

# Data Transmission (Module – 1)

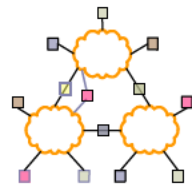


**Dr. Sumit Srivastava**

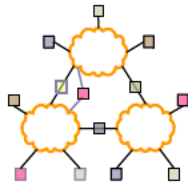
**Dept. of CSE, BIT Mesra Ranchi**

**Email:- [sumit.srivs88@gmail.com](mailto:sumit.srivs88@gmail.com)**

# References



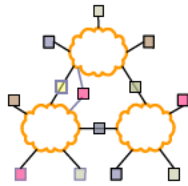
- **Data and Computer Communications, William Stallings, PHI**
- Tanenbaum and David J Wetherall, Computer Networks, 5th Edition, Pearson Edu, 2010
- Computer Networks: A Top-Down Approach, Behrouz A. Forouzan, Firouz Mosharraf, McGraw Hill Education
- Larry L. Peterson and Bruce S. Davie, “Computer Networks – A Systems Approach” (5th ed), Morgan Kaufmann/ Elsevier, 2011
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## Data and Signals

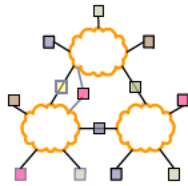
- Analog and Digital
- Analog-to-Analog Conversion
- Digital Signals
- Transmission Impairment
- Data-rate Limits
- Performance

# Terminology



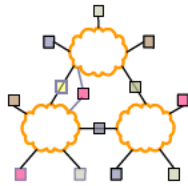
- Transmitter
- Receiver
- Medium
  - Guided medium
    - e.g. twisted pair, optical fiber
  - Unguided medium
    - e.g. air, water, vacuum

# Terminology



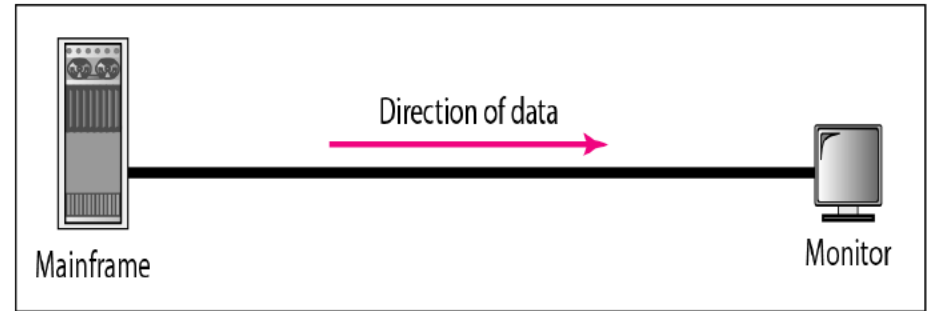
- Direct link
  - No intermediate devices
- Point-to-point
  - Direct link
  - Only 2 devices share link
- Multi-point
  - More than two devices share the link

# Terminology



- Simplex

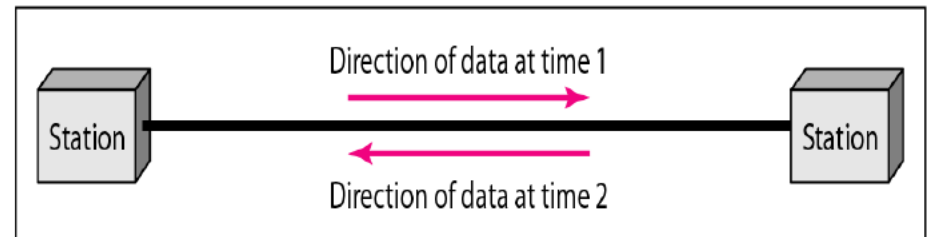
- One direction
  - e.g., Television



a. Simplex

- Half duplex

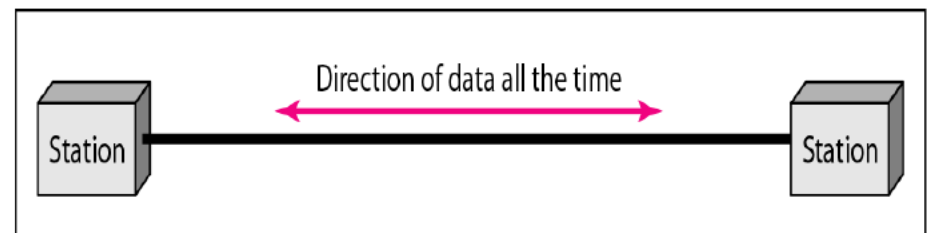
- Either direction, but only one way at a time
  - e.g., police radio



b. Half-duplex

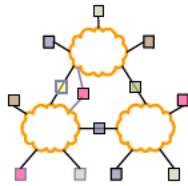
- Full duplex

- Both directions at the same time
  - e.g., telephone



c. Full-duplex

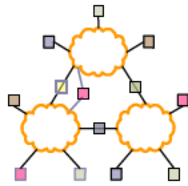
# Analog Data and Digital Data



Data can be **analog** or **digital**

- **Analog data** refers to information that is continuous
- Analog data take on continuous values
  - e.g., analog clock
- **Digital data** refers to information that has discrete states
- Digital data take on discrete values
  - e.g., digital clock

# Analog Signal and Digital Signal



Like the data they represent, signals can be either **analog** or **digital**

- **Analog signals** can have an infinite number of values in a range
- **Digital signals** can have only a limited number of values

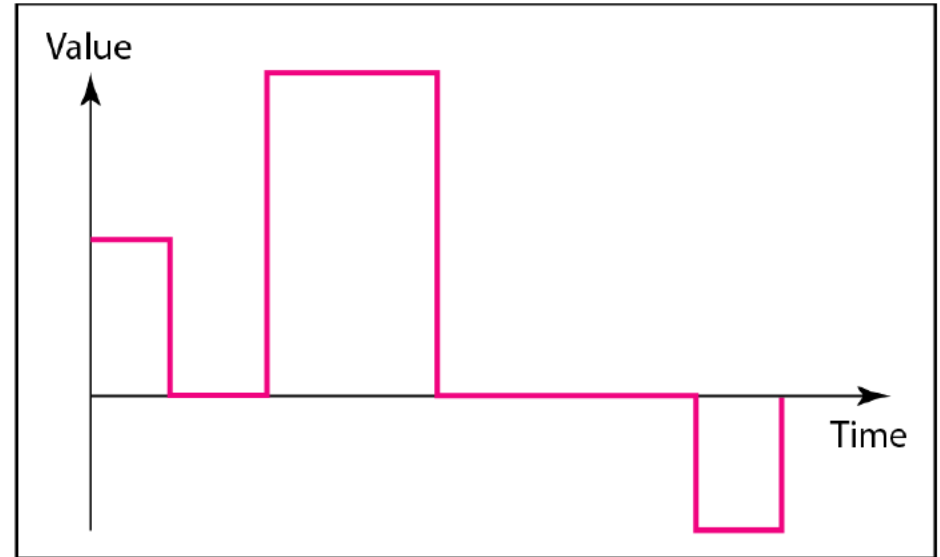
In data communications, we commonly use **periodic analog signals** and **nonperiodic digital signals**.



