

ANNA SCAIFE  
JODRELL BANK CENTRE FOR ASTROPHYSICS

 @RADASTRAT

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# DATA-CENTRIC MACHINE LEARNING FOR SKA POST-PROCESSING

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# DATA-CENTRIC MACHINE LEARNING FOR SKA POST-PROCESSING

**Experimental  
Science**

**Theoretical  
Science**

**Computational  
Science**

**Data Intensive  
Science**



*time*

*adapted from a slide by Tony Hey*

**Experimental  
Science**

**Theoretical  
Science**

**Computational  
Science**

**Data Intensive  
Science**

*time*



Description  
of  
Natural  
Phenomena

*adapted from a slide by Tony Hey*

## **Experimental Science**

## **Theoretical Science**

## **Computational Science**

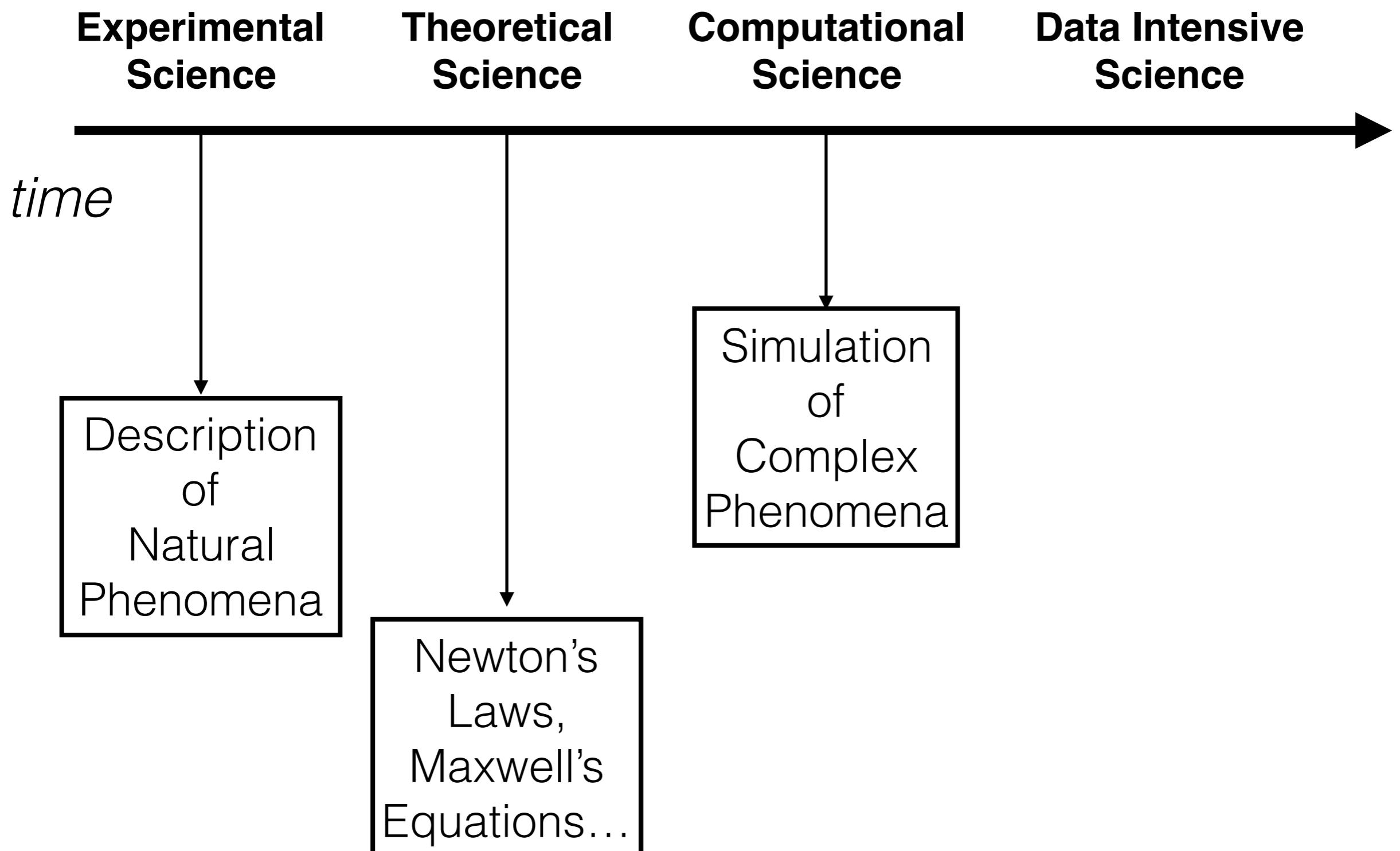
## **Data Intensive Science**

*time*

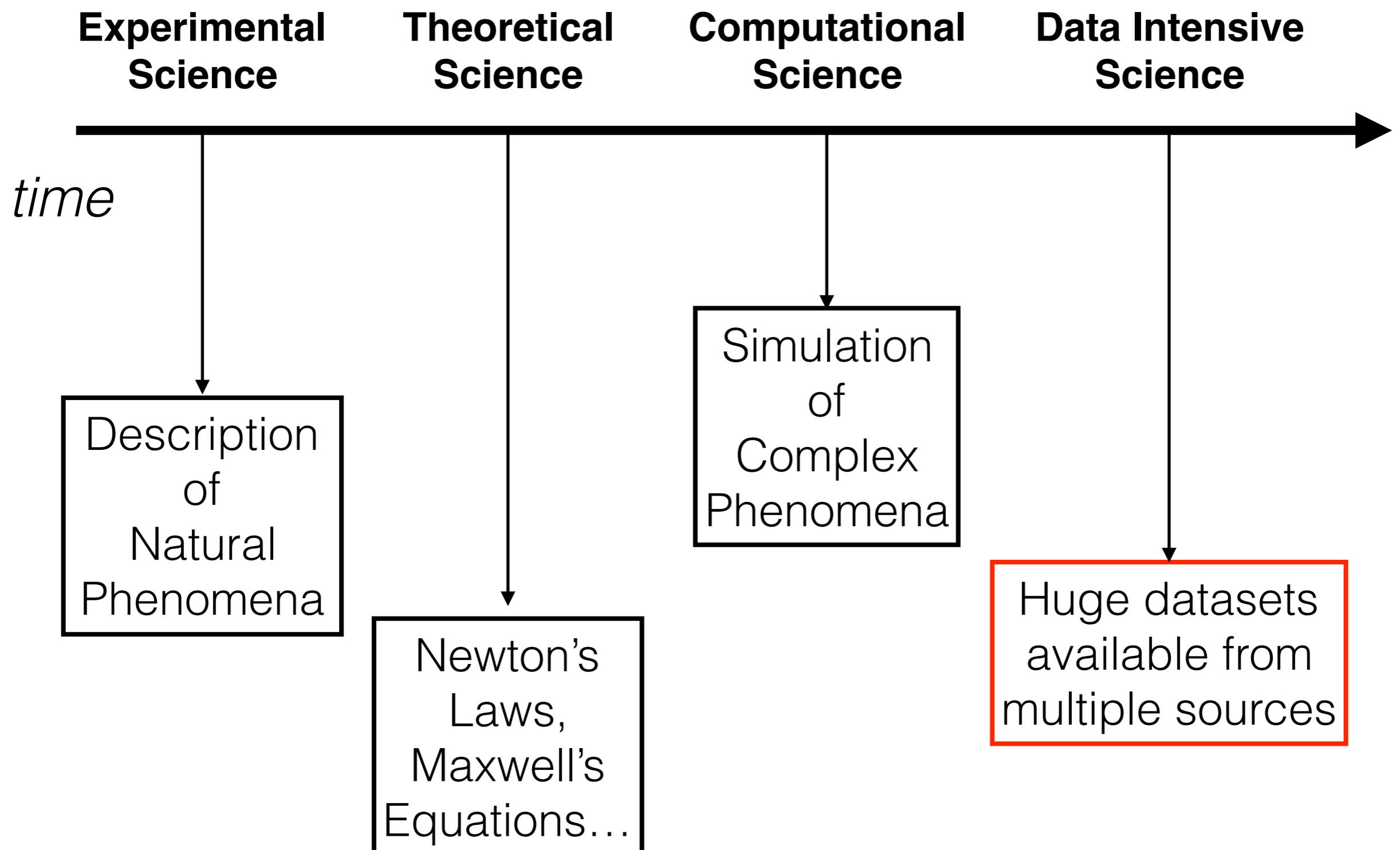
Description  
of  
Natural  
Phenomena

Newton's  
Laws,  
Maxwell's  
Equations...

*adapted from a slide by Tony Hey*



*adapted from a slide by Tony Hey*



*adapted from a slide by Tony Hey*

Too much data is as bad as none at all...

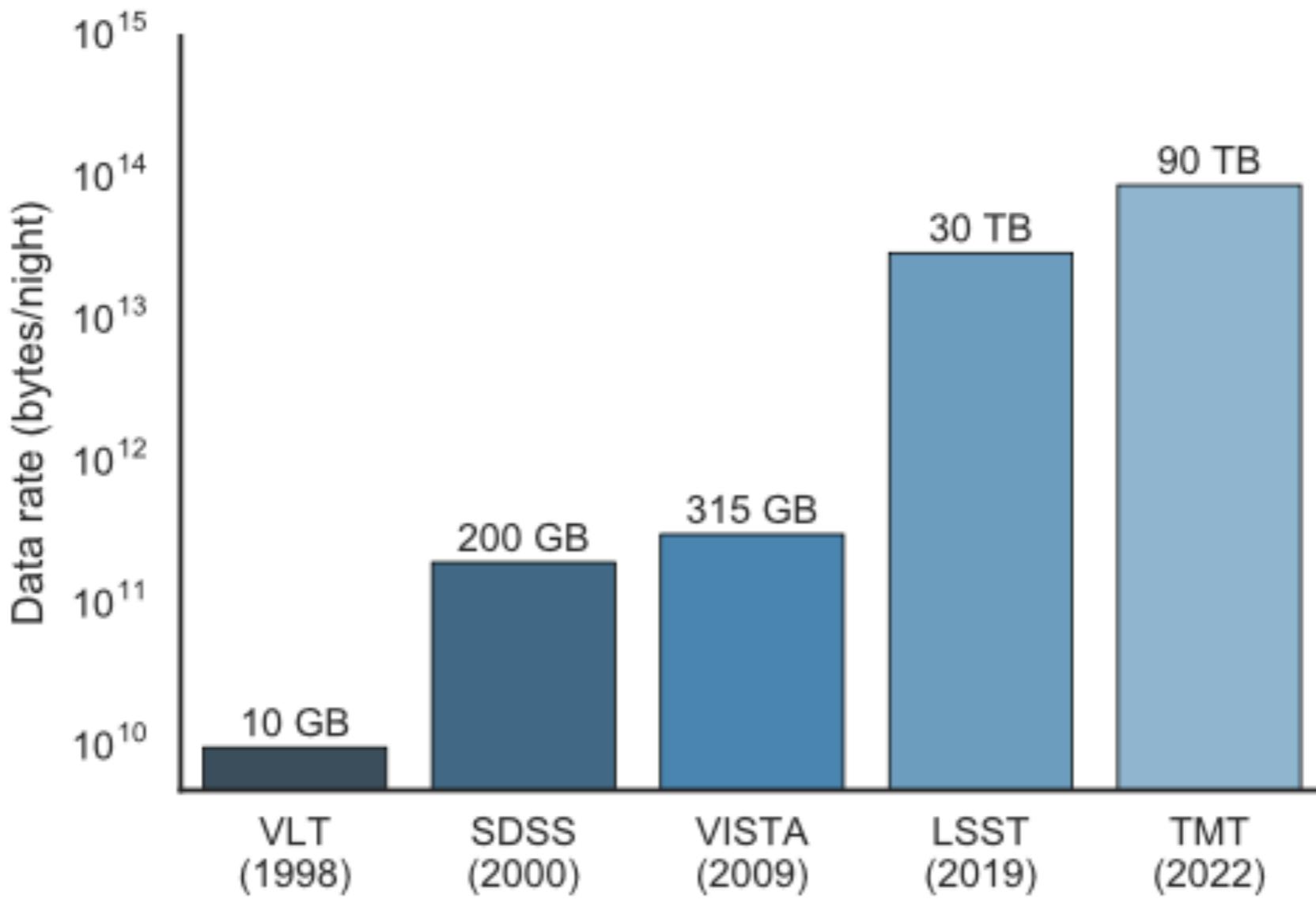
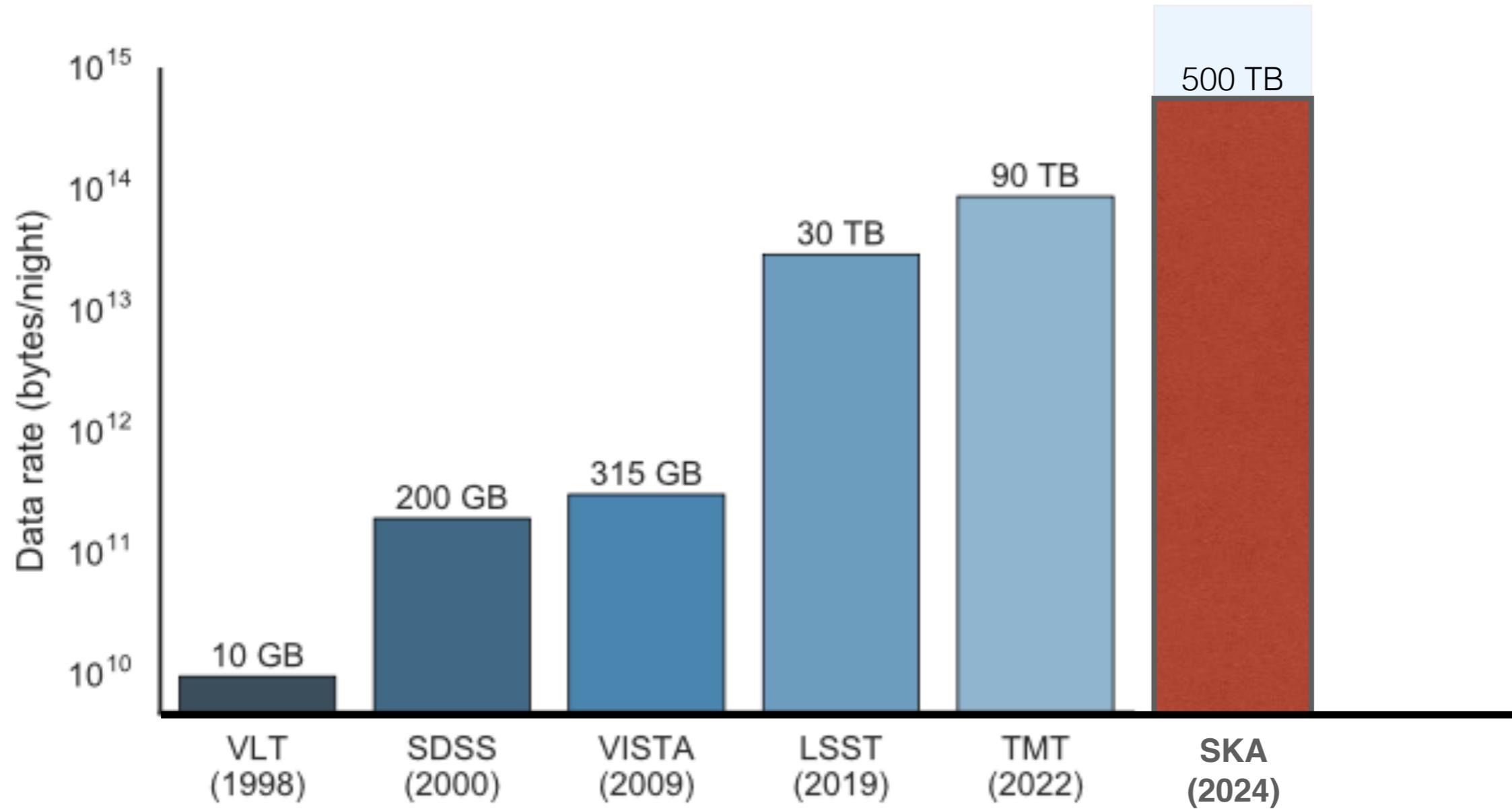


Figure 1: Increasing data volumes of existing and upcoming telescopes: Very Large Telescope (VLT), Sloan Digital Sky Survey (SDSS), Visible and Infrared Telescope for Astronomy (VISTA), Large Synoptic Survey Telescope (LSST) and Thirty Meter Telescope (TMT).

...and then there's the SKA.



*adapted from Kremer et al. 2017 arXiv:1704.04650*

AMAZING

1

SKA FACT

The data collected by the SKA in a single day would take nearly *two million years* to playback on an ipod.

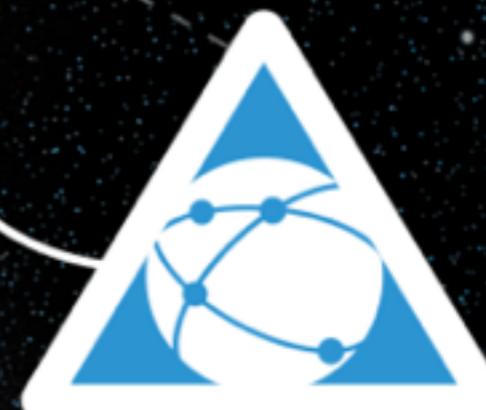


AMAZING

4

SKA FACT

The dishes of the SKA will produce  
*10 times* the global internet traffic.



10x



Let's face it,  
we're not going to be looking  
at it all by eye.

#CHPCNITHEP2019

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#CHPCNITHEP2019

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# Global Network of SKA Regional Centres



WHEN A USER TAKES A PHOTO,  
THE APP SHOULD CHECK WHETHER  
THEY'RE IN A NATIONAL PARK...

SURE, EASY GIS LOOKUP.  
GIMME A FEW HOURS.

... AND CHECK WHETHER  
THE PHOTO IS OF A BIRD.

I'LL NEED A RESEARCH  
TEAM AND FIVE YEARS.



IN CS, IT CAN BE HARD TO EXPLAIN  
THE DIFFERENCE BETWEEN THE EASY  
AND THE VIRTUALLY IMPOSSIBLE.

