



Solving Inverse Problems with Score-Based Generative Priors learned from Noisy Data

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Introduction

- Generative models trained on clean data distribution have shown to outperform end-to-end supervised deep learning.
- A large collection of clean training data is prohibitively expensive to acquire.
- Our method approximately learns a generative model of the clean distribution from noisy data.
- We present SURE-Score: a novel loss function that leverages Stein's unbiased risk estimate (SURE) to jointly denoise the data and learn a score function

Forward Models

Multi-Coil MRI

$$y_i = F_\alpha S_i x + n_i$$

Multi-coil MRI data are acquired in the frequency domain by placing multiple RF coils around the imaging anatomy

$x \in \mathbb{C}^N$	Vectorized Image	$F_\alpha \in \mathbb{C}^{\alpha N \times N}$	Fourier Sampling
$S_i \in \mathbb{C}^{N \times N}$	Coil Sensitivity Map	n_i	Gaussian Noise

Multiple-Input Multiple-Output (MIMO) Channels

$$Y = HP + N$$

Point-to-point MIMO baseband communication scenario where transmitters and receivers equipped with N_t and N_r antennas

$$P \in \mathbb{C}^{N_t \times N_p}$$
 Pilot Measurement

$$H \in \mathbb{C}^{N_r \times N_t}$$
 Channel State Information

$$N$$
 Gaussian Noise

Training SURE-Score

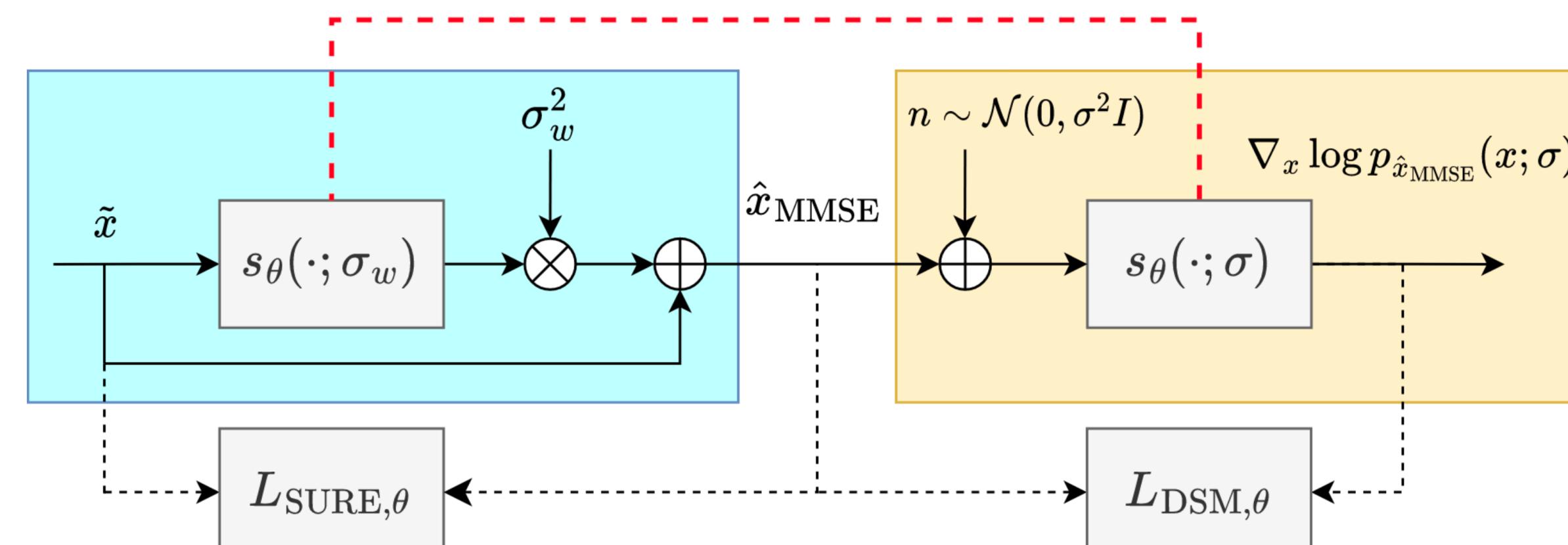
$$\mathcal{L}(\theta) = \alpha \left(\mathbb{E}_{\tilde{H}, n_i} \left[\sigma_w^2 \left\| s_\theta(\tilde{H} + \sigma_w^2 s_\theta(\tilde{H}) + n_i) + \frac{n_i}{\sigma_i^2} \right\|^2 \right] \right) + \left(\mathbb{E}_{\tilde{H}, w} \left[\left\| \sigma_w^2 s_\theta(\tilde{H}) \right\|_2^2 + 2\sigma_w^2 \text{div}_{\tilde{H}}(\tilde{H} + \sigma_w^2 s_\theta(\tilde{H})) \right] \right)$$

