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Artificial Intelligence

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Project Report

Before you compile my program, in the `main()` function of the source code, manually enter the names of the input file (e.g., `Input1.txt`) and output file (e.g., `Output1.txt`).

To compile and run the C++ robot path planning program on Windows, install the g++ compiler by downloading and installing MinGW from the official website. Make sure you are using g++ version 4.8.1 or later and that your system supports C++11 or newer. You can check your version by typing `g++ --version` in the command prompt. Then, open the command prompt (cmd) and use the `cd` command to navigate to the directory where my C++ source file (`AStarSearch.cpp`) and the input files are located. In the command prompt, compile the program with the command `g++ -o AStarSearch AStarSearch.cpp`, which will generate an executable file named `AStarSearch.exe`. Once compiled, run the program by typing `./AStarSearch` in the command line, and it will prompt you to input a value for `k`, which must be an integer.

After you enter the value of `k`, the program will then attempt to find a path from the start to the goal and save the results in an output file. It will print whether a solution was found or not in the console and will put details about the nodes generated, depth of goal node, actions, $f(n)$ values, and workspace in the output file.

Source Code:

```
// Arnik Shah  
// Robot Path Planning Project  
// November 9, 2024
```

```

#include <iostream>
#include <fstream>
#include <vector>
#include <queue>
#include <cmath>
#include <map>
#include <utility>
#include <iomanip> // For formatting output

using namespace std;

// Global Constants
const int rows = 30;
const int cols = 50;
const vector<pair<int, int>> directions = {
    {1, 0},    // Right (0 degrees)
    {1, 1},    // Up-Right (45 degrees)
    {0, 1},    // Up (90 degrees)
    {-1, 1},   // Up-Left (135 degrees)
    {-1, 0},   // Left (180 degrees)
    {-1, -1},  // Down-Left (225 degrees)
    {0, -1},   // Down (270 degrees)
    {1, -1},   // Down-Right (315 degrees)
};

const vector<int> angles = {0, 45, 90, 135, 180, 225, 270, 315};

// Function Prototype for calculating Euclidean distance
double euclideanDistance(pair<int, int> a, pair<int, int> b);

// Class to calculate path cost (f(n) values) for each node
class NodePathCost {
public:
    NodePathCost(int k, int g) : k(k), g(g), h(0) {}

    void updateCost(int currentAngle, int newAngle, int action) {
        // Calculate Angle cost
        int angleDiff = abs(newAngle - currentAngle);
        if (angleDiff > 180) {

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        angleDiff = 360 - angleDiff;
    }
    double angleCost = k * ((double)angleDiff / 180);
    // Calculate Distance cost
    double distanceCost = (action % 2 == 0) ? 1 : sqrt(2);
    // Update g(n) value
    g += angleCost + distanceCost;
}

void setHeuristicCost(pair<int, int> currPos, pair<int, int> goalPos) {
    // Get Euclidian distance between the current position and the goal position
    h = euclideanDistance(currPos, goalPos);
}

double getTotalCost() const { return g + h; }

double getG() const { return g; }

private:
    int k;
    double g;
    double h;
};

// Class for each state
class Node {
public:
    Node(pair<int, int> loc, int angle, int k, int g) : location(loc), angle(angle),
cost(k, g) {}

    void updateNodePathCost(int action, int newAngle, pair<int, int> goalPos) {
        cost.updateCost(angle, newAngle, action);
        cost.setHeuristicCost(location, goalPos);
        angle = newAngle;
    }

    double getCost() const { return cost.getTotalCost(); }

    double getTraveledcost() const { return cost.getG(); }

```

```

    pair<int, int> getLocation() const { return location; }

    int getAngle() const { return angle; }

    const vector<int>& getPrevActions() const { return prevActions; }

    const vector<double>& getPrevCosts() const { return prevfValues; }

    void setPrevActions(const vector<int>& actions) { prevActions = actions; }

    void setPrevCosts(const vector<double>& costs) { prevfValues = costs; }

    void addActions(int action) { prevActions.push_back(action); }

    void addCosts(double cost) { prevfValues.push_back(cost); }

    // Used to compare nodes in the frontier
    bool operator<(const Node& other) const { return this->getCost() >
other.getCost(); }

    bool operator==(const Node& other) const { return location == other.location; }
private:
    pair<int, int> location;
    int angle;
    NodePathCost cost;
    // Stores the path actions taken to reach this node
    vector<int> prevActions;
    // Stores f(n) values along the path
    vector<double> prevfValues;
};

// A* Search Class
class AStarSearch {
public:
    AStarSearch(pair<int, int> start, pair<int, int> goal, int** workspace, int k)
        : start(start), goal(goal), workspace(workspace), k(k) {}

    ~AStarSearch() {