WHEN AN ASTRONOMER TAKES AN  
OBSERVATION THE APP SHOULD CHECK  
WHETHER THEY'RE LOOKING OUT OF  
THE GALACTIC PLANE

SURE, EASY POINTING  
LOOKUP. GIMME A FEW HOURS

...AND AUTOMATICALLY  
CLASSIFY ALL THE OBJECTS  
IN THE FIELD

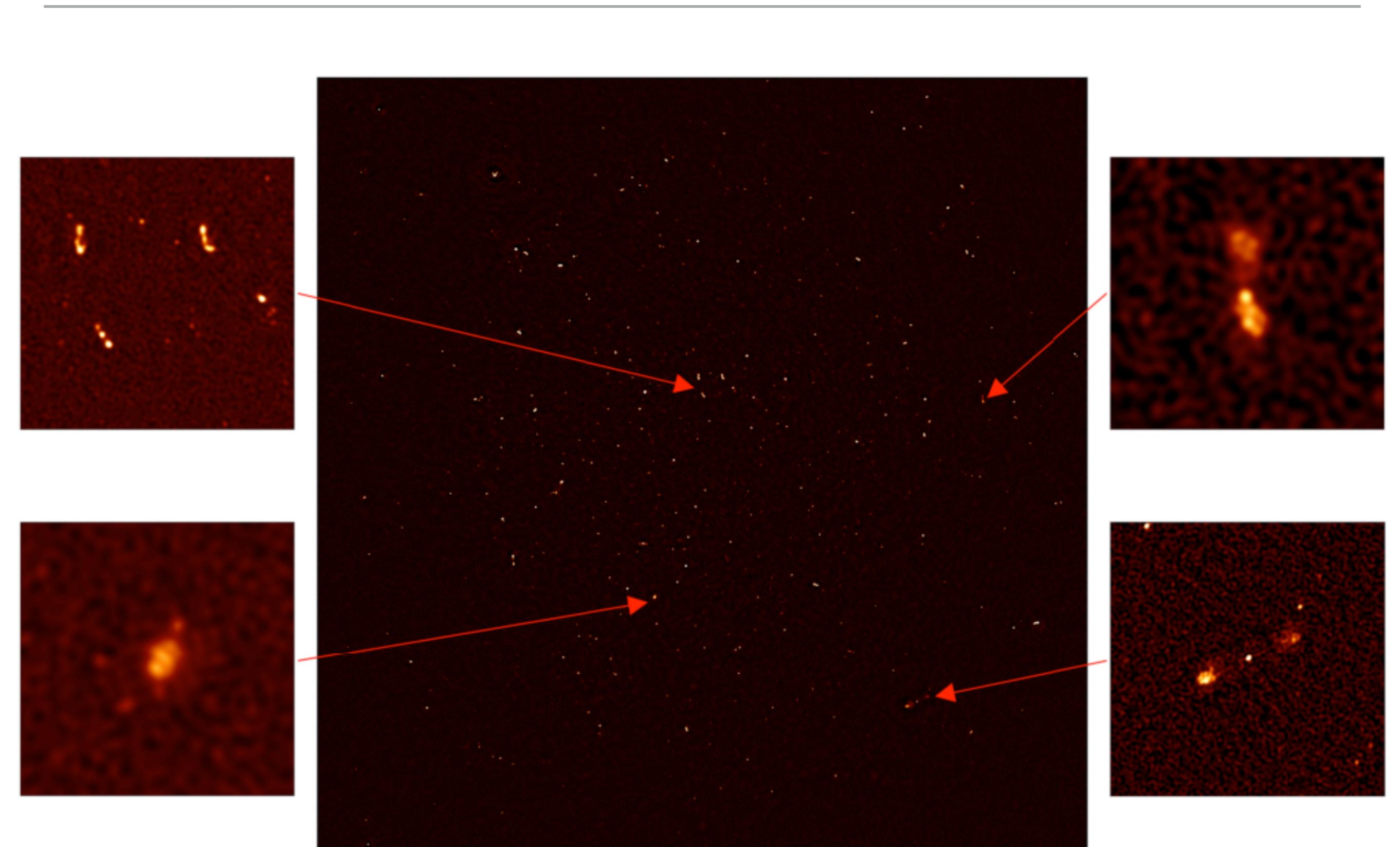
I'LL NEED A RESEARCH TEAM  
AND THE REST OF MY CAREER.

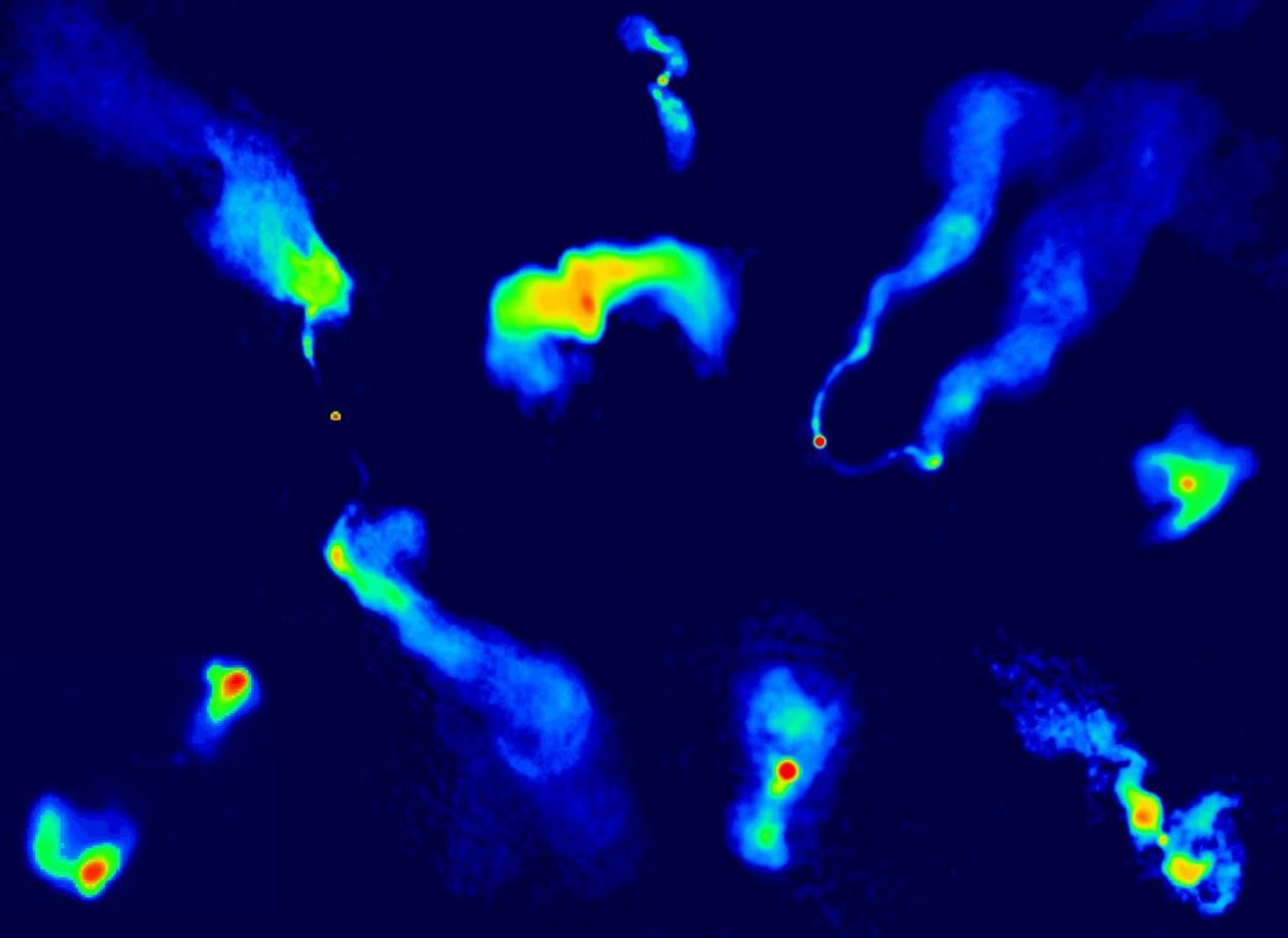


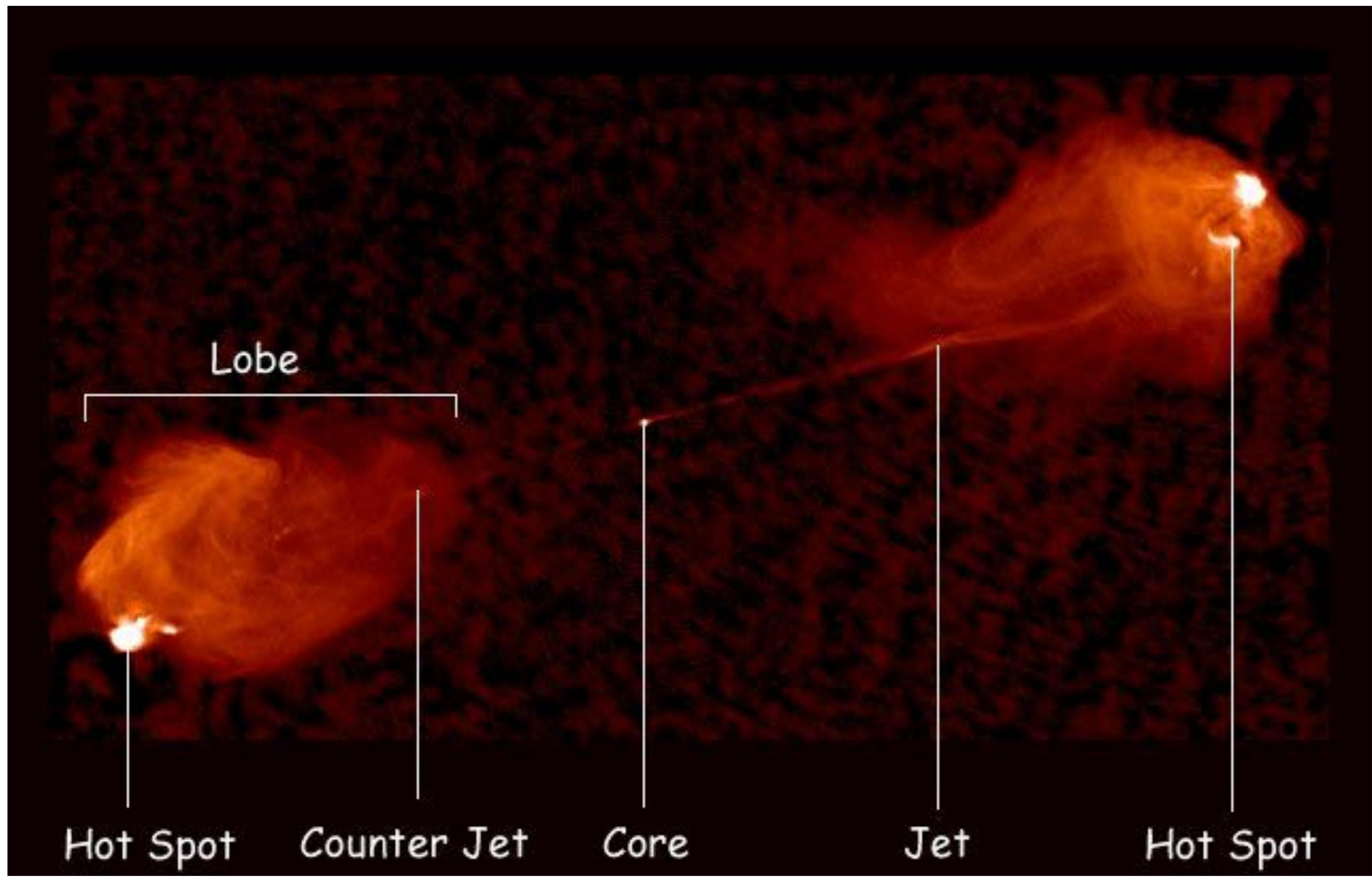
IN ASTRONOMY SUPPORT, IT CAN BE HARD TO EXPLAIN  
THE DIFFERENCE BETWEEN THE EASY  
AND THE VIRTUALLY IMPOSSIBLE.

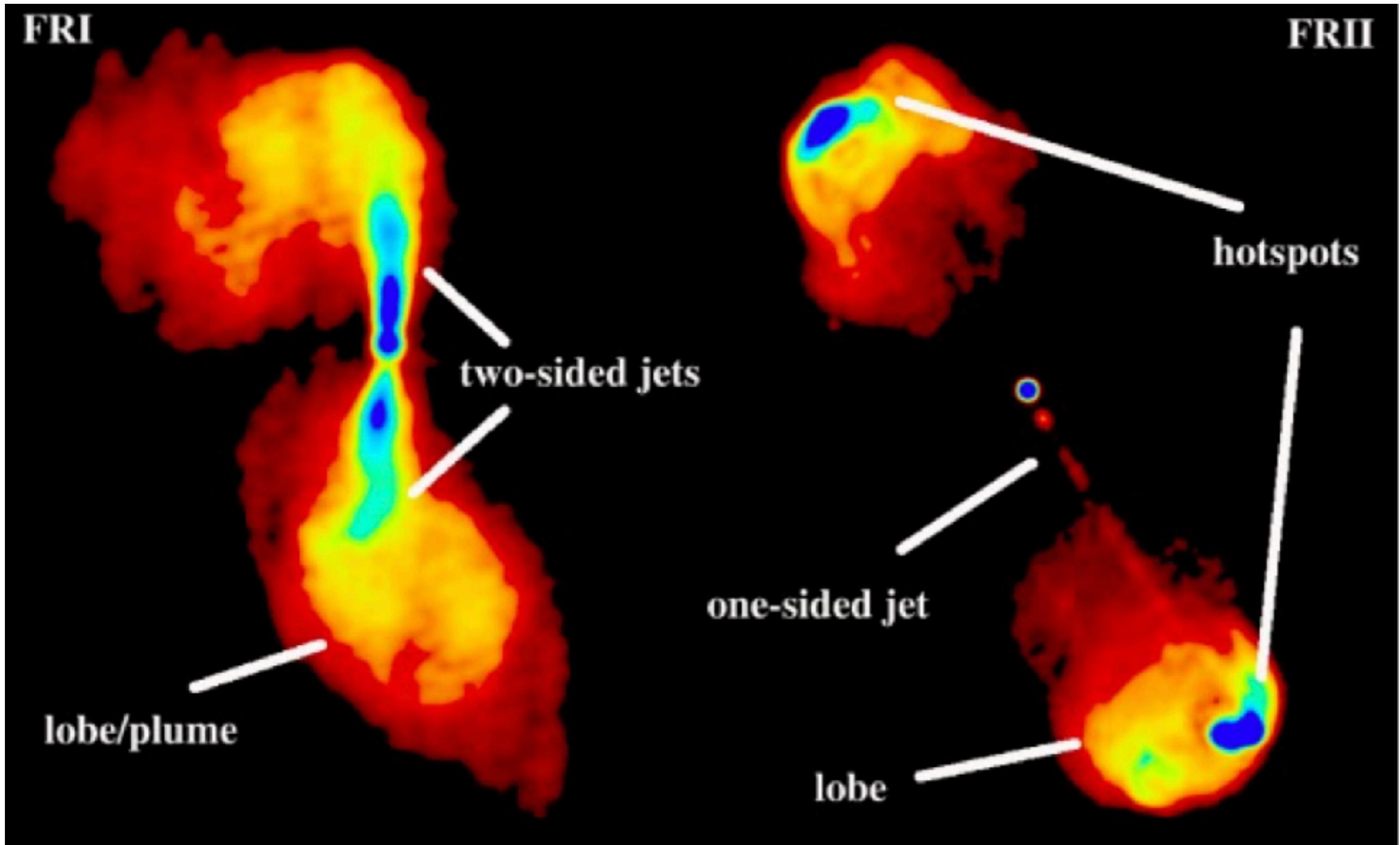


MeerKAT First Light: South African Radio Astronomy Observatory







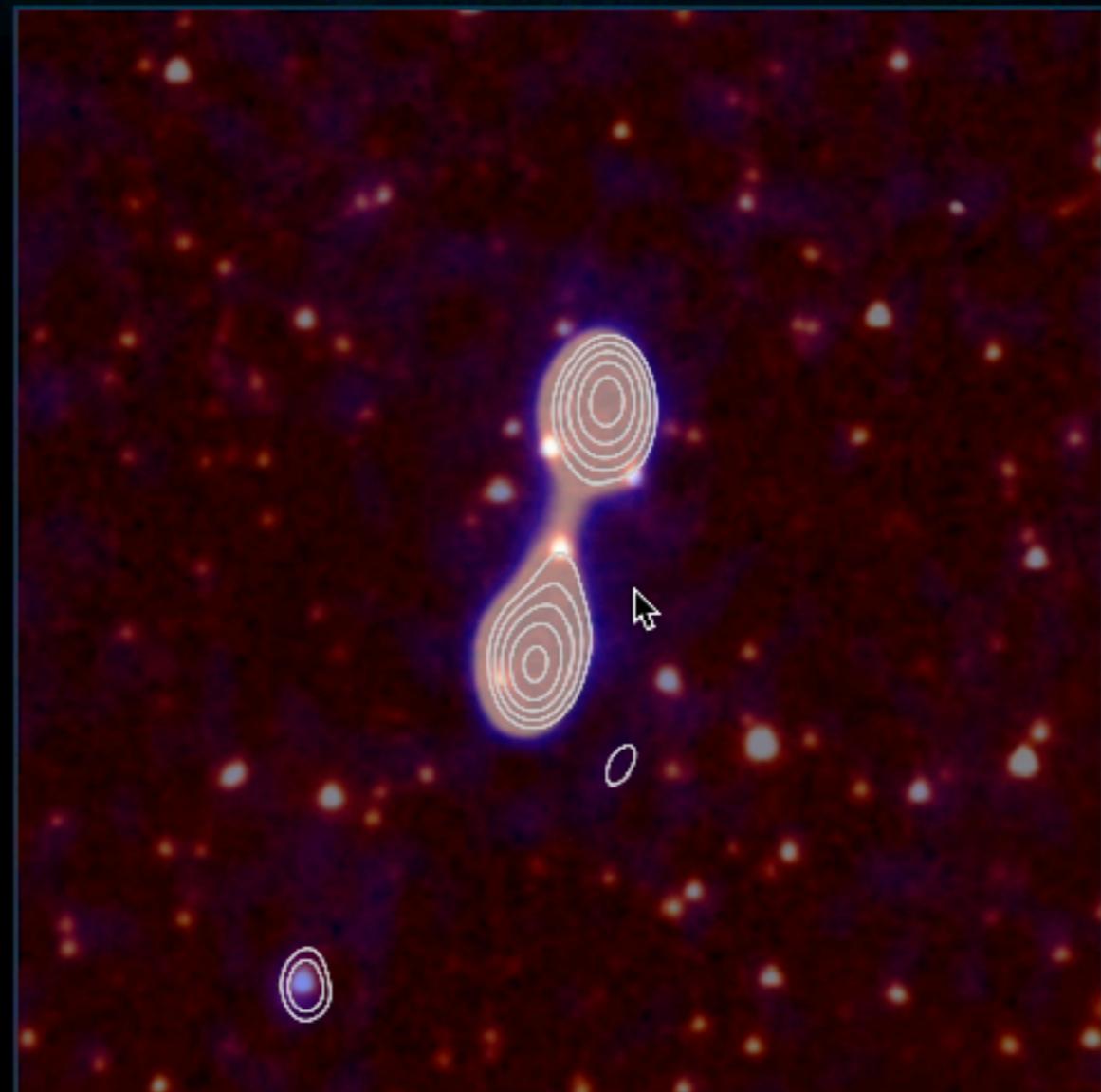


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<https://radio.galaxyzoo.org>