Where $\text{div}_{\tilde{H}}(\tilde{H} + \sigma_w^2 s_\theta(\tilde{H})) = \text{tr}(J_{\tilde{H}} + \sigma_w^2 s_\theta(\tilde{H}))$

Where α is appropriate scaling applied to score model

SURE-based denoising with s_θ

Same model used twice



Generic PyTorch Training Pipeline



Fig. 1. Flow of SURE-Score during training. The same deep neural network s_θ is used first for denoising and subsequently for denoising score matching.

Denoising

- Using Tweedie's rule and training score models with: (i) Noisy Data (Naive), (ii) SURE-Score, and (iii) Noise-Free (Supervised) data
- Following table lists NRMSE ($\mu \pm \sigma$) of 100 validation Multi-Coil MRI slices.

Denoising Performance (NRMSE)		
SNR ^w	0 dB	10 dB
Naive	2.48 ± 0.24	0.70 ± 0.07
Supervised	0.21 ± 0.01	0.14 ± 0.01
SURE-Score	0.23 ± 0.01	0.16 ± 0.01

Takeaways:

- Denoising performance of SURE-Score nearly matches supervised learning
- Shows consistency between the SURE and score-matching objective.

Annealed Langevin Dynamics

$$x_{t+1} = x_t + \alpha_t \left(\frac{A^H(y - Ax_t)}{\sigma_w^2 + \gamma_t^2} + s_\theta(x_t; \sigma_t) \right) + \sqrt{2\beta\alpha_t}\eta_t.$$

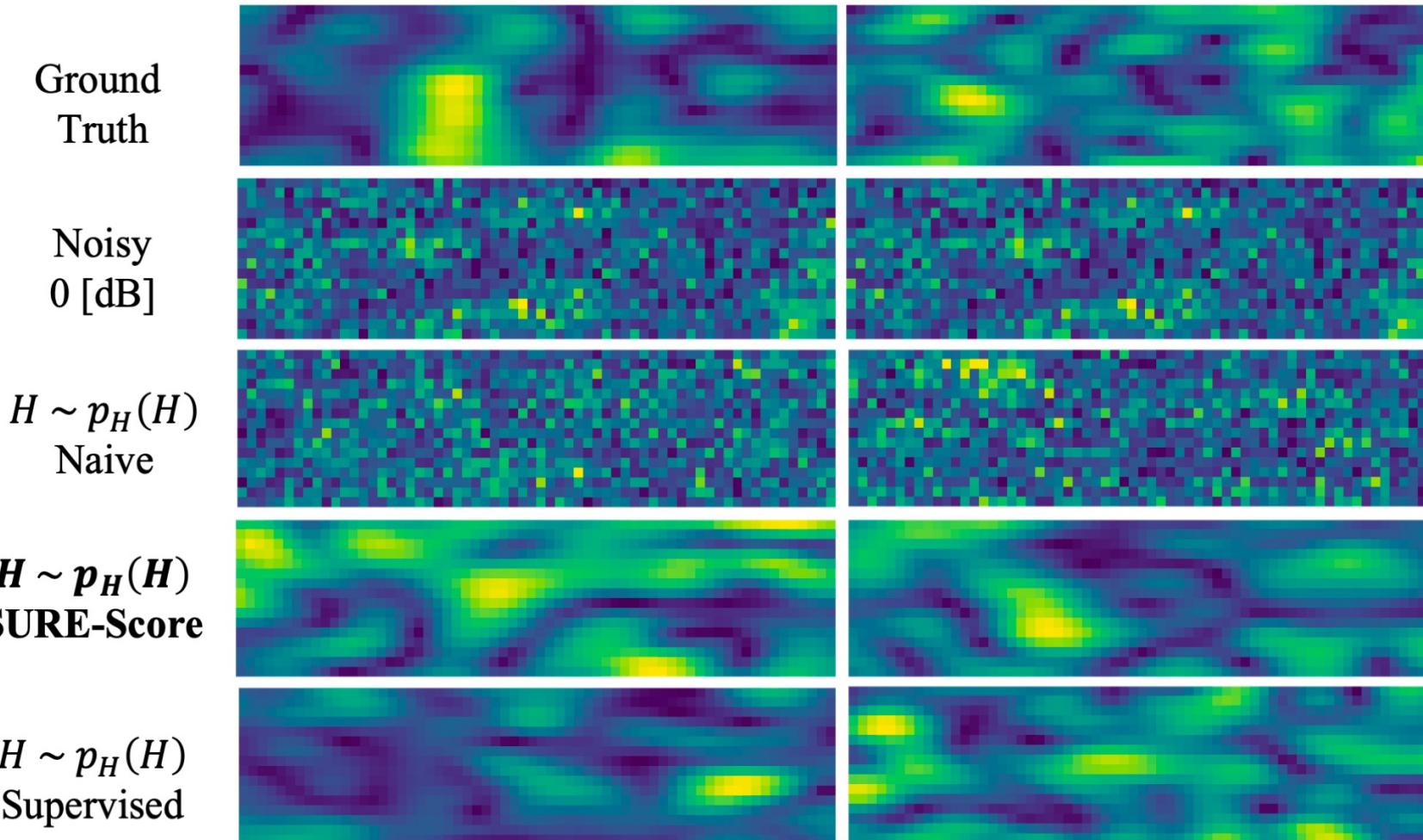
For prior sampling $p_{\hat{x}_{MMSE}}$, we set $A = 0$