# Comparison of Analog and Digital Signals

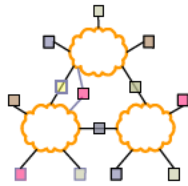


a. Analog signal



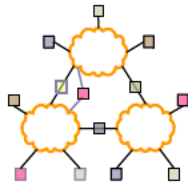
b. Digital signal

# Periodic and Nonperiodic



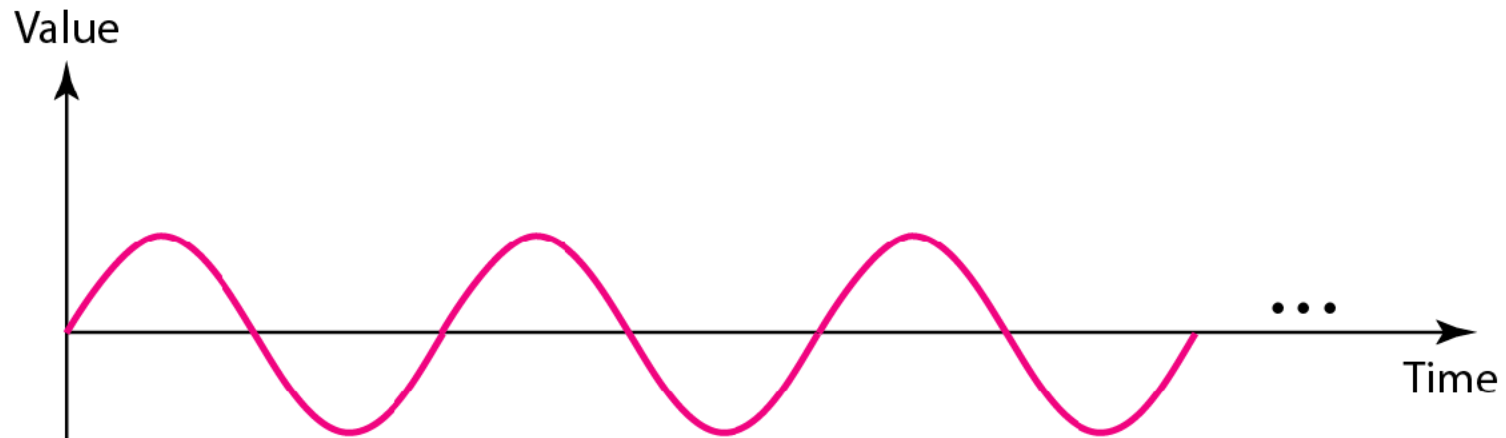
- **A periodic signal** completes a pattern within a measurable time frame, called a period, and repeats that pattern over subsequent identical periods. The completion of one full pattern is called a **cycle**.
- **A nonperiodic signal** changes without exhibiting a pattern or cycle that repeats over time

# PERIODIC ANALOG SIGNALS

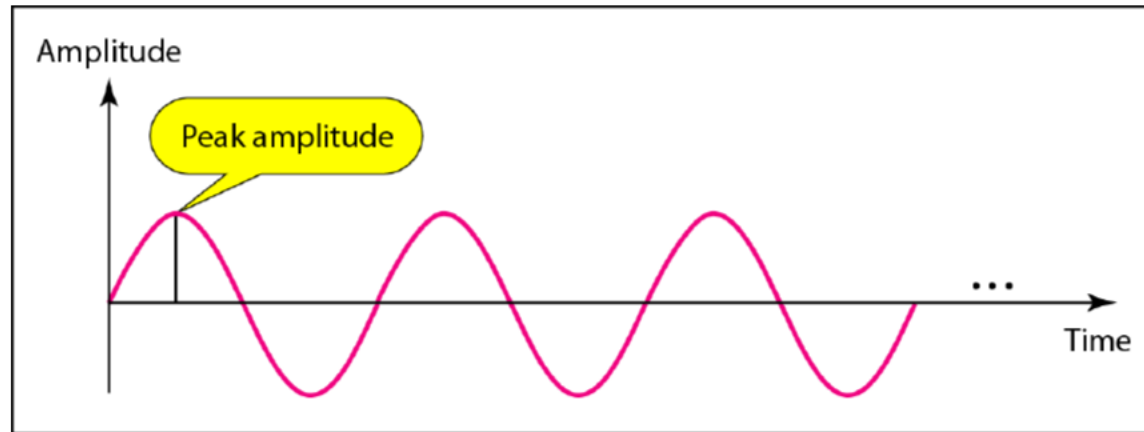
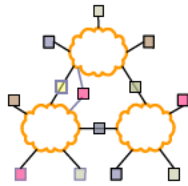


Periodic analog signals can be classified as **simple** or **composite**.

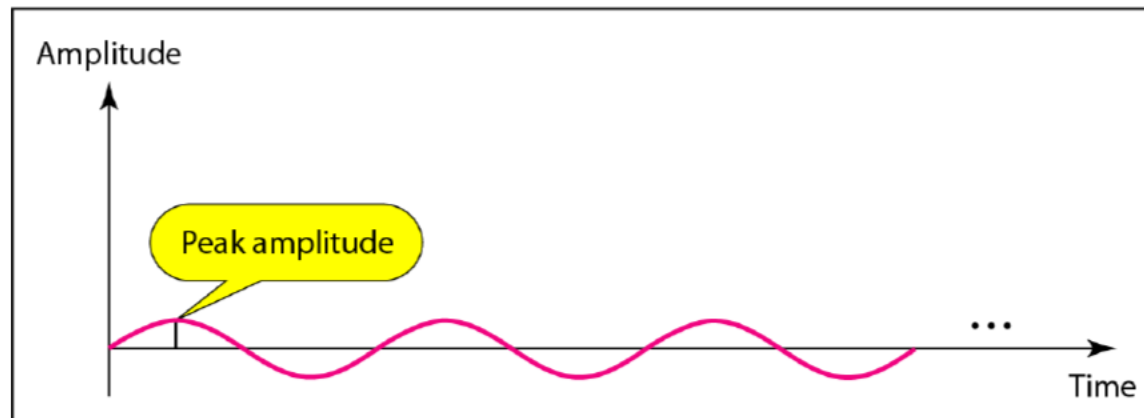
- A simple periodic analog signal, **a sine wave**, cannot be decomposed into simpler signals.
- A composite periodic analog signal is composed of **multiple sine waves**.



# Signal Amplitude

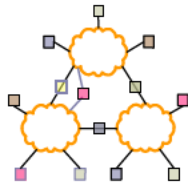


a. A signal with high peak amplitude



b. A signal with low peak amplitude

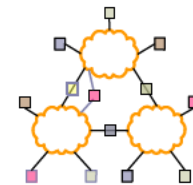
# Frequency



Frequency is the rate of change with respect to time.

- Change in a short span of time means high frequency.
- Change over a long span of time means low frequency.
- If a signal does not change at all, its frequency is zero
- If a signal changes instantaneously, its frequency is infinite.

# Frequency and Period



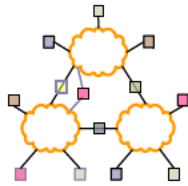
Frequency and period are the inverse of each other.

$$f = \frac{1}{T} \quad \text{and} \quad T = \frac{1}{f}$$

*Units of period and frequency*

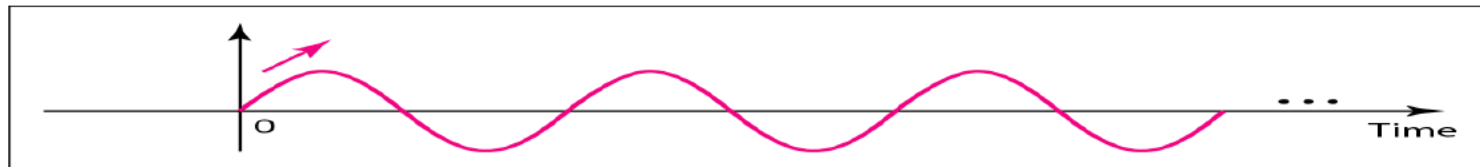
<i>Unit</i>	<i>Equivalent</i>	<i>Unit</i>	<i>Equivalent</i>
Seconds (s)	1 s	Hertz (Hz)	1 Hz
Milliseconds (ms)	$10^{-3}$ s	Kilohertz (kHz)	$10^3$ Hz
Microseconds ( $\mu$ s)	$10^{-6}$ s	Megahertz (MHz)	$10^6$ Hz
Nanoseconds (ns)	$10^{-9}$ s	Gigahertz (GHz)	$10^9$ Hz
Picoseconds (ps)	$10^{-12}$ s	Terahertz (THz)	$10^{12}$ Hz

