Chapter 2:

1. Conditional Prob:

The conditional probability of B, given A, denoted by P(B|A) is defined by

$$P(B|A) = \frac{P(A \cap B)}{P(A)}$$
 provided $P(A) > 0$.

Conditions:

2.
$$A$$
 given that B $P(A|B)$

3. If
$$A_{-}$$
, what is prob B_{-} $P(B|A)$

4. Given that
$$A$$
, what is prob B $P(B|A)$

2. Bayes Law:

If mentioned that find the whole prob of event then use this:

If the events $B \setminus B_2, \dots, B_k$ constitute a partition of the sample space S such that $P(B_i) \neq 0$ for $T = 1, 2, \dots, k$, then for any event A of S,

$$P(A) = \sum_{i=1}^{A:} P(B_i \cap A) = \sum_{i=1}^{K} P(B_i) P(A|B_i).$$

If its mentioned that find prob. from specific location then use this:

(Bayes' Rule) If the events $B_1, B_2, \ldots, objectitute$ a partition of the sample space S such that $P(B_i) \neq 0$ for $i = 1, 2, \ldots, k$, then for any event A in S such that $P(A) \neq 0$,

$$P(B_r|A) = \frac{P(B_r \cap A)}{\sum\limits_{i=1}^{k} P(B_i \cap A)} = \frac{P(B_r)P(A|B_r)}{\sum\limits_{i=1}^{k} P(B_i)P(A|B_i)} \text{ for } r = 1, 2, \dots, k.$$

Chapter 3:

1. Discrete Prob Distribution:

The set of ordered pairs (x, f(x)) is a probability function, probability mass function, or probability distribution of the discrete random variable X if, for each possible outcome x,

$$1. f(x) \geq 0,$$

2.
$$\sum_{x} f(x) = 1$$
,

3.
$$P(X = x) = f(x)$$
.

Steps:

- 1. Draw the table of x,F(x)
- 2. If you have to find value of any variable then use Condition-2 according to prob function.

2. Cummulative Distribution Function for Discrete:

The cumulative distribution function F(x) of a discrete random variable X with probability distribution f(x) is

$$F(x) = P(X \le x) = \sum_{t \le x} (t), \quad \text{for } -00 < x < 00.$$

e.g,
$$\mathbf{F}(\mathbf{x}) = \mathbf{f}(0)$$
 ____Condition___

$$f(2)=f(0)+f(1)$$
 _____Condition__

$$f(3)=f(0)+f(1)+f(2)$$
 ___Condition____

3. Continuous Prob Density Function:

2,
$$\int_{-\infty}^{\infty} f(x) dx = 1$$
.

3.
$$P(a < X < b) = \int_{a}^{b} f(x) dx$$
.

4. Cummulative Distribution Function for Continuous:

The cumulative distribution function F(x) of a continuous random variable A' with density function f(x) is

$$F(x) = P(X \le \mathbf{a}) = \int_{-\infty}^{t/t} f(t) \text{ eff.} \quad \text{for } --00 < \pi : < \infty.$$

5. Joint Prob Distribution of Discrete:

The function f(x,y) is a joint probability distribution or probability mass function of the discrete random variables X and Y if

1.
$$f(x, y) \ge 0$$
 for all (x, y) ,

2.
$$\sum \sum (x, y)_{-} = 1$$
,

3.
$$P(X = x, Y = y) = f(x, y)$$
.

For any region A in the ry plane, $P(X, Y) \in A$] = $\sum_{A} f(x, y)$.

Steps:

- 1. Draw Table of x,y and put prob of their corresponding values.
- 2. Write g(x) and h(y) according to prob.

These g(x) and h(y) are called marginal distribution of X,Y.

6. Joint Density Function of Continuous:

The function f(x,y) is a **joint density function** of the continuous random variables X and Y if

- 1. $f(x,y) \ge 0$, for all (x,y),
- $2. \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} f(x, y) dx dy = l,$
- 3. $P[(X, Y) \in A] = / \int_A f(x, y) dx dy$

for any region A in the xy plane.

