Contents

```
3.4 Max flow . . . . . . . . . . 2
  Basic
                                  4 String
  1.1 Default Code . . . . . . .
                                     4.1 Hash . . . . . . . . . . . .
                                      4.2 Zvalue . . . . . . . . . . .
2 Math
  2.1 快速冪
             . . . . . . . . . . .
  2.2 擴展歐幾里得 . . . . . . . .
                                  5 Geometry
                                     5.1 Static Convex Hull . . . . .
3 Graph
  6 Data Structure
                                     6.1 Sparse Table . . . . . . .
```

3.3 AP/Bridge

1 Basic

1.1 Default Code

```
#include <bits/stdc++.h>
#define int long long
// #pragma GCC target("popent")
// #pragma GCC optimize("03")
using namespace std;

void solve() {
}

signed main() {
  ios_base::sync_with_stdio(false);
  cin.tie(nullptr);
  int tt = 1;
  cin >> tt;
  while (t--) {
    solve();
  }
  return 0;
}
```

2 Math

2.1 快速冪

|// 根據費馬小定

```
理,若 a p 互質,a^(p-2) 為 a 在 mod p 時的乘法逆元
int fast_pow(int a, int b, int mod)
{
    // a^b % mod
    int res = 1;
    while(b)
    {
        if(b & 1) res = (res * a) % mod;
        a = (a * a) % mod;
        b >>= 1;
    }
    return res;
```

2.2 擴展歐幾里得

```
int gcd(int a, int b)
{
    return b == 0 ? a : gcd(b, a % b);
}
int lcm(int a, int b)
{
    return a * b / gcd(a, b);
}

pair < int, int > ext_gcd
    (int a, int b) //擴展歐幾里德 ax+by = gcd(a,b)
{
    if (b == 0)
        return {1, 0};
    if (a == 0)
        return {0, 1};
    int x, y;
    tie(x, y) = ext_gcd(b % a, a);
    return make_pair(y - b * x / a, x);
}
```

3 Graph

3.1 Tarjan SCC

```
class tarjan{
    // 1-base
    int time = 1;
    int id = 1;
    stack<int> s;
    vector<int> low;
    vector<int> dfn;
    vector<bool> in_stack;
    void dfs(int node, vector<vector<int>> &graph){
      in_stack[node] = true;
      s.push(node);
      dfn[node] = low[node] = time++;
      for(auto &j : graph[node]){
        if(dfn[j] == 0){
          dfs(j, graph);
          // 看看往下有沒有辦法回到更上面的點
          low[node] = min(low[node], low[j]);
        else if(in stack[j]){
          low[node] = min(low[node], low[j]);
      }
      vector < int > t; // 儲存這個強連通分量
      if(dfn[node] == low[node]){
        while(s.top() != node){
          t.push_back(s.top());
          in_stack[s.top()] = false;
          scc_id[s.top()] = id;
          s.pop();
        t.push_back(s.top());
        scc_id[s.top()] = id;
        in_stack[s.top()] = false;
        s.pop();
        id++:
      if(!t.empty()) ans.push_back(t);
  public:
    vector<int> scc_id;
    vector<vector<int>> ans:
    // ans ans[i] 代表第 i 個強連通分量裡面包涵的點
    // scc_id[i] 代表第 i 個點屬於第幾個強連通分量
        <vector<int>> scc(vector<vector<int>> &graph){
      int num = graph.size();
      scc_id.resize(num, -1);
      dfn.resize(num, 0);
      low.resize(num, 0);
      in_stack.resize(num, false);
      for(int i = 1; i < num; i++){</pre>
        if(dfn[i] == 0) dfs(i, graph);
      return ans;
};
```

```
3.2 2 SAT
   下面的 tarjan scc 算法來解 2 sat 問題,若 事件 a 發
   生時,事件 b 必然發生,我們須在 a \rightarrow b 建立一條有向
   cses 的 Giant Pizza 來舉例子,給定 n 個人 m 個配料
   表,每個人可以提兩個要求,兩個要求至少要被滿足一個
// 3 5
// + 1 + 2
// - 1 + 3
// + 4 - 2
// 以這
   個例子來說,第一個人要求要加 配料1 或者 配料2 其中
   一項,第二個人要求不要 配料1 或者 要配料3 其中一項
// 試問能不能滿足所有人的要求,我們可以把 要加
   配料 i 當作點 i ,不加配料 i 當作點 i + m(配料數量)
// 關於第一個人的要求 我們可以看成若不加 配
   料1 則必定要 配料2 以及 若不加 配料2 則必定要 配料1
// 關於第二個人要求 可看做加了 配料
   1 就必定要加 配料3 以及 不加 配料3 就必定不加 配料1
```

```
// 以這些條件建立有像圖,並且
    找尋 scc ,若 i 以及 i + m 在同一個 scc 中代表無解
// 若要求解,則若 i 的 scc_id
     小於 i + m 的 scc_id 則 i 為 true , 反之為 false
// tarjan 的模板在上面
cin >> n >> m;
vector<vector<int>> graph(m * 2 + 1);
function < int(int) > tr = [&](int x){
  if(x > m) return x - m;
  return x + m;
for(int i = 0; i < n; i++){</pre>
 char c1, c2;
  int a, b;
  cin >> c1 >> a >> c2 >> b;
  // a 代表 a 為真, m + a 代表 a 為假
 if(c1 == '-') a += m;
if(c2 == '-') b += m;
  graph[tr(a)].push_back(b);
 graph[tr(b)].push_back(a);
tarjan t;
auto scc = t.scc(graph);
for(int i = 1; i <= m; i++){</pre>
  if(t.scc id[i] == t.scc id[tr(i)]){
    cout << "IMPOSSIBLE\n";
    return 0;
}
for(int i = 1; i <= m; i++){</pre>
  if(t.scc_id[i] < t.scc_id[tr(i)]){</pre>
    cout << '+';
  else cout << '-';</pre>
  cout << ' ';
cout << '\n';
```

