RTML 2025 | A1 | Pytorch-AlexNet-GoogleNet

Final Report

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This notebook consists of solutions for the following exercises:

(Note that this is a Jupyter Notebook compiled from the individual python scripts and is not intended to be run as is)

- 1. Create these three networks. Be sure to properly define your Python classes, with one class per file and a main module that sets up your objects, runs the training process, and saves the necessary data.
- 2. Note that the AlexNet implementation here does not have the local response normalization feature described in the paper. Take a look at the PyTorch implementation of LRN and incorporate it into your AlexNet implementation as it is described in the paper. Compare your test set results with and without LRN.
- 3. Note that the backbone of the GoogLeNet implemented thus far does not correspond exactly to the description. Modify the architecture to Use the same backbone (input image size, convolutions, etc.) before the first Inception module Add the two side classifiers
- 4. Compare your GoogLeNet and AlexNet implementations on CIFAR-10. Comment on the number of parameters, speed of training, and accuracy of the two models on this dataset when trained from scratch.
- 5. Experiment with the pretrained GoogLeNet and AlexNet from the torchvision repository. Does it give better results on CIFAR-10 similar to what we found with AlexNet? Comment on what we can glean from the results about the capacity and generalization ability of these two models.

AlexNet Class

SOLVED: Note that the AlexNet implementation here does not have the local response normalization feature described in the paper. Take a look at the PyTorch implementation of LRN and incorporate it into your AlexNet implementation as it is described in the paper. Compare your test set results with and without LRN.

```
# Set HTTP and HTTPS proxy
os.environ['http_proxy'] = 'http://192.41.170.23:3128'
os.environ['https_proxy'] = 'http://192.41.170.23:3128'
import torch
import torch.nn as nn
class AlexNet(nn.Module):
   An AlexNet-like CNN with Local Response Normalization (LRN)
   Attributes
    _____
   num_classes : int
        Number of classes in the final multinomial output layer
   features : Sequential
       The feature extraction portion of the network
    avgpool : AdaptiveAvgPool2d
       Convert the final feature layer to 6x6 feature maps by average pooling i
    classifier : Sequential
       Classify the feature maps into num_classes classes
    use_lrn : bool
       Whether to use Local Response Normalization
    def __init__(self, num_classes: int = 10, use_lrn: bool = True):
        super().__init__()
        self.num_classes = num_classes
        self.use_lrn = use_lrn
        # First conv layer
        self.features_1 = nn.Sequential(
            nn.Conv2d(3, 64, kernel_size=11, stride=4, padding=2),
            nn.ReLU(inplace=True),
        )
        # First LRN layer (after ReLU, before MaxPool)
        self.lrn1 = nn.LocalResponseNorm(size=5, alpha=0.0001, beta=0.75, k=2)
        # First MaxPool and second conv
        self.features_2 = nn.Sequential(
            nn.MaxPool2d(kernel size=3, stride=2),
            nn.Conv2d(64, 192, kernel_size=5, padding=2),
            nn.ReLU(inplace=True),
        )
        # Second LRN layer (after ReLU, before MaxPool)
        self.lrn2 = nn.LocalResponseNorm(size=5, alpha=0.0001, beta=0.75, k=2)
        # Second MaxPool and remaining layers
        self.features 3 = nn.Sequential(
            nn.MaxPool2d(kernel_size=3, stride=2),
            nn.Conv2d(192, 384, kernel_size=3, padding=1),
            nn.ReLU(inplace=True),
            nn.Conv2d(384, 256, kernel_size=3, padding=1),
            nn.ReLU(inplace=True),
            nn.Conv2d(256, 256, kernel_size=3, padding=1),
            nn.ReLU(inplace=True),
            nn.MaxPool2d(kernel_size=3, stride=2),
        )
```

```
self.avgpool = nn.AdaptiveAvgPool2d((6, 6))
    self.classifier = nn.Sequential(
        nn.Dropout(p=0.5), # Added dropout rate as per paper
        nn.Linear(256 * 6 * 6, 4096),
        nn.ReLU(inplace=True),
        nn.Dropout(p=0.5), # Added dropout rate as per paper
        nn.Linear(4096, 4096),
       nn.ReLU(inplace=True),
       nn.Linear(4096, num_classes),
def forward(self, x: torch.Tensor) -> torch.Tensor:
   # First conv + ReLU
   x = self.features_1(x)
   # First LRN (if enabled)
   if self.use_lrn:
       x = self.lrn1(x)
   # First MaxPool + second conv + ReLU
   x = self.features_2(x)
   # Second LRN (if enabled)
   if self.use lrn:
       x = self.lrn2(x)
   # Remaining Layers
   x = self.features_3(x)
   x = self.avgpool(x)
   x = torch.flatten(x, 1)
   x = self.classifier(x)
   return x
```

Output & Results:

1. Training AlexNet With LRN

```
Training AlexNet with LRN...
Epoch 1/20:
Train Loss: 2.3026, Train Acc: 0.1009
Val Loss: 2.3020, Val Acc: 0.1176
Batch Time: 0.0353s
Epoch 2/20:
Train Loss: 2.1474, Train Acc: 0.2016
Val Loss: 1.9162, Val Acc: 0.2708
Batch Time: 0.0381s
Epoch 3/20:
Train Loss: 1.7291, Train Acc: 0.3462
Val Loss: 1.5222, Val Acc: 0.4324
Batch Time: 0.0357s
Epoch 4/20:
Train Loss: 1.4334, Train Acc: 0.4713
Val Loss: 1.3261, Val Acc: 0.5064
Batch Time: 0.0357s
Epoch 5/20:
Train Loss: 1.2513, Train Acc: 0.5426
```

Val Loss: 1.1364, Val Acc: 0.5862

Batch Time: 0.0361s

Epoch 6/20:

Train Loss: 1.0832, Train Acc: 0.6118 Val Loss: 0.9491, Val Acc: 0.6574

Batch Time: 0.0367s

Epoch 7/20:

Train Loss: 0.9441, Train Acc: 0.6650 Val Loss: 0.8691, Val Acc: 0.6924

Batch Time: 0.0356s

Epoch 8/20:

Train Loss: 0.8381, Train Acc: 0.7050 Val Loss: 0.8000, Val Acc: 0.7080

Batch Time: 0.0358s

Epoch 9/20:

Train Loss: 0.7660, Train Acc: 0.7301 Val Loss: 0.6960, Val Acc: 0.7560

Batch Time: 0.0348s

Epoch 10/20:

Train Loss: 0.6950, Train Acc: 0.7567 Val Loss: 0.6654, Val Acc: 0.7678

Batch Time: 0.0361s

Epoch 11/20:

Train Loss: 0.6475, Train Acc: 0.7753 Val Loss: 0.6335, Val Acc: 0.7772

Batch Time: 0.0403s

Epoch 12/20:

Train Loss: 0.5952, Train Acc: 0.7919 Val Loss: 0.6191, Val Acc: 0.7792

Batch Time: 0.0385s

Epoch 13/20:

Train Loss: 0.5538, Train Acc: 0.8068 Val Loss: 0.5497, Val Acc: 0.8060

Batch Time: 0.0389s

Epoch 14/20:

Train Loss: 0.5155, Train Acc: 0.8229 Val Loss: 0.5501, Val Acc: 0.8102

Batch Time: 0.0377s

Epoch 15/20:

Train Loss: 0.4816, Train Acc: 0.8315 Val Loss: 0.5513, Val Acc: 0.8054

Batch Time: 0.0376s

Epoch 16/20:

Train Loss: 0.4449, Train Acc: 0.8455 Val Loss: 0.5023, Val Acc: 0.8252

Batch Time: 0.0407s

Epoch 17/20:

Train Loss: 0.4196, Train Acc: 0.8529 Val Loss: 0.5053, Val Acc: 0.8260

Batch Time: 0.0371s

Epoch 18/20:

Train Loss: 0.3952, Train Acc: 0.8619 Val Loss: 0.5119, Val Acc: 0.8234

Batch Time: 0.0426s

Epoch 19/20:

Train Loss: 0.3698, Train Acc: 0.8722

Val Loss: 0.4756, Val Acc: 0.8362

Batch Time: 0.0422s

Epoch 20/20:

Train Loss: 0.3515, Train Acc: 0.8784 Val Loss: 0.4513, Val Acc: 0.8446

Batch Time: 0.0367s

Total training time for AlexNet with LRN: 17.12 minutes

2. Training Alexnet Without LRN

Training AlexNet without LRN...

Epoch 1/20:

Train Loss: 2.2073, Train Acc: 0.1632 Val Loss: 1.9603, Val Acc: 0.2782

Batch Time: 0.0383s

Epoch 2/20:

Train Loss: 1.6577, Train Acc: 0.3869 Val Loss: 1.4239, Val Acc: 0.4726

Batch Time: 0.0405s

Epoch 3/20:

Train Loss: 1.3588, Train Acc: 0.5036 Val Loss: 1.2013, Val Acc: 0.5752

Batch Time: 0.0415s

Epoch 4/20:

Train Loss: 1.1139, Train Acc: 0.6011 Val Loss: 1.0265, Val Acc: 0.6304

Batch Time: 0.0414s

Epoch 5/20:

Train Loss: 0.9415, Train Acc: 0.6672 Val Loss: 0.8589, Val Acc: 0.6946

Batch Time: 0.0432s

Epoch 6/20:

Train Loss: 0.8340, Train Acc: 0.7078 Val Loss: 0.8179, Val Acc: 0.7124

Batch Time: 0.0424s

Epoch 7/20:

Train Loss: 0.7398, Train Acc: 0.7423 Val Loss: 0.7249, Val Acc: 0.7478

Batch Time: 0.0430s

Epoch 8/20:

Train Loss: 0.6628, Train Acc: 0.7690 Val Loss: 0.6563, Val Acc: 0.7736

Batch Time: 0.0385s

Epoch 9/20:

Train Loss: 0.6059, Train Acc: 0.7881 Val Loss: 0.5994, Val Acc: 0.7886

Batch Time: 0.0405s

Epoch 10/20:

Train Loss: 0.5562, Train Acc: 0.8072 Val Loss: 0.6072, Val Acc: 0.7878

Batch Time: 0.0395s

Epoch 11/20:

Train Loss: 0.5121, Train Acc: 0.8240 Val Loss: 0.5246, Val Acc: 0.8150

Batch Time: 0.0433s

Epoch 12/20:

Train Loss: 0.4741, Train Acc: 0.8329 Val Loss: 0.5355, Val Acc: 0.8130

Batch Time: 0.0428s

Epoch 13/20:

Train Loss: 0.4421, Train Acc: 0.8485 Val Loss: 0.5294, Val Acc: 0.8144

Batch Time: 0.0426s

Epoch 14/20:

Train Loss: 0.4087, Train Acc: 0.8582 Val Loss: 0.5418, Val Acc: 0.8152

Batch Time: 0.0427s

Epoch 15/20:

Train Loss: 0.3846, Train Acc: 0.8661 Val Loss: 0.4777, Val Acc: 0.8366

Batch Time: 0.0405s

Epoch 16/20:

Train Loss: 0.3459, Train Acc: 0.8802 Val Loss: 0.4799, Val Acc: 0.8408

Batch Time: 0.0414s

Epoch 17/20:

Train Loss: 0.3303, Train Acc: 0.8858 Val Loss: 0.4991, Val Acc: 0.8304

Batch Time: 0.0362s

Epoch 18/20:

Train Loss: 0.3070, Train Acc: 0.8925 Val Loss: 0.4683, Val Acc: 0.8492

Batch Time: 0.0408s

Epoch 19/20:

Train Loss: 0.2867, Train Acc: 0.9004 Val Loss: 0.4610, Val Acc: 0.8506

Batch Time: 0.0365s

Epoch 20/20:

Train Loss: 0.2718, Train Acc: 0.9049 Val Loss: 0.4816, Val Acc: 0.8374

Batch Time: 0.0437s

Total training time for AlexNet without LRN: 17.47 minutes

Key Observations:

I. LRN Implementation Details

- Two LRN layers are implemented with parameters:
- size: 5 (local neighborhood)
- alpha: 0.0001 (scaling parameter)
- beta: 0.75 (exponent)
- k: 2 (additive constant)

II. LRN Placement

- First LRN layer: After the first ReLU and before MaxPool
- Second LRN layer: After the second ReLU and before MaxPool

- The implementation uses a modular approach with three feature blocks. LRN layers are conditionally applied using the use_Irn flag
- 1. The version with and without LRN did not demonstrate any major improvements:
- Final test accuracy quite similar (84.56% vs 83.78%)
- Better training accuracy for without LRN (90.49% vs 87.84%)
- 2. Training stability:
- Both models showed similar batch processing times
- Training time difference was minimal (0.35 minutes)
- 3. Generalization:
- Both models showed good generalization with minimal overfitting

GoogleNet Class

SOLVED: Note that the backbone of the GoogLeNet implemented thus far does not correspond exactly to the description. Modify the architecture to Use the same backbone (input image size, convolutions, etc.) before the first Inception module Add the two side classifiers

```
In [ ]: # For our puffer surver we need to browse via a proxy!!
        import os
        # Set HTTP and HTTPS proxy
        os.environ['http_proxy'] = 'http://192.41.170.23:3128'
        os.environ['https_proxy'] = 'http://192.41.170.23:3128'
        import torch
        import torch.nn as nn
        import torch.nn.functional as F
        class Inception(nn.Module):
            Inception block for a GoogLeNet-like CNN
            Attributes
            _____
            in_planes : int
                Number of input feature maps
            n1x1 : int
                Number of direct 1x1 convolutions
            n3x3red : int
                Number of 1x1 reductions before the 3x3 convolutions
            n3x3 : int
                Number of 3x3 convolutions
            n5x5red : int
                Number of 1x1 reductions before the 5x5 convolutions
            n5x5 : int
                Number of 5x5 convolutions
            pool planes : int
                Number of 1x1 convolutions after 3x3 max pooling
```

```
def __init__(self, in_planes, n1x1, n3x3red, n3x3, n5x5red, n5x5, pool_plane
        super(Inception, self).__init__()
        self.in_planes = in_planes
        self.n1x1 = n1x1
        self.n3x3red = n3x3red
        self.n3x3 = n3x3
        self.n5x5red = n5x5red
        self.n5x5 = n5x5
        self.pool_planes = pool_planes
        # 1x1 conv branch
        self.b1 = nn.Sequential(
            nn.Conv2d(in_planes, n1x1, kernel_size=1),
            nn.BatchNorm2d(n1x1),
            nn.ReLU(True),
        # 1x1 conv -> 3x3 conv branch
        self.b2 = nn.Sequential(
            nn.Conv2d(in_planes, n3x3red, kernel_size=1),
            nn.BatchNorm2d(n3x3red),
            nn.ReLU(True),
            nn.Conv2d(n3x3red, n3x3, kernel_size=3, padding=1),
            nn.BatchNorm2d(n3x3),
            nn.ReLU(True),
        )
        # 1x1 conv -> 5x5 conv branch
        self.b3 = nn.Sequential(
            nn.Conv2d(in_planes, n5x5red, kernel_size=1),
            nn.BatchNorm2d(n5x5red),
            nn.ReLU(True),
            nn.Conv2d(n5x5red, n5x5, kernel_size=3, padding=1),
            nn.BatchNorm2d(n5x5),
            nn.ReLU(True),
            nn.Conv2d(n5x5, n5x5, kernel size=3, padding=1),
            nn.BatchNorm2d(n5x5),
            nn.ReLU(True),
        )
        # 3x3 pool -> 1x1 conv branch
        self.b4 = nn.Sequential(
            nn.MaxPool2d(3, stride=1, padding=1),
            nn.Conv2d(in_planes, pool_planes, kernel_size=1),
            nn.BatchNorm2d(pool_planes),
            nn.ReLU(True),
        )
    def forward(self, x):
        y1 = self.b1(x)
        y2 = self.b2(x)
        y3 = self.b3(x)
        y4 = self.b4(x)
        return torch.cat([y1, y2, y3, y4], 1)
class InceptionAux(nn.Module):
    Auxiliary classifier for GoogLeNet
```

```
Attributes
    _____
    conv : Sequential
       Convolutional layers for feature extraction
    fc1 : Linear
        First fully connected layer
    fc2 : Linear
       Output layer
    dropout : Dropout
       Dropout layer for regularization
    def __init__(self, in_channels, num_classes):
        super(InceptionAux, self).__init__()
        self.conv = nn.Sequential(
            nn.AvgPool2d(kernel_size=5, stride=3),
            nn.Conv2d(in_channels, 128, kernel_size=1),
            nn.ReLU(True)
        )
        self.fc1 = nn.Linear(128 * 4 * 4, 1024)
        self.fc2 = nn.Linear(1024, num_classes)
        self.dropout = nn.Dropout(0.7)
    def forward(self, x):
        x = self.conv(x)
       x = torch.flatten(x, 1)
       x = F.relu(self.fc1(x))
        x = self.dropout(x)
        x = self.fc2(x)
       return x
class GoogLeNet(nn.Module):
   GoogLeNet (Inception v1) implementation
   Attributes
    _____
    pre layers : Sequential
       Initial convolutional layers before inception modules
   a3-b5 : Inception
       Inception blocks
    aux1, aux2 : InceptionAux
        Auxiliary classifiers
    avgpool : AvgPool2d
       Average pool layer after final inception block
    dropout : Dropout
       Dropout layer before final classifier
    fc : Linear
       Final classifier layer
    def __init__(self, num_classes=10, aux_logits=True, transform_input=False):
        super(GoogLeNet, self).__init__()
        self.aux_logits = aux_logits
        self.transform_input = transform_input
        # Initial layers before inception modules (matching paper)
        self.conv1 = nn.Sequential(
            nn.Conv2d(3, 64, kernel_size=7, stride=2, padding=3),
            nn.ReLU(True),
            nn.MaxPool2d(kernel_size=3, stride=2, padding=1),
            nn.LocalResponseNorm(size=5, alpha=0.0001, beta=0.75, k=2)
```

```
self.conv2 = nn.Sequential(
        nn.Conv2d(64, 64, kernel_size=1),
        nn.ReLU(True),
        nn.Conv2d(64, 192, kernel size=3, padding=1),
       nn.ReLU(True),
        nn.LocalResponseNorm(size=5, alpha=0.0001, beta=0.75, k=2),
        nn.MaxPool2d(kernel_size=3, stride=2, padding=1)
    )
   self.inception3a = Inception(192, 64, 96, 128, 16, 32, 32)
    self.inception3b = Inception(256, 128, 128, 192, 32, 96, 64)
    self.maxpool3 = nn.MaxPool2d(3, stride=2, padding=1)
   self.inception4a = Inception(480, 192, 96, 208, 16, 48, 64)
    self.inception4b = Inception(512, 160, 112, 224, 24, 64, 64)
   self.inception4c = Inception(512, 128, 128, 256, 24, 64,
   self.inception4d = Inception(512, 112, 144, 288, 32, 64, 64)
    self.inception4e = Inception(528, 256, 160, 320, 32, 128, 128)
    self.maxpool4 = nn.MaxPool2d(3, stride=2, padding=1)
   self.inception5a = Inception(832, 256, 160, 320, 32, 128, 128)
   self.inception5b = Inception(832, 384, 192, 384, 48, 128, 128)
   if aux_logits:
        self.aux1 = InceptionAux(512, num_classes)
        self.aux2 = InceptionAux(528, num_classes)
   self.avgpool = nn.AdaptiveAvgPool2d((1, 1))
    self.dropout = nn.Dropout(0.4)
    self.fc = nn.Linear(1024, num_classes)
def _transform_input(self, x):
   if self.transform_input:
       x_{ch0} = torch.unsqueeze(x[:, 0], 1) * (0.229 / 0.5) + (0.485 - 0.5)
       x ch1 = torch.unsqueeze(x[:, 1], 1) * (0.224 / 0.5) + (0.456 - 0.5)
       x_ch2 = torch.unsqueeze(x[:, 2], 1) * (0.225 / 0.5) + (0.406 - 0.5)
       x = torch.cat((x_ch0, x_ch1, x_ch2), 1)
    return x
def forward(self, x):
   # N x 3 x 224 x 224
   x = self._transform_input(x)
   # N x 64 x 112 x 112
   x = self.conv1(x)
   # N x 192 x 56 x 56
   x = self.conv2(x)
   # N x 256 x 56 x 56
   x = self.inception3a(x)
   # N x 480 x 56 x 56
   x = self.inception3b(x)
   # N x 480 x 28 x 28
   x = self.maxpool3(x)
   # N x 512 x 28 x 28
   x = self.inception4a(x)
```

```
if self.training and self.aux_logits:
    aux1 = self.aux1(x)
x = self.inception4b(x)
x = self.inception4c(x)
x = self.inception4d(x)
if self.training and self.aux_logits:
    aux2 = self.aux2(x)
x = self.inception4e(x)
x = self.maxpool4(x)
x = self.inception5a(x)
x = self.inception5b(x)
x = self.avgpool(x)
x = torch.flatten(x, 1)
x = self.dropout(x)
x = self.fc(x)
if self.training and self.aux_logits:
    return x, aux1, aux2
return x
```

