between a circle and a line. Returns a vector of either 0, 1, or 2 intersection points. P is intended to be Point<double>.

"Point.h"

eea4d5, 7 lines

```
template<class P>
vector<P>circleLine(P c,double r,P a,P b){
if(a==b)return{};
P ab=b-a,p=a+ab*(c-a).dot(ab)/ab.dist2();
double s=a.cross(b,c),h2=r*r-s*s/ab.dist2();
if(h2<0)return{};if(h2==0)return{p};
P h=ab.unit()*sqrt(h2);return{p-h,p+h};}
```

CirclePolygonIntersection.h

Description: Returns the area of the intersection of a circle with a ccw polygon.

Time: $\mathcal{O}(n)$

"../content/geometry/Point.h"

f5c096, 16 lines

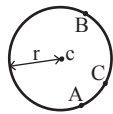
```
typedef Point<double>P;
#define arg(p,q)atan2(p.cross(q),p.dot(q))

double circlePoly(P c,double r,vector<P>ps){
auto tri=[&](P p,P q){auto r2=r*r/2;
P d=q-p;
auto a=d.dot(p)/d.dist2(),b=(p.dist2()-r*r)/
d.dist2();
auto det=a*a-b;
if(det<=0)return arg(p,q)*r2;
auto s=max(0.,-a-sqrt(det)),t=min(1.,-a+sqrt
(det));
if(t<0||1<=s)return arg(p,q)*r2;
P u=p+d*s,v=p+d*t;
return arg(p,u)*r2+u.cross(v)/2+arg(v,q)*r2;
};auto sum=0.0;REP(i,0,SZ(ps))
sum+=tri(ps[i]-c,ps[(i+1)%SZ(ps)]-c);
return sum;}
```

circumcircle.h

Description:

The circumcircle of a triangle is the circle intersecting all three vertices. ccRadius returns the radius of the circle going through points A, B and C and ccCenter returns the center of the same circle.



```
"Point.h"
1caa3a, 8 lines

typedef Point<double>P;
double ccRadius(const P&A,const P&B,const P&C){
return (B-A).dist()*(C-B).dist()*(A-C).dist()
/
abs((B-A).cross(C-A))/2;
P ccCenter(const P&A,const P&B,const P&C){
P b=C-A,c=B-A;
return A+(b*c.dist2()-c*b.dist2()).perp()/b.
cross(c)/2;
}
```

MinimumEnclosingCircle.h

Description: Computes the minimum circle that encloses a set of points.

Time: expected $\mathcal{O}(n)$

```
"circumcircle.h"
69dd52, 10 lines

pair<P,double>mec(vector<P>ps){
```

```
shuffle(ALL(ps),mt19937(time(0)));
P o=ps[0];double r=0,EPS=1+1e-8;
REP(i,0,SZ(ps))if((o-ps[i]).dist()>r*EPS){
o=ps[i],r=0;
REP(j,0,i)if((o-ps[j]).dist()>r*EPS){
o=(ps[i]+ps[j])/2;r=(o-ps[i]).dist();
REP(k,0,j)if((o-ps[k]).dist()>r*EPS){
o=ccCenter(ps[i],ps[j],ps[k]);
r=(o-ps[i]).dist();}}}}return{o,r};}
```

CircleCircleArea.h

Description: Calculates the area of the intersection of 2 circles

8bf2b6, 12 lines

```
template<class P>
double circleCircleArea(P c, double cr, P d,
double dr) {
if (cr < dr) swap(c, d), swap(cr, dr);
auto A = [&](double r, double h) {
return r*r*acos(h/r)-h*sqrt(r*r-h*h);
};
auto l = (c - d).dist(), a = (l*l + cr*cr
- dr*dr)/(2*l);
if (l - cr - dr >= 0) return 0; // far
away
if (l - cr + dr <= 0) return M_PI*dr*dr;
if (l - cr >= 0) return A(cr, a) + A(dr, l
-a);
else return A(cr, a) + M_PI*dr*dr - A(dr,
a-l);
}
```

8.3 Polygons

InsidePolygon.h

Description: Returns true if p lies within the polygon. If strict is true, it returns false for points on the boundary. The algorithm uses products in intermediate steps so watch out for overflow.

