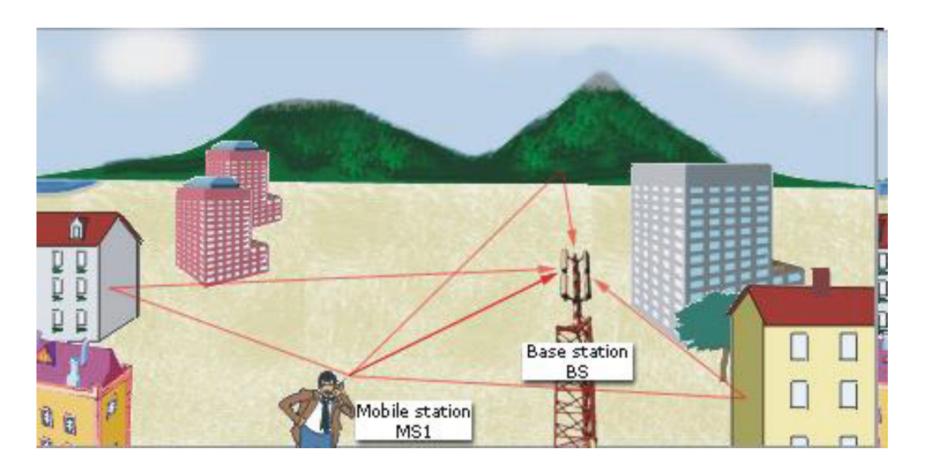
### Small-Scale Fading

PROF. MICHAEL TSAI 2019/10/21

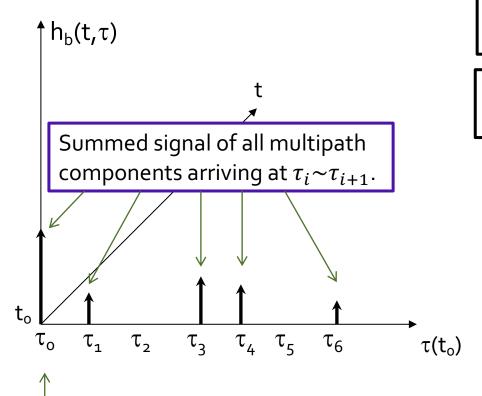
#### Multipath Propagation



RX just sums up all Multi Path Component (MPC).

# Multipath Channel Impulse Response

An example of the time-varying discrete-time impulse response for a multipath radio channel



**Excess delay**: the delay with respect to the first arriving signal ( $\tau$ )

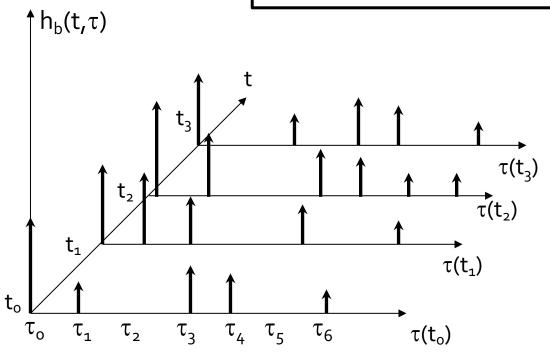
**Maximum excess delay**: the delay of latest arriving signal

The channel impulse response when  $t=t_0$  (what you receive at the receiver when you send an impulse at time  $t_0$ )

 $\tau_0 = 0$ , and represents the time the first signal arrives at the receiver.

#### Time-Variant Multipath Channel Impulse Response

Because the transmitter, the receiver, or the reflectors are moving, the impulse response is time-variant.



### Multipath Channel Impulse Response

The channels impulse response is given by:

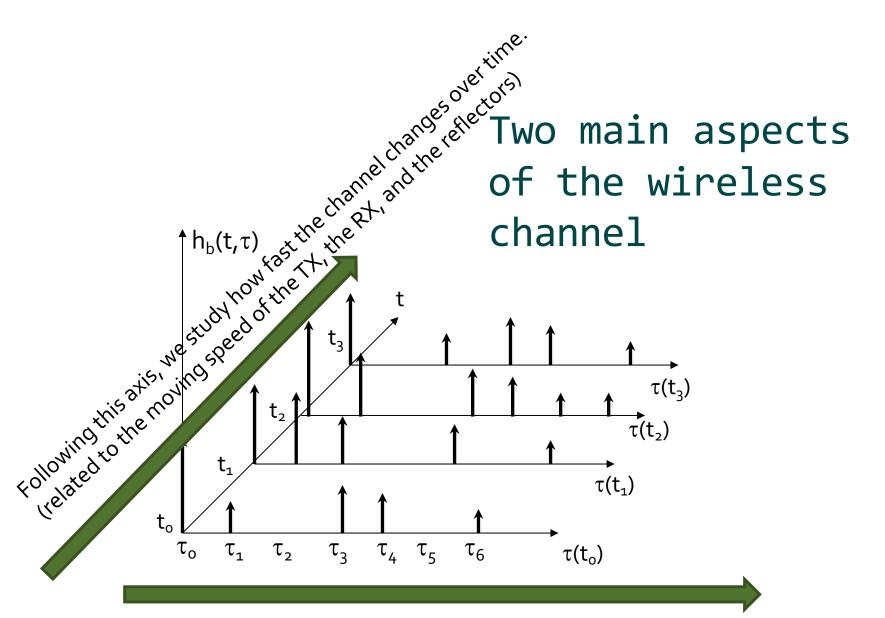
Summation over all MPC Additional phase change due to reflections

Additional phase change due to reflect the harmonic form 
$$h_b(t,\tau) = \sum_{i=0}^{N-1} a_i(t,\tau) \exp\left[-j\left\{2\pi f_c\tau(t_i) + \overline{\phi_i(t,\tau)}\right\}\right] \delta(t-\tau_i(t))$$

Amplitude change (mainly path loss) Phase change due to different arriving time

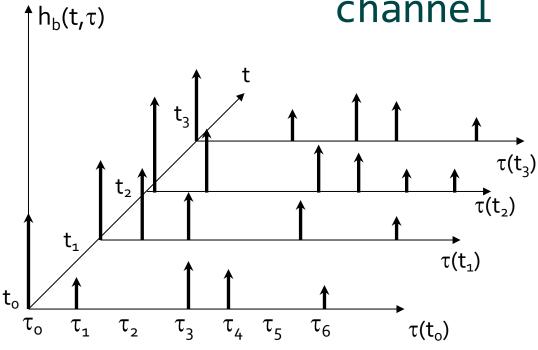
If assumed time-invariant (over a small-scale time or distance):

$$h_b(\tau) = \sum_{i=0}^{N-1} a_i \exp[-j\theta_i] \delta(\tau - \tau_i)$$



Following this axis, we study how "spread-out" the impulse response are. (related to the physical layout of the TX, the RX, and the reflectors at a single time point)

Two main aspects of the wireless channel



Following this axis, we study how "spread-out" the impulse response are. (related to the physical layout of the TX, the RX, and the reflectors at a single time point)

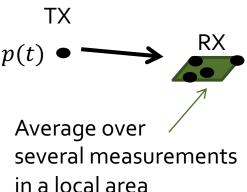
#### Power delay profile

• To predict  $h_b(\tau)$  a probing pulse p(t) is sent s.t.

$$p(t) \approx \delta(t - \tau)$$

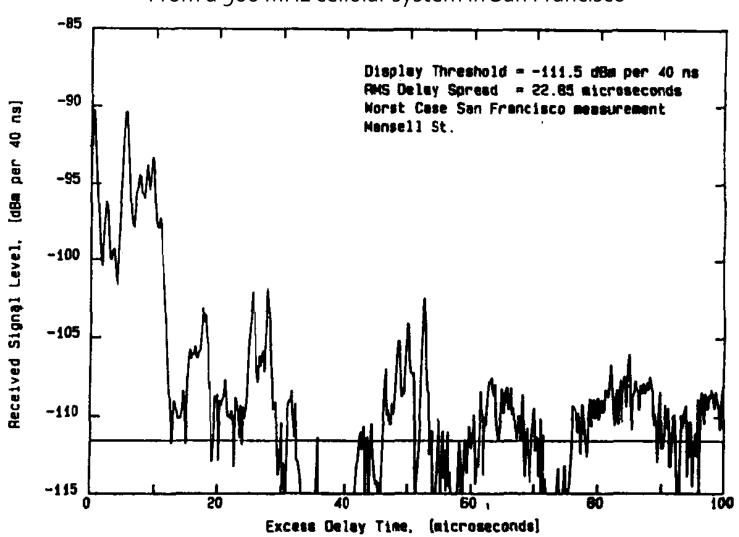
• Therefore, for small-scale channel modeling, POWER DELAY PROFILE is found by computing the spatial average of  $|h_B(t;\tau)|^2$  over a local area.