Fig. 2. Prior sampling for three methods: Naive, SURE-Score at $SNR^w 0$ dB, and Supervised. Each column is different realization of a CDL-C channel.

Posterior Reconstruction – Multi-Coil MRI

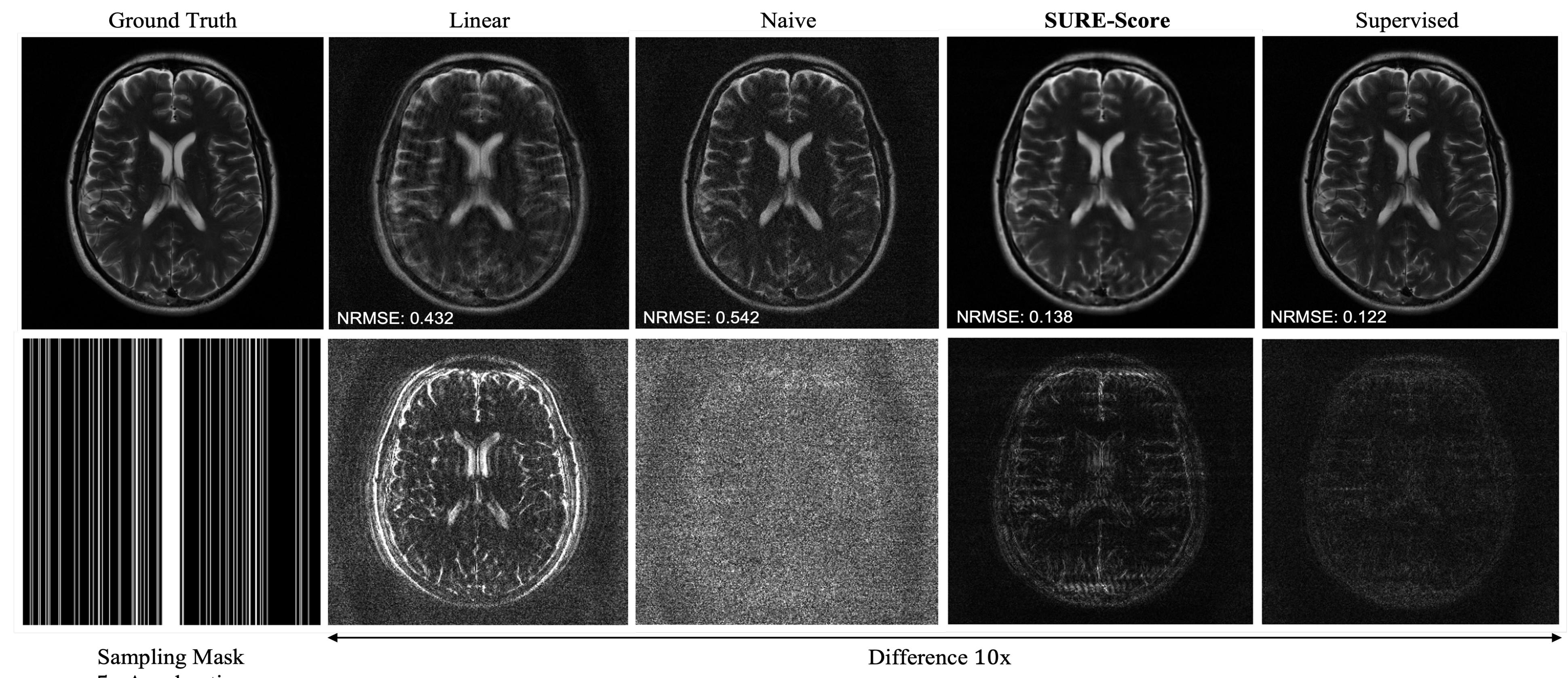


Fig. 3. Multi-coil MRI reconstruction at acceleration factor of 5x. From left to right: fully sampled ground truth, linear reconstruction, posterior sampling after naively training on noisy data at SNR^w , posterior sampling after training with SURE-Score, and posterior sampling after training with noise-free data. The bottom row shows the sampling pattern and difference images for each method, respectively.