Output & Results

```
Training Custom GoogLeNet...
Epoch 1/20:
Train Loss: 2.4877, Train Acc: 0.4582
Val Loss: 1.3349, Val Acc: 0.5264
Batch Time: 0.0830s
Epoch 2/20:
Train Loss: 1.6215, Train Acc: 0.6679
Val Loss: 1.0407, Val Acc: 0.6516
Batch Time: 0.0821s
Epoch 3/20:
Train Loss: 1.2190, Train Acc: 0.7613
Val Loss: 0.7700, Val Acc: 0.7368
Batch Time: 0.0824s
Epoch 4/20:
Train Loss: 0.9855, Train Acc: 0.8140
Val Loss: 0.6541, Val Acc: 0.7804
Batch Time: 0.0793s
Epoch 5/20:
Train Loss: 0.8510, Train Acc: 0.8427
Val Loss: 0.5375, Val Acc: 0.8190
Batch Time: 0.0818s
Epoch 6/20:
Train Loss: 0.7347, Train Acc: 0.8696
Val Loss: 0.5920, Val Acc: 0.8028
Batch Time: 0.0865s
Epoch 7/20:
Train Loss: 0.6557, Train Acc: 0.8856
Val Loss: 0.6266, Val Acc: 0.7988
```

Batch Time: 0.0869s

Epoch 8/20:

Train Loss: 0.5879, Train Acc: 0.8993 Val Loss: 0.5096, Val Acc: 0.8342

Batch Time: 0.0787s

Epoch 9/20:

Train Loss: 0.5376, Train Acc: 0.9102 Val Loss: 0.4639, Val Acc: 0.8470

Batch Time: 0.0860s

Epoch 10/20:

Train Loss: 0.4845, Train Acc: 0.9228 Val Loss: 0.5086, Val Acc: 0.8318

Batch Time: 0.0780s

Epoch 11/20:

Train Loss: 0.4408, Train Acc: 0.9328 Val Loss: 0.4599, Val Acc: 0.8506

Batch Time: 0.0812s

Epoch 12/20:

Train Loss: 0.4018, Train Acc: 0.9390 Val Loss: 0.3782, Val Acc: 0.8848

Batch Time: 0.0827s

Epoch 13/20:

Train Loss: 0.3698, Train Acc: 0.9469 Val Loss: 0.3827, Val Acc: 0.8820

Batch Time: 0.0821s

Epoch 14/20:

Train Loss: 0.3377, Train Acc: 0.9520 Val Loss: 0.4799, Val Acc: 0.8590

Batch Time: 0.0831s

Epoch 15/20:

Train Loss: 0.3187, Train Acc: 0.9567 Val Loss: 0.4732, Val Acc: 0.8614

Batch Time: 0.0856s

Epoch 16/20:

Train Loss: 0.3015, Train Acc: 0.9597 Val Loss: 0.4713, Val Acc: 0.8598

Batch Time: 0.0865s

Epoch 17/20:

Train Loss: 0.2806, Train Acc: 0.9637 Val Loss: 0.5082, Val Acc: 0.8568

Batch Time: 0.0849s

Epoch 18/20:

Train Loss: 0.2513, Train Acc: 0.9686 Val Loss: 0.4500, Val Acc: 0.8720

Batch Time: 0.0848s

Epoch 19/20:

Train Loss: 0.2419, Train Acc: 0.9709 Val Loss: 0.4026, Val Acc: 0.8844

Batch Time: 0.0870s

Epoch 20/20:

Train Loss: 0.2215, Train Acc: 0.9747 Val Loss: 0.4001, Val Acc: 0.8824

Batch Time: 0.0857s

Total training time for Custom GoogLeNet: 33.43 minutes

Training Class | Model Comparison

SOLVED: Create these three networks. Be sure to properly define your Python classes, with one class per file and a main module that sets up your objects, runs the training process, and saves the necessary data.

```
In [ ]: # For our puffer surver we need to browse via a proxy!!
        import os
        # Set HTTP and HTTPS proxy
        os.environ['http proxy'] = 'http://192.41.170.23:3128'
        os.environ['https_proxy'] = 'http://192.41.170.23:3128'
        import torch
        import torch.nn as nn
        import torch.optim as optim
        from torch.utils.data import DataLoader
        from torchvision import datasets, transforms, models
        from torchvision.models import AlexNet_Weights, GoogLeNet_Weights
        import matplotlib.pyplot as plt
        import numpy as np
        import pandas as pd
        import time
        import copy
        from torch.utils.data import DataLoader
        from torchsummary import torchsummary
        from alexnet import AlexNet
        from googlenet import GoogLeNet
        import torchvision.models as models
        def count_parameters(model):
            """Count number of trainable parameters in a model"""
            return sum(p.numel() for p in model.parameters() if p.requires_grad)
        def train_epoch(model, dataloader, criterion, optimizer, device, is_inception=Fa
            """Train one epoch and return average loss and accuracy"""
            model.train()
            running_loss = 0.0
            running_corrects = 0
            total time = 0
            batches = 0
            for inputs, labels in dataloader:
                batch start = time.time()
                inputs = inputs.to(device)
                labels = labels.to(device)
                optimizer.zero_grad()
                with torch.set_grad_enabled(True):
                    if is_inception:
                        outputs = model(inputs)
                        # Handle different output formats for custom vs pretrained GoogL
                        if isinstance(outputs, tuple):
                             if len(outputs) == 3: # Custom GoogLeNet (output, aux1, aux
                                 output, aux1, aux2 = outputs
                                 loss1 = criterion(output, labels)
```

```
loss2 = criterion(aux1, labels)
                        loss3 = criterion(aux2, labels)
                        loss = loss1 + 0.3 * loss2 + 0.3 * loss3
                        outputs = output # Use main output for accuracy
                    else: # Pretrained GoogLeNet (output, aux_outputs)
                        output, aux outputs = outputs
                        loss1 = criterion(output, labels)
                        loss2 = criterion(aux_outputs, labels)
                        loss = loss1 + 0.3 * loss2
                        outputs = output # Use main output for accuracy
                else:
                    outputs = outputs
                    loss = criterion(outputs, labels)
            else:
                outputs = model(inputs)
                loss = criterion(outputs, labels)
            _, preds = torch.max(outputs, 1)
            loss.backward()
            optimizer.step()
        batch_time = time.time() - batch_start
        total_time += batch_time
        batches += 1
        running_loss += loss.item() * inputs.size(0)
        running_corrects += torch.sum(preds == labels.data)
    epoch_loss = running_loss / len(dataloader.dataset)
    epoch_acc = running_corrects.double() / len(dataloader.dataset)
    avg_batch_time = total_time / batches
    return epoch_loss, epoch_acc.item(), avg_batch_time
def evaluate(model, dataloader, criterion, device, is inception=False):
    """Evaluate model on dataloader"""
   model.eval()
   running_loss = 0.0
   running_corrects = 0
   with torch.no grad():
        for inputs, labels in dataloader:
            inputs = inputs.to(device)
            labels = labels.to(device)
            if is_inception:
                outputs = model(inputs)
                if isinstance(outputs, tuple):
                    outputs = outputs[0] # Take only the main output
                outputs = model(inputs)
            loss = criterion(outputs, labels)
            _, preds = torch.max(outputs, 1)
            running_loss += loss.item() * inputs.size(0)
            running_corrects += torch.sum(preds == labels.data)
    epoch_loss = running_loss / len(dataloader.dataset)
    epoch acc = running corrects.double() / len(dataloader.dataset)
```

```
return epoch_loss, epoch_acc.item()
def evaluate_test(model, test_loader, criterion, device, is_inception=False):
   """Evaluate model on test set"""
   model.eval()
   test_loss = 0
   correct = 0
   total = 0
   with torch.no_grad():
        for inputs, targets in test_loader:
            inputs, targets = inputs.to(device), targets.to(device)
            if is_inception:
                outputs = model(inputs)
                if isinstance(outputs, tuple):
                    outputs = outputs[0]
            else:
                outputs = model(inputs)
            loss = criterion(outputs, targets)
            test_loss += loss.item()
            _, predicted = outputs.max(1)
           total += targets.size(0)
            correct += predicted.eq(targets).sum().item()
   test_loss = test_loss / len(test_loader)
   test acc = 100. * correct / total
    return test_loss, test_acc
def plot_training_comparison(histories, title):
    """Plot training histories for multiple models"""
   plt.figure(figsize=(15, 5))
   # Plot training loss
   plt.subplot(1, 2, 1)
   for model_name, history in histories.items():
        plt.plot(history['train_loss'], label=f'{model_name} (train)')
        plt.plot(history['val_loss'], label=f'{model_name} (val)')
    plt.title(f'{title} - Loss')
    plt.xlabel('Epoch')
   plt.ylabel('Loss')
   plt.legend()
   # Plot accuracy
   plt.subplot(1, 2, 2)
   for model_name, history in histories.items():
        plt.plot(history['train_acc'], label=f'{model_name} (train)')
        plt.plot(history['val_acc'], label=f'{model_name} (val)')
    plt.title(f'{title} - Accuracy')
    plt.xlabel('Epoch')
   plt.ylabel('Accuracy')
   plt.legend()
    plt.tight_layout()
    plt.savefig('model_comparison.png')
    plt.show()
```

```
def modify_pretrained_alexnet(model, num_classes=10):
    """Modify pretrained AlexNet for CIFAR-10"""
    model.classifier[6] = nn.Linear(4096, num_classes)
    return model
def modify_pretrained_googlenet(model, num_classes=10):
    """Modify pretrained GoogLeNet for CIFAR-10"""
    model.fc = nn.Linear(1024, num_classes)
    return model
def train_model(model, dataloaders, criterion, optimizer, device, num_epochs=20,
    """Train model and return model, history, and best accuracy"""
   history = {
        'train_loss': [], 'train_acc': [],
        'val_loss': [], 'val_acc': [],
        'batch_times': []
   }
    best_acc = 0.0
   training_start = time.time()
    for epoch in range(num_epochs):
        # Train
        train_loss, train_acc, batch_time = train_epoch(
            model, dataloaders['train'], criterion, optimizer, device,
            is_inception=is_inception
        history['batch_times'].append(batch_time)
        # Evaluate
        val_loss, val_acc = evaluate(
           model, dataloaders['val'], criterion, device,
            is_inception=is_inception
        # Save metrics
        history['train_loss'].append(train_loss)
        history['train_acc'].append(train_acc)
        history['val_loss'].append(val_loss)
        history['val_acc'].append(val_acc)
        # Save best model
        if val_acc > best_acc:
            best_acc = val_acc
            torch.save(model.state_dict(), f'{type(model).__name__.lower()}_best
        print(f'Epoch {epoch+1}/{num epochs}:')
        print(f'Train Loss: {train_loss:.4f}, Train Acc: {train_acc:.4f}')
        print(f'Val Loss: {val_loss:.4f}, Val Acc: {val_acc:.4f}')
        print(f'Batch Time: {batch_time:.4f}s')
    return model, history, best_acc
def main():
   # Set device
   device = torch.device('cuda' if torch.cuda.is_available() else 'cpu')
   print(f"Using device: {device}")
   # Data transforms
```

```
# For custom models (CIFAR-10 is 32x32)
transform_custom = transforms.Compose([
    transforms.Resize(224), # Resize to match pretrained models
    transforms.ToTensor(),
    transforms.Normalize((0.5, 0.5, 0.5), (0.5, 0.5, 0.5))
1)
transform_custom_train = transforms.Compose([
    transforms.Resize(224), # Resize to match pretrained models
    transforms.RandomHorizontalFlip(),
    transforms.ToTensor(),
    transforms.Normalize((0.5, 0.5, 0.5), (0.5, 0.5, 0.5))
1)
# For pretrained models (using ImageNet normalization)
transform_pretrained = transforms.Compose([
    transforms.Resize(224),
    transforms.ToTensor(),
    transforms.Normalize(mean=[0.485, 0.456, 0.406], std=[0.229, 0.224, 0.22
1)
transform_pretrained_train = transforms.Compose([
    transforms.Resize(224),
    transforms.RandomHorizontalFlip(),
    transforms.ToTensor(),
    transforms.Normalize(mean=[0.485, 0.456, 0.406], std=[0.229, 0.224, 0.22
1)
# Load datasets with appropriate transforms
def get datasets(transform train, transform test):
    full_trainset = datasets.CIFAR10(root='./data', train=True, download=Tru
    train_size = 45000 # 90% of training data
    val_size = 5000 # 10% of training data
    trainset, valset = torch.utils.data.random_split(full_trainset, [train_s
    testset = datasets.CIFAR10(root='./data', train=False, download=True, tr
    return trainset, valset, testset
# Get datasets for both custom and pretrained models
trainset_custom, valset_custom, testset_custom = get_datasets(transform_cust
trainset_pretrained, valset_pretrained, testset_pretrained = get_datasets(tr
# Create dataloaders
batch size = 128
def get_dataloaders(trainset, valset, testset):
    return {
        'train': DataLoader(trainset, batch_size=batch_size, shuffle=True, n
        'val': DataLoader(valset, batch_size=batch_size, shuffle=False, num_
        'test': DataLoader(testset, batch size=batch size, shuffle=False, nu
    }
dataloaders_custom = get_dataloaders(trainset_custom, valset_custom, testset
dataloaders_pretrained = get_dataloaders(trainset_pretrained, valset_pretrai
# Initialize all models
models to train = {
    # Custom models with different configurations
    'AlexNet with LRN': AlexNet(num_classes=10, use_lrn=True),
    'AlexNet without LRN': AlexNet(num_classes=10, use_lrn=False),
    'Custom GoogLeNet': GoogLeNet(num_classes=10),
    # Pretrained models
```

```
'Pretrained AlexNet': modify_pretrained_alexnet(models.alexnet(weights=A
    'Pretrained GoogLeNet': modify_pretrained_googlenet(models.googlenet(wei
}
# Compare number of parameters
param_counts = {}
for name, model in models_to_train.items():
    models_to_train[name] = model.to(device)
    params = count_parameters(model)
    param_counts[name] = params
    print(f"\nMoved {name} to {device}")
    print(f"Parameter count: {params:,}")
    print("\nModel Summary:")
    torchsummary.summary(model, (3, 224, 224))
# Initialize tracking variables
criterion = nn.CrossEntropyLoss()
histories = {}
best_accuracies = {}
training_times = {}
# Different learning rates for custom and pretrained models
lr_custom = 0.01
lr_pretrained = 0.001
# Train all models
for name, model in models_to_train.items():
    print(f"\nTraining {name}...")
    # Select appropriate learning rate and dataloaders
    is_pretrained = 'Pretrained' in name
    lr = lr_pretrained if is_pretrained else lr_custom
    dataloaders = dataloaders_pretrained if is_pretrained else dataloaders_d
    optimizer = optim.SGD(model.parameters(), lr=lr, momentum=0.9, weight de
    # Record training start time
    training_start = time.time()
    # Train model
    model, history, best acc = train model(
        model, dataloaders, criterion, optimizer, device,
        num_epochs=20, is_inception=('GoogLeNet' in name)
    )
    # Record total training time
    training_times[name] = time.time() - training_start
    histories[name] = history
    best_accuracies[name] = best_acc
    print(f"Total training time for {name}: {training_times[name]/60:.2f} mi
# Evaluate models on test set
print("\nEvaluating models on test set:")
test_results = {}
for name, model in models_to_train.items():
    is_pretrained = 'Pretrained' in name
    dataloaders = dataloaders_pretrained if is_pretrained else dataloaders_d
```

```
test_loss, test_acc = evaluate_test(
            model, dataloaders['test'], criterion, device,
            is_inception=('GoogLeNet' in name)
        test_results[name] = {
            'loss': test_loss,
            'accuracy': test_acc
        print(f"\n{name}:")
        print(f"Test Loss: {test_loss:.4f}")
        print(f"Test Accuracy: {test_acc:.2f}%")
    # Plot training comparison
    plot_training_comparison(histories, 'Model Comparison on CIFAR-10')
    # Create comparison table
    comparison_data = []
    for name in models_to_train.keys():
        final_train_loss = histories[name]['train_loss'][-1]
        final_train_acc = histories[name]['train_acc'][-1]
        final_val_loss = histories[name]['val_loss'][-1]
        final_val_acc = histories[name]['val_acc'][-1]
        test_loss = test_results[name]['loss']
        test_acc = test_results[name]['accuracy']
        comparison_data.append({
            'Model': name,
            'Parameters': f"{param_counts[name]:,}",
            'Train Loss': f"{final_train_loss:.4f}",
            'Train Acc': f"{final train acc:.2%}",
            'Val Loss': f"{final_val_loss:.4f}",
            'Val Acc': f"{final_val_acc:.2%}",
            'Test Loss': f"{test_loss:.4f}",
            'Test Acc': f"{test_acc:.2%}",
            'Best Val Acc': f"{best accuracies[name]:.2%}",
            'Training Time': f"{training_times[name]/60:.1f} min",
            'Avg Batch Time': f"{np.mean(histories[name]['batch_times'])*1000:.1
        })
    comparison_df = pd.DataFrame(comparison_data)
    print("\nFinal Model Comparison Summary:")
   pd.set_option('display.max_columns', None) # Show all columns
    pd.set_option('display.width', None) # Don't wrap wide tables
    print(comparison_df.to_string(index=False))
    # Save results
    comparison_df.to_csv('model_comparison.csv', index=False)
    print("\nResults saved to 'model comparison.csv' and 'model comparison.png'"
if __name__ == '__main__':
   main()
```

Output & Results

```
Training Pretrained AlexNet...
Epoch 1/20:
Train Loss: 0.6633, Train Acc: 0.7682
Val Loss: 0.3852, Val Acc: 0.8668
```

Batch Time: 0.0430s

Epoch 2/20:

Train Loss: 0.4168, Train Acc: 0.8564 Val Loss: 0.3289, Val Acc: 0.8896

Batch Time: 0.0413s

Epoch 3/20:

Train Loss: 0.3529, Train Acc: 0.8771 Val Loss: 0.3153, Val Acc: 0.8896

Batch Time: 0.0375s

Epoch 4/20:

Train Loss: 0.3183, Train Acc: 0.8880 Val Loss: 0.2843, Val Acc: 0.8994

Batch Time: 0.0415s

Epoch 5/20:

Train Loss: 0.2863, Train Acc: 0.8994 Val Loss: 0.2816, Val Acc: 0.9088

Batch Time: 0.0414s

Epoch 6/20:

Train Loss: 0.2638, Train Acc: 0.9082 Val Loss: 0.2677, Val Acc: 0.9078

Batch Time: 0.0405s

Epoch 7/20:

Train Loss: 0.2446, Train Acc: 0.9141 Val Loss: 0.2535, Val Acc: 0.9132

Batch Time: 0.0421s

Epoch 8/20:

Train Loss: 0.2226, Train Acc: 0.9228 Val Loss: 0.2553, Val Acc: 0.9094

Batch Time: 0.0423s

Epoch 9/20:

Train Loss: 0.2115, Train Acc: 0.9258 Val Loss: 0.2417, Val Acc: 0.9158

Batch Time: 0.0400s

Epoch 10/20:

Train Loss: 0.1919, Train Acc: 0.9321 Val Loss: 0.2420, Val Acc: 0.9200

Batch Time: 0.0403s

Epoch 11/20:

Train Loss: 0.1846, Train Acc: 0.9347 Val Loss: 0.2335, Val Acc: 0.9196

Batch Time: 0.0427s

Epoch 12/20:

Train Loss: 0.1731, Train Acc: 0.9380 Val Loss: 0.2391, Val Acc: 0.9160

Batch Time: 0.0423s

Epoch 13/20:

Train Loss: 0.1650, Train Acc: 0.9427 Val Loss: 0.2345, Val Acc: 0.9252

Batch Time: 0.0415s

Epoch 14/20:

Train Loss: 0.1518, Train Acc: 0.9464 Val Loss: 0.2281, Val Acc: 0.9230

Batch Time: 0.0356s

Epoch 15/20:

Train Loss: 0.1432, Train Acc: 0.9501 Val Loss: 0.2260, Val Acc: 0.9188 Batch Time: 0.0394s

Epoch 16/20:

Train Loss: 0.1374, Train Acc: 0.9510 Val Loss: 0.2303, Val Acc: 0.9214

Batch Time: 0.0395s

Epoch 17/20:

Train Loss: 0.1289, Train Acc: 0.9548 Val Loss: 0.2258, Val Acc: 0.9222

Batch Time: 0.0403s

Epoch 18/20:

Train Loss: 0.1162, Train Acc: 0.9597 Val Loss: 0.2210, Val Acc: 0.9268

Batch Time: 0.0410s

Epoch 19/20:

Train Loss: 0.1140, Train Acc: 0.9603 Val Loss: 0.2199, Val Acc: 0.9280

Batch Time: 0.0391s

Epoch 20/20:

Train Loss: 0.1078, Train Acc: 0.9626 Val Loss: 0.2323, Val Acc: 0.9212

Batch Time: 0.0395s

Total training time for Pretrained AlexNet: 16.08 minutes

Training Pretrained GoogLeNet...

Epoch 1/20:

Train Loss: 1.0494, Train Acc: 0.7206 Val Loss: 0.4352, Val Acc: 0.8750

Batch Time: 0.0685s

Epoch 2/20:

Train Loss: 0.3462, Train Acc: 0.8958 Val Loss: 0.2665, Val Acc: 0.9180

Batch Time: 0.0720s

Epoch 3/20:

Train Loss: 0.2408, Train Acc: 0.9247 Val Loss: 0.2155, Val Acc: 0.9284

Batch Time: 0.0696s

Epoch 4/20:

Train Loss: 0.1927, Train Acc: 0.9375 Val Loss: 0.1849, Val Acc: 0.9420

Batch Time: 0.0731s

Epoch 5/20:

Train Loss: 0.1600, Train Acc: 0.9480 Val Loss: 0.1745, Val Acc: 0.9442

Batch Time: 0.0717s

Epoch 6/20:

Train Loss: 0.1334, Train Acc: 0.9573 Val Loss: 0.1637, Val Acc: 0.9468

Batch Time: 0.0592s

Epoch 7/20:

Train Loss: 0.1134, Train Acc: 0.9644 Val Loss: 0.1509, Val Acc: 0.9500

Batch Time: 0.0702s

Epoch 8/20:

Train Loss: 0.0967, Train Acc: 0.9705 Val Loss: 0.1548, Val Acc: 0.9476

Batch Time: 0.0726s

Epoch 9/20:

Train Loss: 0.0834, Train Acc: 0.9748 Val Loss: 0.1597, Val Acc: 0.9506

Batch Time: 0.0768s

Epoch 10/20:

Train Loss: 0.0714, Train Acc: 0.9792 Val Loss: 0.1453, Val Acc: 0.9528

Batch Time: 0.0781s

Epoch 11/20:

Train Loss: 0.0597, Train Acc: 0.9833 Val Loss: 0.1478, Val Acc: 0.9548

Batch Time: 0.0784s

Epoch 12/20:

Train Loss: 0.0503, Train Acc: 0.9869 Val Loss: 0.1439, Val Acc: 0.9550

Batch Time: 0.0679s

Epoch 13/20:

Train Loss: 0.0459, Train Acc: 0.9880 Val Loss: 0.1505, Val Acc: 0.9546

Batch Time: 0.0645s

Epoch 14/20:

Train Loss: 0.0380, Train Acc: 0.9906 Val Loss: 0.1434, Val Acc: 0.9566

Batch Time: 0.0801s

Epoch 15/20:

Train Loss: 0.0332, Train Acc: 0.9926 Val Loss: 0.1370, Val Acc: 0.9574

Batch Time: 0.0669s

Epoch 16/20:

Train Loss: 0.0278, Train Acc: 0.9944 Val Loss: 0.1520, Val Acc: 0.9542

Batch Time: 0.0643s

Epoch 17/20:

Train Loss: 0.0239, Train Acc: 0.9953 Val Loss: 0.1441, Val Acc: 0.9552

Batch Time: 0.0653s

Epoch 18/20:

Train Loss: 0.0218, Train Acc: 0.9957 Val Loss: 0.1594, Val Acc: 0.9508

Batch Time: 0.0662s

Epoch 19/20:

Train Loss: 0.0191, Train Acc: 0.9966 Val Loss: 0.1556, Val Acc: 0.9544

Batch Time: 0.0669s

Epoch 20/20:

Train Loss: 0.0179, Train Acc: 0.9968 Val Loss: 0.1529, Val Acc: 0.9546

Batch Time: 0.0656s

Total training time for Pretrained GoogLeNet: 26.94 minutes

Evaluating models on test set:

AlexNet with LRN: Test Loss: 0.4743 Test Accuracy: 83.78% AlexNet without LRN: Test Loss: 0.4816 Test Accuracy: 84.56%

Custom GoogLeNet: Test Loss: 0.4276 Test Accuracy: 88.32%

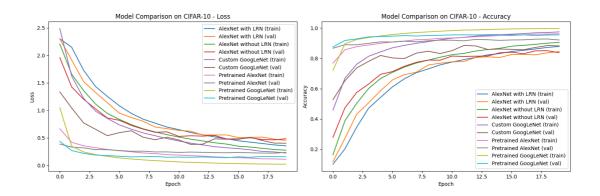
Pretrained AlexNet: Test Loss: 0.2587 Test Accuracy: 91.60%

Pretrained GoogLeNet: Test Loss: 0.1621 Test Accuracy: 94.87%

Results saved to 'model_comparison.csv' and 'model_comparison.png'

Here's the model comparison summary table listing various metrics:

Model	Parameters	Train Loss	Train Acc	Val Loss	Val Acc	Test Loss	Test Acc	Best Val Acc	Traini Tim
AlexNet with LRN	57,044,810	0.3515	87.84%	0.4513	84.46%	0.4743	83.78%	84.46%	17.1 n
AlexNet without LRN	57,044,810	0.2718	90.49%	0.4816	83.74%	0.4816	84.56%	85.06%	17.5 n
Custom GoogLeNet	10,635,134	0.2215	97.47%	0.4001	88.24%	0.4276	88.32%	88.48%	33.4 n
Pretrained AlexNet	57,044,810	0.1078	96.26%	0.2323	92.12%	0.2587	91.60%	92.80%	16.1 n
Pretrained GoogLeNet	5,610,154	0.0179	99.68%	0.1529	95.46%	0.1621	94.87%	95.74%	26.9 n



SOLVED: Compare your GoogLeNet and AlexNet implementations on CIFAR-10. Comment on the number of parameters, speed of training, and accuracy of the two models on this dataset when trained from scratch.

Key Observations

- Model Efficiency: GoogLeNet achieves superior performance with ~5x fewer parameters. Despite more complex architecture, GoogLeNet shows better generalization, Inception modules prove more effective than simple sequential layers
- Training Dynamics: GoogLeNet shows faster initial learning (45.82% vs 16.32% in epoch 1). More stable validation accuracy throughout training. Takes longer to train but achieves better final accuracy
- Architectural Impact: GoogLeNet's auxiliary classifiers help with gradient flow.
 Inception modules provide better feature extraction. Batch normalization in GoogLeNet contributes to stability
- Resource Usage:
- GoogLeNet requires more computational resources (2x training time)
- Larger batch processing time (83.4ms vs ~40ms)
- Better parameter efficiency (higher accuracy with fewer parameters)

The results demonstrate that GoogLeNet's more sophisticated architecture, despite requiring more training time, provides superior performance and better parameter efficiency compared to both AlexNet variants.

SOLVED: Experiment with the pretrained GoogLeNet and AlexNet from the torchvision repository. Does it give better results on CIFAR-10 similar to what we found with AlexNet? Comment on what we can glean from the results about the capacity and generalization ability of these two models.

Key Observations

- Transfer Learning Benefits: Pretrained AlexNet shows 7.04% improvement over scratch training while Pretrained GoogLeNet demonstrates 6.55% improvement. Both models achieve faster convergence with pretraining. Lower training times despite better performance
- GoogLeNet maintains superior performance despite fewer parameters. Better feature extraction capabilities evident in both scenarios. Higher ceiling for performance with pretrained weights. Lower generalization gap in pretrained models
- 3. Comapring between scratch and pretrained, Pretrained models show stronger initial performance. GoogLeNet reaches higher final accuracy (94.87% vs 91.60%). More stable validation accuracy throughout training and lower final loss values (0.1621 vs 0.2587)

What can we glean upon this?