$$P(t;\tau) \approx k|h_b(t;\tau)|^2$$



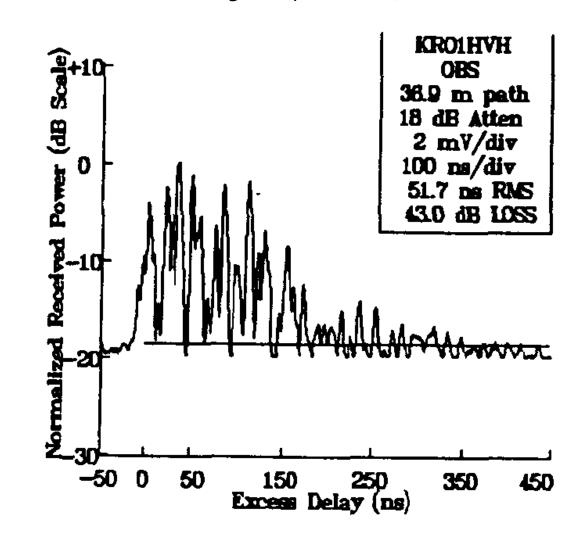
#### Example: power delay profile

From a 900 MHz cellular system in San Francisco



#### Example: power delay profile

Inside a grocery store at 4 GHz



#### Time dispersion parameters

- Power delay profile is a good representation of the average "geometry" of the transmitter, the receiver, and the reflectors.
- To quantify "how spread-out" the arriving signals are, we use time dispersion parameters:

Already talked about this

- Maximum excess delay: the excess delay of the latest arriving MPC
- Mean excess delay: the "mean" excess delay of all arriving MPC
- RMS delay spread: the "standard deviation" of the excess delay of all arriving MPC

#### Time dispersion parameters

Mean Excess Delay

First moment of the power delay profile

$$\overline{\tau} = \frac{\sum_{k} a_k^2 \tau_k}{\sum_{k} a_k^2} = \frac{\sum_{k} P(\tau_k) \tau_k}{\sum_{k} P(\tau_k)}$$

RMS Delay Spread

$$\sigma_{\tau} = \sqrt{\overline{\tau^2} - (\overline{\tau})^2}$$

Square root of the second central moment of the power delay profile

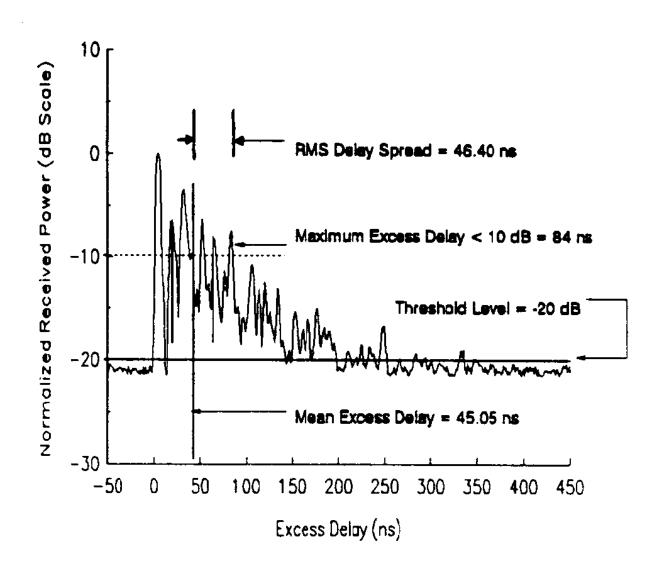
$$\overline{\tau^{2}} = \frac{\sum_{k} a_{k}^{2} \tau_{k}^{2}}{\sum_{k} a_{k}^{2}} = \frac{\sum_{k} P(\tau_{k}) \tau_{k}^{2}}{\sum_{k} P(\tau_{k})}$$

Second moment of the power delay profile

#### Time dispersion parameters

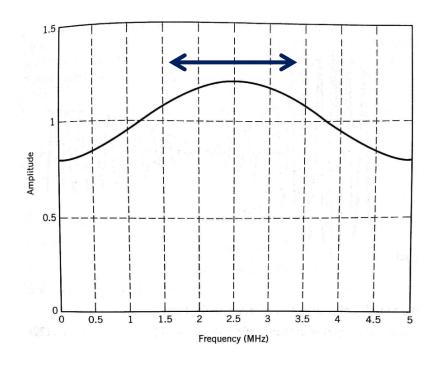
- Maximum Excess Delay:
  - Original version: the excess delay of the **latest** arriving MPC
  - In practice: the latest arriving could be smaller than the noise
  - No way to be aware of the "latest"
- Maximum Excess Delay (practical version):
  - The time delay during which multipath energy falls to X dB below the maximum.
- This X dB threshold could affect the values of the timedispersion parameters
  - Used to differentiate the noise and the MPC
  - Too low: noise is considered to be the MPC
  - Too high: Some MPC is not detected

# Example: Time dispersion parameters



#### Coherence Bandwidth

- Coherence bandwidth is a statistical measure of the range of frequencies over which the channel can be considered "flat"
  - → a channel passes all spectral components with approximately equal gain and linear phase.