# Phase

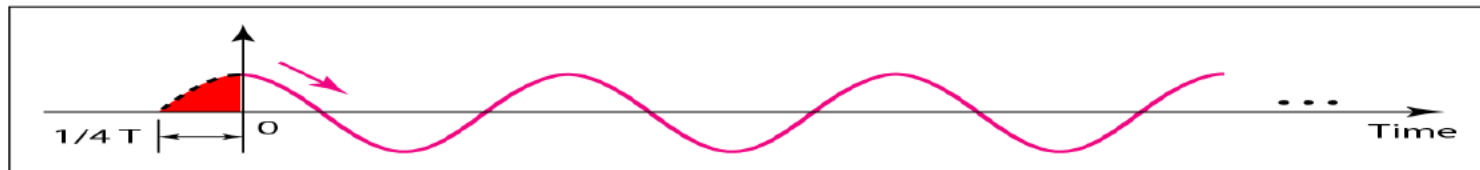


Phase describes the position of the waveform relative to time 0

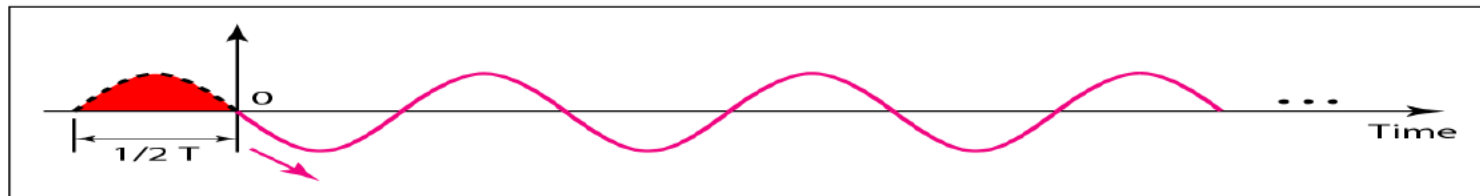
*Three sine waves with the same amplitude and frequency, but different phases*



a. 0 degrees

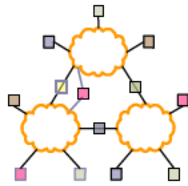


b. 90 degrees



c. 180 degrees

# Example



*A sine wave is offset 1/6 cycle with respect to time 0. What is its phase in degrees and radians?*

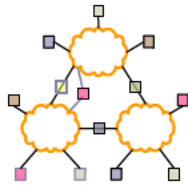
## *Solution*

*We know that 1 complete cycle is 360°. Therefore, 1/6 cycle is*

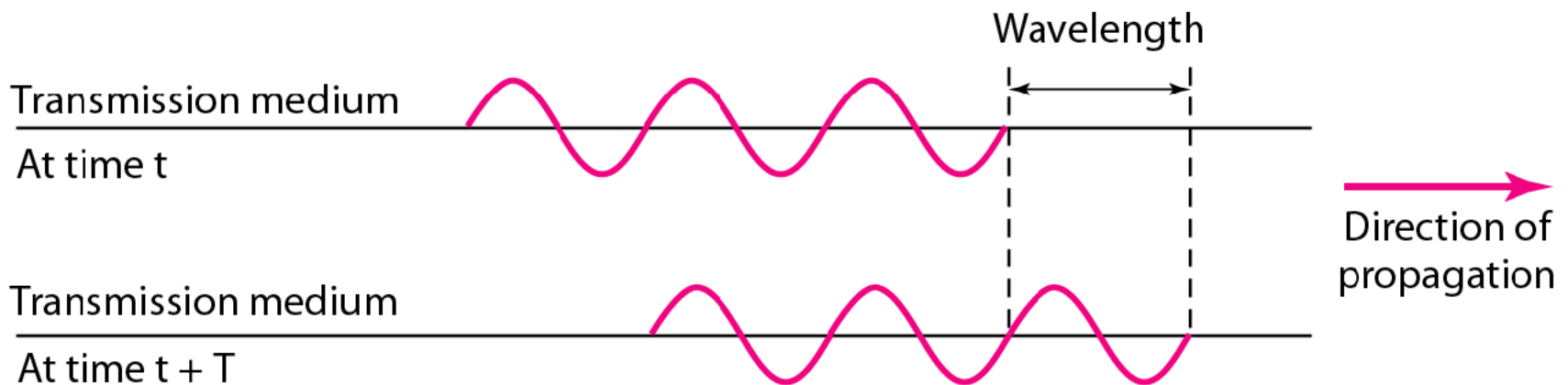
$$\frac{1}{6} \times 360 = 60^\circ = 60 \times \frac{2\pi}{360} \text{ rad} = \frac{\pi}{3} \text{ rad} = 1.046 \text{ rad}$$



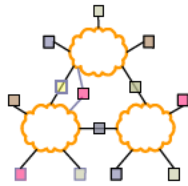
# Wavelength and Period



$$\begin{aligned}\text{Wavelength} &= \text{Propagation speed} \times \text{Period} \\ &= \text{Propagation speed} / \text{Frequency}\end{aligned}$$

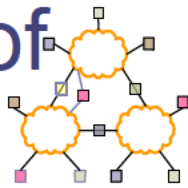


# Time and Frequency Domains

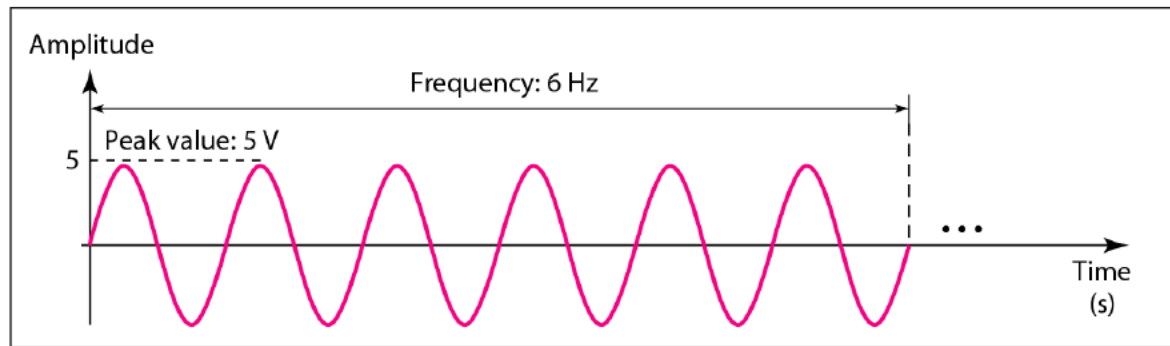


- A sine wave is comprehensively defined by its **amplitude**, **frequency**, and **phase**.
- We have been showing a sine wave by using what is called a time domain plot. The time-domain plot shows **changes in signal amplitude with respect to time** (it is an amplitude-versus-time plot).
- Phase is not explicitly shown on a time-domain plot.

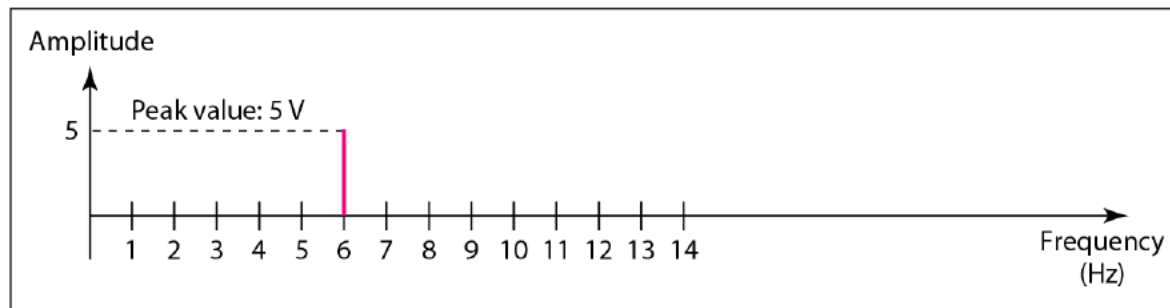
# Time-domain and frequency-domain plots of a sine wave



A complete sine wave in the time domain can be represented by one single spike in the frequency domain.

