Classical Planning in a Deep Latent Space

(WIP project idea)

1 Classical Planning

Scalable, Highly-optimized solver for complex combinatorial problems

Guided by **domain-independent** heuristics

Requires an explicit encoding of the real world, written by human

2 Reinforcement Learning

Policy function π(s): S $\rightarrow$ A — returns action a for state s

Optimal Policy π^*(s)

Goal: Find the best approximation of π^*

3 Reinforcement Learning in Latent Space

4 Deep Reinforcement Learning

5 Comparison

	Deep Reinforcement Learning	**Deep Reinforcement Learning**
Classical Planning **Scalable, Highly-optimized solver** for complex combinatorial problems Guided by **domain-independent** heuristics **Requires an explicit encoding** of the real world, written by human	Works on the **implicit encoding** of the real world Reasoning is limited to the **1-step future** of the current state guided by **instance-specific learned knowledge** (specific object, situation, goal)	Works on the **implicit encoding** of the real world Reasoning is limited to the **1-step future** of the current state guided by **instance-specific learned knowledge** (specific object, situation, goal)

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