7. Marginal Distributions:

The marginal distributions of X alone and of Y alone are

$$g(x) = \sum_{y} f(x, y)$$
 and $h(y) = \sum_{x} f(x, y)$,

for the discrete case, and

$$g(x) = \int_{-\infty}^{\infty} f(x, y) dy$$
 and $h(y) = \int_{-\infty}^{\infty} f(x, y) dx$,

for the continuous case.

8. Conditional Prob distribution:

Let X and Y be two random variables, discrete or continuous. The **conditional** distribution of the random variable Y given that X = x is

$$f(y|x) = \frac{f(x,y)}{g(x)}, \quad g(x) > 0.$$

Similarly the conditional distribution of the random variable X given that Y = y is

$$f(x|y) = \frac{f(x,y)}{h(y)}, h(y) > 0.$$

If want to find prob. Then

If we wish to find the probability that the discrete random variable X falls between u and b when it is known that the discrete variable Y = y, we evaluate

$$P(a < X < b | Y = y) = \sum_{x \in A} f(x|y),$$

where the summation extends over all values of X between a and b. When X and Y are continuous, we evaluate

$$P(a < X < b|Y=y) = \int_{a}^{b} f(x|y) dx.$$

9. Independence:

The random variables X and Y are said to be statistically independent if and only if

$$f(x, y) = g(x)h(y)$$

for all (x, y) within their range.

Otherwise not independent.

Chapter 4:

1. Mean of Random Variable:

Let X be a random variable with probability distribution f(x). The mean or expected value of X is

$$\mu = E(X) = \sum_{x} xf(x)$$

if X is discrete, and

$$\mu = E(X) = \int_{-\infty}^{\infty} x f(x) dx$$

if X is continuous.

Property:

1.

Let X be a random variable with probability distribution f(x). The expected value of the random variable g(X) is

$$\mu_{g(X)} = E[g(X)] = \sum_{x} g(x)f(x)$$

if X is discrete, and

$$\mu_{g(X)} = E[g(X)] = \int_{-\infty}^{\infty} g(x)f(x) dx$$

if X is continuous.

2.

Let X and Y be random variables with joint probability distribution f(x, y). The mean or expected value of the random variable g(X, Y) is

$$\mu_{g(X,Y)} = E[g(X,Y)] = \sum_{x} \sum_{y} g(x,y)f(x,y)$$

if X and Y are discrete, and

$$f_{V(-V,V)} = E[g(X,Y)] = \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} g(x,y)f(x,y) dx dy$$

if X and Y are continuous.

2. Variance:

Condition #1:

Let X be a random variable with probability (fistribution f(x) and mean μ . The variance of X is

$$\sigma^2 = E[(X - \mu)^2] = \sum_x (x - \mu)^2 f(x), \quad \text{if } X \text{ is discrete, and}$$

$$\sigma^2 = E[(X - \mu)^2] = \int_0^\infty (x - \mu)^2 f(x) \, dx, \quad \text{if } X \text{ is continuous.}$$

The positive square root of the variance, σ , is called the standard deviation of X.

For Discrete: $Var(X) = E(X^2) - (E(X))^2$

For Continuous: $E(X^2) = Integral(x^2 f(x))$ from infinity to – infinity.

E(x)= Integral(x f(x)) from infinity to – infinity.

And S.D is Sq. root of Variance.

Condition #2:

Let X be a random variable with probability distribution f(x). The variance of the random variable g(X) is

$$\sigma_{g(X)}^2 = E\{[g(X) - \mu_{g(X)}]^2\} = \sum_{x} [g(x) - \mu_{g(X)}]^2 f(x)$$

if X is discrete, and

$$\sigma_{g(X)}^2 = E\{[g(X) - \mu_{g(X)}]^2\} = \int_{-\infty}^{\infty} [g(x) - \mu_{g(X)}]^2 f(x) dx$$

if X is continuous.