```

```

    // Free each row
    for (int c = 0; c < cols; ++c) {
        delete[] workspace[c];
    }
    // Free array of pointers
    delete[] workspace;
}

bool solve() {
    priority_queue<Node> frontier;
    map<pair<int, int>, double> visited;
    // Add initial state to frontier and set
    Node startNode(start, 0, k, 0);
    frontier.push(startNode);
    visited[start] = startNode.getCost();

    while (!frontier.empty()) {
        Node current = frontier.top();
        frontier.pop();

        // Check if the current node is the goal
        if (current.getLocation() == goal) {
            solutionActions = current.getPrevActions();
            solutionFValues = current.getPrevCosts();
            solutionFValues.push_back(current.getCost()); // Include f(n) at the
goal
            return true;
        }
        // Expand Node if current is not the goal
        // Check all possible actions
        for (size_t i = 0; i < directions.size(); ++i) {
            pair<int, int> newLoc = {
                current.getLocation().first + directions[i].first,
                current.getLocation().second + directions[i].second
            };
            // Check if location is in bounds and if it does not have an obstacle
            if (inBounds(newLoc) && workspace[newLoc.first][newLoc.second] != 1)
{
                // Make new Node and update its f(n) value

```

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        Node newNode(newLoc, current.getAngle(), k,
current.getTraveledcost());
        newNode.updateNodePathCost(i, angles[i], goal);

        // Copy prev actions and prev f(n) values from the current node
        newNode.setPrevActions(current.getPrevActions());
        newNode.setPrevCosts(current.getPrevCosts());
        newNode.addActions(i);
        newNode.addCosts(newNode.getCost());
        // Check if the new node is not in the map or has a smaller cost
than one in the map
        if (visited.find(newLoc) == visited.end() || newNode.getCost() <
visited[newLoc]) {
            frontier.push(newNode);
            visited[newLoc] = newNode.getCost();
            nodesGenerated++;
        }
    }
}
return false;
}

const vector<int>& getSolutionActions() const { return solutionActions; }

const vector<double>& getSolutionFValues() const { return solutionFValues; }

int getNodesGenerated() const { return nodesGenerated; }

private:
    pair<int, int> start, goal;
    int** workspace;
    int k;
    int nodesGenerated = 1;

    vector<int> solutionActions;
    vector<double> solutionFValues;

    bool inBounds(pair<int, int> loc) const {

```

```

        return loc.first >= 0 && loc.first < cols && loc.second >= 0 && loc.second <
rows;
    }
};

// Function prototypes
pair<int, int> getPosition(ifstream& input);
int** getWorkspace(ifstream& input);
void outputResults(const string& filename, AStarSearch& search, int** currentState,
pair<int, int> start);

int main() {
    ifstream input("Input1.txt");
    if (!input) {
        cerr << "Could not open the file.\n";
        exit(1);
    }

    pair<int, int> start = getPosition(input);
    pair<int, int> goal = getPosition(input);
    int** workspace = getWorkspace(input);
    input.close();

    // Get k value
    int k;
    cout << "What is the value of k?" << endl;
    cin >> k;
    AStarSearch search(start, goal, workspace, k);
    bool findSoultion = search.solve();

    // Output the nodes generated, solution actions, solution costs, and solution
workspace
    if (findSoultion) {
        outputResults("Output.txt", search, workspace, start);
        cout << "Solution found and saved to output file." << endl;
    } else {
        cout << "No solution found." << endl;
    }
}

```

```

double euclideanDistance(pair<int, int> a, pair<int, int> b) {
    return sqrt(pow(b.first - a.first, 2) + pow(b.second - a.second, 2));
}

pair<int, int> getPosition(ifstream& input) {
    // Get starting and final coordinates
    int iCoordinate, jCoordinate = 0;
    input >> iCoordinate >> jCoordinate;
    return {iCoordinate, jCoordinate};
}

int** getWorkspace(ifstream& input) {
    // Allocate 50 columns
    int** matrix = new int*[cols];
    for (int c = 0; c < cols; ++c) {
        // For each column, allocate 30 rows
        matrix[c] = new int[rows]();
    }

    // Read the workspace values
    for (int j = rows - 1; j >= 0 ; --j) {
        for (int i = 0; i < cols; ++i) {
            input >> matrix[i][j];
        }
    }
    return matrix; // Return the raw pointer
}

void outputResults(const string& filename, AStarSearch& search, int** workspace,
pair<int, int> start) {
    ofstream output(filename);
    // Depth of Node
    output << search.getSolutionActions().size() << endl;
    // Total nodes generated
    output << search.getNodesGenerated() << endl;

    // Solution path (actions)

```



```

for (int action : search.getSolutionActions()) {
    output << action << " ";
}
output << endl;