# GALAXY ZOO

## RADIO

[Radio](#)[IR](#)

Click on any radio contour or pair of jets

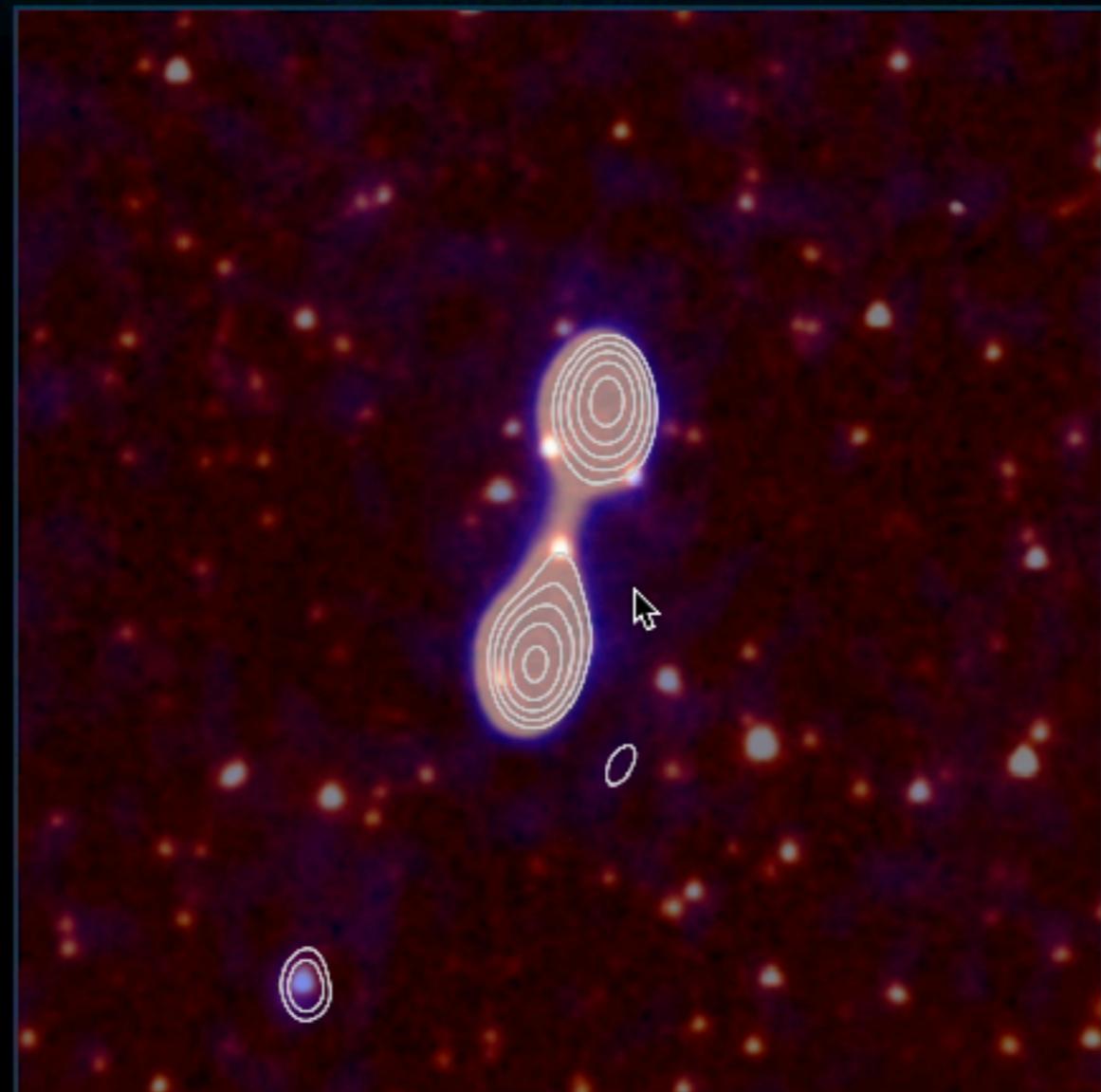
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## RADIO

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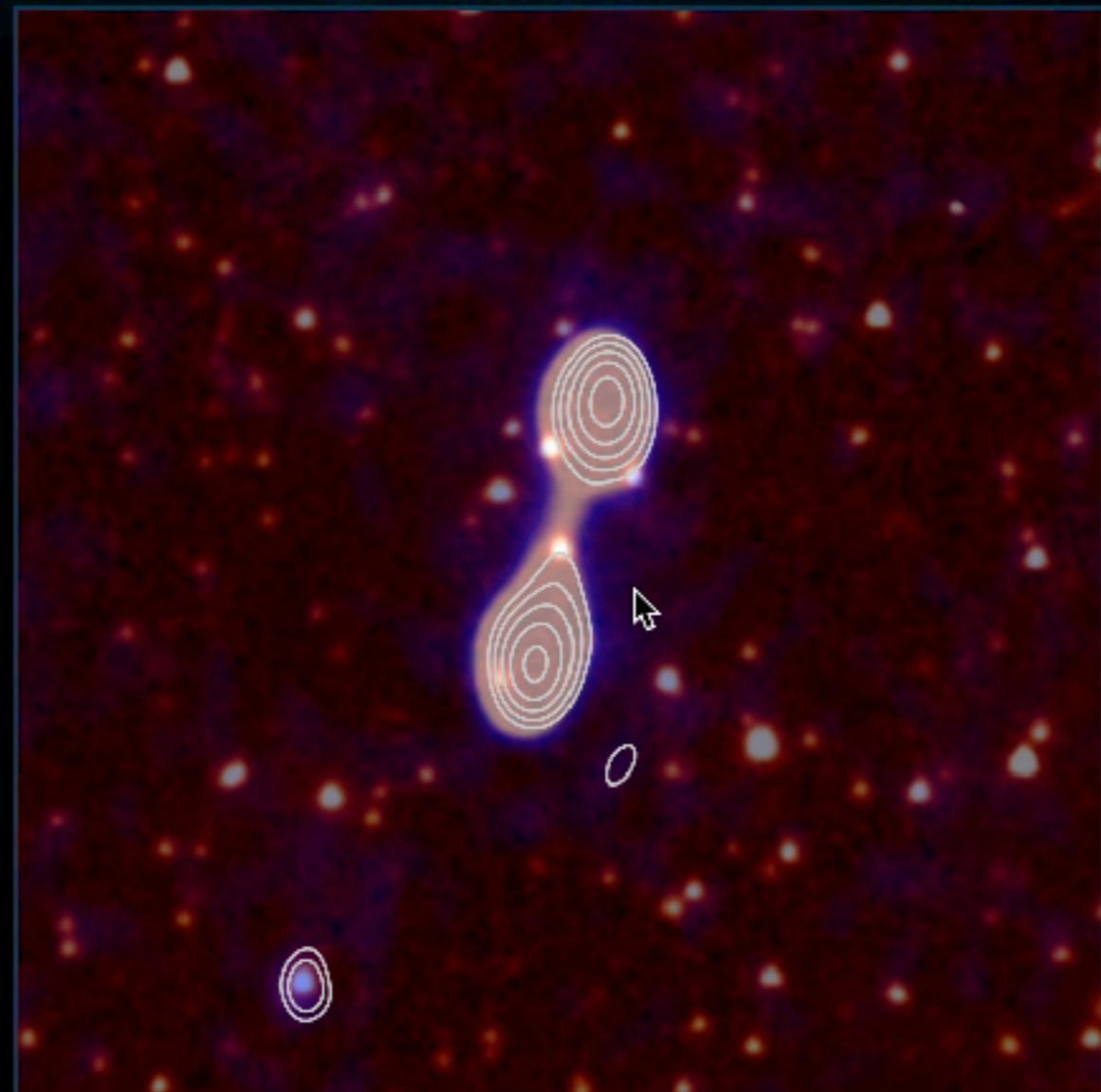
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## RADIO

[Radio](#)[IR](#)

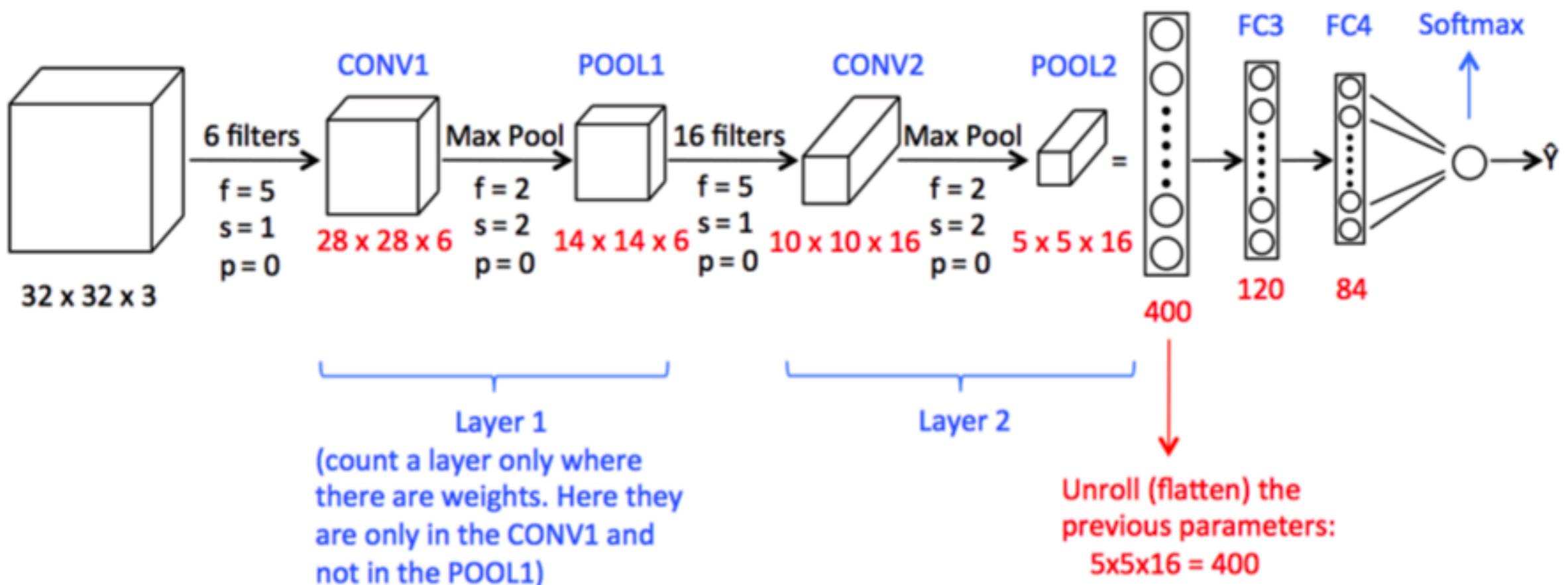
Click on any radio contour or pair of jets

[Cancel](#)[Reset All](#)[No Contours](#)[Done](#)

# CONVOLUTIONAL NEURAL NETWORKS

3 basic types of layer:

- Convolutional Layer
  - ReLu Layer
- Pooling Layer
- Fully-Connected Layer



R

Input Volume (+pad 1) (7x7x3)  
 $x[:, :, 0]$

0	0	0	0	0	0	0	0
0	2	2	1	2	2	0	0
0	0	1	0	2	1	0	0
0	1	0	1	2	2	0	0
0	1	2	2	2	0	0	0
0	1	0	0	0	1	0	0
0	0	0	0	0	0	0	0

G

$x[:, :, 1]$

0	0	0	0	0	0	0	0
0	0	1	1	0	2	0	0
0	0	0	0	0	0	0	0
0	2	0	2	2	0	0	0
0	2	1	1	2	2	0	0
0	0	2	2	1	2	0	0
0	0	0	0	0	0	0	0

B

$x[:, :, 2]$

0	0	0	0	0	0	0	0
0	1	1	1	2	0	0	0
0	1	1	2	0	0	0	0
0	1	2	1	0	1	0	0
0	2	2	0	2	2	0	0
0	0	0	2	1	2	0	0
0	0	0	0	0	0	0	0

Filter W0 (3x3x3)  
 $w0[:, :, 0]$

1	1	-1
-1	0	0
1	1	0

$w0[:, :, 1]$

-1	1	-1
1	-1	1
0	1	0

$w0[:, :, 2]$

1	-1	-1
-1	1	0
-1	-1	-1

Filter W1 (3x3x3)  
 $w1[:, :, 0]$

1	0	1
0	-1	1
0	0	1

$w1[:, :, 1]$

0	-1	-1
0	1	1
1	-1	-1

$w1[:, :, 2]$

0	1	0
-1	0	0
0	1	0

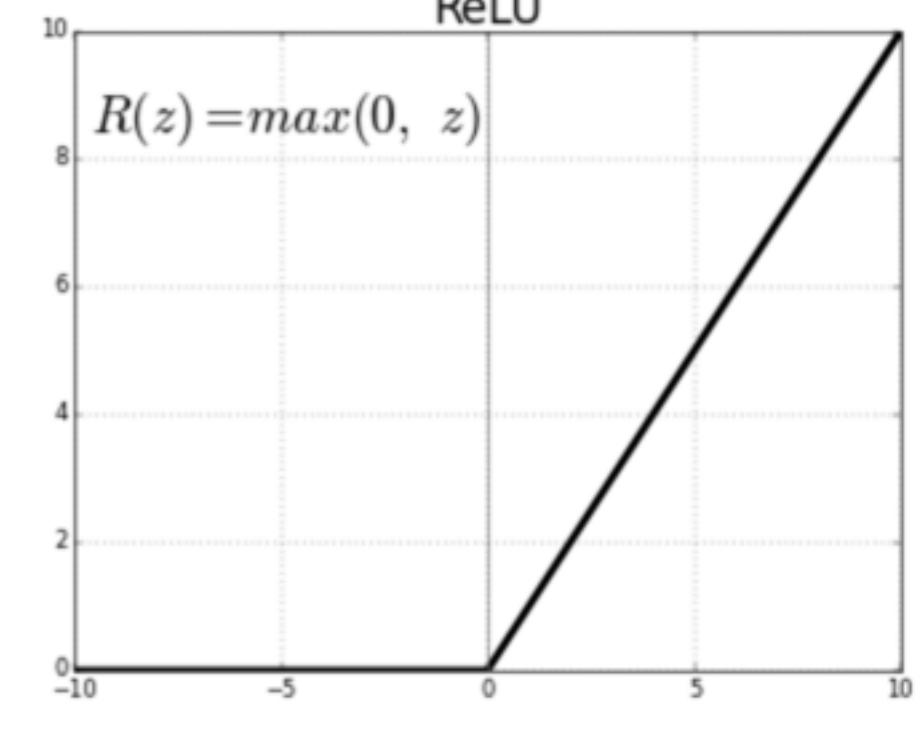
Output Volume (3x3x2)  
 $o[:, :, 0]$

1	-3	-2
-4	-1	5
-1	4	3

$o[:, :, 1]$

3	5	-2
4	8	2
2	4	2

ReLU



R

Input Volume (+pad 1) (7x7x3)  
 $x[:, :, 0]$

0	0	0	0	0	0	0	0
0	2	2	1	2	2	0	0
0	0	1	0	2	1	0	0
0	1	0	1	2	2	0	0
0	1	2	2	2	0	0	0
0	1	0	0	0	1	0	0
0	0	0	0	0	0	0	0

G

$x[:, :, 1]$

0	0	0	0	0	0	0	0
0	0	1	1	0	2	0	0
0	0	0	0	0	0	0	0
0	2	0	2	2	0	0	0
0	2	1	1	2	2	0	0
0	0	2	2	1	2	0	0
0	0	0	0	0	0	0	0

B

$x[:, :, 2]$

0	0	0	0	0	0	0	0
0	1	1	1	2	0	0	0
0	1	1	2	0	0	0	0
0	1	2	1	0	1	0	0
0	2	2	0	2	2	0	0
0	0	0	2	1	2	0	0
0	0	0	0	0	0	0	0