Usage: vector<P> v = {P{4,4}, P{1,2}, P{2,1}};

bool in = inPolygon(v, P{3, 3}, false);

Time: $\mathcal{O}(n)$

```
"Point.h", "OnSegment.h", "SegmentDistance.h"
2261c4, 8 lines

template<class P>
bool inPolygon(vector<P>&p,P a,bool strict=
true){
```

```
int cnt=0,n=SZ(p);REP(i,0,n){
P q=p[(i+1)%n];
if(onSegment(p[i],q,a))return!strict;
//or:if(segDist(p[i],q,a)<=eps)return!strict;
;
cnt^=((a.y<p[i].y)-(a.y<q.y))*a.cross(p[i],q)
)>0;
}return cnt;}
```

PolygonArea.h

Description: Returns twice the signed area of a polygon. Clockwise enumeration gives negative area. Watch out for overflow if using int as T!

```
"Point.h"
e287fe, 5 lines

template<class T>
T polygonArea2(vector<Point<T>>&v){
T a=v.back().cross(v[0]);
REP(i,0,SZ(v)-1)a+=v[i].cross(v[i+1]);
return a;}
```

PolygonCenter.h

Description: Returns the center of mass for a polygon.

Time: $\mathcal{O}(n)$

```
"Point.h"
7d84e0, 6 lines

typedef Point<double>P;
P polygonCenter(const vector<P>&v){
P res(0,0);double A=0;
for(int i=0,j=SZ(v)-1;i<SZ(v);j=i++){
res=res+(v[i]+v[j])*v[j].cross(v[i]);
A+=v[j].cross(v[i]);}return res/A/3;}
```

PolygonCut.h

Description:

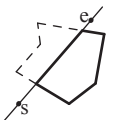
Returns a vector with the vertices of a polygon with everything to the left of the line going from s to e cut away.

Usage: vector<P> p = ...;

p = polygonCut(p, P(0,0), P(1,0));

```
"Point.h", "LineIntersection.h"
f50354, 11 lines

typedef Point<double>P;
vector<P>polygonCut(const vector<P>&poly,P s
,P e){
if(SZ(poly)<=2)return{};vector<P>res;
REP(i,0,SZ(poly)){
P cur=poly[i],prev=i?poly[i-1]:poly.back();
if(zero(s.cross(e,cur))){
```



```
res.push_back(cur);continue;}
bool side=s.cross(e,cur)<0;
if(side!=(s.cross(e,prev)<0))
res.push_back(lineInter(s,e,cur,prev).second);
if(side)res.push_back(cur);return res;}
```

PolygonUnion.h

Description: Calculates the area of the union of n polygons (not necessarily convex). The points within each polygon must be given in CCW order. (Epsilon checks may optionally be added to sideOf/sgn, but shouldn't be needed.)

Time: $\mathcal{O}(N^2)$, where N is the total number of points

"Point.h", "sideOf.h" a0db1d, 25 lines

```
typedef Point<double>P;
double rat(P a,P b){return sgn(b.x)?a.x/b.x:
a.y/b.y;}
double polyUnion(vector<vector<P>>&poly){
double ret=0;
REP(i,0,SZ(poly))REP(v,0,SZ(poly[i])){
P A=poly[i][v],B=poly[i][(v+1)%SZ(poly[i])];
vector<pair<double,int>>segs={{0,0},{1,0}};
REP(j,0,SZ(poly))if(i!=j){
REP(u,0,SZ(poly[j])){
P C=poly[j][u],D=poly[j][(u+1)%SZ(poly[j])];
int sc=sideOf(A,B,C),sd=sideOf(A,B,D);
if(sc!=sd){
double sa=C.cross(D,A),sb=C.cross(D,B);
if(min(sc,sd)<0)
segs.emplace_back(sa/(sa-sb),sgn(sc-sd));
}else if(!sc&&!sd&&j<i&&sgn((B-A).dot(D-C))
>0){
segs.emplace_back(rat(C-A,B-A),1);
segs.emplace_back(rat(D-A,B-A),-1);}}}
sort(ALL(segs));
for(auto&s:segs)s.first=min(max(s.first,0.0),
1.0);
double sum=0;int cnt=segs[0].second;
REP(j,1,SZ(segs)){
if(!cnt)sum+=segs[j].first-segs[j-1].first;
cnt+=segs[j].second;}ret+=A.cross(B)*sum;}
return ret/2;}
```

ConvexHull.h

Description:

Returns a vector of the points of the convex hull in counter-clockwise order. Points on the edge of the hull between two other points are not considered part of the hull.

