

Bilevel MCTS for Amortized O(1) Node Selection in Classical Planning

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Use arrow keys ($\leftarrow \rightarrow$) or n/p keys

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Created: 2025-12-28 Sun 15:36

1. Overview

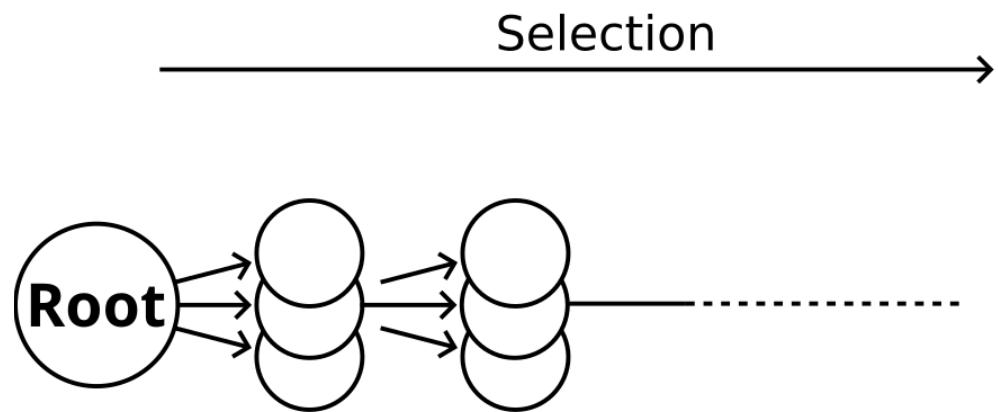
Common Weakness of Monte-Carlo Tree Search

Bilevel MCTS

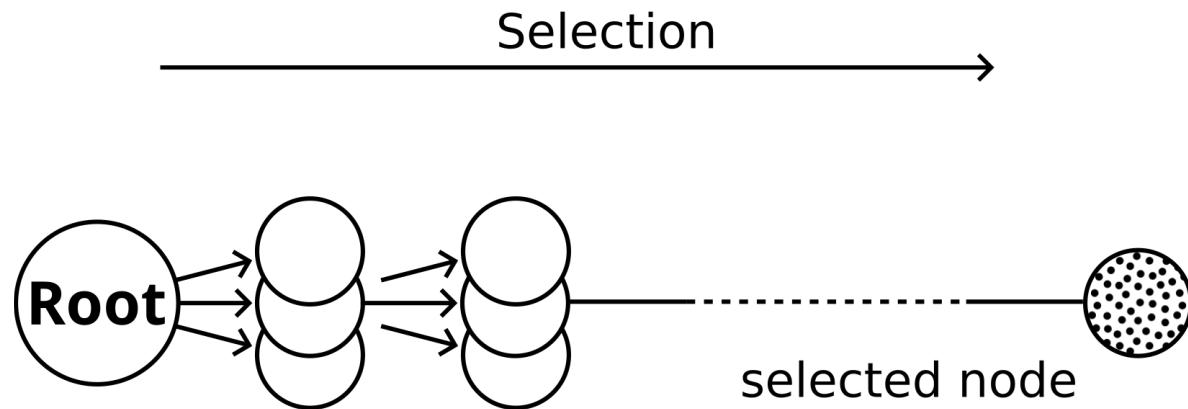
Tree Collapsing

Nebula planner: SoTA results (MCTS+LAMA+BFWS)