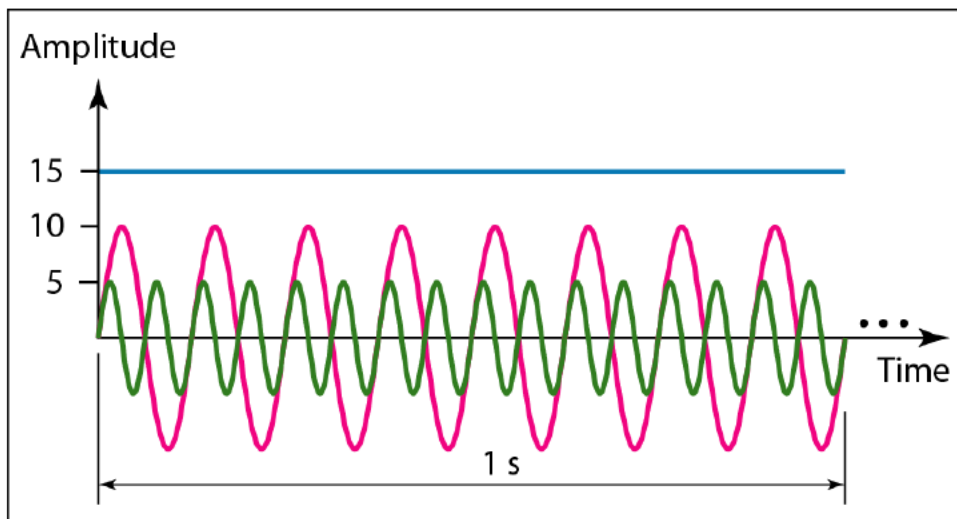
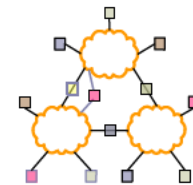


a. A sine wave in the time domain (peak value: 5 V, frequency: 6 Hz)

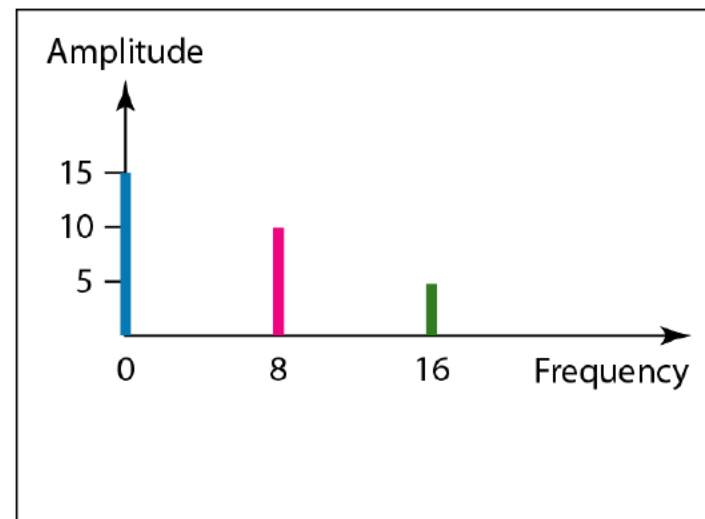


b. The same sine wave in the frequency domain (peak value: 5 V, frequency: 6 Hz)

# Frequency Domain



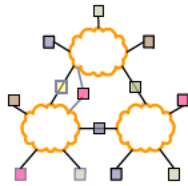
a. Time-domain representation of three sine waves with frequencies 0, 8, and 16



b. Frequency-domain representation of the same three signals

- The frequency domain is more compact and useful when we are dealing with more than one sine wave.
- A single-frequency sine wave is not useful in data communication. We need to send a **composite signal**, a signal made of many simple sine waves.

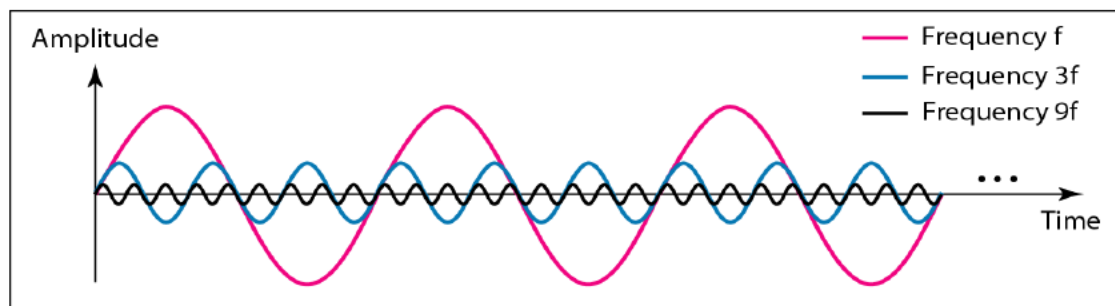
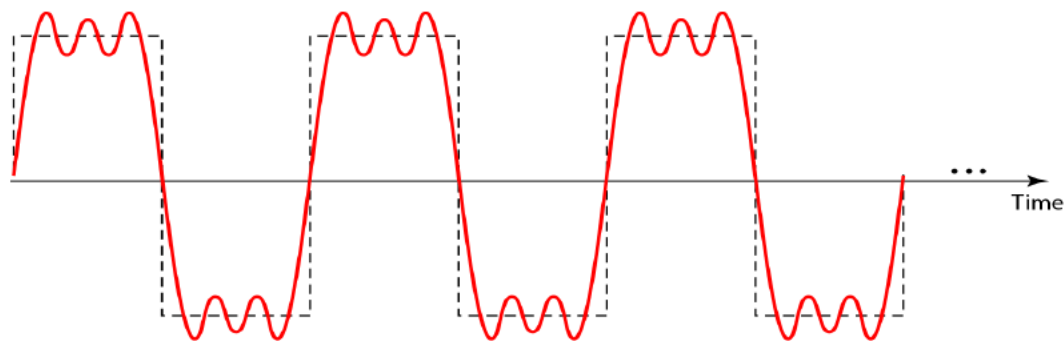
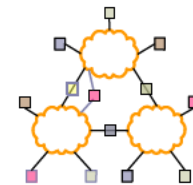
# Fourier analysis



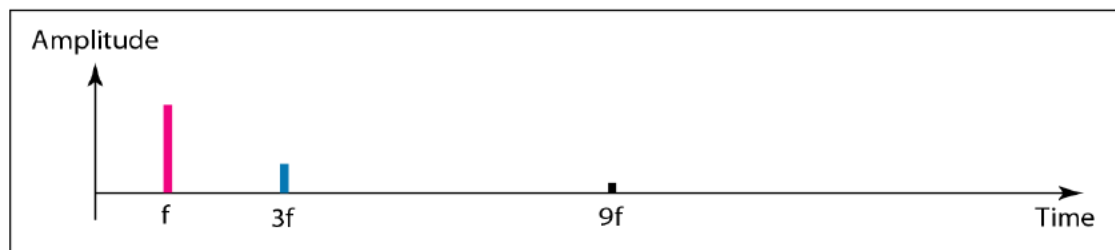
According to Fourier analysis,  
any composite signal is a combination of simple sine waves with different frequencies, amplitudes, and phases.

- If the composite signal is **periodic**, the decomposition gives a *series of signals with discrete frequencies*.
- If the composite signal is **nonperiodic**, the decomposition gives a *combination of sine waves with continuous frequencies*.

