

Lecture 31

7.1 Diagonalization

Previous HW problem 3.4 #57

$$P = \text{span} \{ \vec{v}_1, \vec{v}_2 \} = \text{plane in } \mathbb{R}^3$$

$$\vec{v}_3 \neq 0 \text{ vector } \in P^\perp$$

$T: \mathbb{R}^3 \rightarrow \mathbb{R}^3$ be given by $T(\vec{x}) = \text{refl of } \vec{x} \text{ through } P$.

What is matrix for T ?

Soln: Let $B = \{ \vec{v}_1, \vec{v}_2, \vec{v}_3 \} = \text{basis for } \mathbb{R}^3$

$$\hookrightarrow \text{observe } [T]_B = \begin{bmatrix} [T(\vec{v}_1)]_B & [T(\vec{v}_2)]_B & [T(\vec{v}_3)]_B \end{bmatrix}$$

$$= \begin{bmatrix} [\vec{v}_1]_B & [\vec{v}_2]_B & [-\vec{v}_3]_B \end{bmatrix}$$

$$= \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & -1 \end{bmatrix} = \text{"diagonal matrix"}$$

Def: A linear transformation $T: \mathbb{R}^n \rightarrow \mathbb{R}^n$ is diagonalizable if \exists B for \mathbb{R}^n such that $[T]_B$ is a diagonal matrix.

$$\text{Back to e.g. We have } [T]\vec{x} = S[T]_B S^{-1} = [\vec{v}_1, \vec{v}_2, \vec{v}_3] \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & -1 \end{bmatrix} [\vec{v}_1, \vec{v}_2, \vec{v}_3]$$

Ex Consider the sequence of integers of $x_0, x_1, x_2, x_3, \dots$ given by
 $x_0 = 0$, $x_1 = 1$, and $x_{n+1} = 3x_n - 2x_{n-1}$

Question: Give a formula for x_n .

Solution: let $\vec{x}_n = \begin{bmatrix} x_n \\ x_{n-1} \end{bmatrix}$. Then $\vec{x}_1 = \begin{bmatrix} x_1 \\ x_0 \end{bmatrix} = \begin{bmatrix} 1 \\ 0 \end{bmatrix}$

$$\text{Also } \vec{x}_{n+1} = \begin{bmatrix} x_{n+1} \\ x_n \end{bmatrix} = \begin{bmatrix} 3x_n - 2x_{n-1} \\ x_n \end{bmatrix} = \underbrace{\begin{bmatrix} 3 & -2 \\ 1 & 0 \end{bmatrix}}_{A \vec{x}_n} \begin{bmatrix} x_n \\ x_{n-1} \end{bmatrix}$$

• Hence $\vec{x}_{n+1} = A \vec{x}_n = A(A \vec{x}_{n-1}) = \dots = A^n \vec{x}_1$

$$\begin{bmatrix} x_{n+1} \\ x_n \end{bmatrix}$$

• So now how can we find A^n ?

Hint: Consider $\vec{v}_1 = \begin{bmatrix} 1 \\ 1 \end{bmatrix}$ $\vec{v}_2 = \begin{bmatrix} 2 \\ 1 \end{bmatrix}$

$$\hookrightarrow \text{then } A\vec{v}_1 = \vec{v}_1, \quad A\vec{v}_2 = \begin{bmatrix} 4 \\ 2 \end{bmatrix} = 2\vec{v}_2$$

Side point: $A^n \vec{v}_2 = 2^n \vec{v}_2$

$$\vec{x}_0 = \vec{v}_2 - \vec{v}_1$$

$$\rightarrow A^n \vec{x}_0 = A^n \vec{v}_2 - A^n \vec{v}_1 = 2^n \vec{v}_2 - \vec{v}_1 = \begin{bmatrix} 2^{n+1} & -1 \\ 2^n & -1 \end{bmatrix}$$

$$\rightarrow x_n = 2^n - 1$$

Alt: Let $T: \mathbb{R}^2 \rightarrow \mathbb{R}^2$ be given by $T(\vec{x}) = A\vec{x}$ and $\beta = \left\{ \underset{\vec{v}_1}{\begin{bmatrix} 1 \\ 1 \end{bmatrix}}, \underset{\vec{v}_2}{\begin{bmatrix} 2 \\ 1 \end{bmatrix}} \right\} = \text{basis for } \mathbb{R}^2$

• Then OTOH $A = [T] = S[T]_{\beta} S^{-1}$

$$= \begin{bmatrix} 1 & 2 \\ 1 & 1 \end{bmatrix} \begin{bmatrix} [T(\vec{v}_1)]_{\beta} & [T(\vec{v}_2)]_{\beta} \end{bmatrix} \begin{bmatrix} 1 & 2 \\ 1 & 1 \end{bmatrix}^{-1}$$

$$= \begin{bmatrix} 1 & 2 \\ 1 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 \\ 0 & 2 \end{bmatrix} \begin{bmatrix} 1 & 2 \\ 1 & 1 \end{bmatrix}$$

• Hence A is similar to $\begin{bmatrix} 1 & 0 \\ 0 & 2 \end{bmatrix}$ and $A^n = \left[S \begin{bmatrix} 1 & 0 \\ 0 & 2 \end{bmatrix} S^{-1} \right]^n$

$$\rightarrow A^n = \left[S \begin{bmatrix} 1 & 0 \\ 0 & 2 \end{bmatrix} S^{-1} \right] \left[S \begin{bmatrix} 1 & 0 \\ 0 & 2 \end{bmatrix} S^{-1} \right] \cdots \left[S \begin{bmatrix} 1 & 0 \\ 0 & 2 \end{bmatrix} S^{-1} \right]$$

$$\rightarrow A^n = S \begin{bmatrix} 1 & 0 \\ 0 & 2 \end{bmatrix}^n S^{-1} = S \begin{bmatrix} 1^n & 0^n \\ 0^n & 2^n \end{bmatrix} S^{-1}$$

$$\text{So } \vec{x}_{n+1} = \begin{bmatrix} x_{n+1} \\ x_n \end{bmatrix} = A \vec{x}_n = A^n \begin{bmatrix} 1 \\ 0 \end{bmatrix} = \underbrace{\left(\begin{bmatrix} 1 & 2 \\ 1 & 1 \end{bmatrix} \begin{bmatrix} 1^n & 0^n \\ 0^n & 2^n \end{bmatrix} \begin{bmatrix} 1 & 2 \\ 1 & 1 \end{bmatrix} \right)}_{A^n} \begin{bmatrix} 1 \\ 0 \end{bmatrix}$$

Equivalent Def: A matrix $A \in M_{n \times n}$ is diagonalizable if $A = P \Lambda P^{-1}$ for some diagonal matrix Λ (i.e. if A is similar to a diagonal matrix)

Def: Let $T: \mathbb{R}^n \rightarrow \mathbb{R}^n$ be a linear transformation given by $T(\vec{x}) = A(\vec{x})$. We say $\vec{v} \in \mathbb{R}^n$ is an eigenvector of T with eigenvalue $\lambda \in \mathbb{R}^n$ if $T(\vec{v}) = \lambda \vec{v}$.

(Equivalently $A\vec{v} = \lambda \vec{v}$)

Prop: Let $T: \mathbb{R}^n \rightarrow \mathbb{R}^n$ be linear. Then the following are equivalent:

(i) T is diagonalizable

(ii) $[T]$ is similar to a diagonal matrix

(iii) \exists basis β for \mathbb{R}^n consisting of e-vects for T .