3. Correlation Co-efficient:

Let X and Y be random variables with covariance σ_{XY} ; and standard deviations σ_X and σ_Y , respectively. The correlation coefficient of X and Y is

$$\rho_{XY} = \frac{\sigma_{XY}}{\sigma_{X}\sigma_{Y}}$$

4. Co-variance:

For Continous and Discrete Both.

$$\sigma_{XY} = COV(X, Y) = E(XY) - E(X)E(Y)$$

Properties:

Mean	Variance
1. E(a)=a where a is const	1. Var(a)=0
2. $E(x\pm a)=E(x)\pm a$	2. $Var(x\pm a)=Var(x)$

3. E(ax) = aE(x)	3. $Var(ax)=a^2Var(x)$
4. E(ax+b)=aE(x)+b	4. $Var(ax+b) = a^2Var(x)$

If X,Y are Random Variables:

Mean	Variance
1. $E(x+y)=E(X)+E(Y)$	1. $Var(x+y)=Var(x)-Var(y)$
2. $E(x-y) = E(X) - E(Y)$	$2. \operatorname{Var}(X-Y) = \operatorname{Var}(X) + \operatorname{Var}(Y)$
3. E(XY) = E(X)E(Y)	3. $Var(XY) = Var(X) Var(Y)$

Chapter 5:

1. Discrete Uniform Distribution:

If the random variable X assumes the values $x_1, x_2, \bullet, ..., x_k$, with equal probabilities, then the discrete uniform distribution is given by

$$f(x;k) = \frac{1}{k}$$
 $x = x_1, x_2, ..., x_k$

Mean and Var:

The mean and variance of the discrete uniform distribution f(x; k) are

$$\mu = \frac{1}{k} \sum_{i=1}^{k} x_i$$
, and $\sigma^2 = \frac{1}{k} \sum_{i=1}^{k} (x_i - \mu)^2$.

2. Bernoulli Distribution:

$$f(x) = n_{C_x} q^{n-x} p^x$$

Where x ranges from 0 to n

n is number of trials, p is prob of successful event, q is prob of failure of event.

It is used when selection is done with replacement and independent trials.

Mean and Variance:

Mean=np and Var=npq

2.1. Multinomial Distributions:

Multinomial If a given trial can result in the k outcomes $E_1, E_2, ..., E_k$ with probabilities $p_1, p_2, ..., p_k$, then the probability distribution of the random variables $X_1, X_2, ..., X_k$, representing the number of occurrences for $E_1, E_2, ..., E_k$ in n independent trials is

$$f(x_1, x_2, ..., x_k; p_1, p_2, ..., p_k f n) = \binom{n}{(x_1, x_2, ..., x_k)} p_1^{x_1} p_2^{x_2} ... p_k^{x_k},$$

3. Hyper Geometric Distributions:

$$f(x) = \frac{k_{C_x} N - k_{C_{n-x}}}{N_{C_n}}$$

Where n is total selected items, N is total items, k is total favourable items.

N-k= total unfavourable items, k is total favourable items.

x is random variable.

It is used when selection is done without replacement. And it does not require independence.

Mean and Variance:

Mean=nk/N. and Var=(N-n)/(N-1)*n*k/N(1-k/N)

3.1. Multivariate Hyper Geometric Distributions:

Multivariate:

If N items can be partitioned into the A: cells $A_1, A_2, ... A_k$ with $a_1, a_2, ... a_k$ Hypergeometric elements, respectively, then the probability distribution of the random variables Distribution X_1, X_2, \dots, X_k , representing the number of elements selected from A_1, A_2, \dots, A_k in a random sample of size n, is

$$f(x_1, x_2, ..., x_k; a_1, a_2, ..., a_k, N, n) = \frac{\binom{a_1}{x_1}\binom{a_2}{x_2} \cdots \binom{a_k}{x_k}}{\binom{N}{n}},$$

with
$$\sum_{i=1}^{k} x_i = n$$
 and $\sum_{i=1}^{k} a_i = A'$.

4. Poisson Distributions:

When n is very large and p is very small. i.e, n>30 and p<0.05

$$f(x) = \frac{-e^{\mu}\mu^x}{x!}$$

Where μ =np. And var is np.

5. Negative Binomial Distributions:

When repeated independent trials and number of trial on which kth success occurs

$$*b(x,k,p) = x - 1_{C_{k-1}} p^k q^{k-1}$$

5.1. Geometric Distributions:

When repeated independent trials and number of trials on which 1st success occurs

$$q(x, p) = pq^{x-1}$$

Mean and Variance:

The mean and variance of a random variable following the geometric distribution are

$$\mu = \frac{1}{p}, \quad \sigma^2 = \frac{1-p}{p^2}.$$

