

## Lecture 15

Chapter 3.1 + 3.2 = Linear Independence

$$\text{span} \left\{ \begin{pmatrix} 1 \\ 0 \end{pmatrix}, \begin{pmatrix} 0 \\ 1 \end{pmatrix}, \begin{pmatrix} 1 \\ 1 \end{pmatrix} \right\} = \mathbb{R}^2$$

↑  
redundant

$$\begin{pmatrix} 1 \\ 1 \end{pmatrix} = \begin{pmatrix} 1 \\ 0 \end{pmatrix} + \begin{pmatrix} 0 \\ 1 \end{pmatrix}$$

$$\begin{aligned} \text{So e.g. } & 5 \begin{pmatrix} 1 \\ 0 \end{pmatrix} + (-2) \begin{pmatrix} 0 \\ 1 \end{pmatrix} + 3 \begin{pmatrix} 1 \\ 1 \end{pmatrix} \\ &= 5 \begin{pmatrix} 1 \\ 0 \end{pmatrix} + (-2) \begin{pmatrix} 0 \\ 1 \end{pmatrix} + 3 \left[ \begin{pmatrix} 1 \\ 0 \end{pmatrix} + \begin{pmatrix} 0 \\ 1 \end{pmatrix} \right] \\ &= 8 \begin{pmatrix} 1 \\ 0 \end{pmatrix} + 1 \begin{pmatrix} 0 \\ 1 \end{pmatrix} \end{aligned}$$

Alternatively: we have a "linear relation"  $\begin{pmatrix} 1 \\ 1 \end{pmatrix} - \begin{pmatrix} 1 \\ 0 \end{pmatrix} - \begin{pmatrix} 0 \\ 1 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix}$

$$\begin{pmatrix} 0 \\ 1 \end{pmatrix} = \begin{pmatrix} 1 \\ 1 \end{pmatrix} - \begin{pmatrix} 1 \\ 0 \end{pmatrix}$$

$$\text{so } \text{span} \left\{ \begin{pmatrix} 0 \\ 1 \end{pmatrix}, \begin{pmatrix} 1 \\ 0 \end{pmatrix}, \begin{pmatrix} 1 \\ 1 \end{pmatrix} \right\} = \text{span} \left\{ \begin{pmatrix} 1 \\ 0 \end{pmatrix}, \begin{pmatrix} 0 \\ 1 \end{pmatrix} \right\} = \text{span} \left\{ \begin{pmatrix} 1 \\ 0 \end{pmatrix}, \begin{pmatrix} 1 \\ 1 \end{pmatrix} \right\}$$

Def - A linear relation among vectors  $\vec{v}_1, \dots, \vec{v}_k \in \mathbb{R}^n$  is a list of scalars  $c_1, \dots, c_k \in \mathbb{R}$  such that  $c_1 \vec{v}_1 + \dots + c_k \vec{v}_k = \vec{0}$

Rmk - Always have the trivial relation  $0\vec{v}_1 + \dots + 0\vec{v}_k = \vec{0}$

Rmk - When  $\exists$  a non-trivial relation  $c_1 \vec{v}_1 + \dots + c_k \vec{v}_k = \vec{0}$  we can solve for one of the vecs in terms of the others.

Ex if  $c \neq 0$  then  $\vec{v}_1 = \frac{-c_2}{c_1} \vec{v}_2 + \dots + \frac{-c_k}{c_1} \vec{v}_k$

$$\Rightarrow \text{span} \left\{ \vec{v}_1, \dots, \vec{v}_k \right\} = \text{span} \left\{ \vec{v}_2, \dots, \vec{v}_k \right\}$$

Def - Vectors  $\vec{v}_1, \dots, \vec{v}_k \in \mathbb{R}^n$  are linearly independent if  $c_1\vec{v}_1 + \dots + c_k\vec{v}_k = \vec{0}$  only when  $c_1 = \dots = c_k = 0$ .

