Level 1 and 2 are implemented in python language. In python I used Pulp for Linear Programming.

Pulp can only do linear models so for higher levels I couldn't use it.

I tried to use Pyomo for nonlinear problems but couldn't get the results I wanted and couldn't find any better library with a good documentation so I decided to change the language to Julia for better results.

At first I used JuMP, it was easy to use but not efficient and optimal (over 10 GB of memory for E.Coli using Second-order cone constraint (a) but it could solve level 3 problem.

Next, I found Convex.jl that is better and easier for implementing Second-order Cone and Quadratic problems. I used this library to solve other levels, and even got better result for level 3.

For solving problems, I used the hints in the questions and almost got acceptable results.

I solved last problem as it was formulated in the question and for 0-norm I used this function:

$$\min \quad \sum f(x_i)$$

$$s.t.$$
 $Ax = y$

Were f(x) is:

$$f(x_i) = \exp\left(-\frac{x_i^2}{2\delta^2}\right)$$

And δ is a positive number approaching 0.