Filter W0 (3x3x3)  
 $w0[:, :, 0]$

1	1	-1
-1	0	0
1	1	0

$w0[:, :, 1]$

-1	1	-1
1	-1	1
0	1	0

$w0[:, :, 2]$

1	-1	-1
-1	1	0
-1	-1	-1

Filter W1 (3x3x3)  
 $w1[:, :, 0]$

1	0	1
0	-1	1
0	0	1

$w1[:, :, 1]$

0	-1	-1
0	1	1
1	-1	-1

$w1[:, :, 2]$

0	1	0
-1	0	0
0	1	0

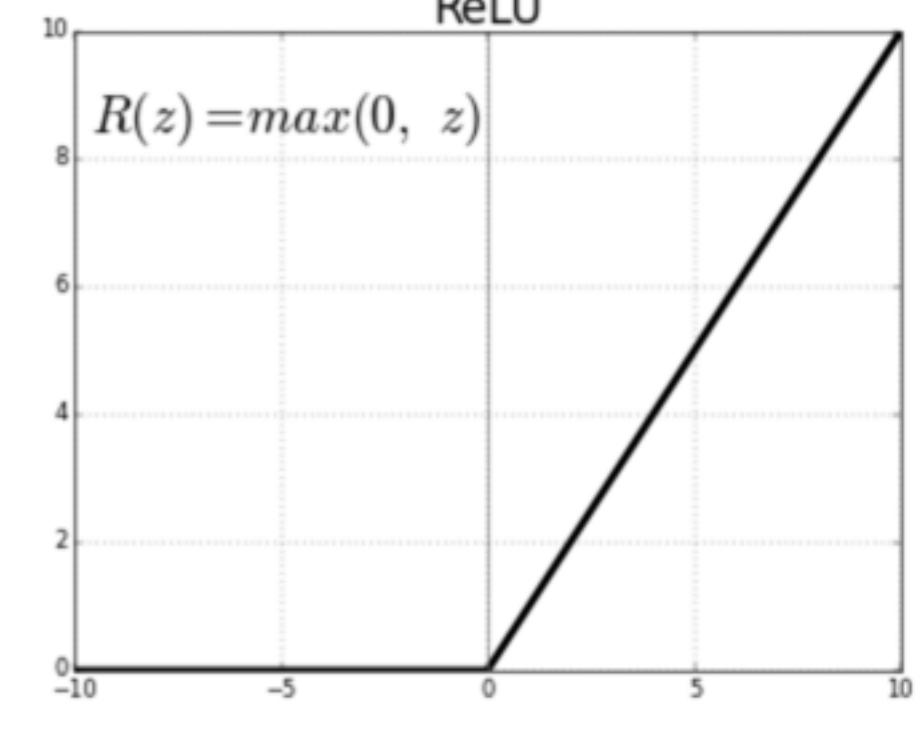
Output Volume (3x3x2)  
 $o[:, :, 0]$

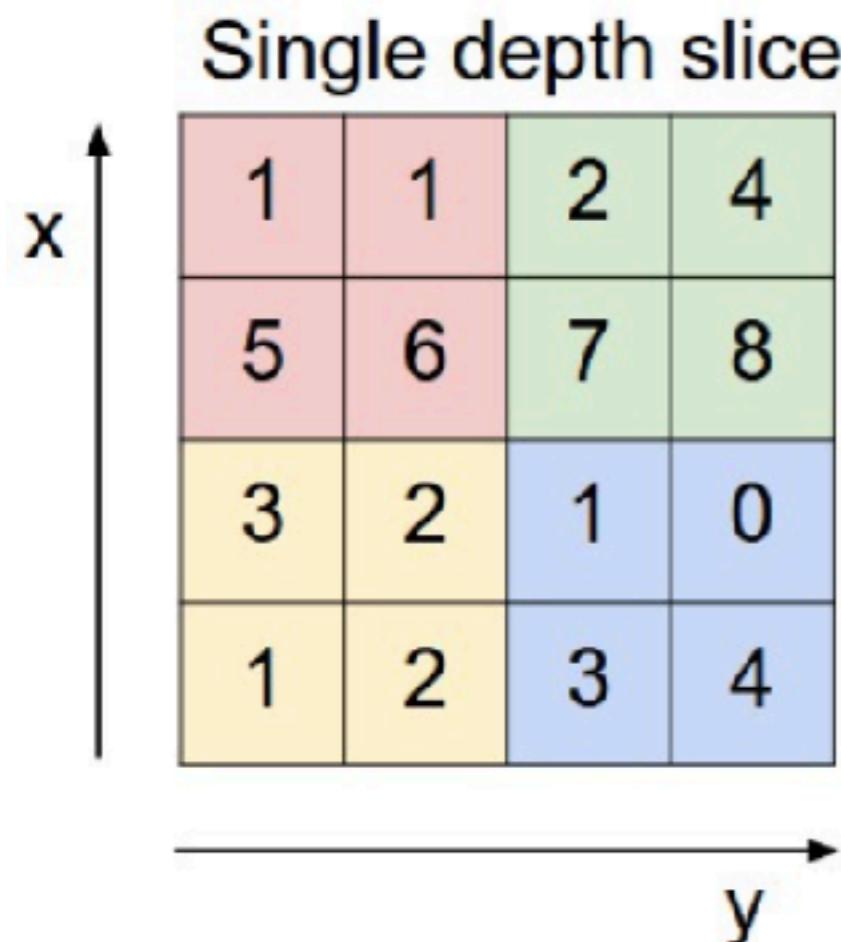
1	-3	-2
-4	-1	5
-1	4	3

$o[:, :, 1]$

3	5	-2
4	8	2
2	4	2

ReLU





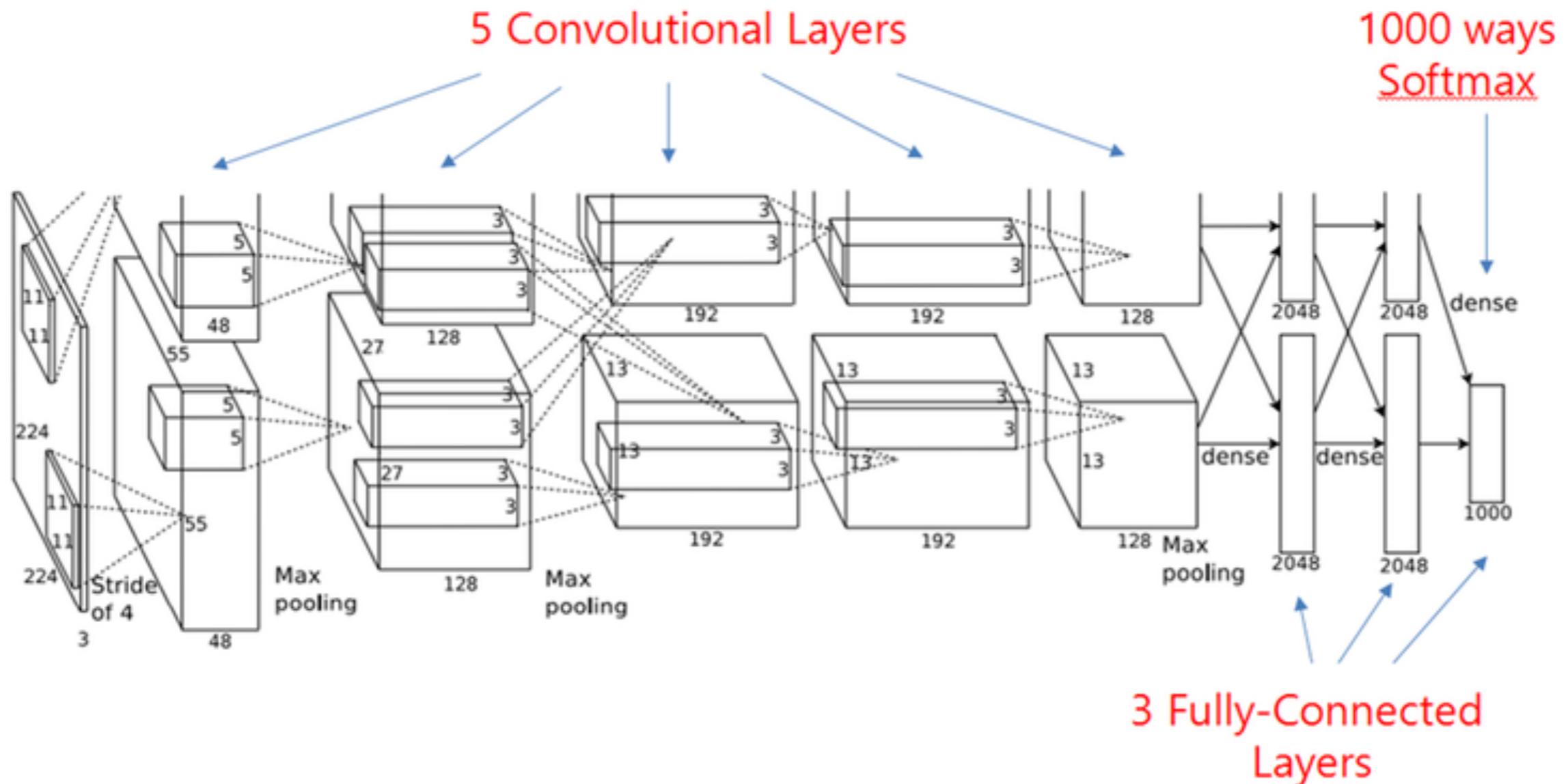
max pool with 2x2 filters  
and stride 2

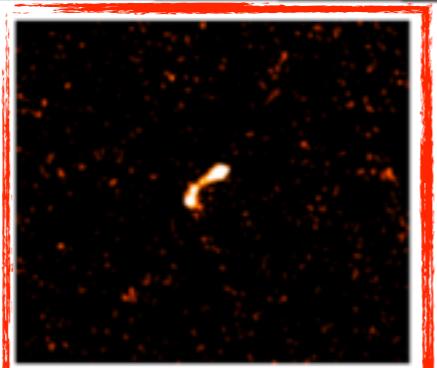
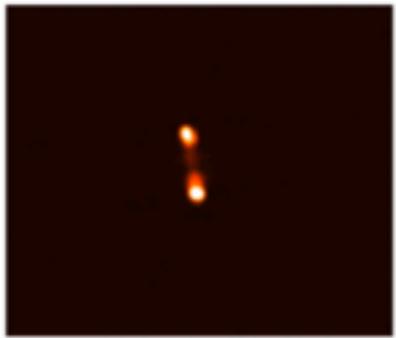
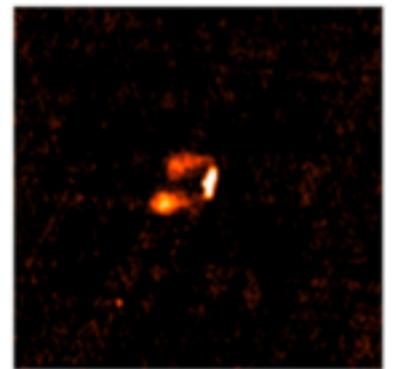
6	8
3	4

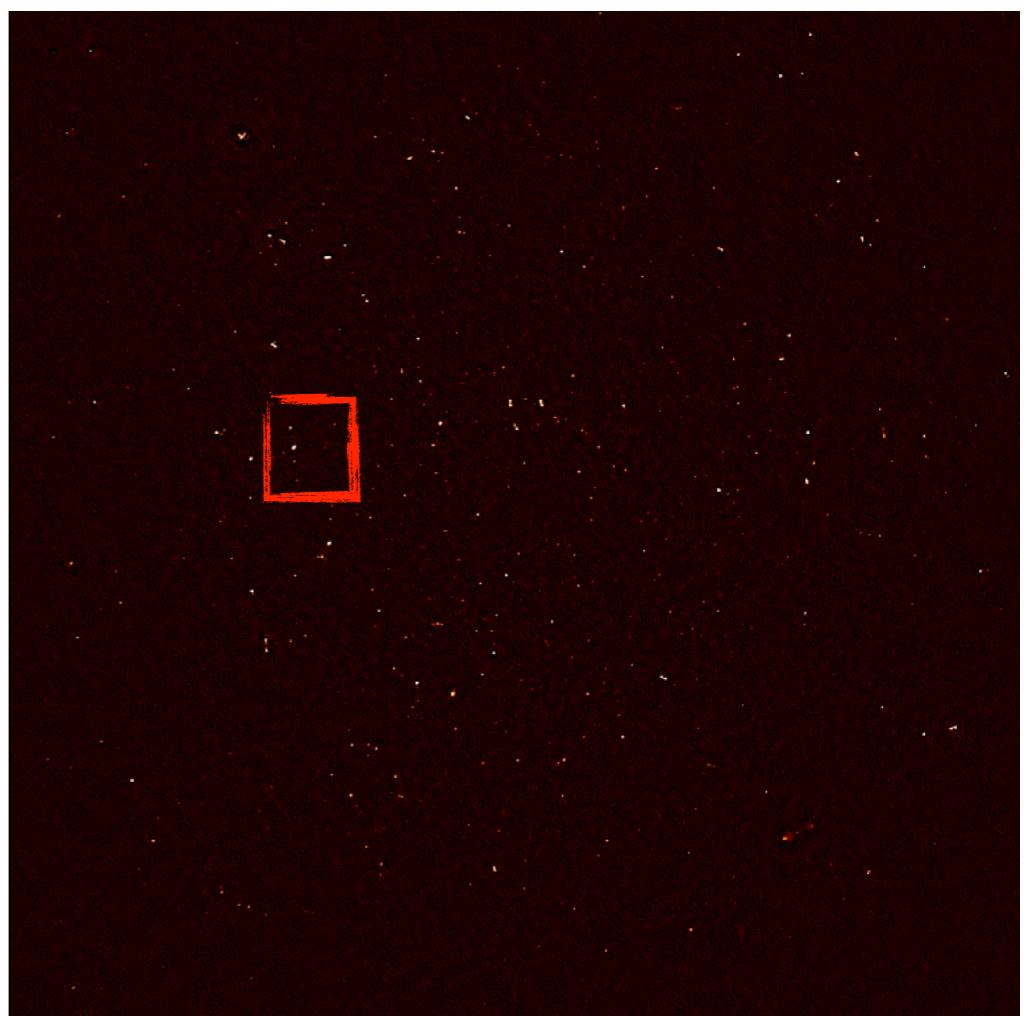
# CONVOLUTIONAL NEURAL NETWORKS

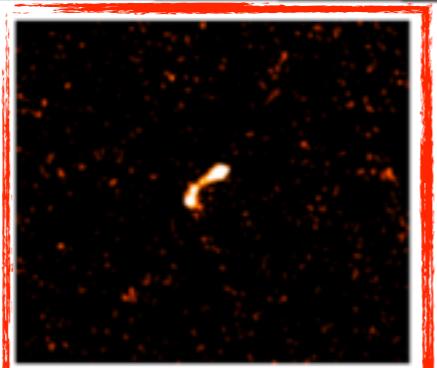
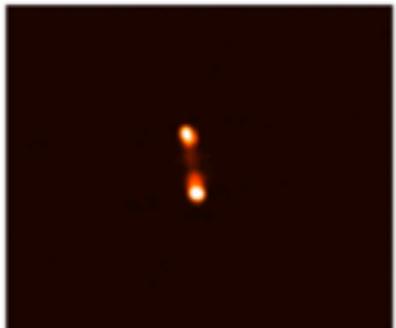
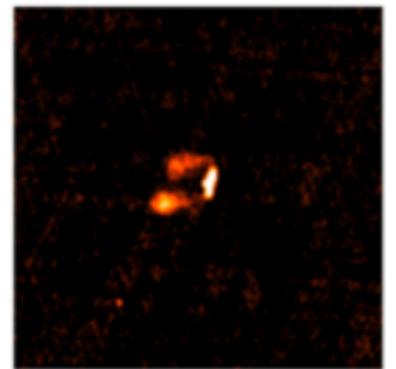
- **LeNet.** The first successful applications of Convolutional Networks were developed by Yann LeCun in 1990's.
- **AlexNet.** The first work that popularized Convolutional Networks in Computer Vision. Very similar architecture to LeNet, but deeper, bigger, and with stacked Convolutional Layers.
- **ZFNet.** An improvement on AlexNet by tweaking the architecture hyperparameters, in particular by expanding the size of the middle convolutional layers and making the stride and filter size on the first layer smaller.
- **GoogLeNet.** Includes the Inception Module that dramatically reduced the number of parameters in the network (4M, compared to AlexNet with 60M). Uses Average Pooling instead of Fully Connected layers at the top of the ConvNet, eliminating a large number of low ranked parameters.
- **VGGNet.** Showed that the depth of the network is a critical component for good performance. An extremely homogeneous architecture that only performs 3x3 convolutions and 2x2 pooling from the beginning to the end.
- **ResNet.** Features special skip connections and a heavy use of batch normalization. ResNets are currently the default state of the art Convolutional Neural Network model.

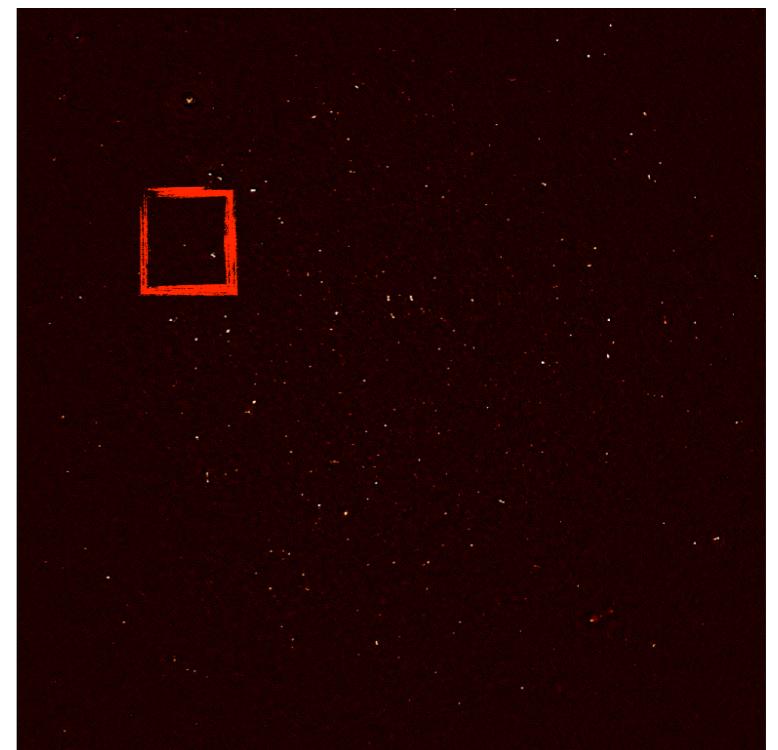
# ALEXNET



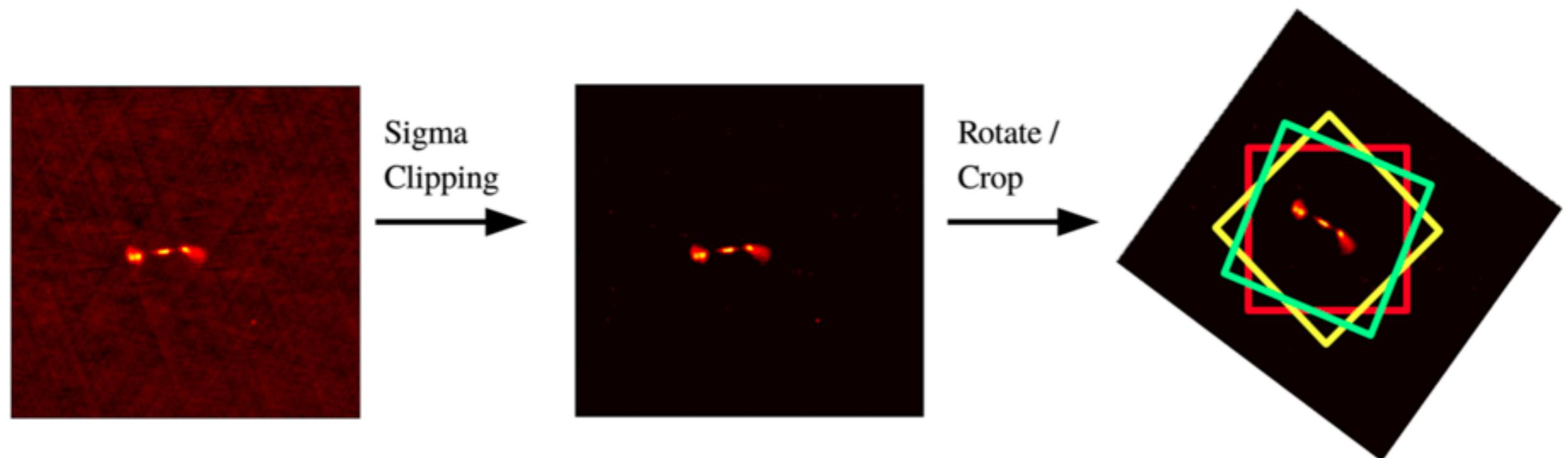
Name, Coordinates	Source Image	Class True / Predicted
J101937.94+001955.7  10 19 37.94 +00 19 55.7		FRI / FRI
3C 228  09 50 10.77 +14 19 57.3		FRII / FRII
J092645.3+030916  09 47 15.887 +52 51 05.20		BENT / BENT