#### Coherence Bandwidth

 Bandwidth over which Frequency Correlation function is above 0.9

$$B_c \approx \frac{1}{50\sigma_{\tau}}$$

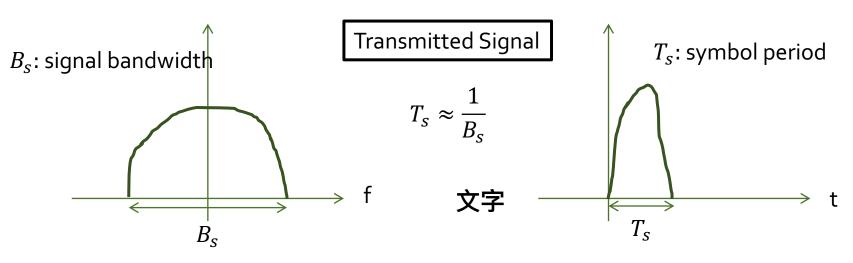
 Bandwidth over which Frequency Correlation function is above 0.5

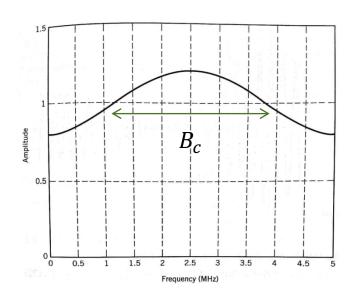
$$B_c \approx \frac{1}{5\sigma_{\tau}}$$

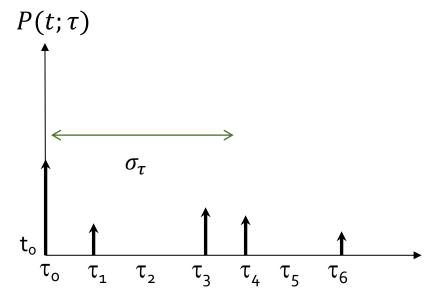
# Typical RMS delay spread values

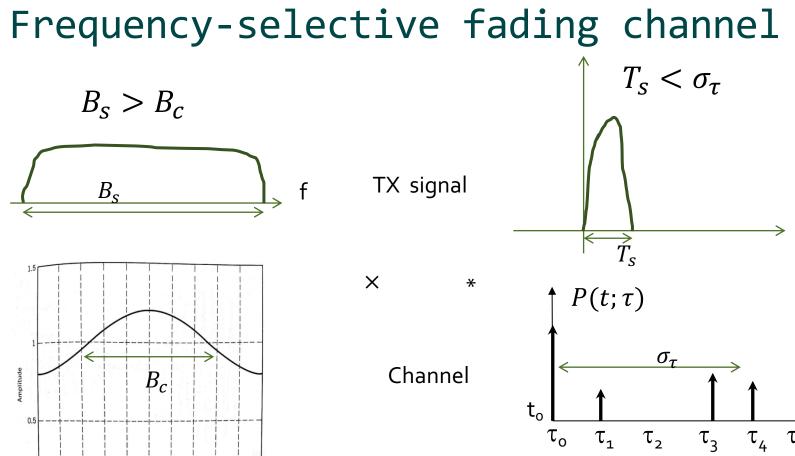
Environment	Frequency (MHz)	RMS Delay Spread (σ <sub>τ</sub> )	Notes	Reference
Urban	910	1300 ns avg. 600 ns st. dev. 3500 ns max.	New York City	[Cox75]
Urban	892	10-25 μs	Worst case San Francisco	[Rap90]
Suburban	910	200-310 ns	Averaged typical case	[Cox72]
Suburban	910	1960-2110 ns	Averaged extreme case	[Cox72]
Indoor	1500	10-50 ns 25 ns median	Office building	[Sal87]
Indoor	850	270 ns max.	Office building	[Dev90a]
Indoor	1900	70-94 ns avg. 1470 ns max.	Three San Francisco buildings	[Sei92a]