Time: $\mathcal{O}(n \log n)$

"Point.h"

c5c490, 10 lines

```
typedef Point<ll>P;
vector<P>convexHull(vector<P>pts){
if(SZ(pts)<=1)return pts;sort(ALL(pts));
vector<P>h(SZ(pts)+1);int s=0,t=0;
for(int it=2;it--;s--t,reverse(ALL(pts)))
for(P p:pts){
while(t>=s+2&&h[t-2].cross(h[t-1],p)<=0)t--;
h[t++]=p;}
return{h.begin(),h.begin()+t-(t==2&&h[0]==h[1])};
}
```

HullDiameter.h

Description: Returns the two points with max distance on a convex hull (ccw, no duplicate/collinear points).

"Point.h"

261063, 8 lines

```
typedef Point<ll>P;
array<P,2>hullDiameter(vector<P>S){
int n=SZ(S),j=n<2?0:1;
pair<ll,array<P,2>>res({0,{S[0],S[0]}});
REP(i,0,j)for(;;j=(j+1)%n){
res=max(res,({S[i]-S[j]}.dist2(),{S[i],S[j]}));
};
if((S[(j+1)%n]-S[j]).cross(S[i+1]-S[i])>=0)
break;}return res.second;}
```

PointInsideHull.h

Description: Determine whether a point t lies inside a convex hull (CCW order, with no collinear points). Returns true if point lies within the hull. If strict is true, points on the boundary aren't included.

Time: $\mathcal{O}(\log N)$

"Point.h", "sideOf.h", "OnSegment.h"

efb6da, 10 lines

```
typedef Point<ll>P;
bool inHull(const vector<P>&l,P p,bool
strict=true){
int a=1,b=SZ(l)-1,r=!strict;
```

```
if(SZ(l)<3)return r&&onSegment(l[0],l.back(),p);
if(sideOf(l[0],l[a],l[b])>0)swap(a,b);
if(sideOf(l[0],l[a],p)>=r||sideOf(l[0],l[b],p)<=-r)
return false;while(abs(a-b)>1){
int c=(a+b)/2;
(sideOf(l[0],l[c],p)>0?b:a)=c;}
return sgn(l[a].cross(l[b],p))<r;}
```

LineHullIntersection.h

Description: Line-convex polygon intersection. The polygon must be ccw and have no collinear points. lineHull(line, poly) returns a pair describing the intersection of a line with the polygon: $\bullet (-1, -1)$ if no collision, $\bullet (i, -1)$ if touching the corner i , $\bullet (i, i)$ if along side $(i, i+1)$, $\bullet (i, j)$ if crossing sides $(i, i+1)$ and $(j, j+1)$. In the last case, if a corner i is crossed, this is treated as happening on side $(i, i+1)$. The points are returned in the same order as the line hits the polygon. extVertex returns the point of a hull with the max projection onto a line.

Time: $\mathcal{O}(\log n)$

"Point.h"

