

# Session 11: Optimality conditions

Optimization and Computational Linear Algebra for Data Science

# Contents

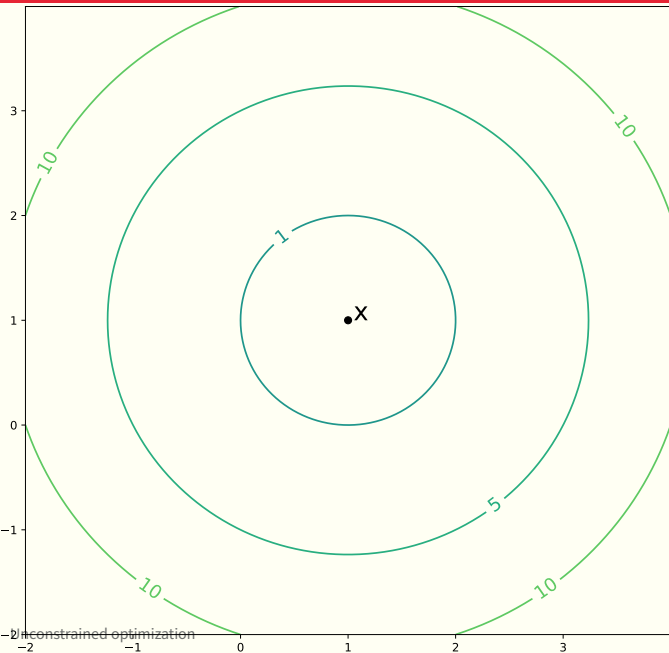
1. Unconstrained optimization
2. Constrained optimization and Lagrange multipliers
3. Convex constrained optimization problems

# Unconstrained optimization

# Questions about the video?

- ❖ Global minimizer  $\implies$  local minimizer  $\implies$  saddle point.
- ❖ Critical point + positive definite Hessian  $\implies$  local minimizer.

# Hessian at a critical point



The Hessian at  $x$  is:

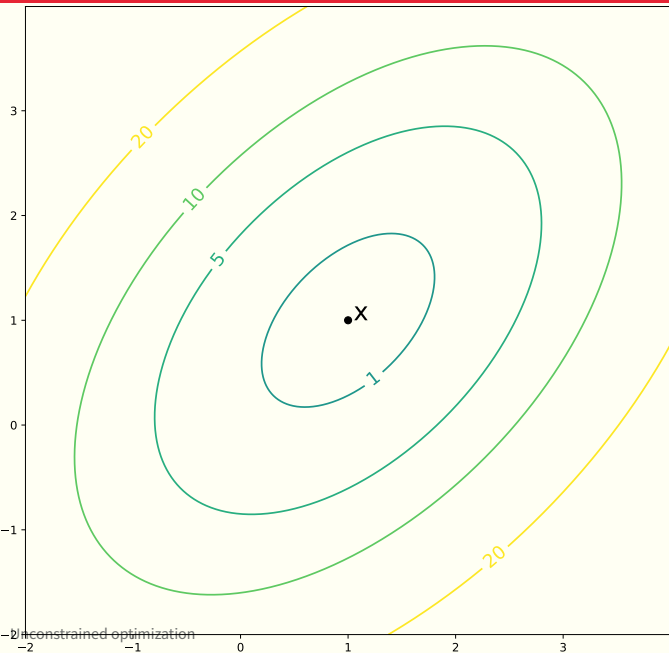
1.  $\begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix}$

2.  $\begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}$

3.  $\begin{pmatrix} 2 & 0 \\ 0 & 1 \end{pmatrix}$

4.  $\begin{pmatrix} -1 & 0 \\ 0 & -1 \end{pmatrix}$

# Hessian at a critical point



The Hessian at  $x$  is:

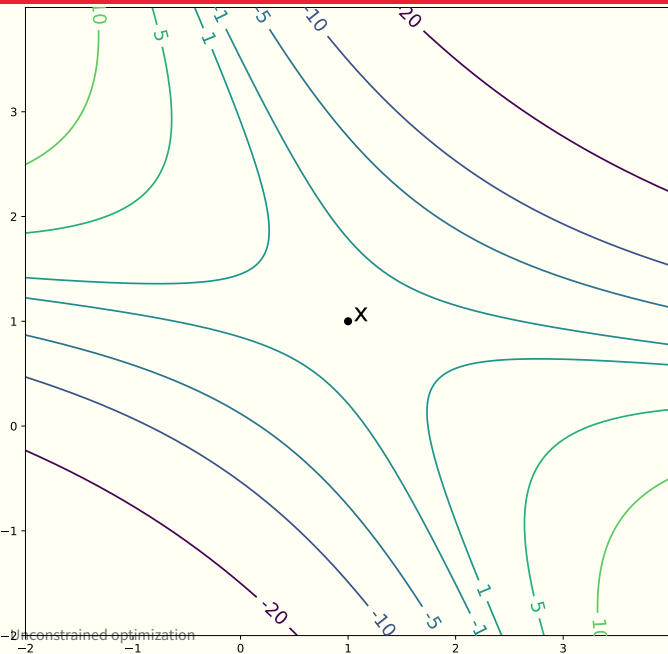
1.  $\begin{pmatrix} 1 & 0 \\ 0 & -3 \end{pmatrix}$