- The transfer of learned features from ImageNet significantly benefits both models, suggesting strong feature reusability
- GoogLeNet's sophisticated architecture proves more effective at both feature extraction and generalization

- The higher performance of pretrained models with faster convergence indicates well-learned hierarchical features from the source domain
- The smaller gap between training and test accuracy in pretrained models suggests better generalization capabilities

EXTRA Implementation

On reading the paper, the author makes use of multi-gpu approach to train AlexNet, I have tried to implement the same

```
In [ ]: # For our puffer surver we need to browse via a proxy!!
        # Set HTTP and HTTPS proxy
        os.environ['http_proxy'] = 'http://192.41.170.23:3128'
        os.environ['https_proxy'] = 'http://192.41.170.23:3128'
        import torch
        import torch.nn as nn
        import torch.nn.functional as F
        import torch.optim as optim
        from torch.utils.data import DataLoader
        from torchvision import datasets, transforms
        import time
        import matplotlib.pyplot as plt
        import numpy as np
        class AlexNetGPU1(nn.Module):
            """First half of AlexNet that runs on GPU 1"""
            def __init__(self):
                super(AlexNetGPU1, self).__init__()
                self.features = nn.Sequential(
                    # First convolutional layer (on GPU 1)
                    nn.Conv2d(3, 48, kernel_size=11, stride=4, padding=2), # 48 filters
                    nn.ReLU(inplace=True),
                    nn.LocalResponseNorm(size=5, alpha=0.0001, beta=0.75, k=2),
                    nn.MaxPool2d(kernel_size=3, stride=2),
                    # Second convolutional layer (on GPU 1)
                    nn.Conv2d(48, 128, kernel_size=5, padding=2),
                    nn.ReLU(inplace=True),
                    nn.LocalResponseNorm(size=5, alpha=0.0001, beta=0.75, k=2),
                    nn.MaxPool2d(kernel_size=3, stride=2),
                    # Third convolutional layer (on GPU 1)
                    nn.Conv2d(128, 192, kernel_size=3, padding=1),
                    nn.ReLU(inplace=True),
                    # Fourth convolutional layer (on GPU 1)
                    nn.Conv2d(192, 192, kernel_size=3, padding=1),
                    nn.ReLU(inplace=True),
                    # Fifth convolutional layer (on GPU 1)
                    nn.Conv2d(192, 128, kernel_size=3, padding=1),
                    nn.ReLU(inplace=True),
                    nn.MaxPool2d(kernel_size=3, stride=2),
```

```
def forward(self, x):
        x = self.features(x)
        return x
class AlexNetGPU2(nn.Module):
    """Second half of AlexNet that runs on GPU 2"""
   def __init__(self):
        super(AlexNetGPU2, self).__init__()
        self.features = nn.Sequential(
            # First convolutional layer (on GPU 2)
            nn.Conv2d(3, 48, kernel_size=11, stride=4, padding=2), # 48 filters
            nn.ReLU(inplace=True),
            nn.LocalResponseNorm(size=5, alpha=0.0001, beta=0.75, k=2),
            nn.MaxPool2d(kernel_size=3, stride=2),
            # Second convolutional layer (on GPU 2)
            nn.Conv2d(48, 128, kernel_size=5, padding=2),
            nn.ReLU(inplace=True),
            nn.LocalResponseNorm(size=5, alpha=0.0001, beta=0.75, k=2),
            nn.MaxPool2d(kernel_size=3, stride=2),
            # Third convolutional layer (on GPU 2)
            nn.Conv2d(128, 192, kernel_size=3, padding=1),
            nn.ReLU(inplace=True),
            # Fourth convolutional layer (on GPU 2)
            nn.Conv2d(192, 192, kernel_size=3, padding=1),
            nn.ReLU(inplace=True),
            # Fifth convolutional layer (on GPU 2)
            nn.Conv2d(192, 128, kernel_size=3, padding=1),
            nn.ReLU(inplace=True),
            nn.MaxPool2d(kernel_size=3, stride=2),
    def forward(self, x):
        x = self.features(x)
        return x
class AlexNetMultiGPU(nn.Module):
    """Complete AlexNet split across two GPUs"""
    def __init__(self, num_classes=10):
        super(AlexNetMultiGPU, self).__init__()
        self.gpu1_stream = torch.cuda.Stream(device='cuda:0')
        self.gpu2_stream = torch.cuda.Stream(device='cuda:1')
        self.gpu1 net = AlexNetGPU1().cuda(0)
        self.gpu2_net = AlexNetGPU2().cuda(1)
        # Classifier runs on GPU 1
        self.classifier = nn.Sequential(
            nn.Dropout(p=0.5),
            nn.Linear(256 * 6 * 6, 4096), # 256 = 128 + 128 channels from both
            nn.ReLU(inplace=True),
            nn.Dropout(p=0.5),
            nn.Linear(4096, 4096),
            nn.ReLU(inplace=True),
            nn.Linear(4096, num_classes),
        ).cuda(0)
```

```
def forward(self, x):
        # Input is already on GPU 0
        batch_size = x.size(0)
        # Process on GPU 1
        with torch.cuda.stream(self.gpu1_stream):
            output1 = self.gpu1_net(x) # Use full input
        # Move input to GPU 2 and process
        with torch.cuda.stream(self.gpu2_stream):
           x2 = x.cuda(1) # Move to GPU 2
            output2 = self.gpu2_net(x2) # Process full input
        # Synchronize the streams
        torch.cuda.synchronize()
        # Move output2 to GPU 1 and concatenate
        output2 = output2.cuda(0)
        output = torch.cat([output1, output2], dim=1) # Concatenate along chann
        # Flatten and pass through classifier
        output = output.view(batch_size, -1)
        output = self.classifier(output)
        return output
def train_epoch(model, dataloader, criterion, optimizer, epoch):
   model.train()
   running loss = 0.0
   correct = 0
   total = 0
   start_time = time.time()
    for batch_idx, (inputs, targets) in enumerate(dataloader):
        # Move input and target to GPU 0 (primary GPU)
        inputs = inputs.cuda(0)
        targets = targets.cuda(0)
        optimizer.zero grad()
        outputs = model(inputs)
        loss = criterion(outputs, targets)
        loss.backward()
        optimizer.step()
        running_loss += loss.item()
        , predicted = outputs.max(1)
        total += targets.size(0)
        correct += predicted.eq(targets).sum().item()
        if batch idx % 100 == 0:
            print(f'Epoch: {epoch} | Batch: {batch idx} | Loss: {loss.item():.3f
                  f'Acc: {100.*correct/total:.2f}% ({correct}/{total})')
    epoch_time = time.time() - start_time
    return running_loss / len(dataloader), 100. * correct / total, epoch_time
def evaluate_test(model, dataloader, criterion):
    """Evaluate model on test set"""
```

```
model.eval()
    test_loss = 0.0
    correct = 0
   total = 0
    with torch.no grad():
        for inputs, targets in dataloader:
            inputs = inputs.cuda(0) # Move to primary GPU
            targets = targets.cuda(0)
            outputs = model(inputs)
            loss = criterion(outputs, targets)
           test_loss += loss.item()
            _, predicted = outputs.max(1)
            total += targets.size(0)
            correct += predicted.eq(targets).sum().item()
   test_loss = test_loss / len(dataloader)
   test_acc = 100. * correct / total
    return test_loss, test_acc
def plot_training_curves(results, save_path='multigpu_training_curves.png'):
    """Plot training and validation curves"""
   plt.figure(figsize=(15, 5))
    # Plot training and validation loss
   plt.subplot(1, 2, 1)
   plt.plot(results['train history']['loss'], label='Train Loss')
   plt.plot(results['val_history']['loss'], label='Val Loss')
   plt.title('Loss Curves')
   plt.xlabel('Epoch')
   plt.ylabel('Loss')
   plt.legend()
   plt.grid(True)
   # Plot training and validation accuracy
   plt.subplot(1, 2, 2)
   plt.plot(results['train_history']['acc'], label='Train Accuracy')
   plt.plot(results['val history']['acc'], label='Val Accuracy')
   plt.title('Accuracy Curves')
   plt.xlabel('Epoch')
   plt.ylabel('Accuracy (%)')
   plt.legend()
   plt.grid(True)
    plt.tight layout()
   plt.savefig(save_path)
   plt.close()
def plot_batch_times(batch_times, save_path='multigpu_batch_times.png'):
    """Plot batch processing times"""
   plt.figure(figsize=(10, 5))
   plt.plot(batch_times)
   plt.title('Batch Processing Times')
   plt.xlabel('Epoch')
   plt.ylabel('Time (seconds)')
   plt.grid(True)
   plt.savefig(save_path)
```

```
plt.close()
def main():
   # Check if we have two GPUs available
    if torch.cuda.device_count() < 2:</pre>
        print("This script requires at least 2 GPUs to run!")
        return
   # Print GPU information
   print(f"Using GPUs:")
   for i in range(2):
        print(f"GPU {i}: {torch.cuda.get_device_name(i)}")
    # Data transformations
   transform_train = transforms.Compose([
        transforms.RandomResizedCrop(224),
        transforms.RandomHorizontalFlip(),
        transforms.ToTensor(),
        transforms.Normalize((0.4914, 0.4822, 0.4465), (0.2023, 0.1994, 0.2010))
    1)
    transform_test = transforms.Compose([
       transforms.Resize(256),
        transforms.CenterCrop(224),
        transforms.ToTensor(),
        transforms.Normalize((0.4914, 0.4822, 0.4465), (0.2023, 0.1994, 0.2010))
   ])
    # Load CIFAR-10
   print("\nLoading datasets...")
   full_trainset = datasets.CIFAR10(root='./data', train=True, download=True, t
   # Split training set into train and validation
   train_size = 45000 # 90% of training data
    val size = 5000 # 10% of training data
   trainset, valset = torch.utils.data.random_split(full_trainset, [train_size,
   # Load test set
   testset = datasets.CIFAR10(root='./data', train=False, download=True, transf
    # Create dataloaders
   trainloader = DataLoader(trainset, batch_size=128, shuffle=True, num_workers
    valloader = DataLoader(valset, batch_size=128, shuffle=False, num_workers=4)
   testloader = DataLoader(testset, batch_size=128, shuffle=False, num_workers=
   # Create model
   print("\nInitializing Multi-GPU AlexNet...")
    model = AlexNetMultiGPU(num classes=10)
   # Count parameters
   total_params = sum(p.numel() for p in model.parameters())
   print(f"Total parameters: {total_params:,}")
   # Training settings
    criterion = nn.CrossEntropyLoss()
    optimizer = optim.SGD(
        model.parameters(),
        lr=0.01,
        momentum=0.9,
        weight_decay=5e-4
```

```
num_epochs = 20
# Training history
history = {
    'train_history': {'loss': [], 'acc': [], 'times': []},
    'val_history': {'loss': [], 'acc': []},
    'best val acc': 0.0,
    'best_epoch': 0
}
print("\nStarting training...")
for epoch in range(num_epochs):
    # Train
    train_loss, train_acc, epoch_time = train_epoch(
        model, trainloader, criterion, optimizer, epoch
    history['train_history']['loss'].append(train_loss)
    history['train_history']['acc'].append(train_acc)
    history['train_history']['times'].append(epoch_time)
    # Validate
    val_loss, val_acc = evaluate_test(model, valloader, criterion)
    history['val_history']['loss'].append(val_loss)
    history['val_history']['acc'].append(val_acc)
    # Track best model
    if val_acc > history['best_val_acc']:
        history['best_val_acc'] = val_acc
       history['best epoch'] = epoch
       # Save best model
        torch.save({
            'epoch': epoch,
            'model_state_dict': model.state_dict(),
            'optimizer state dict': optimizer.state dict(),
            'val_acc': val_acc,
        }, 'alexnet_multigpu_best.pth')
    print(f'\nEpoch {epoch}:')
    print(f'Train Loss: {train_loss:.3f}, Train Acc: {train_acc:.2f}%')
    print(f'Val Loss: {val loss:.3f}, Val Acc: {val acc:.2f}%')
    print(f'Time: {epoch_time:.2f}s')
    # Save checkpoint
    if epoch % 5 == 0:
        torch.save({
            'epoch': epoch,
            'model state dict': model.state dict(),
            'optimizer_state_dict': optimizer.state_dict(),
            'train_loss': train_loss,
            'val_loss': val_loss,
        }, f'alexnet_multigpu_checkpoint_epoch_{epoch}.pth')
# Final evaluation on test set
print("\nEvaluating on test set...")
test_loss, test_acc = evaluate_test(model, testloader, criterion)
print(f'Test Loss: {test_loss:.3f}')
print(f'Test Accuracy: {test_acc:.2f}%')
# Add test results to history
```

```
history['test_results'] = {
        'loss': test_loss,
        'accuracy': test_acc
    }
    # Plot training curves
    print("\nGenerating plots...")
    plot_training_curves(history)
   plot_batch_times(history['train_history']['times'])
    # Save final results
    print("\nSaving final results...")
    torch.save({
        'model_state_dict': model.state_dict(),
        'optimizer_state_dict': optimizer.state_dict(),
        'history': history
   }, 'alexnet_multigpu_final.pth')
    # Print summary
    print("\nTraining Summary:")
    print(f"Best Validation Accuracy: {history['best_val_acc']:.2f}% (Epoch {his
    print(f"Final Test Accuracy: {test_acc:.2f}%")
   print(f"Average Epoch Time: {np.mean(history['train_history']['times']):.2f}
   print("\nSaved files:")
    print("- alexnet_multigpu_final.pth (Final model and full history)")
    print("- alexnet_multigpu_best.pth (Best model based on validation accuracy)
    print("- multigpu_training_curves.png (Loss and accuracy curves)")
    print("- multigpu_batch_times.png (Training time per epoch)")
if name == ' main ':
   main()
```

