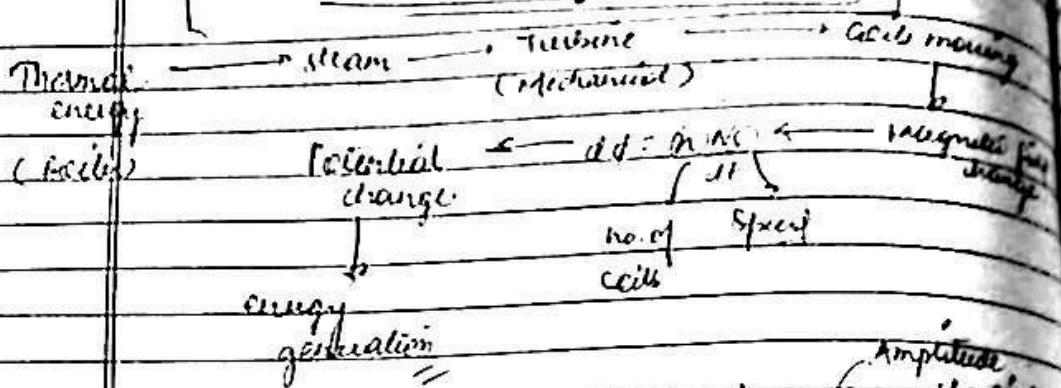
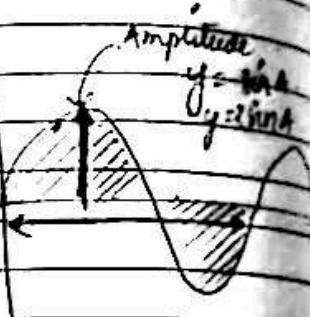


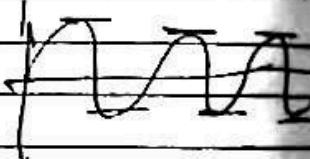
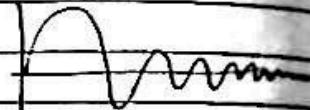
AC Fundamentals



- Average value of current = 0.
(Area induced by area)



- time period should be equal to next repetition (not defined)
- tangent should be equal of each oscillation forming negative half cycle.



* The term AC means 'alternating current'. Such a current reverse its direction periodically. In AC power the voltages and currents vary with time sinusoidally

$$I = I_{\text{max}} \sin \omega t$$

$$V = V_{\text{max}} \sin \omega t$$

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DATE:	/ /
PAGE NO:	

Q.1 A sinusoidal voltage signal is given by $V = 20 \sin(\omega t)$ volts.

- At what angle will the instantaneous voltage be 10 V?
- What is the max. value for the voltage and at what angle?

(a) $\theta = \omega t$

$$\frac{V}{V_{\max}} = \sin(\theta) \Rightarrow \theta = \frac{\pi}{6} / 30^\circ$$

(b) $V_{\max} = 20 \text{ V.}$ and at angle $\pi/2$.

Q.2 $V = 0.04 \sin(2000t + 60^\circ)$ volts. Find f, ω, V at 160°

$\omega = 2000 \quad f = 33.3 \text{ Hz}$

$$T = \frac{2\pi}{\omega} = \frac{2\pi}{2000} = 1000$$

$$f = \frac{1000}{\pi} \quad \frac{100}{8000\pi} \quad \frac{100}{130}$$

$$V = 0.04 \sin(2000 \times 160 \times 10^{-6} + 60^\circ) \quad 3$$

$$= 0.04 \sin(32000\pi + 60^\circ)$$

$$= 0.04 \sin\left(\frac{103\pi}{9}\right)$$

$$= 0.04 \sin(32000\pi \times 10^{-2} + 60^\circ)$$

$$= 0.04 \sin(0.32 + 60^\circ)$$

$$= 0.04 \sin(0.32 + 60^\circ) \quad \frac{0.32 \times 190}{\pi \text{ windo}}$$

First current Windo
degree (base of
alternator)

[Ans in radian] X.

$\rightarrow (\text{Mean}/\text{DC})^{\text{value}}$
magnitude.