2.  $\begin{pmatrix} 2 & 0 \\ 0 & 2 \end{pmatrix}$

3.  $\begin{pmatrix} 1 & 0 \\ 0 & 3 \end{pmatrix}$

4.  $\begin{pmatrix} -1 & 0 \\ 0 & -1 \end{pmatrix}$

# Hessian at a critical point



The Hessian at  $x$  is:

1.  $\begin{pmatrix} 1 & 0 \\ 0 & -3 \end{pmatrix}$

2.  $\begin{pmatrix} 2 & 0 \\ 0 & 2 \end{pmatrix}$

3.  $\begin{pmatrix} 1 & 0 \\ 0 & 3 \end{pmatrix}$

4.  $\begin{pmatrix} -1 & 0 \\ 0 & -1 \end{pmatrix}$

# Constrained optimization



# General formulation

Constrained optimization problems take the form:

$$\begin{array}{ll}\text{minimize} & f(x) \\ \text{subject to} & g_i(x) \leq 0, \quad i = 1, \dots, m \\ & h_i(x) = 0, \quad i = 1, \dots, p,\end{array}$$

with variable  $x \in \mathbb{R}^n$ .

# Question

If  $x$  is a solution to

$$\begin{array}{ll}\text{minimize} & f(x) \\ \text{subject to} & g_i(x) \leq 0, \quad i = 1, \dots, m \\ & h_i(x) = 0, \quad i = 1, \dots, p,\end{array}$$

do we have  $\nabla f(x) = 0$ ?

# Feasible points

## Definition

A point  $x \in \mathbb{R}^n$  is *feasible* if it satisfies all the constraints:

$g_1(x) \leq 0, \dots, g_m(x) \leq 0$  and  $h_1(x) = 0, \dots, h_p(x) = 0$ .

# First order optimality condition

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## Theorem

If  $x$  is a solution and if  $\nabla h_1(x), \dots, \nabla h_p(x), \{\nabla g_i(x) \mid g_i(x) = 0\}$  are linearly independent, then there exists  $\lambda_1, \dots, \lambda_m \geq 0$  and  $\nu_1, \dots, \nu_p \in \mathbb{R}$  such that:

$$\nabla f(x) + \sum_{i=1}^m \lambda_i \nabla g_i(x) + \sum_{i=1}^p \nu_i \nabla h_i(x) = 0. \quad (1)$$

Moreover, for all  $i \in \{1, \dots, m\}$ , if  $g_i(x) < 0$  then  $\lambda_i = 0$ .

# Example

Let  $u \in \mathbb{R}^n$ . Solve:

$$\begin{array}{ll}\text{minimize} & \langle x, u \rangle \\ \text{subject to} & \|x\|^2 = 1.\end{array}$$



# Convex constrained optimization

# General formulation

We say that the constrained optimization problem

$$\begin{array}{ll} \text{minimize} & f(x) \\ \text{subject to} & g_i(x) \leq 0, \quad i = 1, \dots, m \\ & h_i(x) = 0, \quad i = 1, \dots, p, \end{array} \quad (2)$$

is convex when  $f, g_1, \dots, g_m$  are convex and  $h_1, \dots, h_p$  are affine.

# First order optimality condition

## Theorem

Assume that the problem is convex and that there exists a feasible point  $x_0$  such that  $g_i(x_0) < 0$  for all  $i$ .

Then  $x$  is a solution if and only if  $x$  is feasible and there exists  $\lambda_1, \dots, \lambda_m \geq 0, \nu_1, \dots, \nu_p \in \mathbb{R}$  such that:

$$\begin{cases} \nabla f(x) + \sum_{i=1}^m \lambda_i \nabla g_i(x) + \sum_{i=1}^p \nu_i \nabla h_i(x) = 0. \\ \lambda_i g_i(x) = 0, \text{ for all } i \in \{1, \dots, m\}. \end{cases}$$

# Lagrangian

Define the Lagrangian:

$$L(x, \lambda, \nu) = f(x) + \sum_{i=1}^m \lambda_i g_i(x) + \sum_{i=1}^p \nu_i h_i(x), \quad (3)$$

# Example

Let  $u, v \in \mathbb{R}^n$  such that  $\|v\| = 1$ . Solve:

$$\begin{array}{ll} \text{minimize} & \|x - u\|^2 \\ \text{subject to} & x \perp v. \end{array} \quad (4)$$

# Example

Let  $u, v \in \mathbb{R}^n$  such that  $\|v\| = 1$ . Solve:

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