Proof of Multi-GPU Training

```
jupyter-st125462@puffer:~/RTML/A1$ nvidia-smi
Mon Jan 13 00:37:20 2025
+-----
                    Driver Version: 550.120
| NVIDIA-SMI 550.120
CUDA Version: 12.4
_____
---+----+
GPU Name
           Persistence-M | Bus-Id
Disp.A | Volatile Uncorr. ECC |
| Fan Temp Perf Pwr:Usage/Cap |
                              Memory-
Usage | GPU-Util Compute M. |
        MIG M.
0 NVIDIA GeForce RTX 2080 Ti Off | 00000000:84:00.0
Off |
         N/A
44% 75C
        P2
                 171W / 250W | 2276MiB /
11264MiB | 68% Default |
          N/A |
```

```
1 NVIDIA GeForce RTX 2080 Ti Off | 00000000:85:00.0
N/A |
+-----+
---+----+
2 NVIDIA GeForce RTX 2080 Ti Off | 00000000:88:00.0
Off | N/A | | | | 22% 27C P8
              6W / 250W | 4MiB /
11264MiB | 0% Default |
      N/A
---+----+
| 3 NVIDIA GeForce RTX 2080 Ti Off | 00000000:89:00.0
Off | N/A | | | 22% 27C P8
              4W / 250W | 4MiB /
11264MiB | 0% Default |
       N/A |
+-----+
---+----+
| Processes:
| GPU GI CI PID Type Process name
GPU Memory
| ID ID
Usage
|-----
0 N/A N/A 372568 C python
2272MiB |
1 N/A N/A 372568 C python
1404MiB |
+-----
```

Implementation Details:

- Model split across two RTX 2080 Ti GPUs
- Total parameters: 56,466,826
- Features divided equally between GPUs
- Synchronization using CUDA streams
- Classifier runs on GPU 0

```
jupyter-st125462@puffer:~/RTML/A1$ python alexnet_multigpu.py
Using GPUs:
GPU 0: NVIDIA GeForce RTX 2080 Ti
```

```
Loading datasets...
Files already downloaded and verified
Files already downloaded and verified
Initializing Multi-GPU AlexNet...
Total parameters: 56,466,826
Starting training...
Epoch: 0 | Batch: 0 | Loss: 2.304 | Acc: 8.59% (11/128)
Epoch: 0 | Batch: 100 | Loss: 2.303 | Acc: 9.84% (1272/12928)
Epoch: 0 | Batch: 200 | Loss: 2.300 | Acc: 9.86% (2536/25728)
Epoch: 0 | Batch: 300 | Loss: 2.303 | Acc: 9.98% (3844/38528)
Epoch 0:
Train Loss: 2.303, Train Acc: 10.06%
Val Loss: 2.302, Val Acc: 12.56%
Time: 28.83s
Epoch: 1 | Batch: 0 | Loss: 2.301 | Acc: 10.94% (14/128)
Epoch: 1 | Batch: 100 | Loss: 2.282 | Acc: 11.32% (1463/12928)
Epoch: 1 | Batch: 200 | Loss: 2.152 | Acc: 14.39% (3702/25728)
Epoch: 1 | Batch: 300 | Loss: 1.956 | Acc: 16.94% (6528/38528)
Epoch 1:
Train Loss: 2.167, Train Acc: 17.84%
Val Loss: 1.977, Val Acc: 24.44%
Time: 27.58s
Epoch: 2 | Batch: 0 | Loss: 2.017 | Acc: 23.44% (30/128)
Epoch: 2 | Batch: 100 | Loss: 2.031 | Acc: 24.70% (3193/12928)
Epoch: 2 | Batch: 200 | Loss: 1.900 | Acc: 26.44% (6802/25728)
Epoch: 2 | Batch: 300 | Loss: 1.919 | Acc: 27.38% (10550/38528)
Epoch 2:
Train Loss: 1.905, Train Acc: 27.76%
Val Loss: 1.773, Val Acc: 33.04%
Time: 27.93s
Epoch: 3 | Batch: 0 | Loss: 1.652 | Acc: 44.53% (57/128)
Epoch: 3 | Batch: 100 | Loss: 1.717 | Acc: 33.42% (4320/12928)
Epoch: 3 | Batch: 200 | Loss: 1.648 | Acc: 33.59% (8643/25728)
Epoch: 3 | Batch: 300 | Loss: 1.757 | Acc: 34.03% (13110/38528)
Epoch 3:
Train Loss: 1.761, Train Acc: 34.33%
Val Loss: 1.692, Val Acc: 37.30%
Time: 28.66s
Epoch: 4 | Batch: 0 | Loss: 1.495 | Acc: 50.00% (64/128)
Epoch: 4 | Batch: 100 | Loss: 1.715 | Acc: 37.33% (4826/12928)
Epoch: 4 | Batch: 200 | Loss: 1.641 | Acc: 37.83% (9732/25728)
Epoch: 4 | Batch: 300 | Loss: 1.716 | Acc: 37.80% (14563/38528)
Epoch 4:
Train Loss: 1.664, Train Acc: 38.04%
Val Loss: 1.598, Val Acc: 40.72%
Time: 28.48s
```