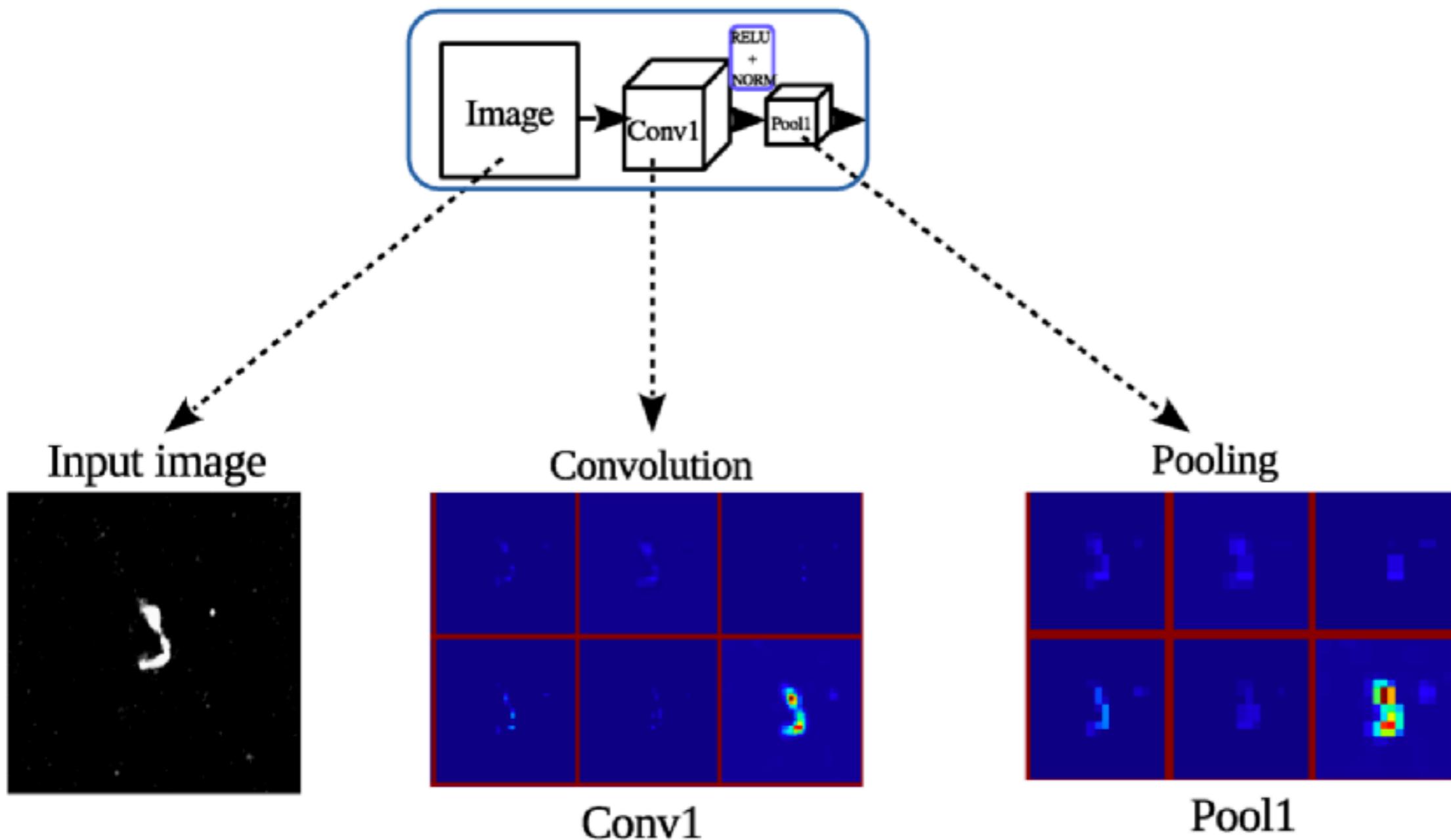
Name, Coordinates	Source Image	Class True / Predicted
J101937.94+001955.7  10 19 37.94 +00 19 55.7		FRI / FRI
3C 228  09 50 10.77 +14 19 57.3		FRII / FRII
J092645.3+030916  09 47 15.887 +52 51 05.20		BENT / BENT



# RADIO GALAXY CLASSIFICATION

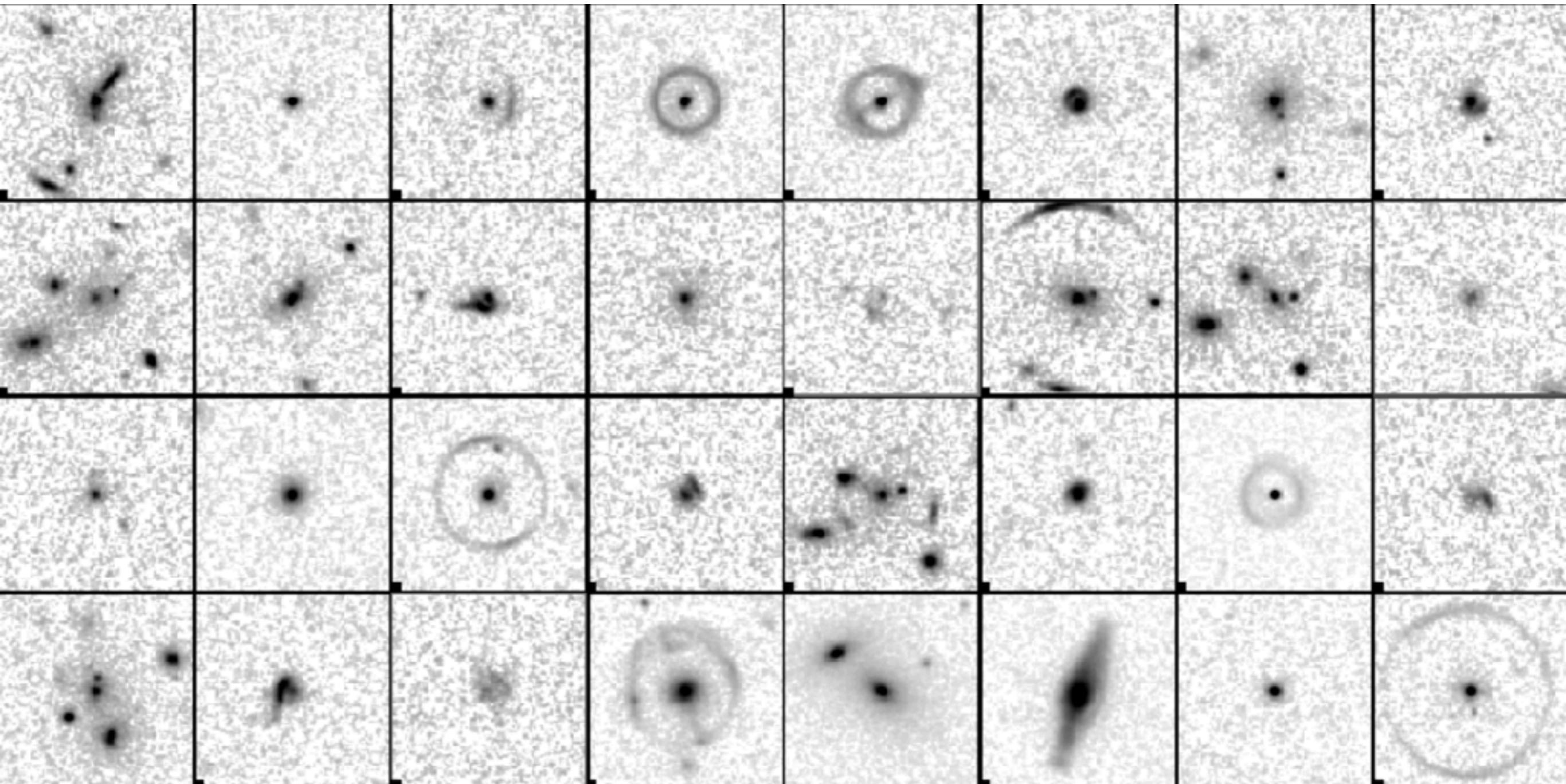


# RADIO GALAXY CLASSIFICATION



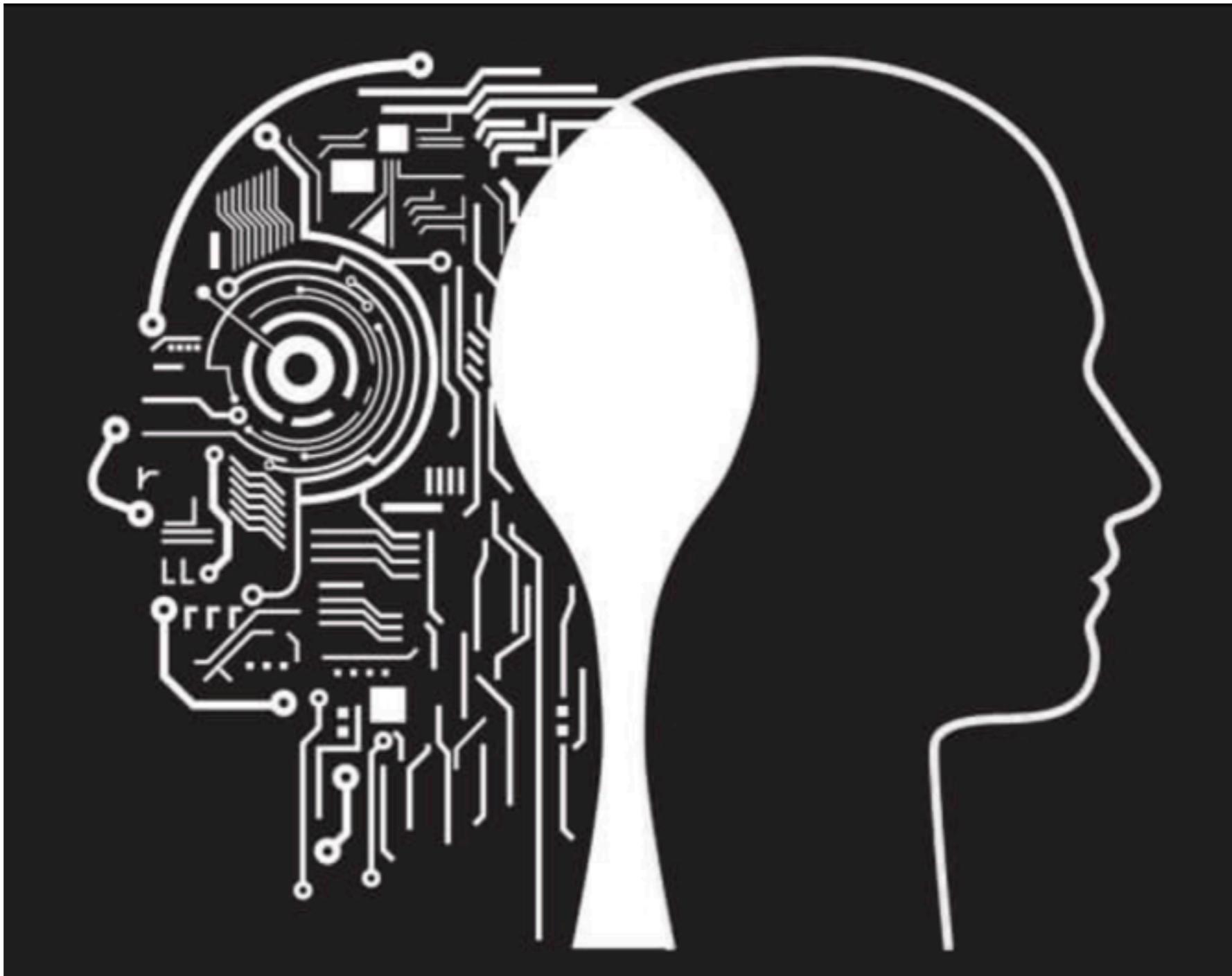
#CHPCNITHEP2019

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# GRAVITATIONAL LENS FINDING CHALLENGE

100,000 simulated images, 48 hours...



Name	type	AUROC	$TPR_0$	$TPR_{10}$	short description
CMU-DeepLens-ResNet-ground3	Ground-Based	0.98	0.09	0.45	CNN
CMU-DeepLens-Resnet-Voting	Ground-Based	0.98	0.02	0.10	CNN
LASTRO EPFL	Ground-Based	0.97	0.07	0.11	CNN
CAS Swinburne Melb	Ground-Based	0.96	0.02	0.08	CNN
AstrOmatic	Ground-Based	0.96	0.00	0.01	CNN
Manchester SVM	Ground-Based	0.93	0.22	0.35	SVM / Gabor
Manchester-NA2	Ground-Based	0.89	0.00	0.01	Human Inspection
ALL-star	Ground-Based	0.84	0.01	0.02	edges/gradiants and Logistic Reg.
CAST	Ground-Based	0.83	0.00	0.00	CNN / SVM
YattaLensLite	Ground-Based	0.82	0.00	0.00	SExtractor
LASTRO EPFL	Space-Based	0.93	0.00	0.08	CNN
CMU-DeepLens-ResNet	Space-Based	0.92	0.22	0.29	CNN
GAMOCLASS	Space-Based	0.92	0.07	0.36	CNN
CMU-DeepLens-Resnet-Voting	Space-Based	0.91	0.00	0.01	CNN
AstrOmatic	Space-Based	0.91	0.00	0.01	CNN
CMU-DeepLens-ResNet-aug	Space-Based	0.91	0.00	0.00	CNN
Kapteyn Resnet	Space-Based	0.82	0.00	0.00	CNN
CAST	Space-Based	0.81	0.07	0.12	CNN
Manchester1	Space-Based	0.81	0.01	0.17	Human Inspection
Manchester SVM	Space-Based	0.81	0.03	0.08	SVM / Gabor
NeuralNet2	Space-Based	0.76	0.00	0.00	CNN / wavelets
YattaLensLite	Space-Based	0.76	0.00	0.00	ArCs / SExtractor
All-now	Space-Based	0.73	0.05	0.07	edges/gradiants and Logistic Reg.
GAHEC IRAP	Space-Based	0.66	0.00	0.01	arc finder

**Table 3.** The AUROC,  $TPR_0$  and  $TPR_{10}$  for the entries in order of AUROC.

Name	type	AUROC	TPR <sub>0</sub>	TPR <sub>10</sub>	short description
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CMU-DeepLens-Resnet-Voting	Space-Based	0.91	0.00	0.01	CNN
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CMU-DeepLens-ResNet-aug	Space-Based	0.91	0.00	0.00	CNN
Kapteyn Resnet	Space-Based	0.82	0.00	0.00	CNN
CAST	Space-Based	0.81	0.07	0.12	CNN
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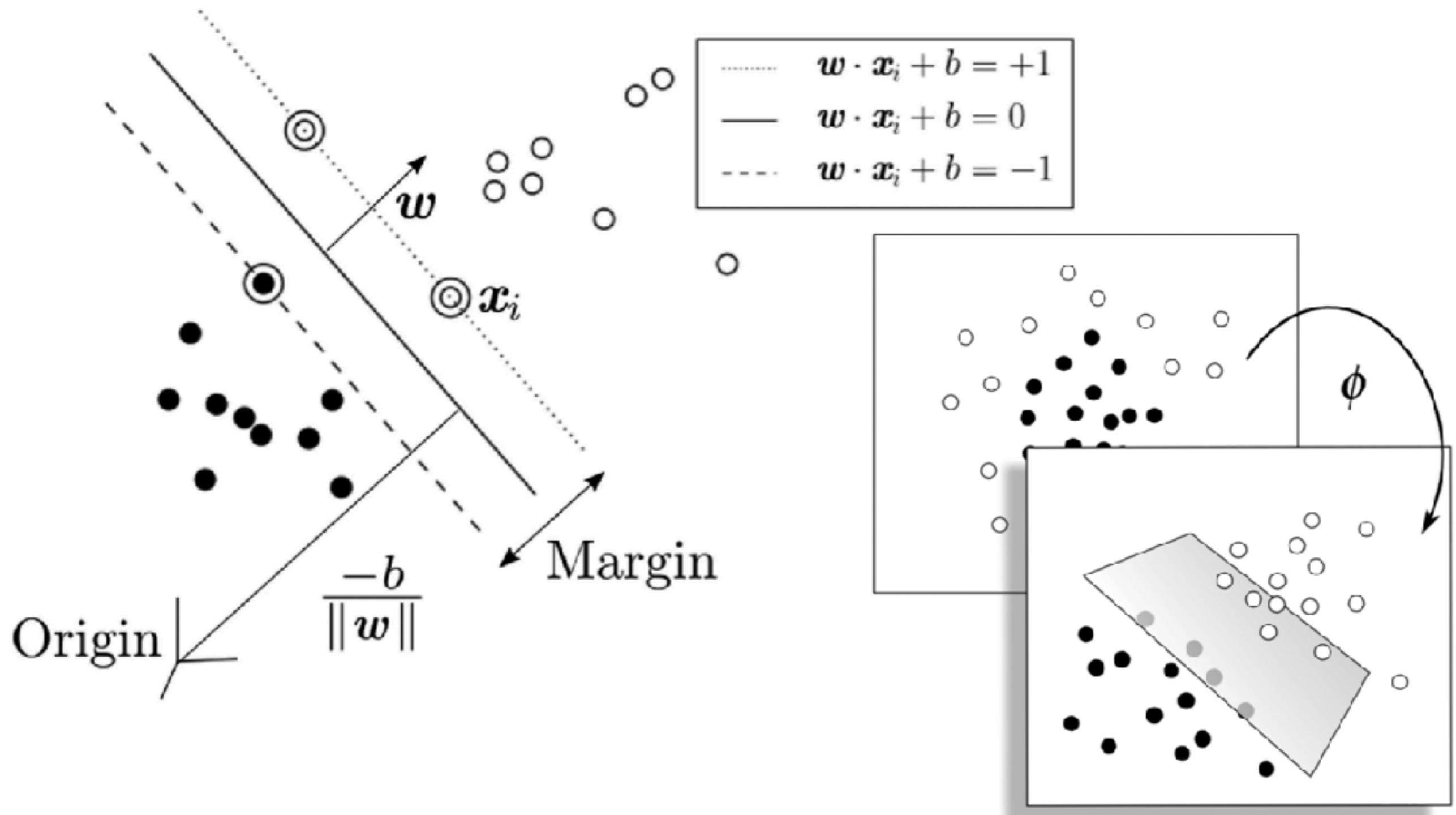
$$\frac{FP}{TP} \simeq \frac{FPR}{TPR} \left( \frac{\text{number of non-lenses in sample}}{\text{number of lenses in sample}} \right)$$

