

Lecture 36

E.g.

$$A = \begin{bmatrix} 3 & -5 \\ 1 & -1 \end{bmatrix}$$

Diagonalize A

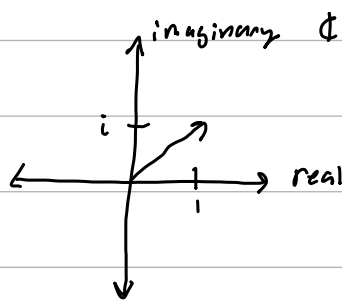
E-vals: $0 = \det(A - \lambda I)$

$$0 = \begin{vmatrix} 3-\lambda & -5 \\ 1 & -1-\lambda \end{vmatrix} = (3-\lambda)(-1-\lambda) - (-5)$$

$$\lambda^2 - 2\lambda + 2 = 0$$

$$\lambda = \frac{2 \pm (\sqrt{2})^2 - 4(1)(2)}{2} = 1 \pm \sqrt{-1} = 1 \pm i$$

$1+i \in \mathbb{C}$ (complex numbers)



e-vecs:

$$\lambda = 1+i \quad \text{so} \quad \left[A - (1+i)I \mid \vec{0} \right] = \left[\begin{array}{cc|c} 2-i & -5 & 0 \\ 1 & -2-i & 0 \end{array} \right] \rightarrow \left[\begin{array}{cc|c} 1 & -2-i & 0 \\ 0 & 0 & 0 \end{array} \right]$$

$$\text{e-vec} = \vec{v} = \begin{bmatrix} 2+i \\ 1 \end{bmatrix} \in \mathbb{R}^2$$

for $\lambda = 1+i$

For $\lambda = 1-i$, use "complex conjugation"

$$\lambda = a+bi \in \mathbb{C} \quad \bar{\lambda} := a-bi$$

$$\boxed{\text{ex}} \quad \lambda = 1+i \quad \bar{\lambda} = 1-i$$

Also: if $A \in M_{n \times n}$ real matrix and $A\vec{v} = \lambda\vec{v} \rightarrow \overline{A\vec{v}} = \overline{\lambda\vec{v}}$

$$\rightarrow \overline{A\vec{v}} = \bar{\lambda}\vec{v}$$

$$\text{Write: } \vec{v} = v_1 + iv_2$$

$$\rightarrow A\vec{v} = \bar{\lambda}\vec{v}$$

$$\bar{\vec{v}} = v_1 - iv_2$$

so $\bar{\vec{v}}$ is an e-vec with e-val $\bar{\lambda}$.

Back to eg

e-vals	$1+i$	$1-i$
evec	$\begin{bmatrix} 2+i \\ 1 \end{bmatrix}$	$\begin{bmatrix} 2-i \\ 1 \end{bmatrix}$

Basis β for \mathbb{C}^2

$$\begin{bmatrix} 3 & -5 \\ 1 & -1 \end{bmatrix} = \begin{bmatrix} 2+i & 2-i \\ 1 & 1 \end{bmatrix} \begin{bmatrix} 1+i & 0 \\ 0 & 1-i \end{bmatrix} \begin{bmatrix} 2+i & 2-i \\ 1 & 1 \end{bmatrix}^{-1}$$

Alternative: instead of using basis $\mathcal{B} = \{\vec{v}_1, \vec{v}_2\}$

• use basis $\mathcal{B}_{\mathbb{R}} = \{\vec{v}_2, \vec{v}_1\}$ where \vec{v}_1 and \vec{v}_2 are real and imaginary parts of \vec{v} .

• In e.g. $\mathcal{B}_{\mathbb{R}} = \left\{ \begin{bmatrix} 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \end{bmatrix} \right\}$

Q: If $T(\vec{v}) = A\vec{v}$ then what is $[T]_{\mathcal{B}_{\mathbb{R}}}$?

Ans: $[T]_{\mathcal{B}_{\mathbb{R}}} = \begin{bmatrix} [T(\vec{v}_2)]_{\mathcal{B}_{\mathbb{R}}} & [T(\vec{v}_1)]_{\mathcal{B}_{\mathbb{R}}} \end{bmatrix}$

$$A\vec{v} = \lambda\vec{v}$$

$$\rightarrow A(v_1 + iv_2) = (a+bi)(v_1 + iv_2)$$

$$\rightarrow Av_1 + iAv_2 = (av_1 - bv_2) + i(bv_1 + av_2)$$

$$\rightarrow \begin{cases} Av_1 = av_1 - bv_2 \\ Av_2 = bv_1 + av_2 \end{cases}$$

$$[T]_{\mathcal{B}_{\mathbb{R}}} = \begin{bmatrix} [bv_1 + av_2]_{\mathcal{B}_{\mathbb{R}}} & [av_1 - bv_2]_{\mathcal{B}_{\mathbb{R}}} \end{bmatrix} = \begin{bmatrix} a & -b \\ b & a \end{bmatrix}$$

$$\text{so } A = [v_2 \ v_1] \begin{bmatrix} a & -b \\ b & a \end{bmatrix} [v_2 \ v_1]^{-1}$$

$$\text{"} S [T]_{\mathcal{B}_{\mathbb{R}}} S^{-1} \text{"}$$

In Eq)

$$\begin{bmatrix} 3 & -5 \\ 1 & -1 \end{bmatrix} = \begin{bmatrix} 2 & 1 \\ 1 & 0 \end{bmatrix} \begin{bmatrix} 1 & -1 \\ 1 & 1 \end{bmatrix} \begin{bmatrix} 2 & 1 \\ 1 & 0 \end{bmatrix}^{-1}$$

↑
This is rotation
and scaling matrix

$$\begin{bmatrix} 3 & -5 \\ 1 & -1 \end{bmatrix} = (\sqrt{2}) \begin{bmatrix} 2 & 1 \\ 1 & 0 \end{bmatrix} \begin{bmatrix} \frac{1}{\sqrt{2}} & -\frac{1}{\sqrt{2}} \\ \frac{1}{\sqrt{2}} & \frac{1}{\sqrt{2}} \end{bmatrix} \begin{bmatrix} 2 & 1 \\ 1 & 0 \end{bmatrix}^{-1}$$

↑
Scalar
part

↑
rotation
matrix