// f(n) values along the solution path
for (double fValue : search.getSolutionFValues()) {
    // Show all values with 2 decimal points
    output << fixed << setprecision(2) << fValue << " ";
}
output << endl;

// Mark the path in the currentState
for (size_t i = 1; i < search.getSolutionActions().size(); ++i) {
    int action = search.getSolutionActions()[i];
    start.first += directions[action].first;
    start.second += directions[action].second;
    workspace[start.first][start.second] = 4;
}

// Print Workspace
for (int row = rows - 1; row >= 0; --row) {
    for (int col = 0; col < cols; ++col) {
        output << workspace[col][row] << " ";
    }
    output << endl;
}

output.close();
}

```

Output Files:

Output for Input1.txt and k = 0:

```

31
134
7 0 0 7 7 7 7 7 7 7 7 0 7 7 0 0 0 0 0 0 0 0 1 1 1 0 0 0 7 0

```

[illegible]

[illegible]

Output for Input1.txt and k = 2:

[illegible]

[illegible]

```
0 0 0 1 1 0 1 1 1 0 1 1 0 0 0 1 1 4 4 0 0 1 1 1 0 0 1 1 0 0 4 0 0 0 0 4 4 0 1 1 0 0 0
0 0 0 0 0 0 0
0 0 0 1 1 0 1 1 1 0 0 0 0 0 0 1 1 0 0 4 0 0 1 0 0 0 1 1 1 4 0 0 0 0 1 1 0 5 1 1 0 0 0
0 0 0 0 0 0 0
0 0 0 1 1 0 1 1 1 0 0 0 0 0 1 1 0 0 1 1 4 4 4 4 4 4 4 4 1 0 0 0 0 1 1 0 0 0 0 0 0 0 0
0 0 0 0 0 0 0
0 0 0 0 0 0 1 1 1 0 0 0 0 0 0 1 1 0 0 1 0 0 0 0 0 0 0 0 0 0 0 1 1 0 0 0 0 0 0 0 0 0 0
0 0 0 0 0 0 0
0 0 0 0 0 0 1 1 1 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
0 0 0 0 0 0 0
0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
0 0 0 0 0 0 0
0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
0 0 0 0 0 0 0
```

Output for Input1.txt and k = 4:

```
31
330
0 0 7 7 7 7 7 7 7 7 7 0 7 7 7 0 0 0 0 0 0 0 0 0 0 0 0 1 1 1
32.62 32.68 33.83 33.57 33.34 33.12 32.93 32.76 32.62 32.51 32.44 32.41 33.00 34.44
34.54 34.71 35.32 35.34 35.37 35.40 35.44 35.49 35.54 35.62 35.71 35.83 36.00 36.24
37.24 36.83 36.41 36.41
0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
0 0 0 0 0 0 0
0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
0 0 0 0 0 0 0
0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
0 0 0 0 0 0 0
0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 1 1 1 1 0 0 0 0 0 1 1 0 0 0 0 0 0 0 0 0 0
0 0 0 0 0 0 0
0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 1 1 1 1 0 0 0 0 0 1 1 1 0 0 0 0 0 0 0 0 0
0 0 0 0 0 0 0
0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 1 1 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
0 0 0 0 0 0 0
0 0 0 0 0 1 1 0 0 0 0 0 0 0 0 0 0 0 1 1 0 0 1 0 0 0 1 1 1 1 0 0 0 0 0 0 0 0 0
0 0 0 0 0 0 0
1 1 1 1 1 1 1 1 0 1 1 1 1 1 1 1 1 1 0 0 0 1 1 0 0 1 1 0 0 1 1 1 1 0 0 0 0 0 0 0 0
```

0 0 0 0 0 0 0
1 1 1 1 1 1 1 1 0 0 0 1 1 1 1 1 1 1 0 0 0 1 1 0 0 0 0 0 0 1 1 1 1 0 0 0 0 0 0 0
0 0 0 0 0 0 0
0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 1 1 1 1 0 0 0 1 1 1 1 0 1 1 0 0 1 1 1 1 0 0 0 0 0 0 0
0 0 0 0 0 0 0
0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 1 1 1 0 0 0 0 1 1 1 0 0 1 1 0 0 1 1 1 1 0 0 0 0 0 0
0 0 0 0 0 0 0
0 0 0 0 0 0 0 0 0 1 0 0 0 1 1 0 1 1 1 1 0 0 0 0 1 1 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
0 0 0 0 0 0 0
0 0 0 0 0 0 0 0 0 1 1 0 0 1 0 0 0 0 1 1 0 0 0 0 0 0 0 0 0 0 1 1 1 1 0 0 0 0 0 0 0
0 0 0 0 0 0 0
0 0 0 0 0 0 0 0 0 1 1 0 0 1 0 0 0 0 1 0 0 0 0 0 0 0 0 0 0 1 1 1 1 0 0 0 0 0 0 0
0 0 0 0 0 0 0
0 0 0 0 0 0 0 0 0 1 1 0 0 0 0 0 0 0 1 0 1 1 0 0 0 0 0 0 0 1 1 1 1 0 0 0 0 0 0 0
0 0 0 0 0 0 0
0 0 0 0 0 0 0 0 0 1 1 0
0 0 0 0 0 0 0 0 0 1 0
0 0 0 0 0 0 0
0 0 0 1 1 1 1 1 1 4 0 0 0 1 1 1 0 0 1 1 0 1 1 1 1 0 0 0 1 0 1 1 0 0 0 1 1 0 0 0 0
0 0 0 0 0 0 0
0 0 0 1 1 1 1 1 1 4 0 0 0 1 1 0 0 1 1 0 1 1 1 1 0 0 0 1 0 0 1 1 0 0 0 1 0 0 0 0
0 0 0 0 0 0 0
0 0 0 0 0 0 0 1 0 0 0 4 0 0 1 1 1 0 1 0 0 1 1 1 1 0 0 0 0 0 0 1 1 0 0 0 0 0 0 0
0 0 0 0 0 0 0
0 0 0 0 0 0 0 0 0 0 0 4 0 0 1 1 0 0 0 0 0 0 1 1 1 0 0 0 0 1 0 0 0 0 0 0 0 0 0
0 0 0 0 0 0 0
0 0 0 0 0 0 1 1 1 0 0 0 0 4 0 1 1 1 0 0 1 1 0 0 1 1 1 0 0 0 0 0 0 0 0 0 0 0 0
0 0 0 0 0 0 0
0 0 0 0 0 0 1 1 1 0 1 1 0 0 4 0 1 1 0 0 0 0 0 0 0 0 0 0 0 0 1 1 1 0 0 1 1 1 0 0 0 0
0 0 0 0 0 0 0
0 0 0 1 1 0 1 1 1 0 1 1 0 0 0 4 0 0 0 0 0 1 0 0 0 0 0 0 0 0 1 1 0 0 0 1 1 1 1 0 0 0
0 0 0 0 0 0 0
0 0 0 1 1 0 1 1 1 0 0 0 0 0 1 1 0 0 1 4 0 1 1 1 1 0 0 1 1 1 0 0 0 0 1 4 0 0 0 0 0 0
0 0 0 0 0 0 0
0 0 0 0 0 0 1 1 1 0 0 0 0 0 1 1 0 0 1 4 0 0 0 0 0 0 0 0 0 0 1 1 0 0 4 0 0 0 0 0 0 0
0 0 0 0 0 0 0


```
0 0 0 0 0 0 0 0
0 0 0 0 0 0 0 0 0 1 1 0 0 1 0 0 0 0 1 1 0 0 0 1 0 4 0 0 0 0 0 1 1 1 1 0 0 0 0 0 0 0
0 0 0 0 0 0 0 0
0 0 0 0 0 0 0 0 0 0 1 1 0 0 0 0 0 0 1 1 0 0 1 1 4 0 0 1 0 0 0 0 1 1 1 1 0 0 0 0 0 0
0 0 0 0 0 0 0 0
0 0 0 0 0 0 0 0 0 0 1 1 0 1 1 0 0 0 0 0 4 4 4 4 1 0 1 1 0 0 0 0 0 0 0 0 0 1 0 0 0
0 0 0 0 0 0 0 0
0 0 0 0 0 0 0 0 0 0 0 0 0 0 1 0 0 0 0 4 0 0 0 0 0 0 0 0 0 1 1 1 1 0 0 1 1 1 0 0 0 0
0 0 0 0 0 0 0 0
0 0 0 1 1 1 1 1 1 1 0 0 0 1 1 1 0 0 1 4 0 1 1 1 1 1 0 0 0 1 0 1 1 0 0 0 1 1 0 0 0 0
0 0 0 0 0 0 0 0
0 0 0 1 1 1 1 1 1 1 0 0 0 0 1 1 0 0 1 4 0 1 1 1 1 1 0 0 0 1 0 0 1 1 0 0 0 1 0 0 0 0
0 0 0 0 0 0 0 0
0 0 0 0 0 0 0 1 0 0 0 0 0 0 1 1 1 0 1 4 0 1 1 1 1 1 0 0 0 0 0 0 1 1 0 0 0 0 0 0 0 0
0 0 0 0 0 0 0 0
0 0 0 0 0 0 0 0 0 0 0 0 0 0 1 1 0 4 0 0 0 0 1 1 1 0 0 0 0 1 0 0 0 0 0 0 0 0 0 0 0
0 0 0 0 0 0 0 0
0 0 0 0 0 0 1 1 1 0 0 0 0 0 0 1 1 4 0 0 1 1 0 0 1 1 0 0 1 1 1 0 0 0 0 0 0 0 0 0 0
0 0 0 0 0 0 0 0
0 0 0 0 0 0 1 1 1 0 1 1 0 4 4 4 4 1 0 0 0 0 0 0 0 0 0 0 0 0 1 1 1 0 0 1 1 1 0 0 0 0 0
0 0 0 0 0 0 0 0
0 0 0 1 1 0 1 1 1 0 1 1 4 0 0 0 0 0 0 0 0 0 1 0 0 0 0 0 0 0 0 1 1 0 0 0 1 1 1 1 0 0 0
0 0 0 0 0 0 0 0
0 0 0 1 1 0 1 1 1 0 1 4 0 0 0 1 1 0 0 0 0 1 1 1 0 0 1 1 0 0 0 0 0 0 0 0 1 0 1 1 0 0
0 0 0 0 0 0 0 0
0 0 0 1 1 0 1 1 1 0 4 0 0 0 0 1 1 0 0 0 0 0 1 0 0 0 1 1 1 0 0 0 0 0 1 1 0 0 1 1 0 0
0 0 0 0 0 0 0 0
0 0 0 1 1 0 1 1 1 4 0 0 0 0 1 1 0 0 1 1 0 1 1 1 1 0 0 1 1 1 0 0 0 0 1 1 0 0 0 0 0 0
0 0 0 0 0 0 0 0
0 0 0 0 0 0 1 1 4 0 0 0 0 0 1 1 0 0 1 0 0 0 0 0 0 0 0 0 0 0 0 1 1 0 0 0 0 0 0 0 0 0
0 0 0 0 0 0 0 0
0 0 0 2 4 4 4 4 1 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
0 0 0 0 0 0 0 0
0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
0 0 0 0 0 0 0 0
0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
0 0 0 0 0 0 0 0
```

Output for Input2.txt and k = 2:

[illegible]

[illegible]