**TPR<sub>0</sub>** = the highest TPR reached before a single false positive occurs in the test set of 100,000 cases

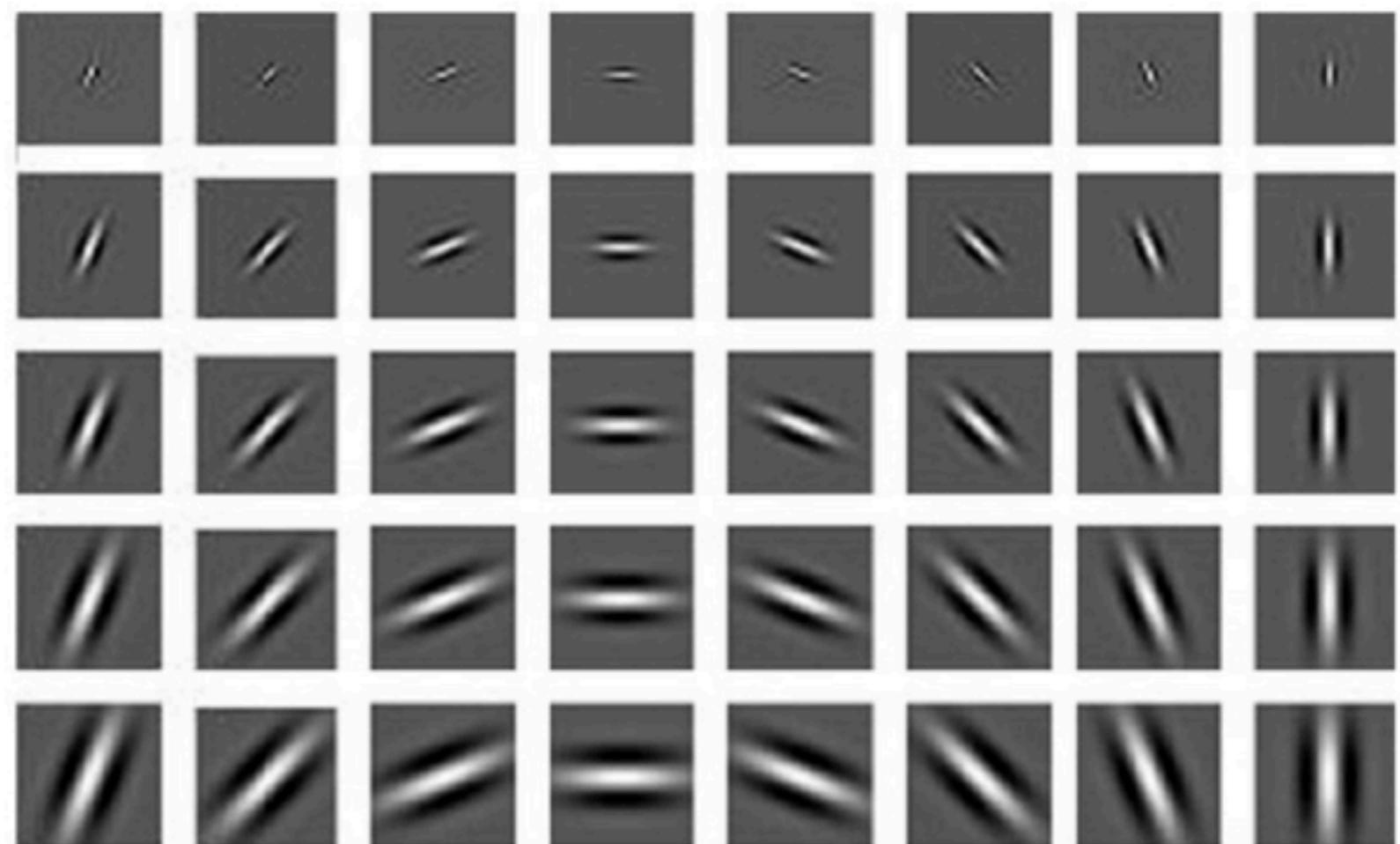
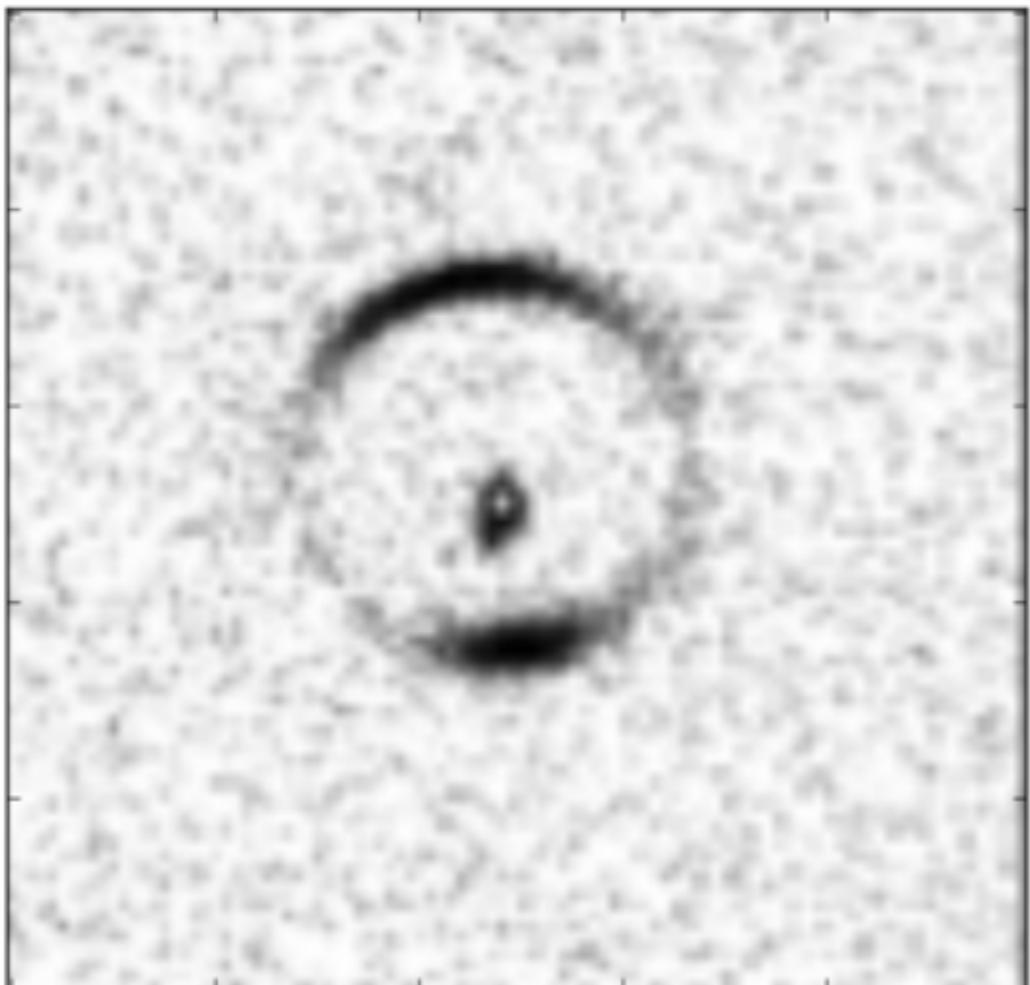
**TPR<sub>10</sub>** = the TPR at the point where fewer than ten false positives are made

Name	type	AUROC	TPR <sub>0</sub>	TPR <sub>10</sub>	short description
Manchester SVM	Ground-Based	0.93	0.22	0.35	SVM / Gabor
CMU-DeepLens-ResNet-ground3	Ground-Based	0.98	0.09	0.45	CNN
LASTRO EPFL	Ground-Based	0.97	0.07	0.11	CNN
CMU-DeepLens-Resnet-Voting	Ground-Based	0.98	0.02	0.10	CNN
CAS Swinburne Melb	Ground-Based	0.96	0.02	0.08	CNN
ALL-star	Ground-Based	0.84	0.01	0.02	edges/gradiants and Logistic Reg.
Manchester-NA2	Ground-Based	0.89	0.00	0.01	Human Inspection
YattaLensLite	Ground-Based	0.82	0.00	0.00	SExtractor
CAST	Ground-Based	0.83	0.00	0.00	CNN / SVM
AstrOmatic	Ground-Based	0.96	0.00	0.01	CNN
CMU-DeepLens-ResNet	Space-Based	0.92	0.22	0.29	CNN
GAMOCLASS	Space-Based	0.92	0.07	0.36	CNN
CAST	Space-Based	0.81	0.07	0.12	CNN
All-now	Space-Based	0.73	0.05	0.07	edges/gradiants and Logistic Reg.
Manchester SVM	Space-Based	0.80	0.03	0.07	SVM / Gabor
Manchester1	Space-Based	0.81	0.01	0.17	Human Inspection
LASTRO EPFL	Space-Based	0.93	0.00	0.08	CNN
GAHEC IRAP	Space-Based	0.66	0.00	0.01	arc finder
AstrOmatic	Space-Based	0.91	0.00	0.01	CNN
Kapteyn Resnet	Space-Based	0.82	0.00	0.00	CNN
CMU-DeepLens-ResNet-aug	Space-Based	0.91	0.00	0.00	CNN
CMU-DeepLens-Resnet-Voting	Space-Based	0.91	0.00	0.01	CNN
NeuralNet2	Space-Based	0.76	0.00	0.00	CNN / wavelets
YattaLensLite	Space-Based	0.76	0.00	0.00	Arcts / SExtractor

**Table 4.** The AUROC, TPR<sub>0</sub> and TPR<sub>10</sub> for the entries in order of TPR<sub>0</sub>.

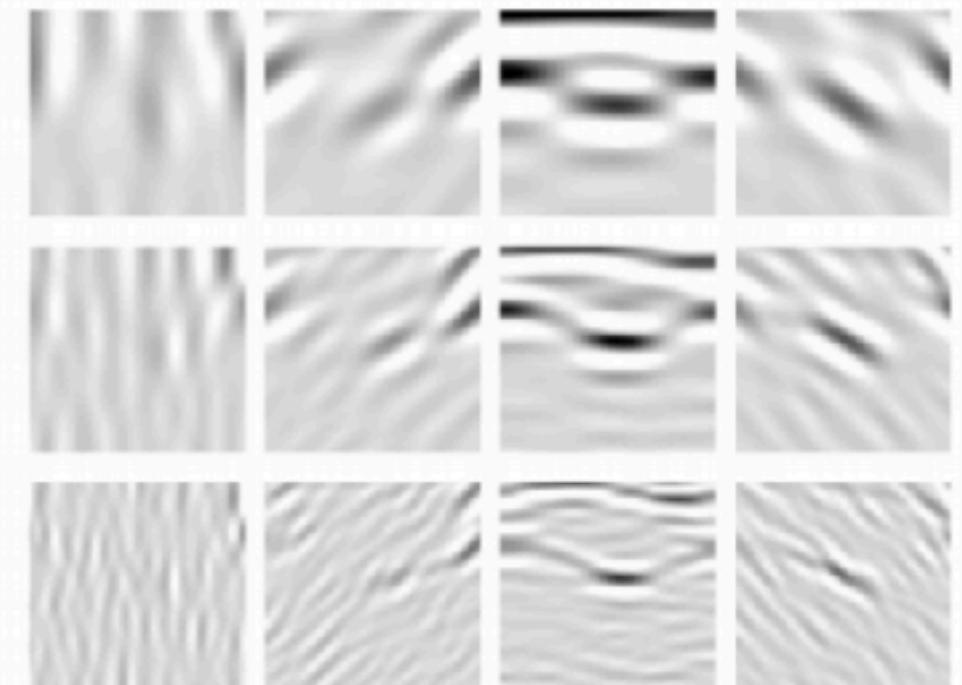
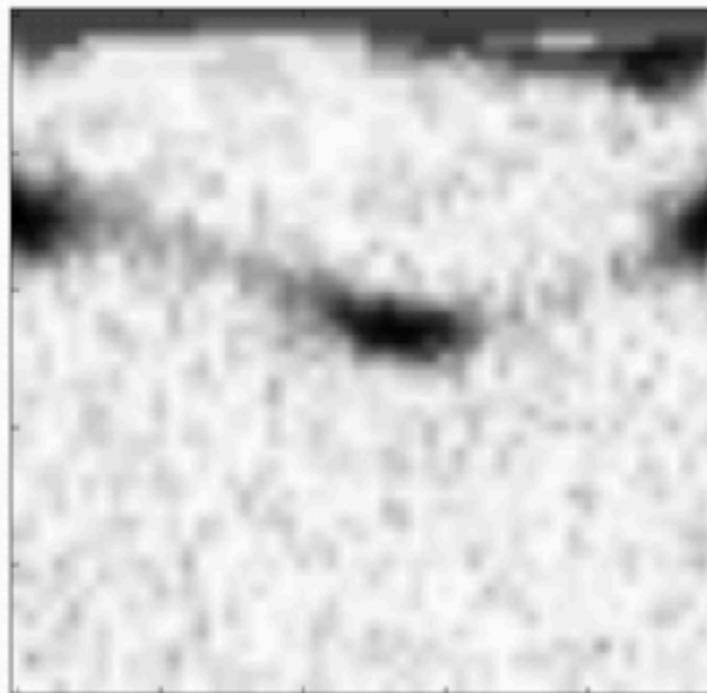
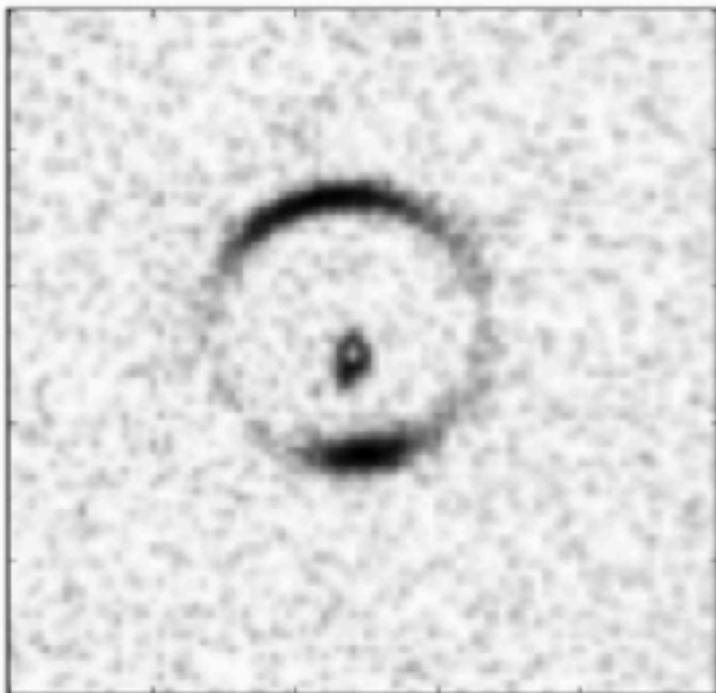


## Simulated gravitational lens



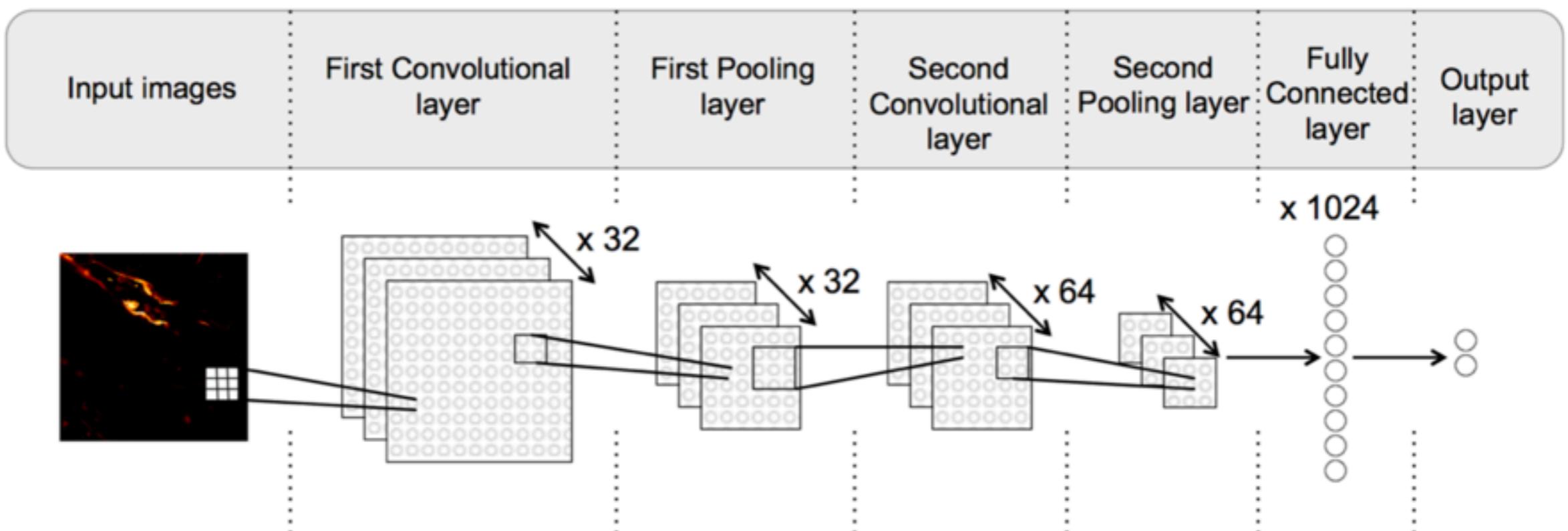
**Gabor filters:** model the simple cells of  
the mammalian visual cortex  
(Marcelja 1980)