# A composite periodic signal



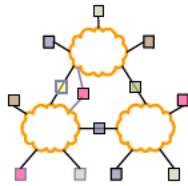
a. Time-domain decomposition of a composite signal



b. Frequency-domain decomposition of the composite signal

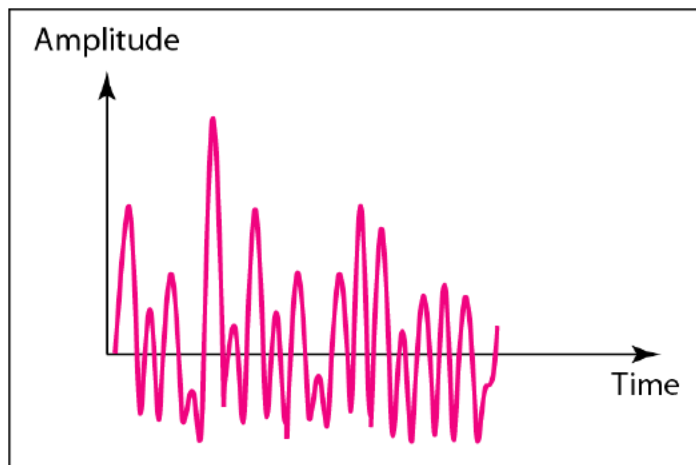
Decomposition of the composite periodic signal in the time and frequency domains

# Time and frequency domains of a nonperiodic signal

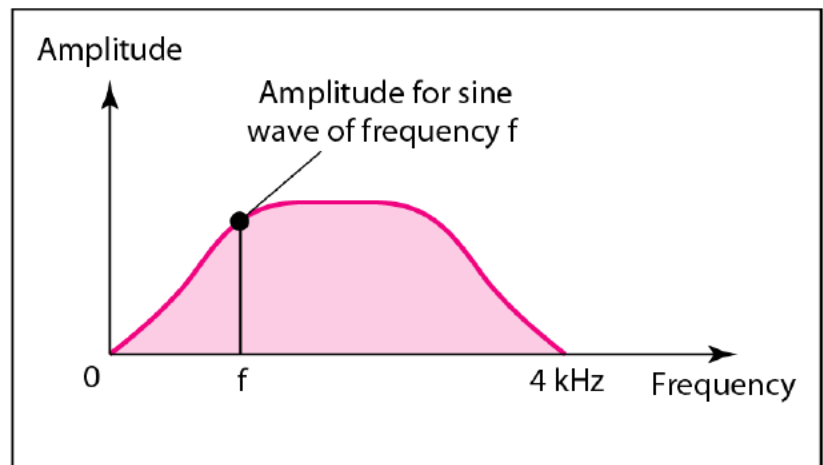


## A nonperiodic composite signal

- It can be a signal created by a microphone or a telephone set when a word or two is pronounced.
- In this case, the composite signal cannot be periodic
- because that implies that we are repeating the same word or words with exactly the same tone.

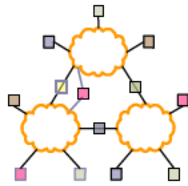


a. Time domain

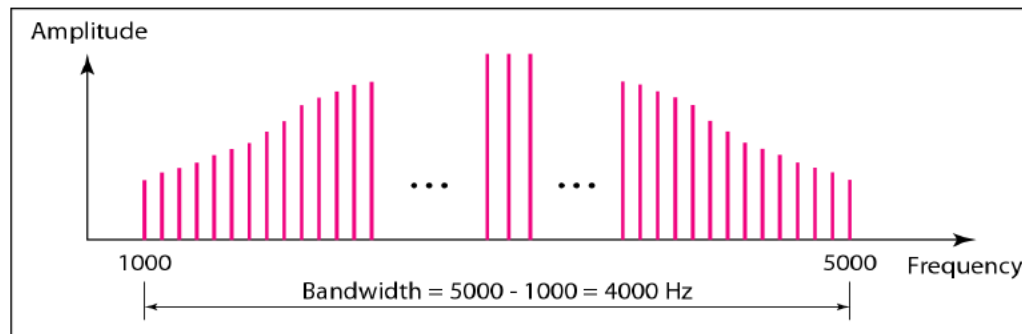


b. Frequency domain

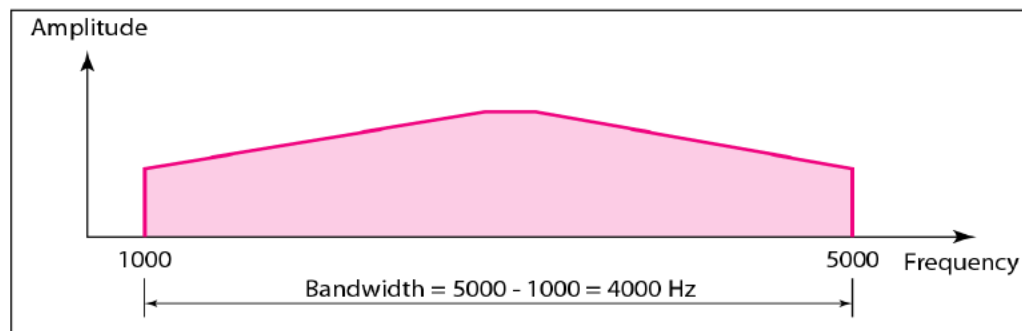
# Bandwidth



The bandwidth of a composite signal is the difference between the highest and the lowest frequencies contained in that signal.



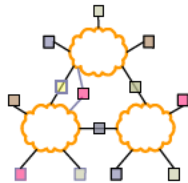
a. Bandwidth of a periodic signal



b. Bandwidth of a nonperiodic signal

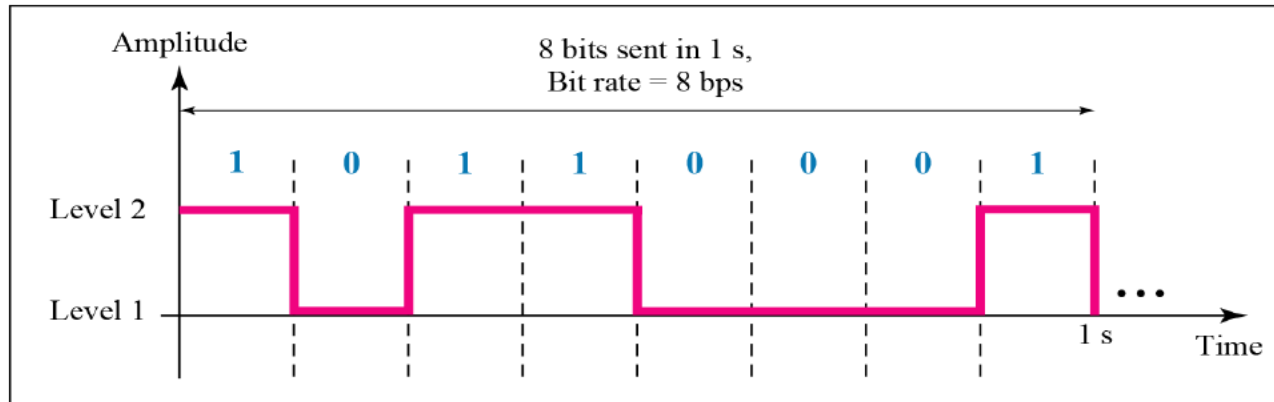
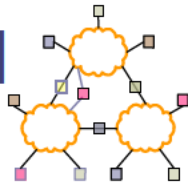


# DIGITAL SIGNALS

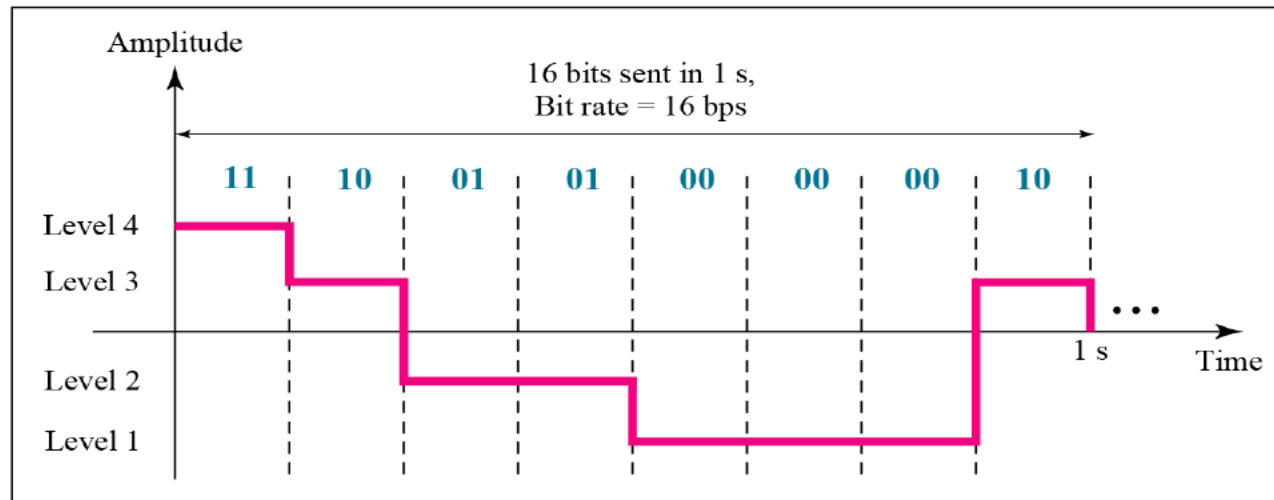


- In addition to being represented by an analog signal, information can also be represented by a **digital signal**.
- For example, a 1 can be encoded as a positive voltage and a 0 as zero voltage.
- A digital signal can have more than two levels.
- In this case, we can send more than 1 bit for each level.