```
0 0 0 0 0 0 0
0 0 0 1 1 0 1 1 1 0 1 1 0 4 4 4 4 0 0 0 0 1 0 0 0 0 0 0 0 0 1 1 0 0 0 1 1 1 1 0 0 0 0
0 0 0 0 0 0 0
0 0 0 1 1 0 1 1 1 0 1 1 4 0 0 1 1 0 0 0 0 1 1 1 0 0 1 1 0 0 0 0 0 0 0 0 1 0 1 1 0 0 0
0 0 0 0 0 0 0
0 0 0 1 1 0 1 1 1 0 0 4 0 0 0 1 1 0 0 0 0 0 1 0 0 0 1 1 1 0 0 0 0 0 1 1 0 0 1 1 0 0 0
0 0 0 0 0 0 0
0 0 0 1 1 0 1 1 1 0 4 0 0 0 1 1 0 0 1 1 0 1 1 1 1 0 0 1 1 1 0 0 0 0 1 1 0 0 0 0 0 0 0
0 0 0 0 0 0 0
0 0 0 0 0 0 1 1 1 4 0 0 0 0 0 1 1 0 0 1 0 0 0 0 0 0 0 0 0 0 0 0 1 1 0 0 0 0 0 0 0 0 0 0
0 0 0 0 0 0 0
0 0 0 2 4 0 1 1 4 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
0 0 0 0 0 0 0
0 0 0 0 0 4 4 4 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
0 0 0 0 0 0 0
0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
0 0 0 0 0 0 0
```

Output for Input3.txt and k = 0:

```
48
236
1 1 2 2 2 2 2 1 0 1 0 1 1 1 2 1 0 7 0 0 0 0 1 1 1 0 7 0 0 1 0 0 0 0 0 0 0 0 1 1 1
0 0 1 0 0 0
46.60 46.28 46.46 47.08 47.72 48.38 49.06 49.22 48.85 49.01 48.64 48.81 48.59 48.37
48.73 48.97 48.58 49.22 48.83 48.86 48.89 48.93 49.12 48.93 48.76 48.36 49.00 48.62
48.65 48.85 48.46 48.49 48.52 48.56 48.60 48.65 48.70 48.77 48.85 48.96 48.69 48.50
48.10 48.12 48.41 48.00 48.00 48.00 48.00
0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 1 1 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
0 0 0 0 0 0 0 0
0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 1 1 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
0 0 0 0 0 0 0 0
0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 1 1 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
0 0 1 1 0 0 0 0
0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 1 1 1 1 0 0 0 0 0 1 1 0 0 0 0 0 0 0 0 0 0 1
1 1 1 1 1 1 1 1
0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 1 1 0 0 0 0 0 0 0 0 0 0 0 0 0 0 1
1 1 1 1 1 1 1 1
0 0 0 0 0 1 1 0 0 0 0 0 0 0 0 0 0 0 0 0 1 1 0 0 1 0 0 0 1 1 1 1 0 0 0 0 0 0 0
0 0 0 0 0 0 0 0
```

1 1 1 1 1 1 1 1 0 1 1 1 1 1 1 1 1 1 0 0 0 1 1 0 0 1 1 0 0 1 1 1 1 0 0 0 0 0 0 0 0
0 0 0 5 0 0 0 0
1 1 1 1 1 1 1 1 0 0 0 1 1 1 1 1 1 1 1 0 0 0 1 1 0 0 0 0 0 0 0 1 1 1 1 0 0 0 0 0 0 4
4 4 4 0 0 0 0 0
0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 1 1 1 1 0 0 0 1 1 1 1 0 1 1 0 0 1 1 1 1 0 0 4 4 4 0
0 0 0 0 0 0 0 0
0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 1 1 1 0 0 0 0 1 1 1 0 0 1 1 0 0 1 1 1 1 4 0 0 0 0
0 0 1 1 1 0 0 0
0 0 0 0 0 0 0 0 0 1 0 0 0 1 1 0 1 1 1 1 1 0 0 0 0 1 1 0 0 0 0 0 0 0 0 0 4 0 0 0 0 0
0 0 1 1 1 0 0 0
0 0 0 0 0 0 0 0 0 1 1 0 0 1 0 0 0 0 1 1 0 4 4 1 0 0 4 4 4 4 4 4 4 4 0 0 0 0 0 0
0 0 1 1 1 0 0 0
0 0 0 0 0 0 0 0 0 0 1 1 0 0 0 0 0 0 1 1 4 0 1 4 4 4 0 1 0 0 0 0 1 1 1 1 0 0 0 0 0
0 0 0 0 0 0 0 0
0 0 0 0 0 0 0 0 0 0 1 1 4 4 1 0 0 0 0 4 0 0 0 0 1 0 1 1 0 0 0 0 0 0 0 0 0 1 0 0 0
0 0 0 0 0 0 0 0
0 0 0 0 0 0 0 0 0 0 0 4 0 0 4 4 4 4 4 0 0 0 0 0 0 0 0 0 1 1 1 1 0 0 1 1 1 0 0 0 0
1 1 0 0 0 0 0 0
0 0 0 1 1 1 1 1 1 1 0 4 0 1 1 1 0 0 1 1 0 1 1 1 1 1 0 0 0 1 0 1 1 0 0 0 1 1 0 0 0
1 1 1 0 0 0 0 0
0 0 0 1 1 1 1 1 1 1 4 0 0 0 1 1 0 0 1 1 0 1 1 1 1 1 0 0 0 1 0 0 1 1 0 0 0 1 0 0 0
0 0 0 0 0 0 0 0
0 0 0 0 0 0 0 1 0 4 0 0 0 0 1 1 1 0 1 0 0 1 1 1 1 1 0 0 0 0 0 0 1 1 0 0 0 0 0 0 0
0 0 0 0 0 0 0 0
0 0 0 0 0 0 0 4 4 0 0 0 0 0 0 1 1 0 0 0 0 0 0 1 1 1 0 0 0 0 1 0 0 0 0 0 0 0 0 0
0 1 1 1 0 0 0 0
0 0 0 0 4 4 1 1 0 0 0 0 0 0 1 1 1 0 0 1 1 0 0 1 1 1 0 0 0 0 0 0 0 0 0 0 0 0 0
0 1 1 1 0 0 0 0
0 0 0 0 4 0 1 1 1 0 1 1 0 0 0 0 1 1 0 0 0 0 0 0 0 0 0 0 1 1 1 0 0 1 1 1 0 0 0 0
0 1 1 1 0 0 0 0
0 0 0 1 4 0 1 1 1 0 1 1 0 0 0 0 0 0 0 0 0 0 1 0 0 0 0 0 0 0 1 1 0 0 0 1 1 1 0 0
0 0 0 0 0 0 0 0
0 0 0 1 4 0 1 1 1 0 0 0 0 0 0 1 1 0 0 0 0 0 1 0 0 0 1 1 1 0 0 0 0 0 1 1 0 0
0 0 0 0 0 0 0 0
0 0 0 1 4 0 1 1 1 0 0 0 0 0 1 1 0 0 1 1 0 1 1 1 1 0 0 1 1 1 0 0 0 0 1 1 0 0 0
0 1 1 1 0 0 0 0
0 0 0 0 4 0 1 1 1 0 0 0 0 0 0 1 1 0 0 1 0 0 0 0 0 0 0 0 0 0 1 1 0 0 0 0 0 0 0 0