Posterior Reconstruction – MIMO Channels

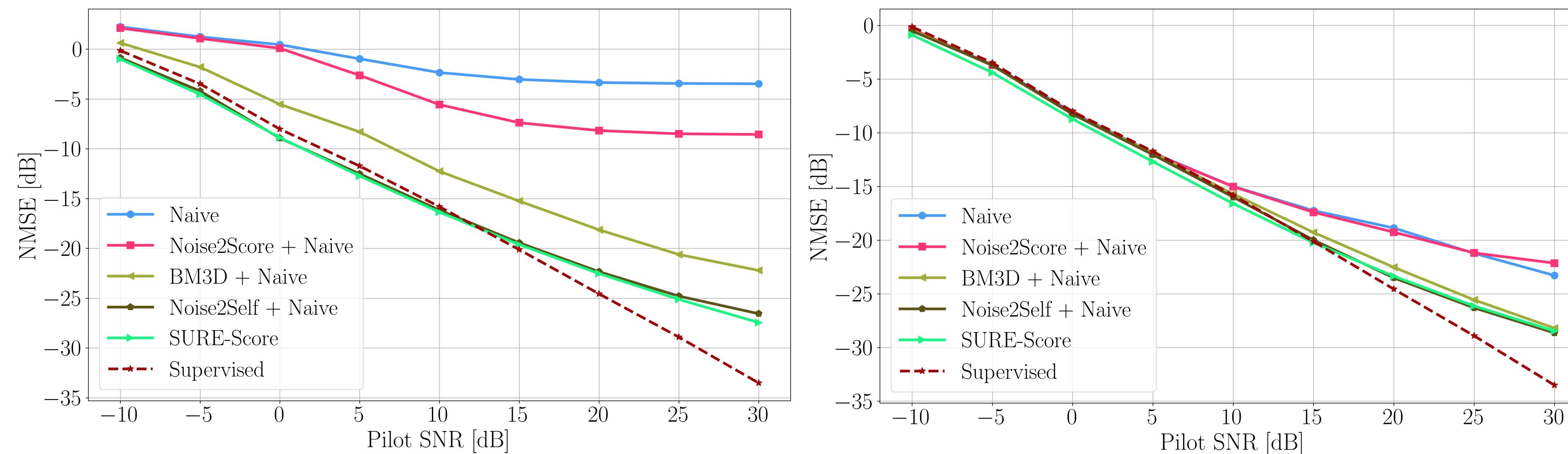


Fig. 3. Channel estimation performance at $\alpha = 0.6$ (38 pilots) using score models trained on CDL-C channels at SNR^w : 0 dB (left) and 10 dB (right).

Key Takeaways:

- SURE-Score performs close to optimal with respect to supervised DSM except at higher pilot SNR
- Naive training plateaus in estimation performance because of overfitting
- Noise2Score and BM3D suffer at lower SNR^w and improve at higher SNR
- Performance gap at high pilot SNR likely due to performance limits of MMSE denoiser and finite training data

Generalized SURE-Score

- Goal: Learn the score directly from noisy measurements y

$$y = Ax + n$$

- Where n is a zero-mean Gaussian random vector
- A is full-rank

Methodology:

- Utilize extended SURE principle to obtain unbiased MSE estimate for exponential family noise corruption

$$s(h) = \|x\|^2 + \|h(u)\|^2 + 2 \left(\text{Tr} \left(\frac{\partial h(u)}{\partial u} \right) + h^T(u) \frac{\partial \ln q(u)}{\partial u} \right)$$

- Use a single-network to jointly denoise the data and learn score-function

Discussion and Conclusion

- Self-supervised techniques can match supervised techniques in denoising and inverse problem performance
- Runtime per iteration increases due to additional pass through the network
- Choosing hyper-parameters without access to ground truth data is an open challenge
- Next Steps:** Our work currently assumes white Gaussian noise corruption but could be extended to arbitrary exponential families

Selected References

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