# Two digital signals: one with two signal levels and the other with four signal levels

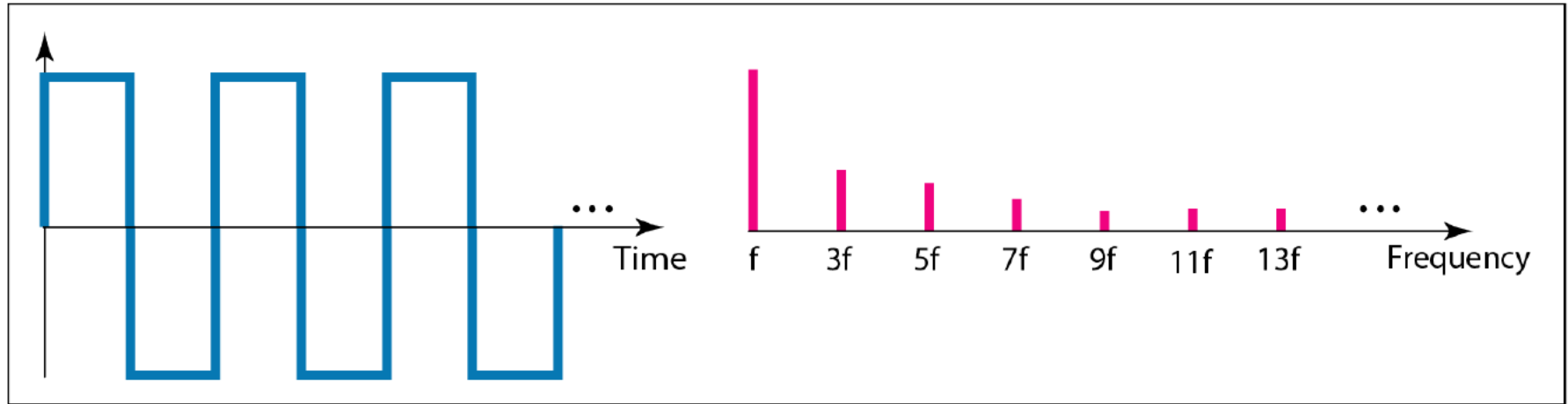
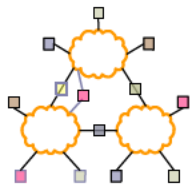


a. A digital signal with two levels

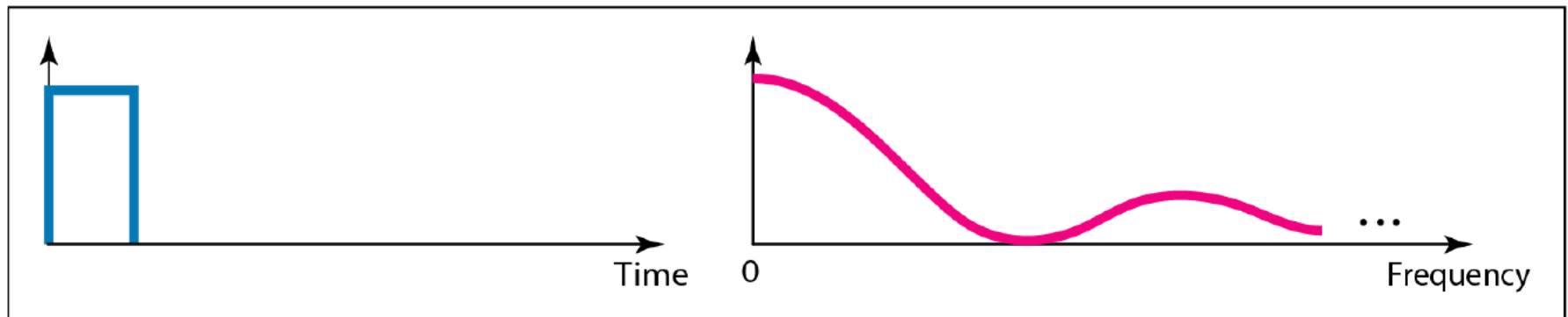


b. A digital signal with four levels

# The time and frequency domains of periodic and nonperiodic digital signals

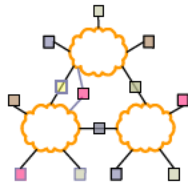


a. Time and frequency domains of periodic digital signal

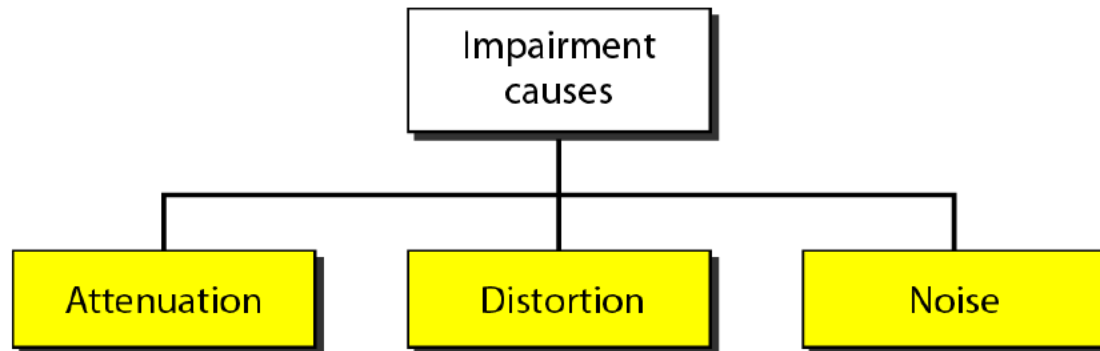


b. Time and frequency domains of nonperiodic digital signal

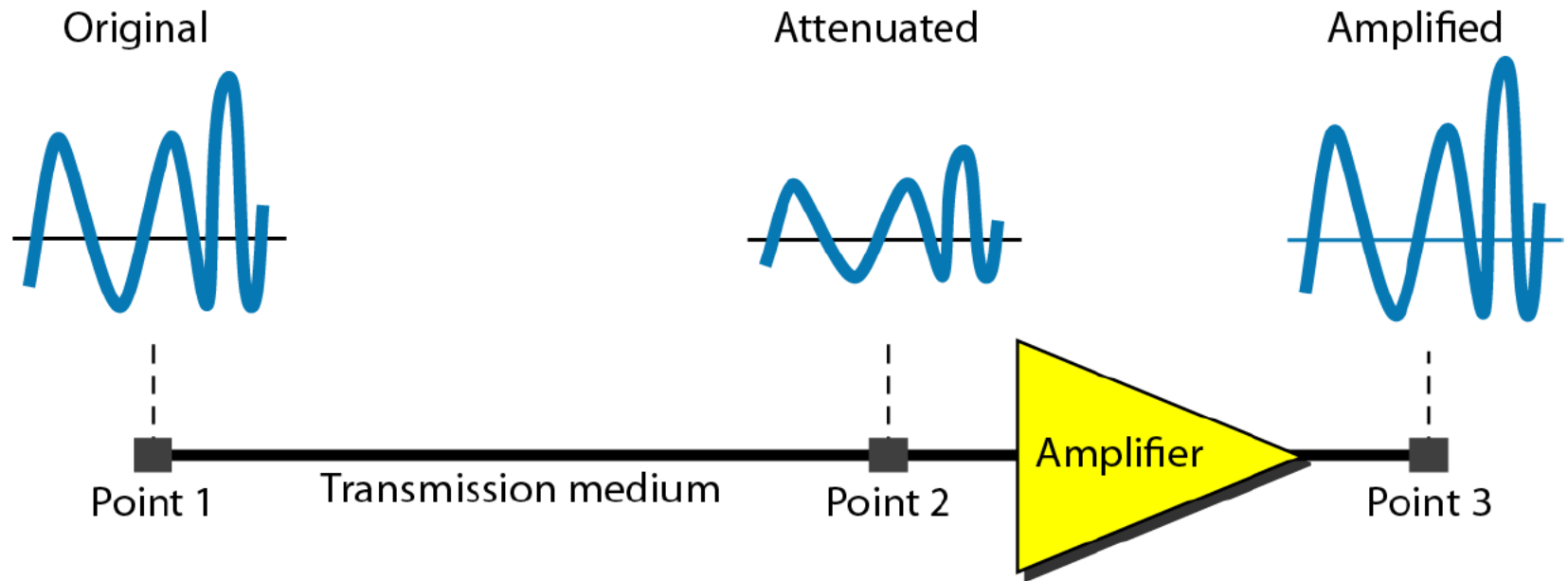
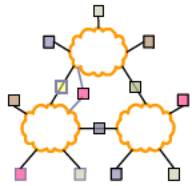
# TRANSMISSION IMPAIRMENT