[illegible]

Output for Input3.txt and k = 2:

48																																								
229																																								
1	1	2	2	2	2	2	1	0	1	0	1	1	1	2	1	1	0	7	7	0	0	1	1	1	0	7	0	0	1	0	0	0	0	0	0	0	1	1	1	
1	0	0	0	0	0																																			
47.10	46.28	46.96	47.08	47.72	48.38	49.06	49.72	49.35	49.51	49.14	49.31	48.59	48.37																											
49.23	49.47	48.81	48.91	49.53	49.28	49.39	48.93	49.62	48.93	48.76	48.86	49.50	49.12																											
48.65	49.35	48.96	48.49	48.52	48.56	48.60	48.65	48.70	48.77	48.85	49.46	48.69	48.50																											
48.41	48.50	48.00	48.00	48.00	48.00	48.00																																		
0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	1	1	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0		
0	0	0	0	0	0	0																																		
0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	1	1	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0		
0	0	0	0	0	0	0																																		
0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	1	1	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0		
0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	1	1	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0		
0	0	1	1	0	0	0																																		
0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	1	1	1	1	0	0	0	0	0	1	1	0	0	0	0	0	0	0	0	0	1		
1	1	1	1	1	1	1	1																																	
0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	1		
1	1	1	1	1	1	1	1																																	
0	0	0	0	0	1	1	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	1	1	0	0	1	0	0	0	1	1	1	1	0	0	0	
0	0	0	0	0	0	0																																		
1	1	1	1	1	1	1	1	0	1	1	1	1	1	1	1	1	1	1	0	0	0	1	1	0	0	1	1	0	0	1	1	1	1	0	0	0	0	0	0	
0	0	0	5	0	0	0																																		
1	1	1	1	1	1	1	1	0	0	0	1	1	1	1	1	1	1	1	0	0	0	1	1	0	0	0	0	0	0	0	0	1	1	1	1	0	0	0	4	
4	4	4	0	0	0	0																																		
0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	1	1	1	1	0	0	0	1	1	1	1	0	1	1	0	0	1	1	1	1	0	0	4	0	
0	0	0	0	0	0	0																																		
0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	1	1	1	0	0	0	0	1	1	1	0	0	1	1	0	0	1	1	1	1	4	0	0	
0	0	1	1	1	0	0																																		

0 0 0 0 0 0 0 0 0 0 1 0 0 0 1 1 0 1 1 1 1 1 0 0 0 0 1 1 0 0 0 0 0 0 0 0 0 4 0 0 0 0 0 0
0 0 1 1 1 0 0 0
0 0 0 0 0 0 0 0 0 0 1 1 0 0 1 0 0 0 0 1 1 0 4 4 1 0 0 4 4 4 4 4 4 4 4 0 0 0 0 0 0
0 0 1 1 1 0 0 0
0 0 0 0 0 0 0 0 0 0 0 1 1 0 4 4 0 0 0 1 1 4 0 1 4 4 4 0 1 0 0 0 0 1 1 1 1 0 0 0 0 0 0
0 0 0 0 0 0 0 0
0 0 0 0 0 0 0 0 0 0 0 1 1 4 1 1 4 0 0 0 4 0 0 0 0 1 0 1 1 0 0 0 0 0 0 0 0 0 0 1 0 0 0
0 0 0 0 0 0 0 0
0 0 0 0 0 0 0 0 0 0 0 0 4 0 0 1 0 4 4 4 0 0 0 0 0 0 0 0 0 0 0 1 1 1 1 0 0 1 1 1 0 0 0 0
1 1 0 0 0 0 0 0
0 0 0 1 1 1 1 1 1 1 0 4 0 1 1 1 0 0 1 1 0 1 1 1 1 1 0 0 0 1 0 1 1 0 0 0 1 1 0 0 0 0
1 1 1 0 0 0 0 0
0 0 0 1 1 1 1 1 1 1 4 0 0 0 1 1 0 0 1 1 0 1 1 1 1 1 0 0 0 1 0 0 1 1 0 0 0 1 0 0 0 0
