Homework 3- COMS 311 aryanrao

Part- A

```
2. function findAcceptablePoints(points):
  if size(points) <= 1:
     return points
  sort(points) based on x-coordinate
  mid = size(points) / 2
  S1 = points[0:mid]
  S2 = points[mid:end]
  acceptablePoints = merge(findAcceptablePoints(S1), findAcceptablePoints(S2))
  return acceptablePoints
function merge(S1, S2):
  i = 0, j = 0
  acceptablePoints = []
  while i < size(S1) and j < size(S2):
     if S1[i].x < S2[i].x and S1[i].y < S2[i].y:
       add S1[i] to acceptablePoints
       increment i
     else:
       increment i
  append remaining points in S1 starting from i to acceptablePoints
  return acceptablePoints
```

This pseudo code uses divide and conquer algorithm. It first sorts the points based on their x-coordinates and then recursively divides the points into two halves. It then merges the acceptable points found in the left and right halves, considering the condition x < p and y < q.

Problem: Given a set of two-dimensional points S, find all acceptable points such that there exists a point $\langle p, q \rangle$ in S where x < p and y < q.

Solution:

- 1. Implement the **findAcceptablePoints** function:
 - Base case: If the size of points is less than or equal to 1, return points.
 - Sort the points based on their x-coordinates.
 - Split the points into two halves, S1 and S2.
 - Recursively find acceptable points in S1 and S2 using **findAcceptablePoints**.
 - Merge the acceptable points from S1 and S2 using merge.
 - Return the merged acceptable points.
- 2. Implement the **merge** function:
 - Initialize pointers i and j to 0.
 - Initialize an empty list **acceptablePoints** to store the merged acceptable points.

- While i is less than the size of S1 and j is less than the size of S2, do the following:
 - If S1[i].x < S2[j].x and S1[i].y < S2[j].y, add S1[i] to acceptablePoints and increment i.
 - Otherwise, increment j.
- Append the remaining points in S1 starting from index i to acceptablePoints.
- Return acceptablePoints.
- 3. Call **findAcceptablePoints** with the input set of points S.

Let T(n) be the time complexity of the algorithm when there are n points in the set. The algorithm follows a divide and conquer approach. In each recursive call, the set is divided into two halves. The merge operation takes linear time to merge the acceptable points from the left and right halves. Therefore, the recurrence relation can be stated as:

$$T(n) = 2T(n/2) + O(n)$$

This recurrence relation represents that the algorithm recursively solves two subproblems of size n/2 and performs a merge operation in linear time O(n) to combine the results.

The time complexity of the algorithm is $O(n \log n)$ since the sorting step takes $O(n \log n)$ time and the recursive calls divide the set into two halves.