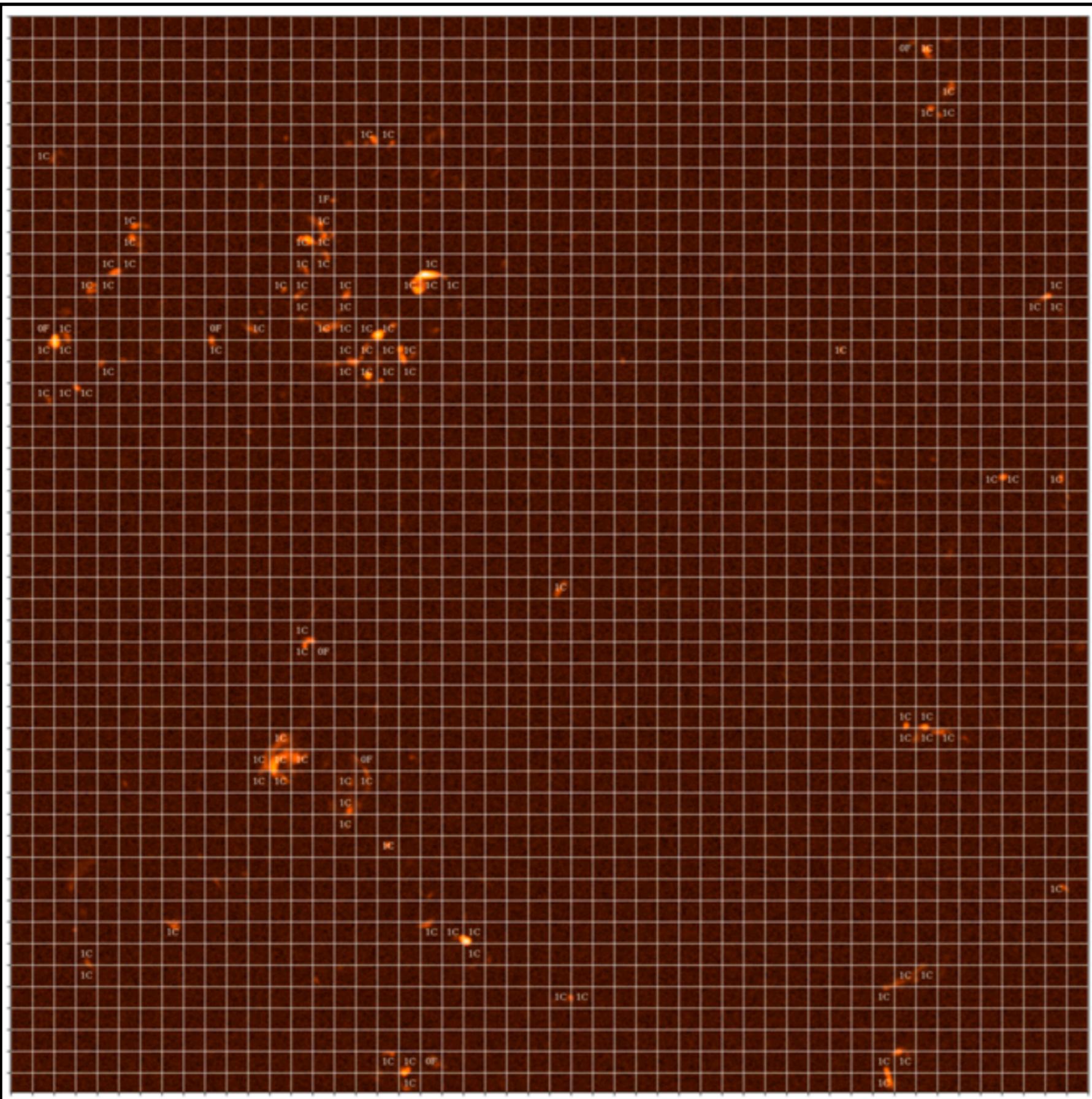
input data → polar transform → Gabor filterbank

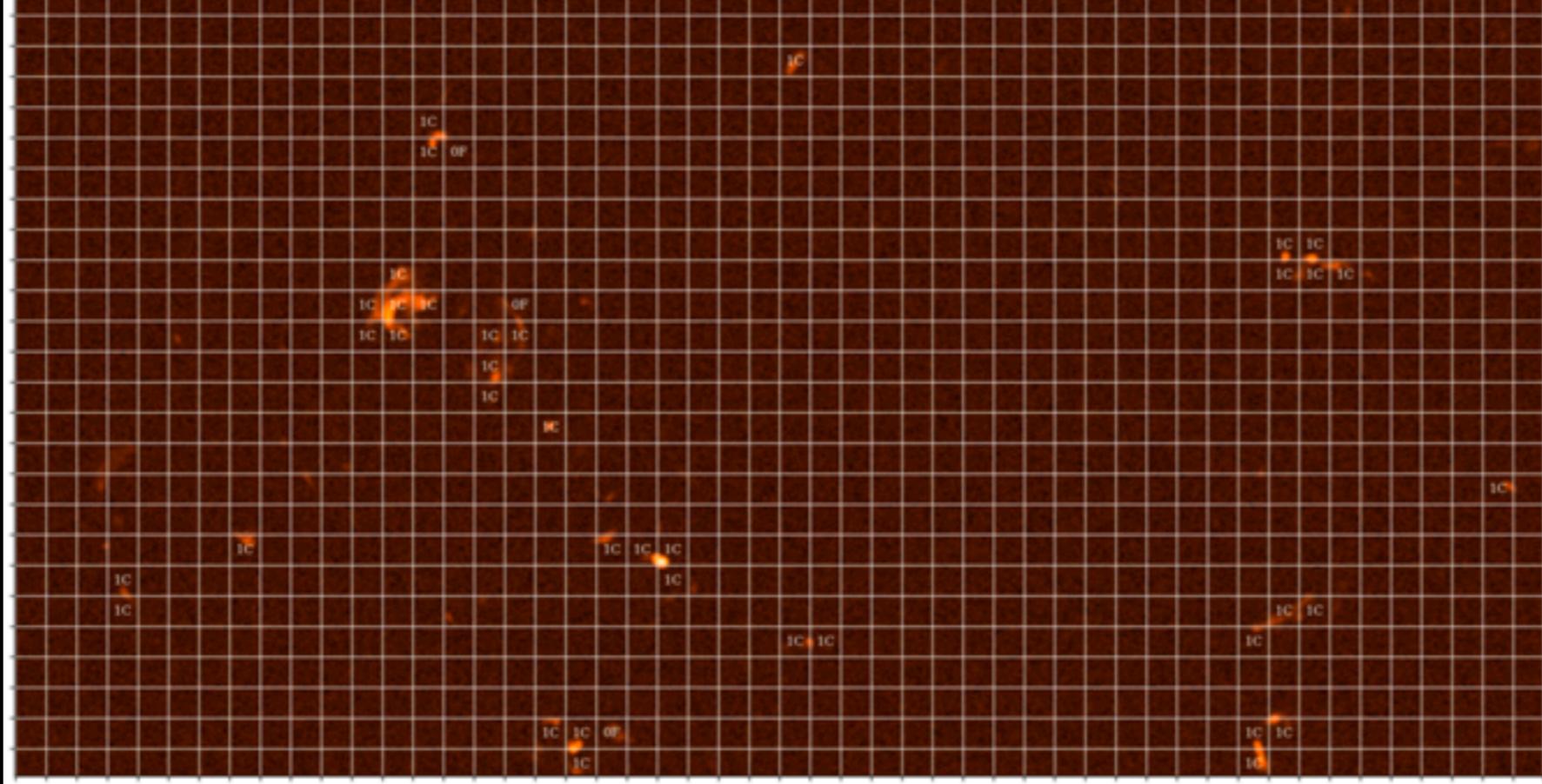
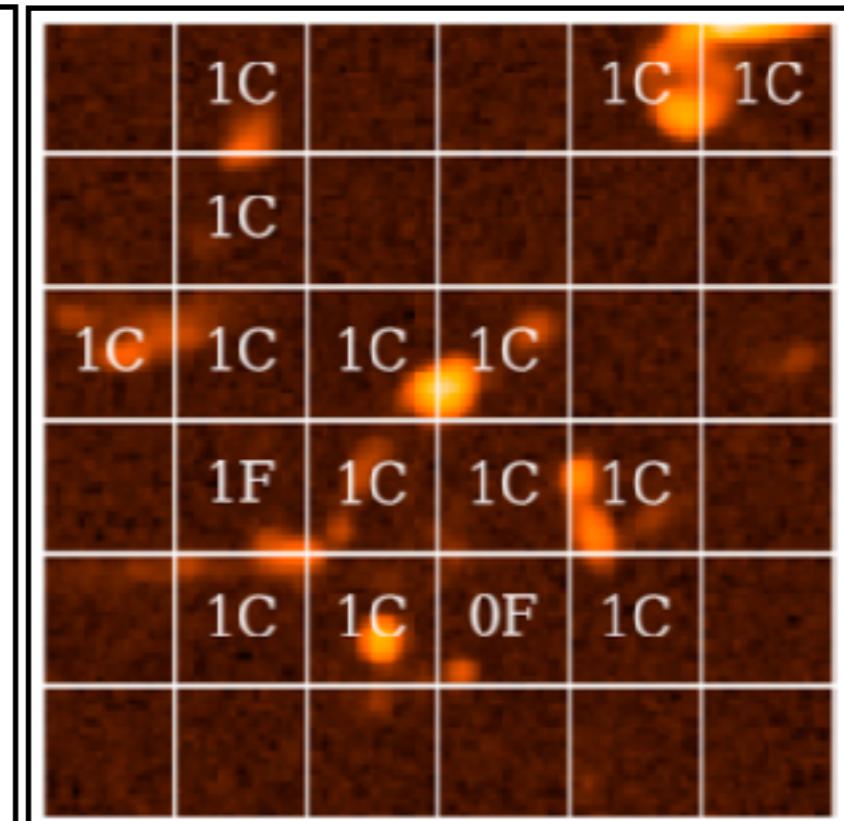
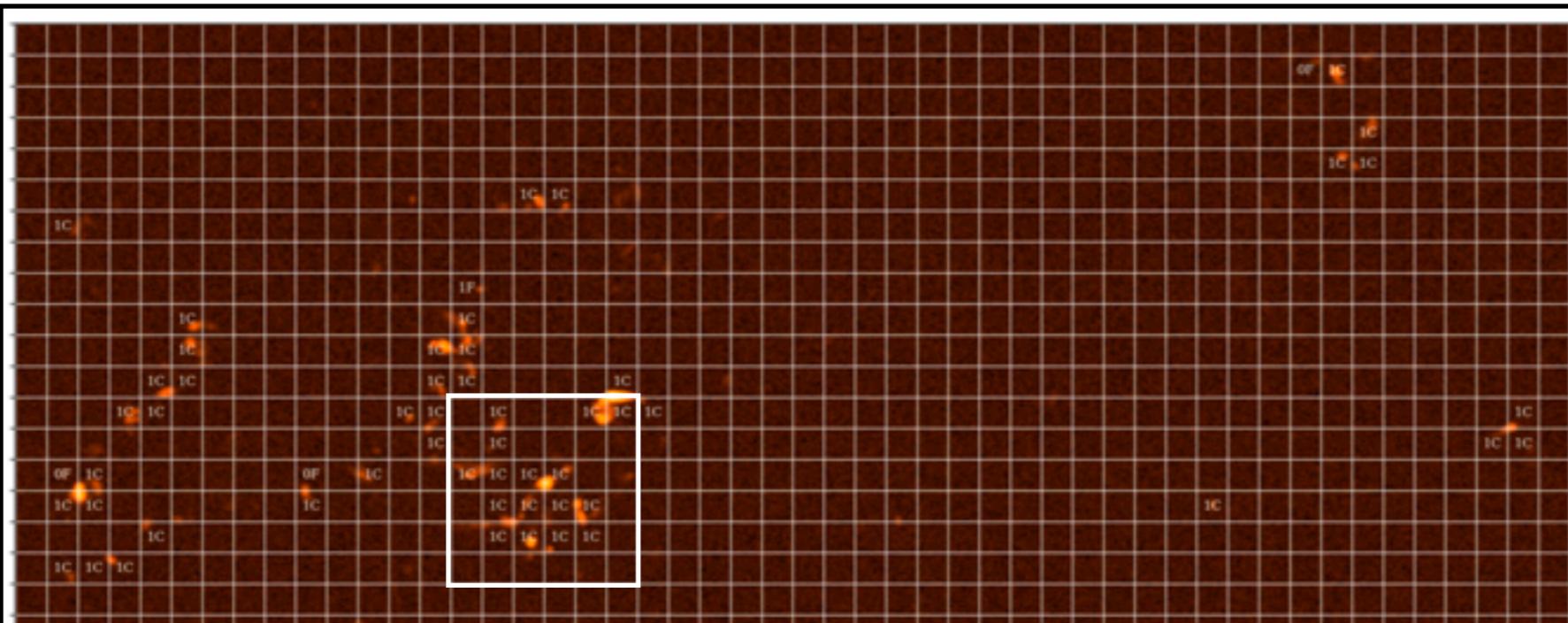


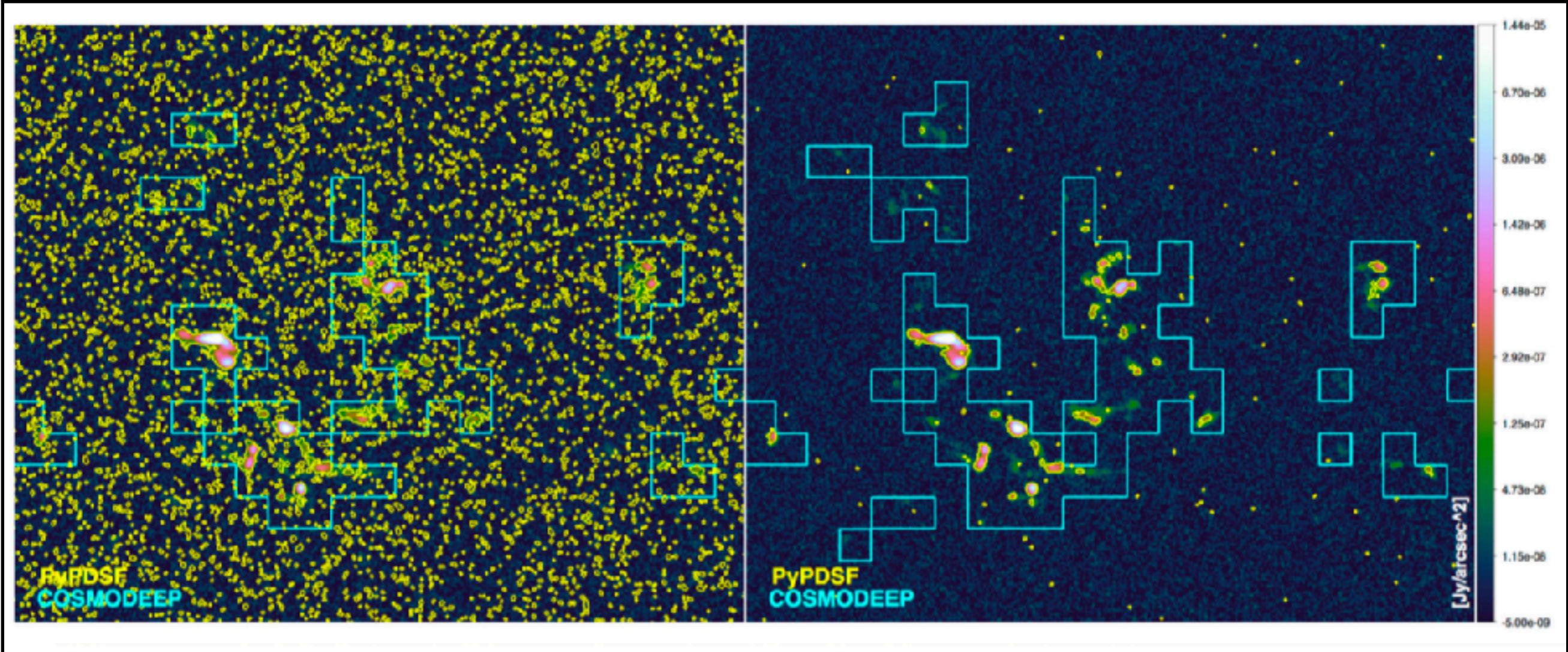
1260 features per example

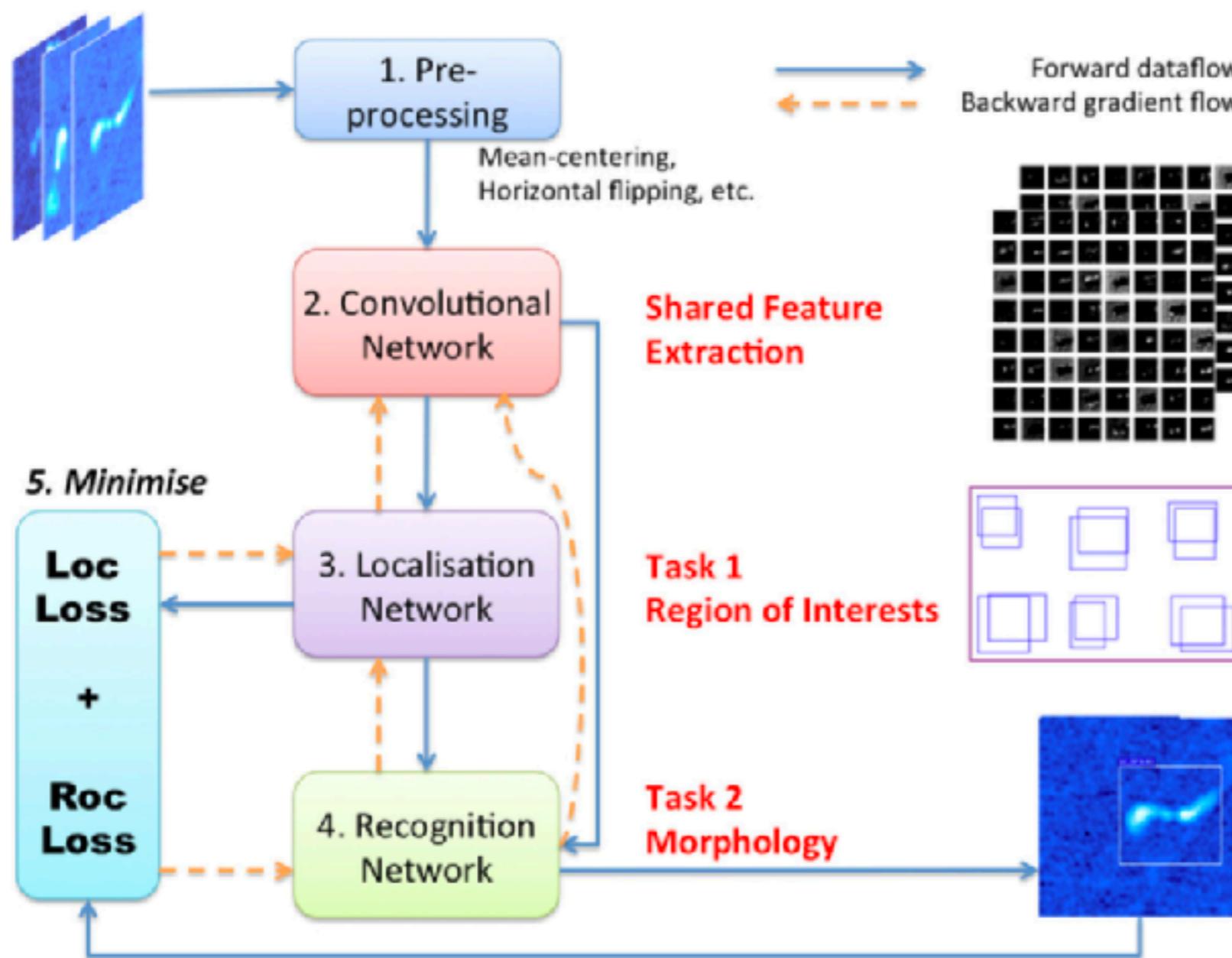
calculate moments  
(mean, variance, skew,  
kurtosis, local energy)