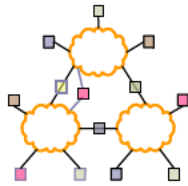
- Signals travel through transmission media, which are not perfect.
- The **imperfection causes signal impairment**.
- This means that the signal at the beginning of the medium is not the same as the signal at the end of the medium ( i.e., **What is sent is not what is received**).
- Three causes of impairment are **attenuation, distortion, and noise**.



# Attenuation

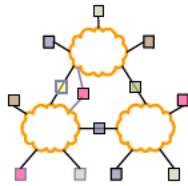


# Attenuation



- Attenuation can be considered as the **loss of energy**
- When a signal travels through a medium it loses energy overcoming the **resistance of the medium**. That is why a wire carrying electric signals gets warm, if not hot, after a while. Some of the electrical energy in the signal is converted to heat.
- It decides **how far the signal can go** without amplification
- **Amplifiers** are used to compensate for this loss of energy by amplifying the signal.

# Decibel

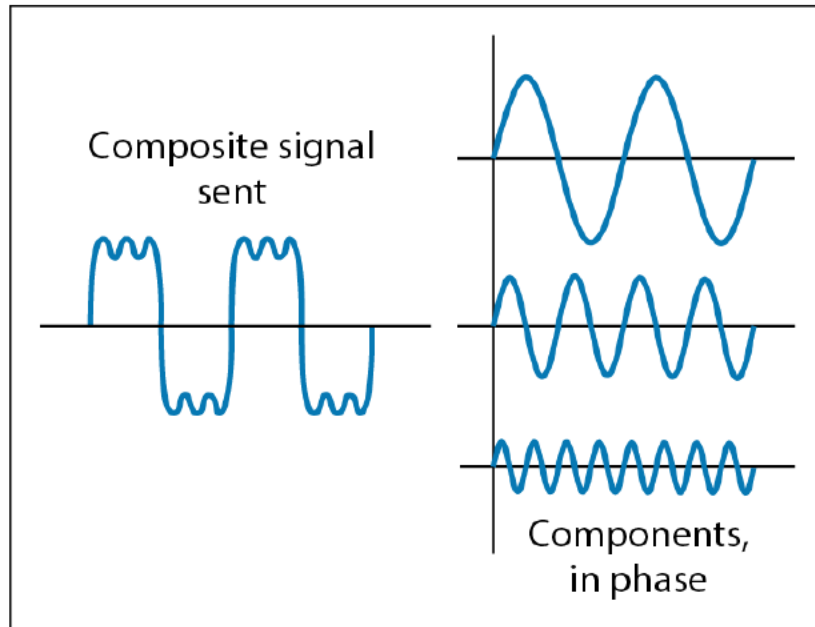
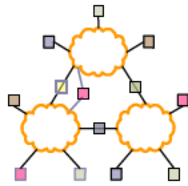


- To show that a signal has lost or gained strength, we use the unit of the **decibel**.
- The decibel (dB) **measures** the **relative strengths** of two signals or one signal at two different points.
- Note that the decibel is:
  - **Negative** if a signal is **attenuated** and
  - **Positive** if a signal is **amplified**.

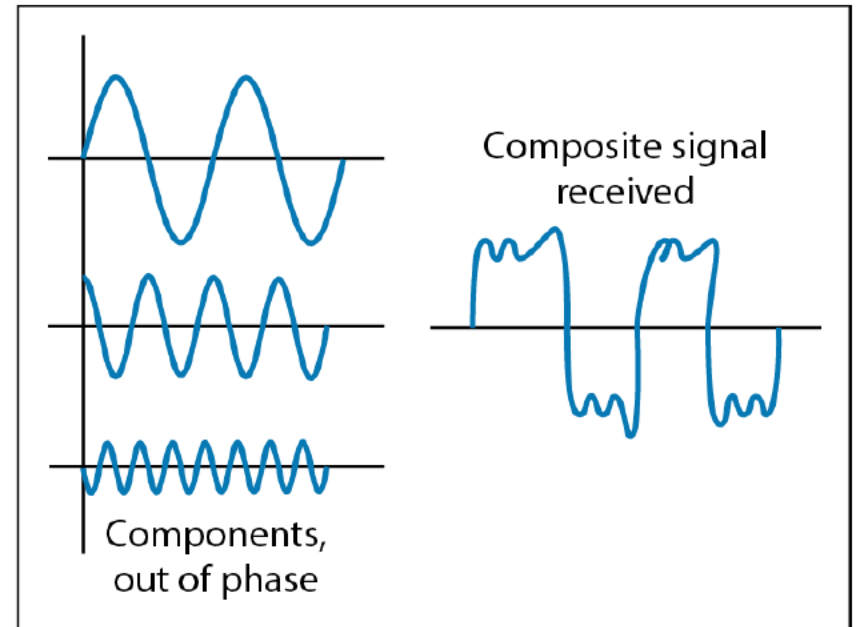
$$\text{dB} = 10 \log_{10} \frac{P_2}{P_1}$$

- $P_1$  and  $P_2$  are the powers of a signal at points 1 and 2, respectively

# Distortion



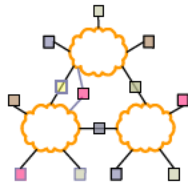
At the sender



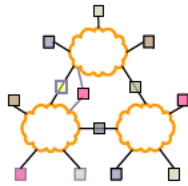
At the receiver



# Distortion

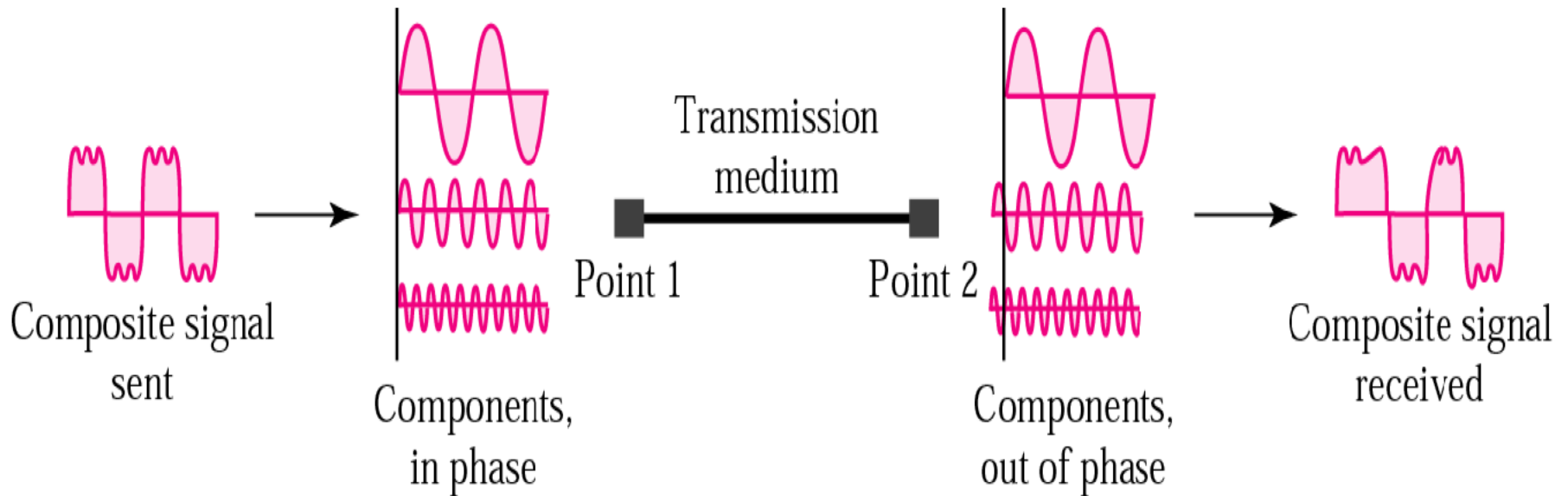
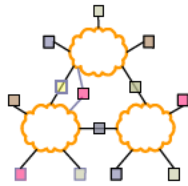