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DATE: / /
Page No.: /

Average value:-

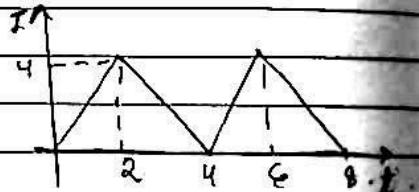
discuss

It is the algebraic sum of all the values divided by the total no. of values.

- In a waveform, the continuous variation of the value of a quantity with time t or angle θ repeated after its cycle. The area under the waveform is found by integration of the given wave.

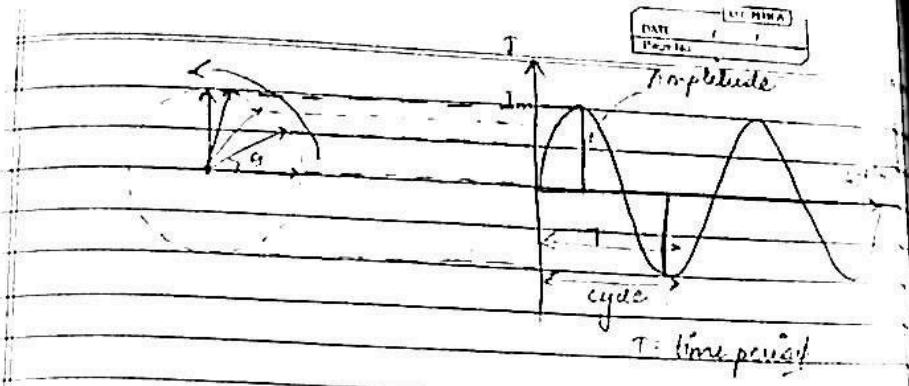
$$\text{Average value} = \frac{\text{Area under the full cycle}}{\text{time period (length of one cycle)}}$$

Q: Find average value?



$$y - y_1 = m(x - x_1)$$

$$y = mx + c$$



- Cycle → One complete set of positive and negative values of the function (which goes on & going) is called a cycle.
- Maximum value / peak value → It is the maximum value positive or negative of the quantity. It is also sometimes called the amplitude of the sinusoidal functions.
- Instantaneous value → The value of alternating quantity (Voltage, current, emf) at any particular instant is called instantaneous value.
- Time period → the time taken in seconds by an alternating quantity to complete one cycle is known as time period denoted by (T) Unit → seconds
- Frequency → the no. of cycles completed per second by an alternating quantity is known as Frequency denoted by f .

$$f = \frac{1}{T}$$

The Frequency of AC supply in India is 50Hz.
USA is 60Hz

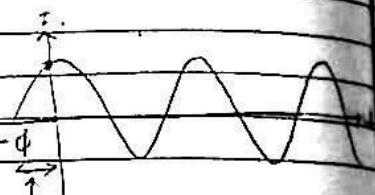
- Angular Frequency (ω) → The values of a sine function repeat after every 2π radians. denoted by (ω).
 $(\omega) = \text{no. of radians caused in } 1 \text{ sec}$
 Its unit is radians/seconds.

$$\omega = \frac{2\pi}{T}$$

- PHASE SHIFT →

$$I = I_m \sin(\omega t \pm \phi)$$

at $\omega t = 0$



comparison can only be done with respect to anyone read.

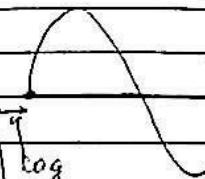
$$\text{Ex: } I_1 = 2 \sin(4t - 30^\circ)$$

$$I_2 = 2 \sin(4t - 50^\circ)$$

$$I_3 = 2 \sin(4t - 80^\circ)$$

deg w.r.t.

I_1 should be same.



The initial shift of the waveforms on the time axis or angular axis is called phase shift.

Angle of lead

→ If ϕ is +ve number \Rightarrow waveform shift towards left.