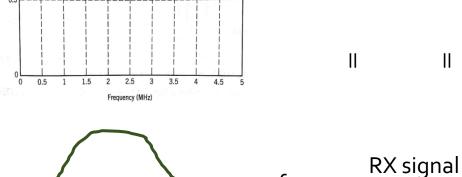
## Signal Bandwidth & Coherence Bandwidth

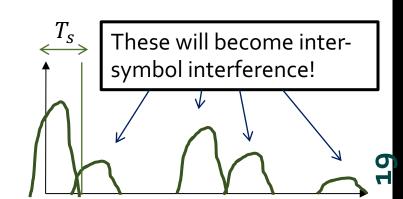




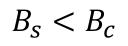


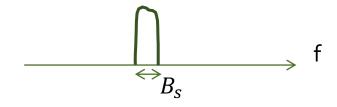






#### Flat fading channel



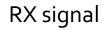


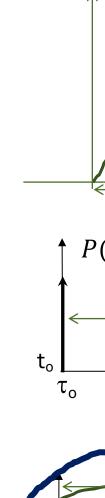
TX signal

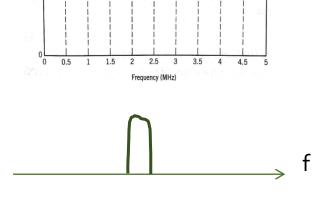


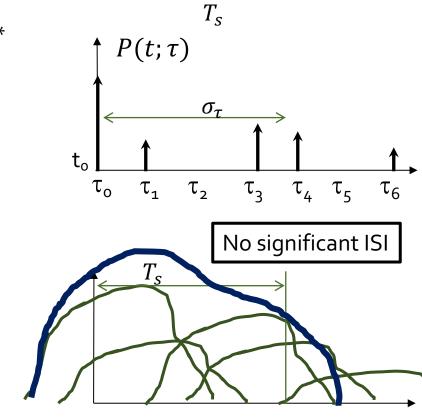










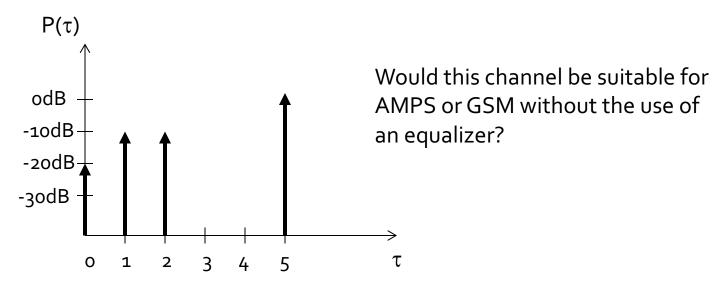


 $T_{\rm S} > \sigma_{\rm T}$ 

#### Equalizer 101

- An equalizer is usually used in a frequency-selective fading channel
  - When the coherence bandwidth is low, but we need to use high data rate (high signal bandwidth)
- Channel is unknown and time-variant
  - Step 1: TX sends a known signal to the receiver
  - Step 2: the RX uses the TX signal and RX signal to estimate the channel
  - Step 3: TX sends the real data (unknown to the receiver)
  - Step 4: the RX uses the estimated channel to process the RX signal
  - Step 5: once the channel becomes significantly different from the estimated one, return to step 1.

#### Example



Mean Excess Delay = 
$$\frac{1}{\tau} = \frac{\sum_{k} P(\tau_k) \tau_k}{\sum_{k} P(\tau_k)} = \frac{5(1) + 2(0.1) + 1(0.1) + 0(0.01)}{1 + 0.1 + 0.01} = 4.38 \,\mu\text{s}$$

$$\overline{\tau^2} = \frac{\sum_{k} P(\tau_k) \tau_k^2}{\sum_{k} P(\tau_k)} = \frac{(1)5^2 + (0.1)2^2 + (0.1)1^2 + (0.01)0^2}{1 + 0.1 + 0.01} = 21.07 \,\mu\text{s}^2$$

#### Example

• Therefore:

RMS Delay Spread = 
$$\sigma_{\tau} = \sqrt{\overline{\tau^2} - (\overline{\tau})^2} = \sqrt{21.07 - (4.38)^2} = 1.37 \,\mu\text{s}$$

Coherence Bandwidth = 
$$B_C = \frac{1}{5\sigma_{\tau}} = \frac{1}{5(1.37 \,\mu\text{s})} = 146 \text{KHz}$$

- Since B<sub>c</sub> > 3oKHz, AMPS would work without an equalizer.
- GSM requires 200 KHz BW >  $B_c \rightarrow$  An equalizer would be needed.