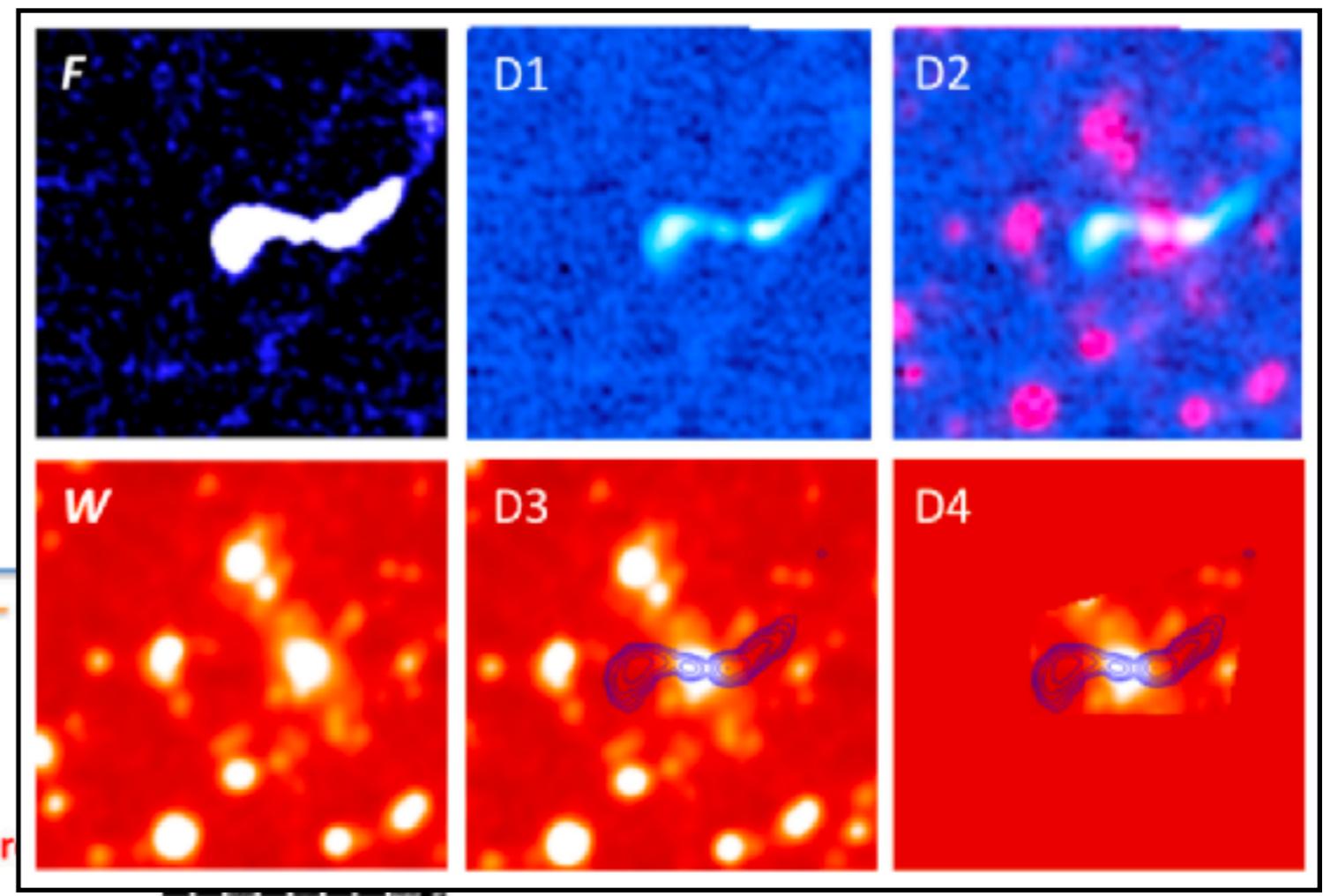
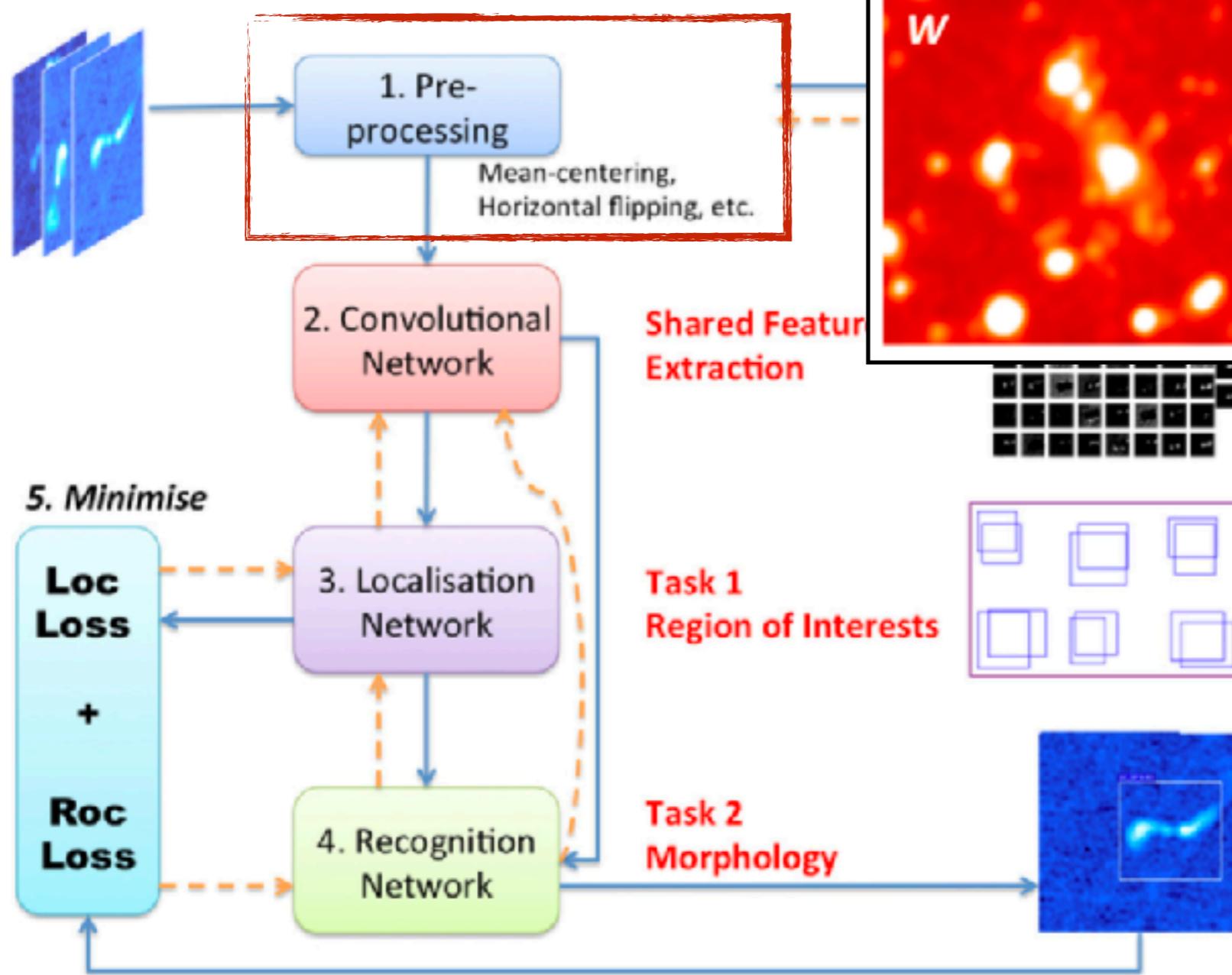


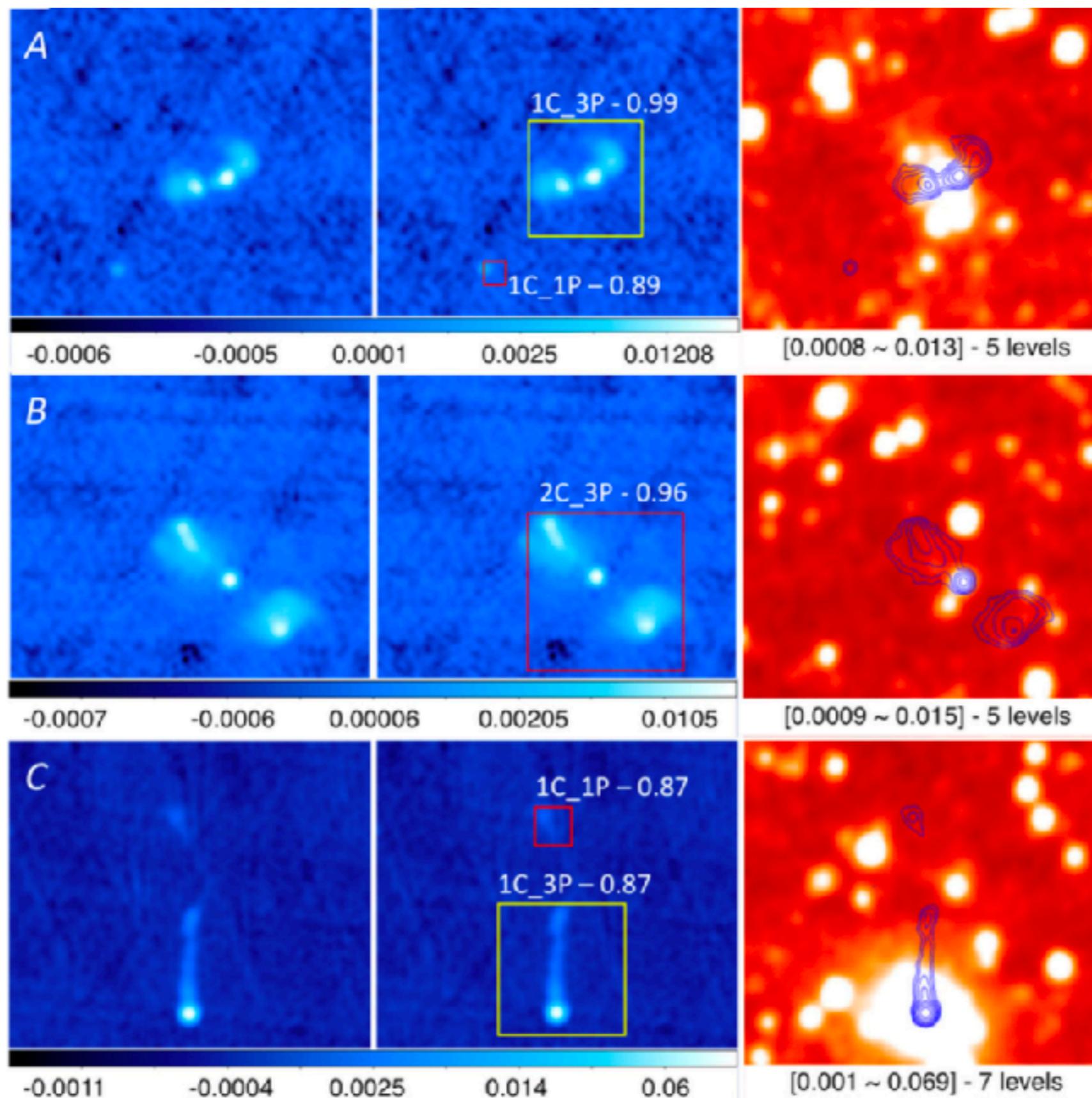


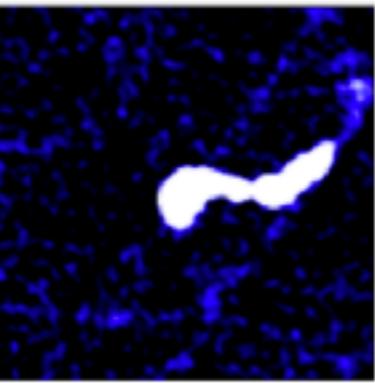
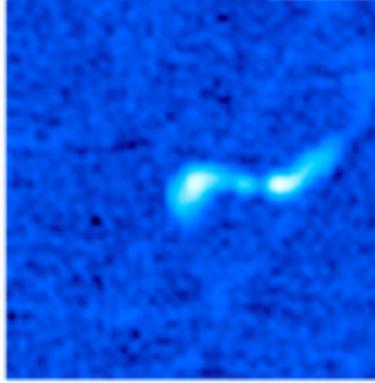
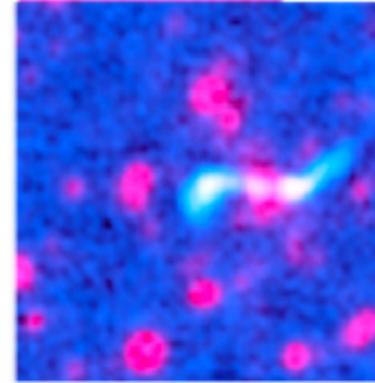
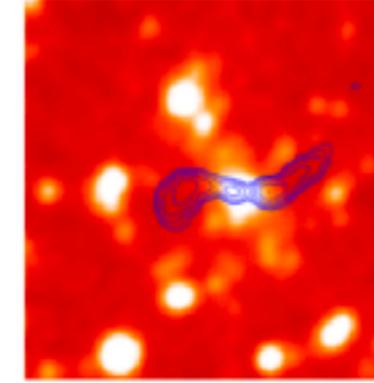
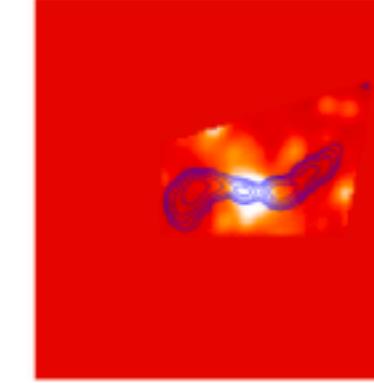




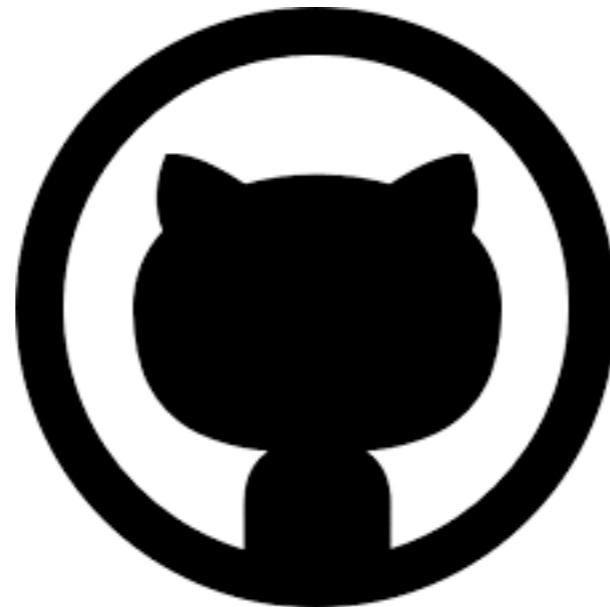






Methods	<i>F</i>	<i>D</i> 1	<i>D</i> 2	<i>D</i> 3	<i>D</i> 4
					
1C_1P	0.8087	0.8580	0.8242	0.8485	<b>0.8784</b>
1C_2P	0.6376	0.6882	0.6843	0.6746	<b>0.7074</b>
1C_3P	0.8250	0.8816	0.8561	0.8876	<b>0.8941</b>
2C_2P	0.7474	0.7014	0.7231	0.7983	<b>0.8200</b>
2C_3P	<b>0.8087</b>	0.7099	0.6989	0.8047	0.7916
3C_3P	0.7708	0.8636	0.8561	<b>0.9424</b>	0.9269
mean AP	78.5%	78.4%	77.4%	82.6%	<b>83.6%</b>

## LECTURES & TUTORIALS



<https://github.com/as595/NITheP>