331463, 28 lines

```
#define cmp(i,j)sgn(dir.perp().cross(poly[(i)%n]-poly[(j)%n]))
#define extr(i)cmp(i+1,i)>=0&&cmp(i,i-1+n)<0
template<class P>int extrVertex(vector<P>&
poly,P dir){
int n=SZ(poly),lo=0,hi=n;
if(extr(0))return 0;while(lo+1<hi){
int m=(lo+hi)/2;if(extr(m))return m;
int ls=cmp(lo+1,lo),ms=cmp(m+1,m);
(ls<ms||(ls==ms&&ls==cmp(lo,m))?hi:lo)=m;}
return lo;}
#define cmpL(i)sgn(a.cross(poly[i],b))
template<class P>
array<int,2>lineHull(P a,P b,vector<P>&poly)
{
int endA=extrVertex(poly,(a-b).perp());
int endB=extrVertex(poly,(b-a).perp());
if(cmpL(endA)<0||cmpL(endB)>0)
return{-1,-1};array<int,2>res;REP(i,0,2){
int lo=endB,hi=endA,n=SZ(poly);
while((lo+1)%n!=hi){
```

```
int m=((lo+hi+(lo<hi?0:n))/2)%n;
(cmpL(m)==cmpL(endB)?lo:hi)=m;}
res[i]=(lo+!cmpL(hi))%n;swap(endA,endB);}
if(res[0]==res[1])return{res[0],-1};
if(!cmpL(res[0])&&!cmpL(res[1]))
switch((res[0]-res[1]+SZ(poly)+1)%SZ(poly)){
case 0:return{res[0],res[0]};
case 2:return{res[1],res[1]};}return res;}
```

8.4 Misc. Point Set Problems

ClosestPair.h

Description: Finds the closest pair of points.

Time: $\mathcal{O}(n \log n)$

"Point.h" ac393c, 12 lines

```
typedef Point<ll>P;
pair<P,P>closest(vector<P>&v){
assert(SZ(v)>1);set<P>S;
sort(ALL(v),[](P a,P b){return a.y<b.y;});
pair<ll,pair<P,P>>ret{LLONG_MAX,{P(),P()}};
int j=0;for(P p:v){
P d{1+(ll)sqrt(ret.first),0};
while(v[j].y<=p.y-d.x)S.erase(v[j++]);
auto lo=S.lower_bound(p-d),hi=S.upper_bound(
p+d);
for(;lo!=hi;++lo)
ret=min(ret,({*lo-p}).dist2(),{*lo,p});
S.insert(p);}return ret.second;}
```

8.5 3D

PolyhedronVolume.h

Description: Magic formula for the volume of a polyhedron.
Faces should point outwards.

3058c3, 5 lines

```
template<class V,class L>
double signedPolyVolume(const V&p,const L&
trilist){
double v=0;
for(auto i:trilist)v+=p[i.a].cross(p[i.b]).
dot(p[i.c]);
return v/6;}
```

Point3D.h

Description: Class to handle points in 3D space. T can be
e.g. double or long long.

8058ae, 29 lines

```
template<class T>struct Point3D{
```

```
typedef Point3D P;typedef const P&R;
T x,y,z;
explicit Point3D(T x=0,T y=0,T z=0):x(x),y(y)
,z(z){}
bool operator<(R p)const{
return tie(x,y,z)<tie(p.x,p.y,p.z);}
bool operator==(R p)const{
return tie(x,y,z)==tie(p.x,p.y,p.z);}
P operator+(R p)const{return P(x+p.x,y+p.y,z
+p.z);}
P operator-(R p)const{return P(x-p.x,y-p.y,z
-p.z);}
P operator*(T d)const{return P(x*d,y*d,z*d);
}
P operator/(T d)const{return P(x/d,y/d,z/d);
}
T dot(R p)const{return x*p.x+y*p.y+z*p.z;}
P cross(R p)const{
return P(y*p.z-z*p.y,z*p.x-x*p.z,x*p.y-y*p.x
);}
T dist2()const{return x*x+y*y+z*z;}
double dist()const{return sqrt((double)dist2
());}
//Azimuthal angle(longitude)to x-axis in
interval[-pi,pi]
double phi()const{return atan2(y,x);}
//Zenith angle(latitude)to the z-axis in
interval[0,pi]
double theta()const{return atan2(sqrt(x*x+y*y
),z);}
P unit()const{return*this/(T)dist();} //makes
dist()==1
//returns unit vector normal to*this and p
P normal(P p)const{return cross(p).unit();}
//returns point rotated'angle'radians ccw
around axis
P rotate(double angle,P axis)const{
double s=sin(angle),c=cos(angle);P u=axis.
unit();
return u*dot(u)*(1-c)+(*this)*c-cross(u)*s;
}};
```

3dHull.h

Description: Computes all faces of the 3-dimension hull of a
point set. *No four points must be coplanar*, or else random
results will be returned. All faces will point outwards.