0 0 0 0 0 0 0 0
0 0 0 0 0 0 0 0 1 0 4 0 0 0 0 1 1 1 0 1 0 0 1 1 1 1 1 0 0 0 0 0 0 1 1 0 0 0 0 0 0 0
0 0 0 0 0 0 0 0
0 0 0 0 0 0 0 0 4 4 0 0 0 0 0 0 1 1 0 0 0 0 0 0 1 1 1 0 0 0 0 0 1 0 0 0 0 0 0 0 0
0 1 1 1 0 0 0 0
0 0 0 0 0 4 4 1 1 0 0 0 0 0 0 1 1 1 0 0 1 1 0 0 1 1 0 0 1 1 1 0 0 0 0 0 0 0 0 0 0
0 1 1 1 0 0 0 0
0 0 0 0 4 0 1 1 1 0 1 1 0 0 0 0 1 1 0 0 0 0 0 0 0 0 0 0 0 0 1 1 1 0 0 1 1 1 0 0 0 0
0 1 1 1 0 0 0 0
0 0 0 1 4 0 1 1 1 0 1 1 0 0 0 0 0 0 0 0 0 0 1 0 0 0 0 0 0 0 0 1 1 0 0 0 1 1 1 0 0 0
0 0 0 0 0 0 0 0
0 0 0 1 4 0 1 1 1 0 1 1 0 0 0 0 1 1 0 0 0 0 1 1 1 0 0 1 1 0 0 0 0 0 0 0 1 0 1 1 0 0
0 0 0 0 0 0 0 0
0 0 0 1 4 0 1 1 1 0 0 0 0 0 0 1 1 0 0 1 1 0 1 1 1 0 0 1 1 1 0 0 0 0 1 1 0 0 0 0 0
0 1 1 1 0 0 0 0
0 0 0 0 4 0 1 1 1 0 0 0 0 0 0 1 1 0 0 1 0 0 0 0 0 0 0 0 0 0 0 1 1 0 0 0 0 0 0 0 0
0 1 1 1 0 0 0 0
0 0 0 2 0 0 1 1 1 0
0 1 1 1 0 0 0 0
0 0 0 0 0 0 1 1 1 0
0 0 0 0 0 0 0 0
0 0 0 0 0 0 1 1 1 0
0 0 0 0 0 0 0 0
0 0 0 0 0 0 1 1 1 0

0 0 0 0 0 0 0 0

Output for Input3.txt and k = 4:

48

596

1 1 2 2 2 2 2 1 0 0 1 1 1 1 2 1 0 0 0 0 7 7 0 0 0 0 0 1 1 1 1 0 0 0 0 0 0 0 0 1 1 1
1 0 0 0 0 0

47.60 47.28 48.46 49.08 49.72 50.38 51.06 52.22 52.85 52.90 54.06 53.81 53.59 53.37
54.73 55.97 56.58 56.59 56.61 56.64 58.31 58.62 59.25 59.30 59.35 59.41 59.47 60.60
60.34 60.10 59.88 60.49 60.52 60.56 60.60 60.65 60.70 60.77 60.85 61.96 61.69 61.50
61.41 62.00 62.00 62.00 62.00 62.00 62.00

0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 1 1 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
0 0 0 0 0 0 0 0

0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 1 1 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
0 0 0 0 0 0 0 0

0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 1 1 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
0 0 1 1 0 0 0 0

0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 1 1 1 1 0 0 0 0 0 1 1 0 0 0 0 0 0 0 0 1
1 1 1 1 1 1 1 1

0 1 1 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 1
1 1 1 1 1 1 1 1

0 0 0 0 0 1 1 0 0 0 0 0 0 0 0 0 0 0 0 0 0 1 1 0 0 1 0 0 0 1 1 1 1 0 0 0 0 0 0 0
0 0 0 0 0 0 0 0

1 1 1 1 1 1 1 1 0 1 1 1 1 1 1 1 1 1 0 0 0 1 1 0 0 1 1 0 0 1 1 1 1 0 0 0 0 0 0 0
0 0 0 5 0 0 0 0

1 1 1 1 1 1 1 1 0 0 0 1 1 1 1 1 1 1 0 0 0 1 1 0 0 0 0 0 0 0 1 1 1 1 0 0 0 0 4 4 4
4 4 4 0 0 0 0 0

0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 1 1 1 1 0 0 0 1 1 1 0 1 1 0 0 1 1 1 0 0 4 0 0 0
0 0 0 0 0 0 0 0

0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 1 1 1 0 0 0 0 1 1 1 0 0 1 1 0 0 1 1 1 4 0 0 0 0
0 0 1 1 1 0 0 0

0 0 0 0 0 0 0 0 0 1 0 0 0 1 1 0 1 1 1 1 0 0 0 0 1 1 0 0 0 0 0 0 0 0 0 0 4 0 0 0 0 0
0 0 1 1 1 0 0 0

0 0 0 0 0 0 0 0 0 1 1 0 0 1 0 0 0 0 1 1 0 0 0 1 0 0 0 4 4 4 4 4 4 4 4 0 0 0 0 0 0
0 0 1 1 1 0 0 0

0 0 0 0 0 0 0 0 0 0 1 1 0 0 0 0 0 0 1 1 0 0 1 1 1 0 4 1 0 0 0 0 1 1 1 1 0 0 0 0 0 0
0 0 0 0 0 0 0 0

0 0 0 0 0 0 0 0 0 0 1 1 4 4 4 4 4 0 0 0 0 0 0 0 1 4 1 1 0 0 0 0 0 0 0 0 0 0 1 0 0 0
0 0 0 0 0 0 0 0

[illegible]