Alternative -  $\vec{v}_1, \dots, \vec{v}_k \in \mathbb{R}^n$  are LI if  $\exists$  no non-trivial linear relations among them.

Cases ( $k$  is number of vectors) :

$k=1$   $\vec{v} \in \mathbb{R}^n$  is LI i.f.f.  $\vec{v} \neq \vec{0}$ .

$k=2$   $\vec{v}, \vec{w} \in \mathbb{R}^n$  are LI i.f.f. neither is a multiple of the other.

$k=3$ :

$$c_1\vec{v}_1 + c_2\vec{v}_2 + c_3\vec{v}_3 = \vec{0}$$

i.e.  $A = [\vec{v}_1 \ \vec{v}_2 \ \vec{v}_3]$ ,  $\vec{x} = \begin{pmatrix} c_1 \\ c_2 \\ c_3 \end{pmatrix}$

$$A\vec{x} = \vec{0}$$

So row reduce  $[A | \vec{0}]$

If we end with free variables, thevecs  $\vec{v}_1, \vec{v}_2, \vec{v}_3$  are dependent.

$$\begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix} = \begin{pmatrix} 3 \\ -1 \\ 1 \end{pmatrix} X_3$$

Set  $x_3 = 3 \Rightarrow \vec{x} = \begin{pmatrix} c_1 \\ c_2 \\ c_3 \end{pmatrix} = \begin{pmatrix} 9 \\ -3 \\ 3 \end{pmatrix}$  gives us  $9\vec{v}_1 - 3\vec{v}_2 + 3\vec{v}_3 = \vec{0}$

$$\vec{v}_2 = 3\vec{v}_1 + \vec{v}_3$$

$$\Rightarrow \text{span}\{\vec{v}_1, \vec{v}_2, \vec{v}_3\} = \text{span}\{\vec{v}_2, \vec{v}_3\}$$

The standard choice of vectors to eliminate are the ones corresponding to free variables.

In the  
Big eg from last time:  
||

$$A\vec{x} = \vec{0} \Rightarrow \vec{x} = \vec{x}_2 \begin{pmatrix} -4 \\ 1 \\ 0 \\ 0 \\ 0 \end{pmatrix} + \vec{x}_4 \begin{pmatrix} -2 \\ 0 \\ 1 \\ 0 \\ 0 \end{pmatrix} + \vec{x}_5 \begin{pmatrix} 0 \\ 0 \\ 0 \\ 0 \\ 1 \end{pmatrix}$$

$\left[ \vec{v}_1, \dots, \vec{v}_k \right]$

$\Rightarrow$  non trivial linear relations

$\Rightarrow$  So the columns  $\vec{v}_1, \dots, \vec{v}_5$  of A are dependent.

Claim further:  $\vec{v}_1, \vec{v}_3$  are linearly independent and  $\text{span} \{ \vec{v}_1, \vec{v}_3 \} = \text{span} \{ \vec{v}_1, \dots, \vec{v}_5 \}$

Why does this work?

[Eg] Why can  $\vec{v}_2$  go?

ANS - Set  $x_2 = 1, x_4 = x_5 = 0$

$$\Rightarrow \vec{x} = \begin{bmatrix} -4 \\ 1 \\ 0 \\ 0 \\ 0 \end{bmatrix} \Rightarrow -4\vec{v}_1 + \vec{v}_2 = \vec{0} \Rightarrow \vec{v}_2 = 4\vec{v}_1$$

i.e. I can write 2<sup>nd</sup> col of A as a linear combination of the pivot columns.

Likewise: setting  $x_4 = 1, x_2 = x_5 = 0$

$$\text{gives } \vec{x} = \begin{pmatrix} -2 \\ 0 \\ 1 \\ 0 \\ 0 \end{pmatrix} \quad -2\vec{v}_1 + \vec{v}_3 + \vec{v}_4 = \vec{0}$$

$$\vec{v}_4 = 2\vec{v}_1 - \vec{v}_3$$

$\Rightarrow \vec{v}_4$  can go