→ If ϕ is -ve number \Rightarrow waveform shift towards right

Angle of lag

\rightarrow (AC value magnitude)

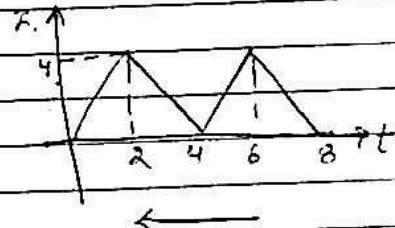
Rms Value :- / Effective value

- An effective value of an AC current depends on the basis of its heating effect.
- Let an AC sinusoidal current $I = I_m \sin \omega t$ flow through a resistor R , our aim is to find that value of DC current I which gives the same amount of heating, if it flows through a resistor of the same value R . This would be the effective value of the AC sinusoidal current.

$$I_{\text{eff}} / I_{\text{rms}} = \sqrt{\frac{1}{T} \int (I^2)^2 dt}$$

Q: Find rms value? Ans: $\sqrt{\frac{16}{3}}$

$$\text{Ans: } I_{\text{rms}} = \sqrt{\int_0^2 4t^2 dt + \int_2^4 (8-2t)^2 dt}$$



RMS.
Root square mean

$$m = \sqrt{\frac{y_1 - y_2}{x_2 - x_1}}$$

(2)

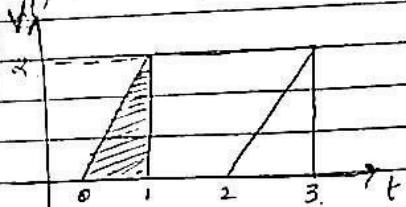
(2)

$$\frac{y_1 - y_2}{x_2 - x_1} = \frac{4 - 0}{2 - 0} = \frac{4}{2} = 2$$

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Q. Find average and rms values of following :-

(a)

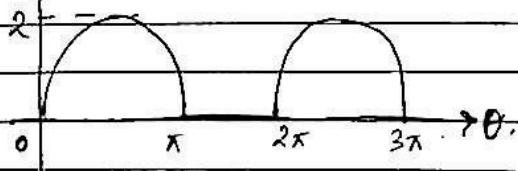


$$\text{Average} = \frac{1}{2}$$

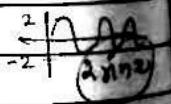
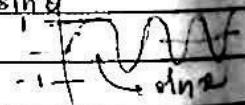
$$V_{rms} = \frac{\sqrt{3}}{\sqrt{3}}$$

v(θ)

(b)



$$\text{Max} = 2 \sin \theta$$



minimum

$$\text{Avg. value.} = \frac{\int_0^{\pi} 2 \sin \theta d\theta}{2\pi}$$

$$= \frac{\int_0^{\pi} 2 \sin \theta d\theta + \int_{\pi}^{2\pi} 0 d\theta}{2\pi}$$

Addition was
10 → so far

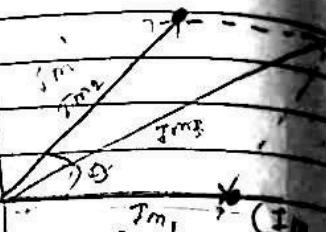
DATE	EXERCISE
Page No.	

PHASOR ALGEBRA :-

Methods to find net impedance -

- ① By using concepts of Phasor -

Resultant of I_{m1} and I_{m2} -



Rectangular form / complex form

$$z = r(\cos \theta + j \sin \theta)$$

$$\theta = \tan^{-1}(\frac{y}{x})$$

$$I_{m1} = I_m \sin(\theta_1)$$

$$I_{m2} = I_m' \sin(\theta_2)$$

Trigonometric to

Polar form representation

$$z = r \angle \theta \quad \text{--- max. value. angle with reference.}$$

$$I_{m1} = I_m \angle \theta_1$$

$$I_{m2} = I_m' \angle \theta_2$$

Polar to rectangular form

$$\Rightarrow r \angle \theta \quad (\text{polar})$$

$$\Rightarrow r \cos \theta + j r \sin \theta \quad (\text{rectangular})$$

$$I_{m3} = I_{m1} + I_{m2}$$

$$= I_m \angle \theta_1 + I_m' \cos \theta_2 + j I_m' \sin \theta_2$$

With example :-

1) From to polar

$$z = 2 \cos 40^\circ + j 2 \sin 40^\circ \rightarrow 2 \times L30^\circ \text{ at } 2e^{j40^\circ}$$

