

Steps for successful setup for custom model deployment on NVIDIA Jetson Nano:

1. Download SD card image for Jetson Nano Jetpack 4.6.4.  
Link: <https://developer.nvidia.com/jetpack-sdk-464>
2. Download and install NVIDIA Deepstream 6.0 SDK. (Download using .deb file)  
Link: [https://docs.nvidia.com/metropolis/deepstream/6.0/dev-guide/text/DS\\_Quickstart.html](https://docs.nvidia.com/metropolis/deepstream/6.0/dev-guide/text/DS_Quickstart.html)
3. Clone YoloV5 - Ultralytics repo from GitHub:  
Bash Command: git clone <https://github.com/ultralytics/yolov5>
4. Go into yolov5 directory and then checkout to v7.0 branch for yolov5 - ultralytics repo  
Bash Command: cd yolov5  
Bash Command: git checkout v7.0
5. Update requirements.txt file in yolov5 folder:  
Bash Command: vi requirements.txt

Edit the following lines. Here you need to press i first to enter editing mode. Press ESC, then type :wq to save and quit

**torch>=1.8.0**

**torchvision>=0.9.0**

Note: torch and torchvision are excluded for now because they will be installed later.

6. Install the below dependency  
Bash Command: sudo apt install -y libfreetype6-dev
7. Install the necessary packages  
Bash Command: pip3 install -r requirements.txt
8. Install numpy 1.19.4 using following command:  
Bash Command: pip3 install --force-reinstall --no-cache-dir numpy=1.19.4
9. Install PyTorch  
First install PyTorch v1.10.0  
(Supported by JetPack 4.4 (L4T R32.4.3) / JetPack 4.4.1 (L4T R32.4.4) / JetPack 4.5 (L4T R32.5.0) / JetPack 4.5.1 (L4T R32.5.1) / JetPack 4.6 (L4T R32.6.1) with Python 3.6)  
Bash Command:  
cd ~  
sudo apt-get install -y libopenblas-base libopenmpi-dev  
wget <https://nvidia.box.com/shared/static/fjtbno0vpo676a25cgvuqc1wty0fkkg6.whl> -O  
torch-1.10.0-cp36-cp36m-linux\_aarch64.whl  
pip3 install torch-1.10.0-cp36-cp36m-linux\_aarch64.whl
10. Install TorchVision  
Bash Command:  
sudo apt install -y libjpeg-dev zlib1g-dev  
git clone --branch v0.11.1 <https://github.com/pytorch/vision> torchvision  
cd torchvision  
sudo python3 setup.py install

11. DeepStream Configuration for YOLOv5

Bash Command:

```
cd ~
git clone https://github.com/marcoslucianops/DeepStream-Yolo
git checkout e7c77ee9fe78d8b82caa5b01574792af429fe923
cp DeepStream-Yolo/utils/gen_wts_yoloV5.py yolov5
cd yolov5
wget https://github.com/ultralytics/yolov5/releases/download/v6.1/yolov5s.pt
python3 gen_wts_yoloV5.py -w yolov5s.pt
```

12. To change the inference size (default: 640) use flags as mentioned below

```
-s SIZE
--size SIZE
-s HEIGHT WIDTH
--size HEIGHT WIDTH
```

Example for 1280:

```
-s 1280
or
-s 1280 1280
```

13. Copy the generated cfg and wts files into the DeepStream-Yolo folder

Bash Command:

```
cp yolov5s.cfg ~/DeepStream-Yolo
cp yolov5s.wts ~/DeepStream-Yolo
```

14. Open the DeepStream-Yolo folder and compile the library

Bash Command:

```
cd ~/DeepStream-Yolo
CUDA_VER=11.4 make -C nvdsinfer_custom_impl_Yolo # for DeepStream 6.1
CUDA_VER=10.2 make -C nvdsinfer_custom_impl_Yolo # for DeepStream 6.0.1 / 6.0 (Used
this one in my case)
```

15. Edit the config\_infer\_primary\_yoloV5.txt file according to your [property]

```
...
custom-network-config=yolov5s.cfg
model-file=yolov5s.wts
...
```

16. Edit the deepstream\_app\_config file

```
...
[primary-gie]
...
config-file=config_infer_primary_yoloV5.txt (CHECK THIS USUALLY THE DEFAULT VALUE IS
DIFFERENT)
```

17. Change the video source in deepstream\_app\_config file. Here a default video file is loaded as you can see below

```
...
[source0]
...
uri=file:///opt/nvidia/deepstream/deepstream/samples/streams/sample_1080p_h264.mp4
```

18. Run the Inference

```
deepstream-app -c deepstream_app_config.txt
```