- Means that the signal changes its form or shape
- Distortion occurs in **composite** signals
- Each frequency component has its own **propagation speed** traveling through a medium.
- The different components therefore arrive with **different delays** at the receiver.
- That means that the signals have **different phases** at the receiver than they did at the source.



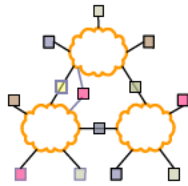
- Distortion means that the signal changes its form or shape.
- Distortion can occur in a composite signal made of different frequencies.
  - Each signal component has its own propagation speed through a medium and, therefore, its own delay in arriving at the final destination.
  - Differences in delay may create a difference in phase if the delay is not exactly the same as the period duration.
  - In other words, signal components at the receiver have phases different from what they had at the sender.
  - The shape of the composite signal is therefore not the same.





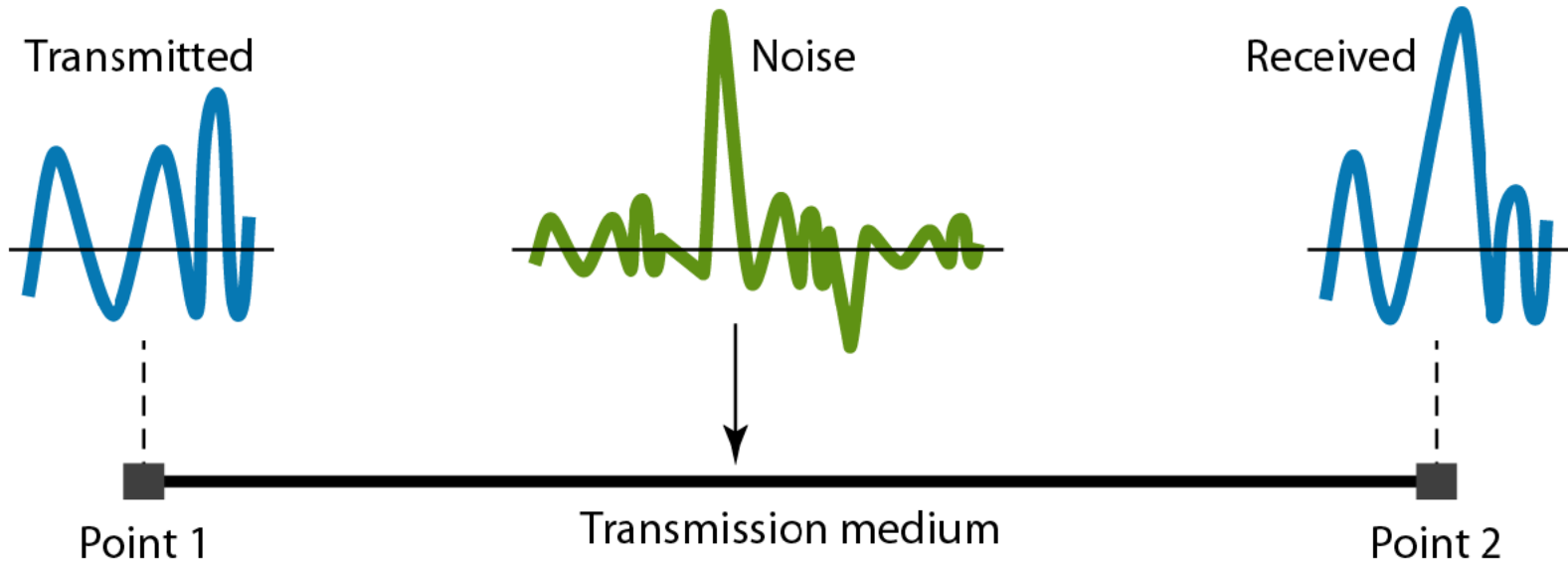
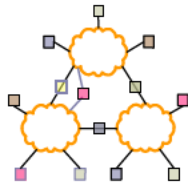
## Effect Of Distortion On A Composite Signal.

# Delay distortion

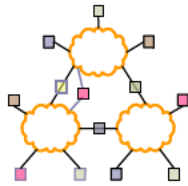


- Delay distortion **arises** particularly in a **guided media** but not in air
- Delay distortion arises because **velocity** of propagation **varies with frequency**.
- That means this signal components that we are sending will have different velocities for different frequency components as it passes through a guided media, and this leads to delay distortion

# Noise

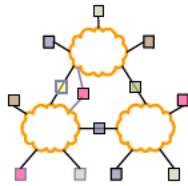


# Noise



- **Thermal noise** is the random motion of electrons in a wire which creates an extra signal not originally sent by the transmitter.
- **Induced noise** comes from sources such as motors and appliances.
  - These devices act as a sending antenna, and the transmission medium acts as the receiving antenna.
- **Cross-talk** is the effect of one wire on the other. One wire acts as a sending antenna and the other as the receiving antenna.
- **Impulse noise** is a spike (a signal with high energy in a very short time) that comes from power lines, lightning, and so on.

# Signal-to-Noise Ratio (SNR)

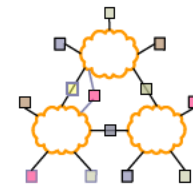


- To find the theoretical bit rate limit, we need to know the ratio of the signal power to the noise power.
- The signal-to-noise ratio is defined as:

$$\text{SNR} = \text{average signal power} / \text{average noise power}$$

- We need to consider the average signal power and the average noise power because these may change with time.

# Idea of SNR



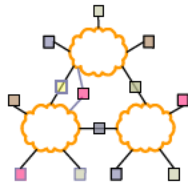
- The values of SNR and SNR<sub>dB</sub> for a noiseless channel are

$$\text{SNR} = \frac{\text{signal power}}{0} = \infty$$
$$\text{SNR}_{\text{dB}} = 10 \log_{10} \infty = \infty$$

*We can never achieve this ratio in real life; it is an ideal.*



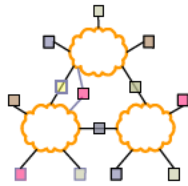
# Signal-to-Noise Ratio (SNR)



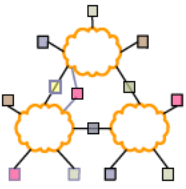
- SNR is actually the ratio of what is wanted (signal) to what is not wanted (noise).
  - A high SNR means the signal is less corrupted by noise;
  - A low SNR means the signal is more corrupted by noise.
- Because SNR is the ratio of two powers, it is often described in decibel units,  $\text{SNR}_{\text{dB}}$  defined as:

$$\text{SNR}_{\text{dB}} = 10 \log_{10} \text{SNR}$$

# Data Rate Limits



- A very important consideration in data communications is how fast we can send data, in **bits per second**, over a channel.
- Data rate depends on **three factors**:
  1. The bandwidth available
  2. The level of the signals we use
  3. The quality of the channel (the level of noise)
- Two theoretical formulas were developed to calculate the data rate:
  - **By Nyquist**: For a noiseless channel
  - **By Shannon**: For a noisy channel.



Thank You