2) Polar to complex / Rectangular

$$2 \times L30^\circ \rightarrow 2 \cos 30^\circ + j 2 \sin 30^\circ$$

3) Rectangular to Polar

$$z = 2 \cos 30^\circ + j 2 \sin 30^\circ =$$

$$\sqrt{(2 \cos 30^\circ)^2 + (2 \sin 30^\circ)^2} = \sqrt{2^2 + 2^2} = \sqrt{2^2 + 2^2}$$

$$\theta = \tan^{-1}\left(\frac{2 \sin 30^\circ}{2 \cos 30^\circ}\right)$$

4) Polar to Polar

$$x + y = r \angle \theta$$

$$r = \sqrt{x^2 + y^2}$$

$$\angle \theta = \tan^{-1}\left(\frac{y}{x}\right)$$

$$\theta = \tan^{-1}(\tan 30^\circ)$$

$$\theta = 30^\circ$$

$$z = r e^{j\theta}$$

$$= 2 \times L30^\circ$$

② Addition, Subtraction, Multiplication, Division
of two no.s :-

e.g., $z_1 = 2 + 4j$ Find: $z_1 + z_2$, $z_1 - z_2$, $z_1 \times z_2$, $\frac{z_1}{z_2}$

$$z_2 = 1 + 3j$$

$$z_1 = 2 + 4j = \sqrt{2^2 + 4^2} \times \angle \tan^{-1}\left(\frac{4}{2}\right)$$

$$z_2 = 1 + 3j = \sqrt{1^2 + 3^2} \times \angle \tan^{-1}\left(\frac{3}{1}\right)$$

(complex)
from
only)

$z_1 + z_2 = 2 + 4j + 1 + 3j = 3 + 7j \Rightarrow \sqrt{3^2 + 7^2} \times \angle \tan^{-1}\left(\frac{7}{3}\right)$

$$z_1 - z_2 = 2 + 4j - 1 - 3j = 1 + j \Rightarrow \sqrt{1^2 + 1^2} \times \angle \tan^{-1}\left(\frac{1}{1}\right)$$

(Total sum only)

$$x_1 \cdot x_2 =$$

Generalized form:

$$x_1 = r_1 \angle \theta_1$$

$$x_2 = r_2 \angle \theta_2$$

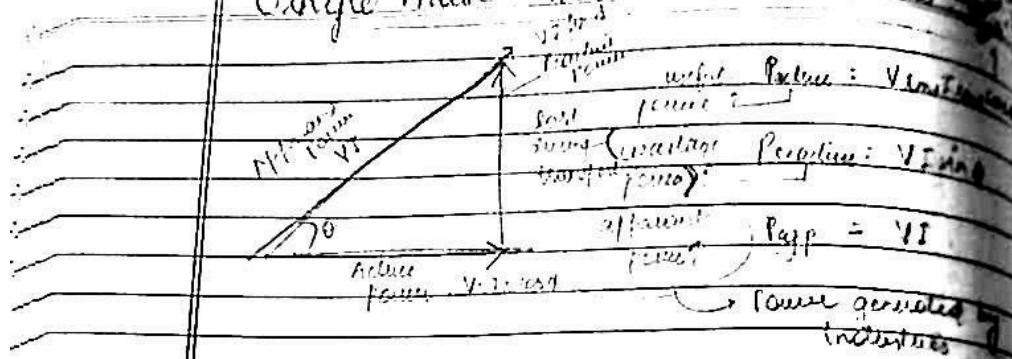
$$x_3 = r_3 \angle \theta_3.$$

$$x_1 \cdot x_2 \cdot x_3 = r_1 \times r_2 \times r_3 \angle \theta_1 + \theta_2 + \theta_3.$$

$$\frac{x_1 \cdot x_2}{x_3} = \frac{r_1 \cdot r_2 \angle (\theta_1 + \theta_2)}{r_3 \angle \theta_3}.$$

$$= \frac{r_1 \cdot r_2}{r_3} \angle \theta_1 + \theta_2 - \theta_3.$$

Single Phase Series ac circuit



$$\text{Apparent Power} = \sqrt{(\text{Active Power})^2 + (\text{Reactive Power})^2}$$

Only resistive element -

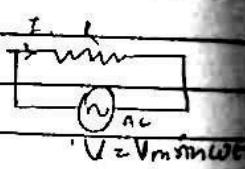
Phase diff = 0
 I and V → same direction.