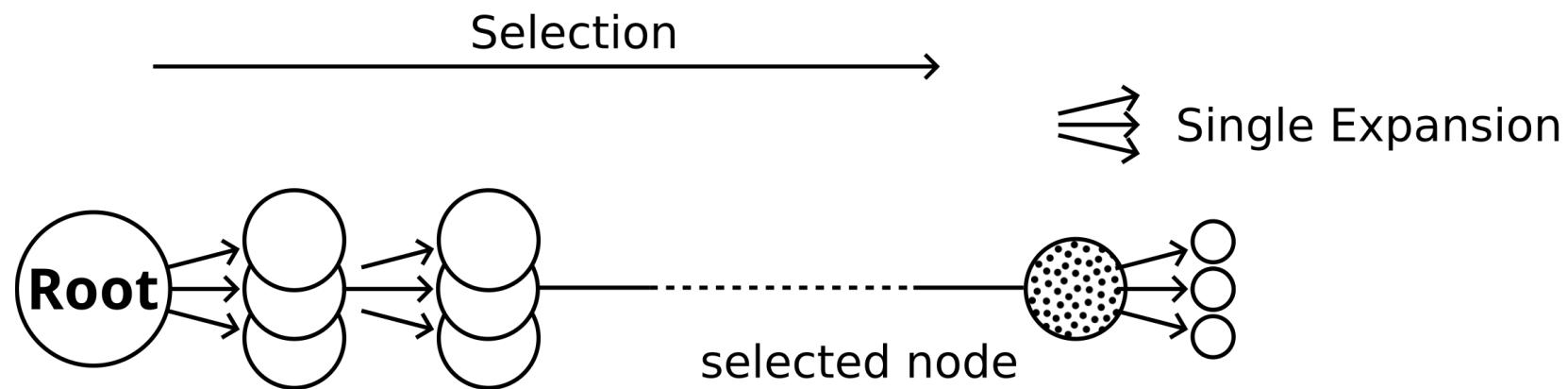
2. Monte Carlo Tree Search



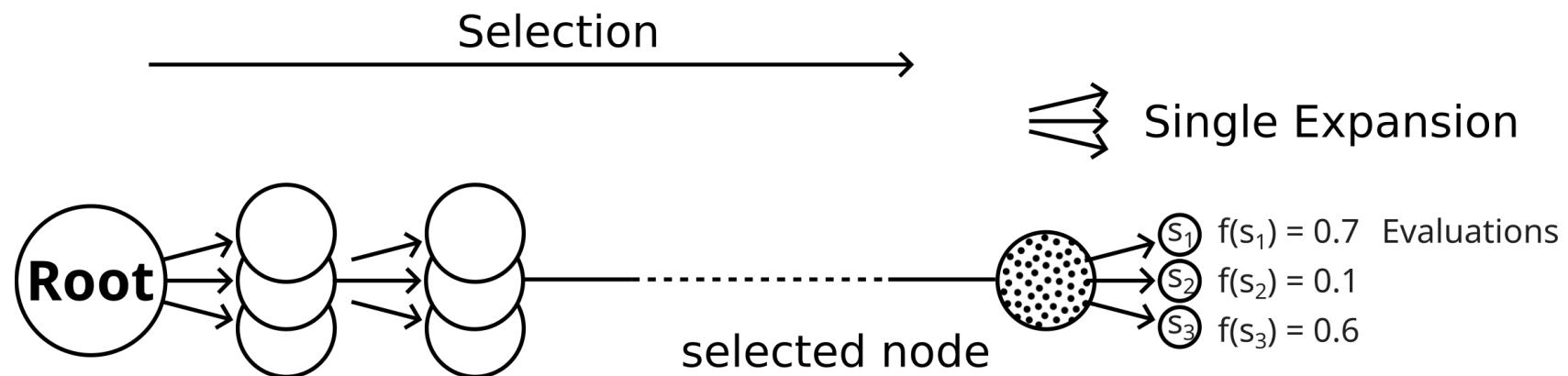
2.1. Monte Carlo Tree Search



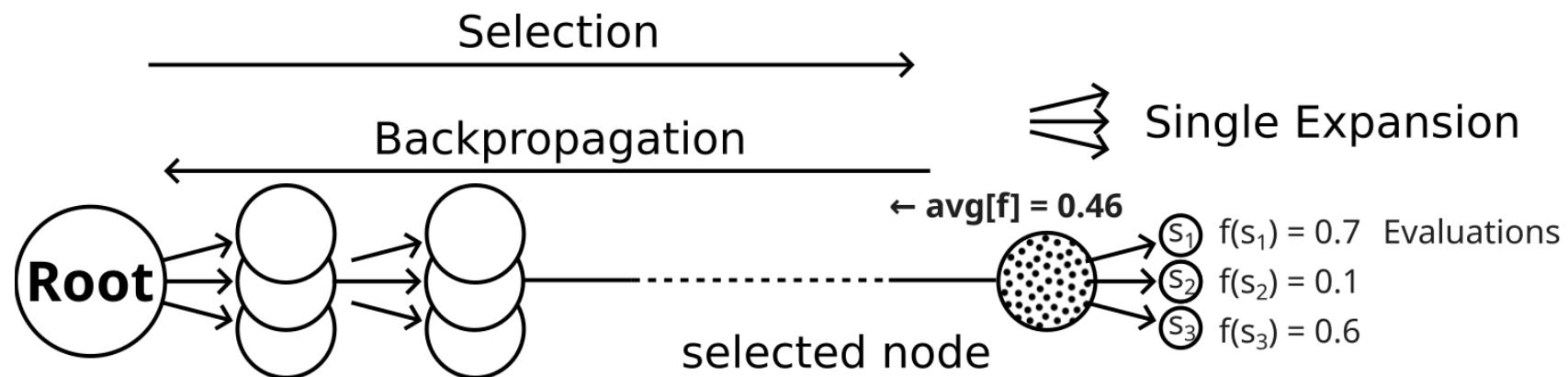
