# Ph.D. Christian Arzate Cruz

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## **Professional Experience**

Scientist Japan

#### HONDA RESEARCH INSTITUTE JP

2023/04 - present

· Social Robotics Lab

• I'm working on interactive reinforcement learning algorithms for social robotics applications. My colleagues and I are making robots that develop bonds through empathy by responding to human emotions with rich expressiveness.

Assistant Professor Japan

#### RITSUMEIKAN UNIVERSITY

2022/04 - 2023/03

· Reality Media Lab

• I worked on human augmentation through artificial intelligence and human-computer interaction methods. My collaborators and I designed human-computer interaction methods to transform and expand human perception.

**Researcher** Japan

#### THE UNIVERSITY OF TOKYO

2019/04 - 2022/03

· Takeo Igarashi Lab

• I worked on AI and human-computer interaction methods that minimize the needed human feedback and reinforcement learning-based agents that explain their thinking process.

Research Assistant USA
HEWLETT PACKARD LABS 2012/01 - 2013/03

• Mobile and Immersive Experiences Lab

• I developed artificial vision based technologies aimed to improve the man-machine interaction of Hewlett-Packard systems for the visualization of data on 3D displays in real-time.

## **Education**

#### **Ph.D. in Computer Science**

Mexico

#### **TECNOLOGICO DE MONTERREY**

2013 - 2018

- Thesis: HRLB^2: A Game AI Architecture For Believable Bots That Unifies the Elements of Flow and Reinforcement Learning
- Thesis Advisor: Jorge Adolfo Ramirez Uresti
- Description: My work is aimed towards maximizing the player's enjoyment through artificial intelligence techniques in real-time. Specifically, my thesis' main objective was to create non-player characters that behave in a human-like manner. Our approach to achieve this goal is based on reinforcement learning techniques.

### **M.Sc. in Computer Science**

Mexico

2010 - 2011

- **TECNOLOGICO DE MONTERREY** Graduated with honors
- Thesis: Body Part Detection Using a Low Cost Depth Camera
- Thesis Advisor: Isaac Rudimín Goldberg
- Description: The main objective of my dissertation was to design and implement real- time algorithms to detect body parts using the Kinect depth camera. Our algorithms make use of parallel computing they were coded in the GPU (CUDA). The principal application of the proposed algorithms was the generation of human-like crowd behaviors.

#### **B.Sc. Mechatronics Engineering**

Mexico

2004 - 2009

- **TECNOLOGICO DE MONTERREY** Graduated with honors
- Specialization: Automotive engineering
- Description: For my specialization in automotive engineering, I took courses of mechanical vibrations and the finite element method.

APRIL 12, 2023 CHRISTIAN ARZATE CRUZ

## **Honours & Awards**.

JST CREST AIP Challenge, a $10,000$ dollars support for young researchers by the Japan Society for the Promotion of Science.	2021
COMECYT <b>Studies Financial Support</b> , living expenses support throughout the duration of Ph.D. studies.	2017 - 2018
Tec de <b>Tuition Scholarship</b> , full tuition support as a student of Ph.D. program in Computer Monterrey Science.	2013 - 2018
CONACYT National Studies Financial Support, living expenses support throughout the duration of Ph.D. studies.	2013 - 2016

## Invited Talks\_\_\_\_\_

**Conference Talk** ISID 2023 2023

• Invited talk at the International Symposium on Intelligence Design (ISID) 2023 on designing interactive reinforcement learning applications.

## Teaching Experience \_\_\_\_\_

**Part-Time Faculty Member** 

2016

Universidad Mexicana de Innovación en Negocios

• Teacher of undergraduate students on operating systems and computational architecture courses.

## Selected Publications \_\_\_\_\_

	Interactive Reinforcement Learning for Autonomous Behavior Design, Christian Arzate	
2021	Cruz, and Takeo Igarashi. In: Li Y., Hilliges O. (eds) Artificial Intelligence for Human Computer	Book Chapter
	Interaction: A Modern Approach. Human–Computer Interaction Series. Springer, Cham.	
	Interactive Explanations: Diagnosis and Repair of Reinforcement Learning Based Agent	
2021	<b>Behaviors</b> , Christian Arzate Cruz, and Takeo Igarashi. In the IEEE Conference on Games (CoG).	Conference
	MarioMix: Creating Aligned Playstyles for Bots with Interactive Reinforcement	
2020	<b>Learning</b> , Christian Arzate Cruz, and Takeo Igarashi. In Extended Abstracts of the Annual	Conference
	Symposium on Computer-Human Interaction in Play (CHI Play).	
	A Survey on Interactive Reinforcement Learning: Design Principles and Open	
2020	Challenges, Christian Arzate Cruz, and Takeo Igarashi. Designing Interactive Systems	Conference
	Conference (DIS).	
2018	HRLB^2: A Reinforcement Learning Based Framework for Believable Bots, Christian	1
	Arzate Cruz and Jorge Adolfo Ramirez Uresti. Applied Sciences (MDPI).	Journal
	Player-centered game AI from a flow perspective: Towards a better understanding of	
2017	<b>past trends and future directions</b> , Christian Arzate Cruz and Jorge Adolfo Ramirez Uresti. Entertainment Computing.	Journal

## Reviewer\_

PC member IEEE Conference on Games (CoG). The ACM Symposium on User Interface Software and Technology (UIST), IEEE Conference

Conference

on Games (CoG).

Conference

IEEE Transactions on Games (ToG), Elsevier Entertainment Computing, and Springer 3D Reviewer

Research.

Journal

## Technical Skills\_\_\_\_\_

#### PROGRAMMING SKILLS

• My background includes parallel computing and, data-driven programming techniques. My main programming languages are: C, C++, CUDA, OpenCL, Matlab, Java, and Python. Furthermore, since my work focus on computer graphics and game Al, I have experience in the next programming libraries: **OpenGL**, **OpenCV**, and **PyTorch**.

English, Spanish, and Japanese (basic level).