$$I = \frac{V_m}{R}$$

1) Purely resistive circuit :-

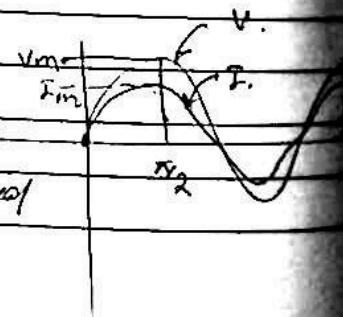
$$I = \frac{V}{R} = \frac{V_m \sin \omega t}{R} \Rightarrow I_m \sin \omega t$$

$$I = I_m \sin \omega t$$



→ Wave form representation :-

=) diff. between V_m and I_m is identified by resistance R .



→ Phasor representation :-

$$\begin{aligned} \text{Power} &= VT \cos \phi \\ &= VT \cos \frac{\pi}{2} \\ P &= 0 \end{aligned}$$

$\vec{V} = V \angle 0^\circ$

phasor diff = \vec{V}

I

3) Purely Capacitive circuits :-

$$T = \frac{V}{X_C} \quad X_C = \frac{1}{j\omega} = -\frac{j}{\omega} \quad X_C = \frac{1}{j\omega} = \frac{-j}{\omega} \quad \omega = \frac{1}{\sqrt{LC}} \quad V = V_m \sin \omega t$$

$$I = \frac{V_m \sin \omega t + j0}{-\frac{j}{\omega}} = \frac{V_m \sin \omega t}{\omega C}$$

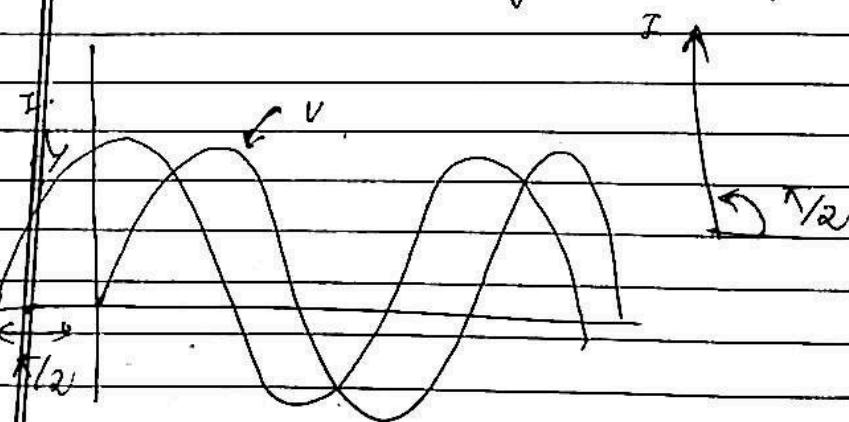
$$I = I_m \angle \frac{\pi}{2}$$

$$\tan^{-1} \left(\frac{-1}{\omega C} \right)$$

$$\tan^{-1}(\infty) = -\frac{\pi}{2}$$

Leading nature circuit. → all are current.

⇒ Current lead voltage by an angle of $\frac{\pi}{2}$.

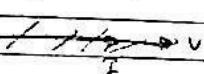


Physical representation :-

$$\text{max diff } (\phi) = 0$$

In purely resistive, no reactance, voltage and current are in same phase.

$$\text{Power} = VI \cos \phi + \text{Power factor} = P$$
$$P = VI$$
$$V_{\text{rms}}$$



Purely Inductive circuits :-

H.W.K	$i_{\text{rms}} = I_{\text{m}}$
F.W.R	$Z_{\text{rms}} = \frac{I_{\text{m}}}{i_{\text{rms}}} = \sqrt{2}$

$$P = V$$
$$(X_L = j\omega L)$$
$$(2) \quad V = V_{\text{m}} \sin \omega t$$

$$V_{\text{rms}} = \frac{V_m}{\sqrt{2}}$$
$$V_{\text{rms}} = \frac{I_m}{\sqrt{2}}$$