3.3 AP/Bridge

```
// adj[u] = adjacent nodes of u
// ap = AP = articulation points
// p = parent

// disc[u] = discovery time of u

// low[u] = 'low' node of u
int dfsAP(int u, int p) {
  int children = 0;
  low[u] = disc[u] = ++Time;
  for (int& v : adj[u]) {
    if (v == p) continue; //
         we don't want to go back through the same path.
                            // if we go back is because
                                we found another wav back
    if (!disc
         [v]) { // if V has not been discovered before
      children++;
      dfsAP(v, u); // recursive DFS call
      if (disc[u] <= low[v]) // condition #1</pre>
        ap[u] = 1;
      low[u] = min(low[u],
           low[v]); // low[v] might be an ancestor of u
    } else // if v was already
          discovered means that we found an ancestor
      low[u] = min(low[u], disc[v]); // finds
            the ancestor with the least discovery time
  }
  return children;
void AP() {
  ap = low = disc = vector<int>(adj.size());
  Time = 0:
  for (int u = 0; u < adj.size(); u++)</pre>
    if (!disc[u])
      ap[u] = dfsAP(u, u) > 1; // condition #2
// br = bridges, p = parent
```

```
vector<pair<int, int>> br;
int dfsBR(int u, int p) {
  low[u] = disc[u] = ++Time;
  for (int& v : adj[u]) {
    if (v == p) continue; //
        we don't want to go back through the same path.
                           // if we go back is because
                               we found another way back
    if (!disc
        [v]) { // if V has not been discovered before
      dfsBR(v, u); // recursive DFS call
      if (disc
          [u] < low[v]) // condition to find a bridge</pre>
        br.push_back({u, v});
      low[u] = min(low[u],
           low[v]); // low[v] might be an ancestor of u
    } else // if v was already
         discovered means that we found an ancestor
      low[u] = min(low[u], disc[v]); // finds
           the ancestor with the least discovery time
 }
}
void BR() {
  low = disc = vector<int>(adj.size());
  Time = 0;
  for (int u = 0; u < adj.size(); u++)</pre>
    if (!disc[u])
      dfsBR(u, u)
```

3.4 Max flow

```
#define int long long
// Edmonds-Karp Algorithm Time: O(VE^2) 實際上會快一點
class edge{
  public:
    int next;
    int capicity;
    int rev;
    edge(int _n, int _c
        , int _r) : next(_n), capicity(_c), rev(_r){};
};
vector<vector<edge>> graph;
void add_edge(int a, int b, int capacity){
      a].push_back(edge(b, capacity, graph[b].size()));
  graph[b].push_back(edge(a, 0, graph[a].size() - 1));
int dfs(int now, int end
     int flow, vector<pair<int, int>> &path, int idx){
  if(now == end) return flow;
  auto &e = graph[now][path[idx + 1].second];
  if(e.capicity > 0){
    auto ret = dfs(e.next
         end, min(flow, e.capicity), path, idx + 1);
    if(ret > 0){
      e.capicity -= ret;
      graph[e.next][e.rev].capicity += ret;
      return ret;
   }
  }
  return 0;
vector<pair<int, int>> search_path(int start, int end){
 vector<pair<int, int>> ans;
  queue<int> q;
  vector
      <pair<int, int>> parent(graph.size(), {-1, -1});
  q.push(start);
  while(!q.empty()){
    int now = q.front();
    q.pop();
    for(int i = 0; i < (int)graph[now].size(); i++){</pre>
      auto &e = graph[now][i];
      if(e.
          capicity > 0 and parent[e.next].first == -1){
        parent[e.next] = {now, i};
```

```
if(e.next == end) break;
        q.push(e.next);
      }
    }
  if(parent[end].first == -1) return ans;
  int now = end;
  while(now != start){
    auto [node, idx] = parent[now];
    ans.emplace_back(node, idx);
    now = node;
  ans.emplace_back(start, -1);
  reverse(ans.begin(), ans.end());
  return ans;
}
int maxflow(int start, int end, int node_num){
  while(1){
    vector < bool > visited(node_num + 1, false);
    auto tmp = search_path(start, end);
    if(tmp.size() == 0) break;
    auto flow = dfs(start, end, 1e9, tmp, \theta);
    ans += flow:
  }
  return ans;
}
```