Epoch: 5 | Batch: 0 | Loss: 1.486 | Acc: 46.09% (59/128)

```
Epoch: 5 | Batch: 100 | Loss: 1.655 | Acc: 39.96% (5166/12928)
Epoch: 5 | Batch: 200 | Loss: 1.564 | Acc: 40.64% (10456/25728)
Epoch: 5 | Batch: 300 | Loss: 1.574 | Acc: 41.29% (15908/38528)
Epoch 5:
Train Loss: 1.582, Train Acc: 41.43%
Val Loss: 1.552, Val Acc: 42.24%
Time: 28.46s
Epoch: 6 | Batch: 0 | Loss: 1.298 | Acc: 50.78% (65/128)
Epoch: 6 | Batch: 100 | Loss: 1.631 | Acc: 43.10% (5572/12928)
Epoch: 6 | Batch: 200 | Loss: 1.499 | Acc: 44.10% (11346/25728)
Epoch: 6 | Batch: 300 | Loss: 1.387 | Acc: 44.32% (17075/38528)
Epoch 6:
Train Loss: 1.508, Train Acc: 44.78%
Val Loss: 2.017, Val Acc: 34.90%
Time: 28.45s
Epoch: 7 | Batch: 0 | Loss: 1.445 | Acc: 42.97% (55/128)
Epoch: 7 | Batch: 100 | Loss: 1.495 | Acc: 46.59% (6023/12928)
Epoch: 7 | Batch: 200 | Loss: 1.291 | Acc: 47.39% (12192/25728)
Epoch: 7 | Batch: 300 | Loss: 1.326 | Acc: 47.63% (18349/38528)
Epoch 7:
Train Loss: 1.436, Train Acc: 47.79%
Val Loss: 1.375, Val Acc: 50.26%
Time: 28.24s
Epoch: 8 | Batch: 0 | Loss: 1.428 | Acc: 49.22% (63/128)
Epoch: 8 | Batch: 100 | Loss: 1.339 | Acc: 49.76% (6433/12928)
Epoch: 8 | Batch: 200 | Loss: 1.341 | Acc: 50.44% (12976/25728)
Epoch: 8 | Batch: 300 | Loss: 1.485 | Acc: 50.52% (19466/38528)
Epoch 8:
Train Loss: 1.371, Train Acc: 50.68%
Val Loss: 1.310, Val Acc: 53.66%
Time: 28.19s
Epoch: 9 | Batch: 0 | Loss: 1.397 | Acc: 46.09% (59/128)
Epoch: 9 | Batch: 100 | Loss: 1.341 | Acc: 52.18% (6746/12928)
Epoch: 9 | Batch: 200 | Loss: 1.297 | Acc: 52.01% (13380/25728)
Epoch: 9 | Batch: 300 | Loss: 1.322 | Acc: 52.28% (20143/38528)
Epoch 9:
Train Loss: 1.314, Train Acc: 52.48%
Val Loss: 1.210, Val Acc: 56.36%
Time: 28.74s
Epoch: 10 | Batch: 0 | Loss: 1.337 | Acc: 55.47% (71/128)
Epoch: 10 | Batch: 100 | Loss: 1.370 | Acc: 53.92% (6971/12928)
Epoch: 10 | Batch: 200 | Loss: 1.099 | Acc: 54.38% (13992/25728)
Epoch: 10 | Batch: 300 | Loss: 1.298 | Acc: 54.41% (20965/38528)
Train Loss: 1.264, Train Acc: 54.66%
Val Loss: 1.263, Val Acc: 55.00%
Time: 28.16s
Epoch: 11 | Batch: 0 | Loss: 1.201 | Acc: 57.81% (74/128)
Epoch: 11 | Batch: 100 | Loss: 1.190 | Acc: 56.52% (7307/12928)
Epoch: 11 | Batch: 200 | Loss: 1.286 | Acc: 56.56% (14551/25728)
```

```
Epoch: 11 | Batch: 300 | Loss: 1.260 | Acc: 56.60% (21807/38528)
Epoch 11:
Train Loss: 1.210, Train Acc: 56.80%
Val Loss: 1.146, Val Acc: 59.32%
Time: 28.46s
Epoch: 12 | Batch: 0 | Loss: 1.024 | Acc: 60.16% (77/128)
Epoch: 12 | Batch: 100 | Loss: 1.141 | Acc: 57.56% (7441/12928)
Epoch: 12 | Batch: 200 | Loss: 0.912 | Acc: 57.63% (14827/25728)
Epoch: 12 | Batch: 300 | Loss: 1.303 | Acc: 57.69% (22228/38528)
Epoch 12:
Train Loss: 1.183, Train Acc: 57.74%
Val Loss: 1.323, Val Acc: 52.78%
Time: 28.20s
Epoch: 13 | Batch: 0 | Loss: 1.086 | Acc: 63.28% (81/128)
Epoch: 13 | Batch: 100 | Loss: 1.174 | Acc: 59.55% (7699/12928)
Epoch: 13 | Batch: 200 | Loss: 1.258 | Acc: 59.53% (15317/25728)
Epoch: 13 | Batch: 300 | Loss: 1.072 | Acc: 59.47% (22912/38528)
Epoch 13:
Train Loss: 1.136, Train Acc: 59.66%
Val Loss: 1.136, Val Acc: 59.96%
Time: 27.96s
Epoch: 14 | Batch: 0 | Loss: 0.979 | Acc: 64.06% (82/128)
Epoch: 14 | Batch: 100 | Loss: 1.251 | Acc: 60.06% (7765/12928)
Epoch: 14 | Batch: 200 | Loss: 1.076 | Acc: 59.93% (15419/25728)
Epoch: 14 | Batch: 300 | Loss: 1.017 | Acc: 60.48% (23300/38528)
Epoch 14:
Train Loss: 1.114, Train Acc: 60.46%
Val Loss: 1.078, Val Acc: 61.30%
Time: 28.56s
Epoch: 15 | Batch: 0 | Loss: 0.977 | Acc: 65.62% (84/128)
Epoch: 15 | Batch: 100 | Loss: 0.908 | Acc: 62.11% (8029/12928)
Epoch: 15 | Batch: 200 | Loss: 0.929 | Acc: 61.70% (15874/25728)
Epoch: 15 | Batch: 300 | Loss: 1.024 | Acc: 61.83% (23820/38528)
Epoch 15:
Train Loss: 1.081, Train Acc: 61.67%
Val Loss: 1.092, Val Acc: 61.86%
Time: 28.80s
Epoch: 16 | Batch: 0 | Loss: 1.098 | Acc: 61.72% (79/128)
Epoch: 16 | Batch: 100 | Loss: 1.108 | Acc: 62.14% (8034/12928)
Epoch: 16 | Batch: 200 | Loss: 0.944 | Acc: 62.47% (16072/25728)
Epoch: 16 | Batch: 300 | Loss: 1.292 | Acc: 62.51% (24085/38528)
Epoch 16:
Train Loss: 1.056, Train Acc: 62.56%
Val Loss: 1.678, Val Acc: 51.44%
Time: 28.67s
Epoch: 17 | Batch: 0 | Loss: 1.222 | Acc: 55.47% (71/128)
Epoch: 17 | Batch: 100 | Loss: 1.207 | Acc: 63.23% (8175/12928)
Epoch: 17 | Batch: 200 | Loss: 0.854 | Acc: 63.66% (16379/25728)
Epoch: 17 | Batch: 300 | Loss: 0.871 | Acc: 63.73% (24553/38528)
```

Epoch 17:

Train Loss: 1.023, Train Acc: 63.93% Val Loss: 1.060, Val Acc: 62.18%

Time: 28.00s

Epoch: 18 | Batch: 0 | Loss: 0.946 | Acc: 66.41% (85/128)

Epoch: 18 | Batch: 100 | Loss: 0.985 | Acc: 64.18% (8297/12928) Epoch: 18 | Batch: 200 | Loss: 0.836 | Acc: 64.11% (16495/25728) Epoch: 18 | Batch: 300 | Loss: 0.995 | Acc: 64.31% (24777/38528)

Epoch 18:

Train Loss: 1.008, Train Acc: 64.43% Val Loss: 1.021, Val Acc: 63.46%

Time: 28.75s

Epoch: 19 | Batch: 0 | Loss: 0.994 | Acc: 64.06% (82/128)

Epoch: 19 | Batch: 100 | Loss: 1.036 | Acc: 64.73% (8368/12928) Epoch: 19 | Batch: 200 | Loss: 0.986 | Acc: 64.55% (16607/25728) Epoch: 19 | Batch: 300 | Loss: 0.957 | Acc: 64.71% (24930/38528)

Epoch 19:

Train Loss: 0.989, Train Acc: 64.87% Val Loss: 1.017, Val Acc: 65.12%

Time: 28.12s

Evaluating on test set...

Test Loss: 0.668
Test Accuracy: 77.37%

Generating plots...

Saving final results...

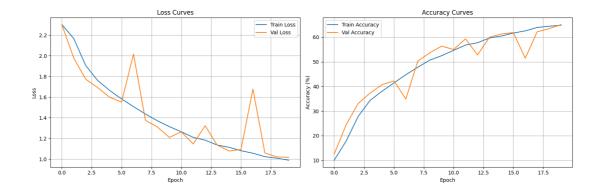
Training Summary:

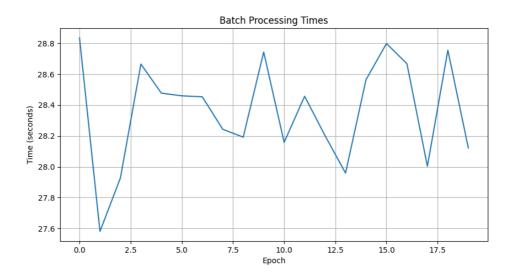
Best Validation Accuracy: 65.12% (Epoch 19)

Final Test Accuracy: 77.37% Average Epoch Time: 28.36s

Saved files:

- alexnet_multigpu_final.pth (Final model and full history)
- alexnet_multigpu_best.pth (Best model based on validation accuracy)
- multigpu_training_curves.png (Loss and accuracy curves)
- multigpu_batch_times.png (Training time per epoch)





Key Observations:

- 1. Total Training Time 567.2 seconds (9.45 minutes)
- 2. Average Epoch Time 28.36 seconds
- 3. Best Validation Accuracy 65.12%
- 4. Final Test Accuracy 77.37%

Was Multi-GPU Efficient?

- 1. Speed Comparison
- Single GPU AlexNet: ~17 minutes
- Multi-GPU AlexNet: ~9.45 minutes
- Achieved ~1.8x speedup with two GPUs
- 2. Training Characteristics
- Consistent epoch times (28-29 seconds)
- Stable batch processing
- Good GPU utilization with parallel processing
- Effective synchronization between GPUs
- 3. Performance Trade-offs
- Lower accuracy compared to single-GPU version (77.37% vs 84.56%)
- More complex implementation
- Additional overhead from cross-GPU communication
- Memory split between GPUs requires careful batch management

The multi-GPU implementation successfully reduced training time by almost half, demonstrating good scaling. However, the complexity of the implementation and the communication overhead between GPUs may have impacted the final model accuracy.

The trade-off between speed and accuracy should be considered when deciding whether to use this approach.

Thank You 🧐

- Here's the Github Repository Link: https://github.com/aryashah2k/RTML/tree/main/A1
- Model Checkpoints and Weights can be downloaded from the Terabox Drive here: https://1024terabox.com/s/1m0pW0GHvsc80-MEoMAlzbA