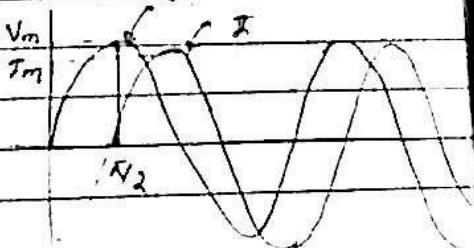
Inductive reactance :-

Unit :- (2)

$$Ex: I = \frac{V}{Z} = \frac{V_m \sin \omega t}{\omega L} = \frac{V_m}{\omega L} \sin \omega t \quad S = \frac{V_m^2 L - \bar{N}_2}{\omega L}$$

$$(\text{RMS}) \quad I = \frac{V_m}{\omega L} \sin(\omega t - \pi/2)$$

Current lag w.r.t. voltage by $\pi/2$



→ Wave form representation :-

$$V = \sqrt{V_R^2 + V_C^2}$$

$$J = \frac{V}{R+j\omega L}$$

$$V = I R \angle j\omega L$$

$$V = (V_R) \angle j\omega L$$

$$V = \sqrt{V_R^2 + (j\omega L)^2}$$

5) R-C series circuit :-

$$I = \frac{V}{Z}$$

$$I = V_m \angle 0^\circ$$

$$\sqrt{R^2 + \left(\frac{1}{\omega C}\right)^2} \angle \tan^{-1}\left(\frac{1}{\omega C R}\right) = \sqrt{R^2 + \left(\frac{1}{\omega C}\right)^2}$$

$$Z = \sqrt{R^2 + \left(\frac{1}{\omega C}\right)^2} = V_m \angle 0^\circ$$

$$I = V_m \cdot \angle \tan^{-1}\left(\frac{1}{\omega C R}\right)$$

$$\sqrt{R^2 + \left(\frac{1}{\omega C}\right)^2}$$

$\Rightarrow I$ lead w.r.t. ϕ to voltage

by angle

$$\cos \phi = \frac{R}{Z}$$

$$\tan^{-1}\left(\frac{1}{\omega C R}\right)$$

$$= \underline{R} \quad (\text{lead}).$$

$$\sqrt{R^2 + \left(\frac{1}{\omega C}\right)^2}$$

$Z = R - j \frac{1}{\omega C}$ (Impedance Triangle).

$$\angle \phi = \tan^{-1}\left(\frac{1}{\omega C R}\right)$$

$$(Z = \sqrt{R^2 + \left(\frac{1}{\omega C}\right)^2})$$

In AC circuits, V & I cannot be alone represented by magnitude & phase should be in place or complex form.