Time: $\mathcal{O}(n^2)$

"Point3D.h" 0754b0, 29 lines

```
typedef Point3D<double>P3;struct PR{
void ins(int x){(a==-1?a:b)=x;}
void rem(int x){(a==x?a:b)=-1;}
int cnt(){return(a!=-1)+(b!=-1);}
int a,b;};struct F{P3 q;int a,b,c;};
vector<F>hull3d(const vector<P3>&A){
assert(SZ(A)>=4);
vector<vector<PR>>E(SZ(A),vector<PR>(SZ(A),{
-1,-1}));
#define E(x,y)E[f.x][f.y]
vector<F>FS;
auto mf=[&](int i,int j,int k,int l){
P3 q=(A[j]-A[i]).cross((A[k]-A[l]));
if(q.dot(A[l])>q.dot(A[i]))q=q*-1;
F f{q,i,j,k};
E(a,b).ins(k);E(a,c).ins(j);E(b,c).ins(i);
FS.push_back(f);};
REP(i,0,4)REP(j,i+1,4)REP(k,j+1,4)
mf(i,j,k,6-i-j-k);REP(i,4,SZ(A)){
REP(j,0,SZ(FS)){F f=FS[j];
if(f.q.dot(A[i])>f.q.dot(A[f.a])){
E(a,b).rem(f.c);E(a,c).rem(f.b);
E(b,c).rem(f.a);swap(FS[j--],FS.back());
FS.pop_back();}int nw=SZ(FS);REP(j,0,nw){
F f=FS[j];
#define C(a,b,c)if(E(a,b).cnt()!=2)mf(f.a,f.
b,i,f.c);
C(a,b,c);C(a,c,b);C(b,c,a);}}
for(F&it:FS)if((A[it.b]-A[it.a]).cross(
A[it.c]-A[it.a]).dot(it.q)<=0)swap(it.c,it.b
);
return FS;};
```

sphericalDistance.h

Description: Returns the shortest distance on the sphere with radius r between the points with azimuthal angles (longitude) ϕ_1 and ϕ_2 from x axis and zenith angles (latitude) θ_1 and θ_2 from z axis (0 = north pole). All angles measured in radians. The algorithm starts by converting the spherical coordinates to cartesian coordinates so if that is what you have you can use only the two last rows. $dx \cdot r$ is then the difference between the two points in the x direction and $d \cdot r$ is the total distance between the points.

611f07, 7 lines

```
double sphericalDistance(double f1, double t1,
    double f2, double t2, double radius){
    double dx=sin(t2)*cos(f2)-sin(t1)*cos(f1);
    double dy=sin(t2)*sin(f2)-sin(t1)*sin(f1);
    double dz=cos(t2)-cos(t1);
    double d=sqrt(dx*dx+dy*dy+dz*dz);
    return radius*2*asin(d/2);}
```

HalfPlane.h

Description: Computes the intersection of a set of half-planes. Input is given as a set of planes, facing left. Output is the convex polygon representing the intersection. The points may have duplicates and be collinear. Will not fail catastrophically if 'eps > sqrt(2)(line intersection error)'. Likely to work for more ranges if 3 half planes are never guaranteed to intersect at the same point.

Time: $\mathcal{O}(n \log n)$

"Point.h", "sideOf.h", "lineIntersection.h"