4 String

4.1 Hash

```
vector<int> Pow(int num){
  int p = 1e9 + 7;
  vector<int> ans = {1};
  for(int i = 0; i < num; i++)</pre>
    ans.push_back(ans.back() * b % p);
  return ans;
}
vector<int> Hash(string s){
 int p = 1e9 + 7;
  vector < int > ans = {0};
  for(char c:s){
    ans.push_back((ans.back() * b + c) % p);
  return ans;
}
// 閉區間[l, r]
int query
    (vector<int> &vec, vector<int> &pow, int l, int r){
  int p = 1e9 + 7;
  int length = r - l + 1;
  return
       (vec[r + 1] - vec[l] * pow[length] % p + p) % p;
```

4.2 Zvalue

5 Geometry

5.1 Static Convex Hull

```
#define mp(a, b) make_pair(a, b)
#define pb(a) push_back(a)
#define F first
#define S second
template < typename T>
pair<T, T> operator -(pair<T, T> a, pair<T, T> b){
    return mp(a.F - b.F, a.S - b.S);
template < typename T>
T cross(pair<T, T> a, pair<T, T> b){
    return a.F * b.S - a.S * b.F;
template < typename T >
vector<pair
    <T, T>> getConvexHull(vector<pair<T, T>>& pnts){
    sort(pnts.begin
        (), pnts.end(), [](pair<T, T> a, pair<T, T> b)
    { return
         a.F < b.F || (a.F == b.F && a.S < b.S); });
    auto cmp = [&](pair<T, T> a, pair<T, T> b)
    { return a.F == b.F && a.S == b.S; };
    pnts.erase(unique
        (pnts.begin(), pnts.end(), cmp), pnts.end());
    if(pnts.size()<=1)</pre>
        return pnts;
    int n = pnts.size();
    vector<pair<T, T>> hull;
    for(int i = 0; i < 2; i++){</pre>
        int t = hull.size();
        for(pair<T, T> pnt : pnts){
             while(hull.size() - t >= 2 &&
                 cross(hull.back() - hull[hull.size()
                 2], pnt - hull[hull.size() - 2]) <= 0){
                 hull.pop_back();
             hull.pb(pnt);
        hull.pop_back();
        reverse(pnts.begin(), pnts.end());
    return hull;
}
```

6 Data Structure

6.1 Sparse Table

```
class Sparse_Table{
  // 0-base
  // 要改成找最大把min换成max就好
  public:
    int spt[500005][22][2];
    Sparse_Table(vector<int> &ar){
      int n = ar.size();
      for (int i = 0; i < n; i++){</pre>
          spt[i][0][0] = ar[i];
          // spt[i][0][1] = ar[i];
      for (int j = 1; (1 << j) <= n; j++) {</pre>
        for (int i = 0; (i + (1 << j) - 1) < n; i++) {
          spt[i][j][0] = min(spt[i + (1 <<
                (j - 1))][j - 1][0], spt[i][j - 1][0]);
          // spt[i][j][1] = max(spt[i + (1 <<
                (j - 1))][j - 1][1], spt[i][j - 1][1]);
        }
      }
    int query_min(int l, int r)
      if(l>r) return INT_MAX;
      int j = (int)__lg(r - l + 1);
      ///j = 31 - \_builtin_clz(r - l+1);
      return min
          (spt[l][j][0], spt[r - (1 << j) + 1][j][0]);
    int query_max(int l, int r)
      if(l>r) return INT_MAX;
      int j = (int)__lg(r - l + 1);
///j = 31 - __builtin_clz(r - l+1);
      return max
          (spt[l][j][1], spt[r - (1 << j) + 1][j][1]);
```

| } |};