1) R-L series circuit -

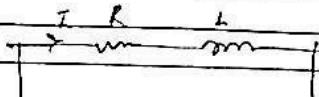
$$R = \frac{V}{I}$$

$$(R + j\omega L)$$

$$\therefore Z = R + j\omega L$$

$$I = \frac{V}{Z}$$

DATE _____
Page No. _____



$$V = V_m \sin(\omega t)$$

$$|Z| = \sqrt{R^2 + (\omega L)^2}$$

$$\angle Z = \tan^{-1} \left(\frac{\omega L}{R} \right)$$

$$I = V_m \sin \omega t$$

$$\sqrt{R^2 + (\omega L)^2} \times \tan^{-1} \left(\frac{\omega L}{R} \right)$$

$$\therefore \tan \frac{\omega L}{R} = \theta$$

$$I = V_m \sin \omega t$$

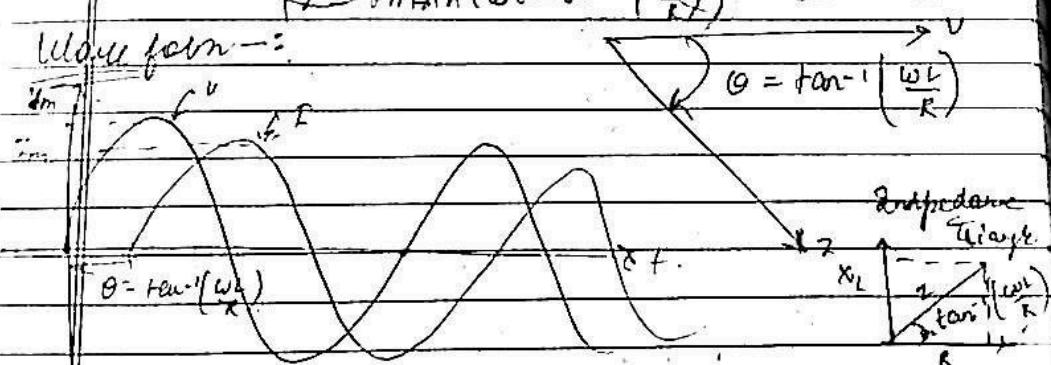
$$I = V_m \angle \theta$$

$$\sqrt{R^2 + (\omega L)^2} \angle \tan^{-1} \left(\frac{\omega L}{R} \right) - \tan^{-1} \left(\frac{\omega L}{R} \right)$$

$$I = \frac{V_m}{\sqrt{R^2 + (\omega L)^2}} \angle \tan^{-1} \left(\frac{\omega L}{R} \right) \quad \text{(phase representation)}$$

$$I = I_m \sin(\omega t - \tan^{-1} \left(\frac{\omega L}{R} \right))$$

Wave form :-



In RL series AC circuits, current lags w.r.t. voltage by angle $\tan^{-1} \left(\frac{\omega L}{R} \right)$.

$$\text{Power} = VI \cos \phi$$

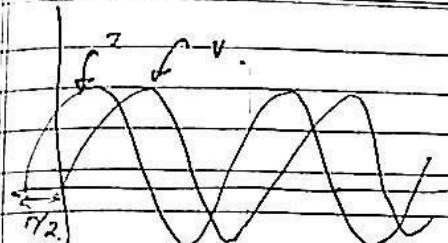
$$= VI \cos \left(\tan^{-1} \left(\frac{\omega L}{R} \right) \right)$$

$$\cos \phi = \frac{R}{\sqrt{R^2 + (\omega L)^2}}$$

$$\boxed{P = \frac{VI \times R}{\sqrt{R^2 + (\omega L)^2}}}$$

$$V = \sqrt{(VR)^2 + (V_L)^2}$$

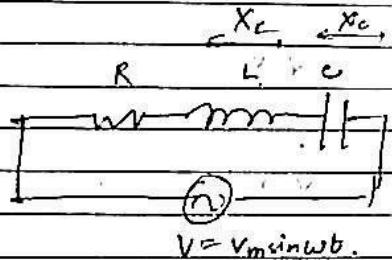
DATE _____
Page No. _____



$$\textcircled{6} \quad I = \frac{V}{Z}$$

$$= V_m L \omega$$

$$R + j(\omega L - \frac{1}{\omega C})$$



$$V = V_m \sin \omega t$$

$$V = V_m L \omega$$

$$I = \frac{V_m / \omega}{\sqrt{R^2 + (\omega L - \frac{1}{\omega C})^2}} \angle \tan^{-1} \left(\frac{\omega L - \frac{1}{\omega C}}{R} \right) Z = R + j(\omega L + \frac{1}{\omega C})$$

$$Z = R + j(\omega L - \frac{1}{\omega C})$$

$$I = V_m \angle \tan^{-1} \left(\frac{\omega L - \frac{1}{\omega C}}{R} \right)$$

$$\sqrt{R^2 + (\omega L - \frac{1}{\omega C})^2}$$

$$= \frac{V_m}{\sqrt{R^2 + ((X_L - X_C))^2}} \angle -\tan^{-1} \left(\frac{X_L - X_C}{R} \right)$$

$$\sqrt{R^2 + ((X_L - X_C))^2}$$

Case-1 :- Purely resistive circuit. (Phase diff. = 0).
where ($X_R = R_C$)

Case-2 :- ~~Purely~~ Inductive circuit. (I lag phase diff. = $\tan^{-1}(\frac{X_L}{R})$)
where ($X_L > X_C$)

Case-3 :- Capacitive circuit (I lead phase diff. = $\tan^{-1}(\frac{X_C}{R})$)
where ($X_L < X_C$)

Impedance Triangle!

Starform Format

DATE:
Page No.

X_L

$(X_L \ X_C)$
when $(X_L > X_C)$

'Phase Diagram'

V_{LA}

X_C

$(X_L > X_C)$

V_R

$(X_C > X_L)$

I

V_R

V_C