eda44b, 27 lines

```
typedef Point<double>P;
typedef array<P,2>Line;
#define sp(a)a[0],a[1]

#define ang(a)(a[1]-a[0]).angle()

int angDiff(Line a,Line b){return sgn(ang(a)-ang(b));}
bool cmp(Line a,Line b){
    int s=angDiff(a,b);
    return(s?s:sideOf(sp(a),b[0]))<0;}
vector<P>halfPlaneIntersection(vector<Line> vs){
    const double EPS=sqrt(2)*1e-8;
    sort(all(vs),cmp);
    vector<Line>deq(sz(vs)+5);}
```

```
vector<P>ans(sz(vs)+5);deq[0]=vs[0];
int ah=0,at=0,n=sz(vs);rep(i,1,n+1){
    if(i==n)vs.push_back(deq[ah]);
    if(angDiff(vs[i],vs[i-1])==0)continue;
    while(ah<at&&sideOf(sp(vs[i]),ans[at-1],EPS)<0)
        at--;
    while(i!=n&&ah<at&&sideOf(sp(vs[i]),ans[ah],EPS)<0)
        ah++;
    auto res=lineInter(sp(vs[i]),sp(deq[at]));
    if(res.first!=1)continue;
    ans[at++]=res.second,deq[at]=vs[i];
    if(at-ah<=2)return{};
    return{ans.begin()+ah,ans.begin()+at};}
```

Miscellaneous (9)

9.1 RNG, Intervals, T.S

TernarySearch.h

Description: Find the smallest i in $[a, b]$ that maximizes $f(i)$, assuming that $f(a) < \dots < f(i) \geq \dots \geq f(b)$. To reverse which of the sides allows non-strict inequalities, change the $<$ marked with (A) to \leq , and reverse the loop at (B). To minimize f , change it to $>$, also at (B).

Usage: `int ind = ternSearch(0, n-1, [&](int i){return a[i];});`

Time: $\mathcal{O}(\log(b-a))$

a9cf52, 8 lines

```
template<class F>
int ternSearch(int a,int b,F f){
    assert(a<=b);while(b-a>=5){
        int mid=(a+b)/2;
        if(f(mid)<f(mid+1))a=mid;//(A)
        else b=mid+1;}
    REP(i,a+1,b+1)if(f(a)<f(i))a=i;//(B)
    return a;}
```

RNGs.h

5 lines

```
SEED = chrono::steady_clock::now().
    time_since_epoch().count(); // or use '
    high_resolution_clock'
random_device rd; auto SEED = rd();
mt19937 rng(SEED);
```

```
uniform_int_distribution<> dis(MIN, MAX); //
    usage: dis(rng)
// others: uniform_real_distribution,
```

DebuggingTricks.cpp

Description: Debug

Time: $\mathcal{O}(k \log \frac{n}{k})$

26e792, 4 lines

```
1. signal(SIGSEGV, [](int) { _Exit(0); });
converts segfaults into Wrong Answers.
Similarly one can catch SIGABRT (
assertion failures) and SIGFPE (zero
divisions). _GLIBCXX_DEBUG failures
generate. SIGABRT (or SIGSEGV on gcc
5.4.0 apparently).
2. feenableexcept(29);
kills the program on NaNs(1), 0-divs(4),
infinities(8) and denormals(16).
```

Contest (10)

template.cpp

26 lines

```
// #pragma GCC optimize("O3,unroll-loops")
// #pragma GCC target("avx2,bmi,bmi2,lzcnt,
    popcnt")
#include <bits/stdc++.h>
using namespace std;
#include <ext/pb_ds/assoc_container.hpp>
#include <ext/pb_ds/tree_policy.hpp>
using namespace __gnu_pbds;
template <class T>
using o_set = tree<T, null_type, less<T>,
    rb_tree_tag,
    tree_order_statistics_node_update>;
// order_of_key (val): no. of values less
    than val
// find_by_order (k): kth largest element
    . (0-based)
// t.join(t1) -> merges t1 with t in linear
    time
#define int long long
#define FOR(i, a, b) for (int i = (a); i < (
    b); ++i)
#define ALL(x) begin(x), end(x)
#define SZ(x) ((int)(x).size())
```



```
#define SET(a, v) memset((a),(v),sizeof(a))
using LL = long long; using VI = vector<int>;
#define deb(a) cerr<<#a<<"="<<(a)<<"\n";
#define endl "\n"
const long long mod = 1e9 + 7;
signed main() {
    // freopen("sample.in", "r", stdin);
    cin.tie(0)->sync_with_stdio(0);
    cin.exceptions(cin.failbit); // RTE if out
    of bound
    return 0;}
```