2.2. Monte Carlo Tree Search



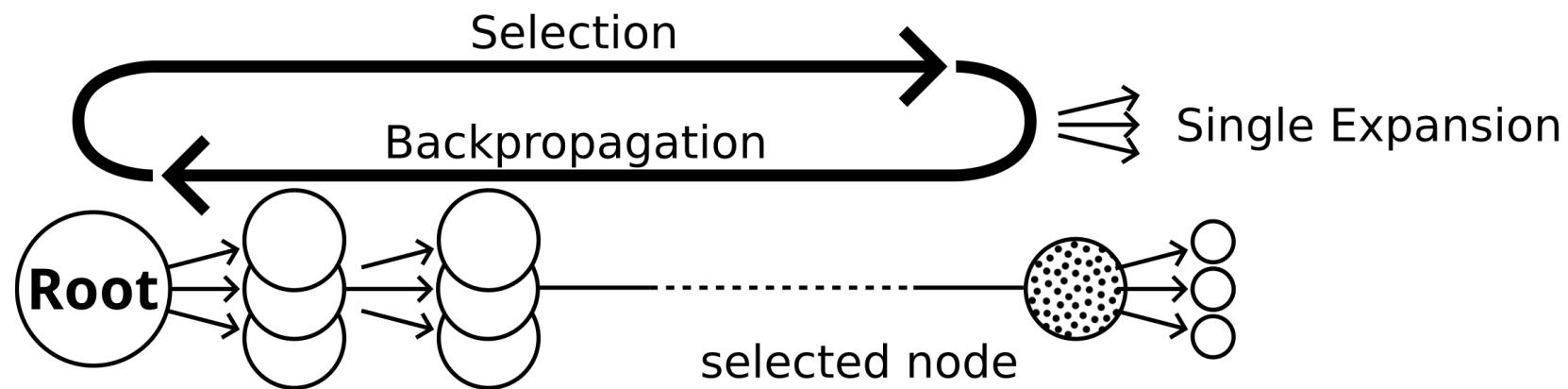
2.3. Monte Carlo Tree Search



2.4. Monte Carlo Tree Search

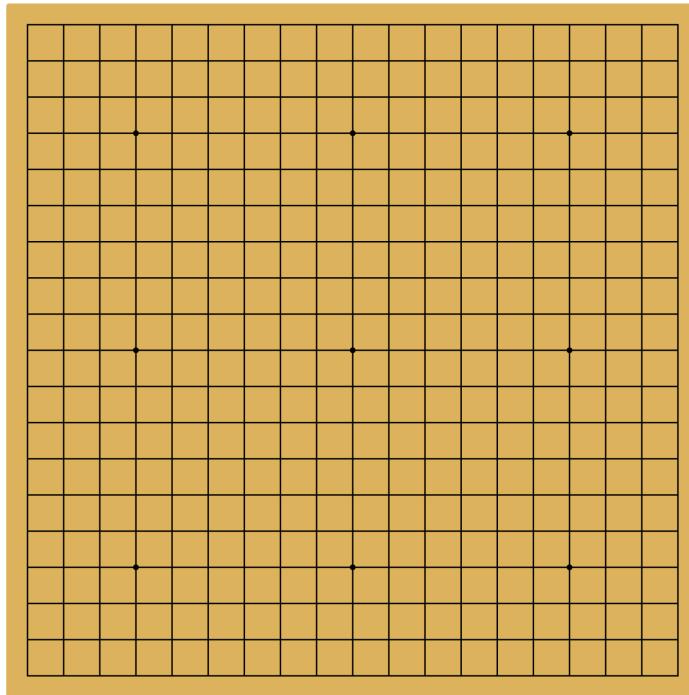


2.5. Monte Carlo Tree Search



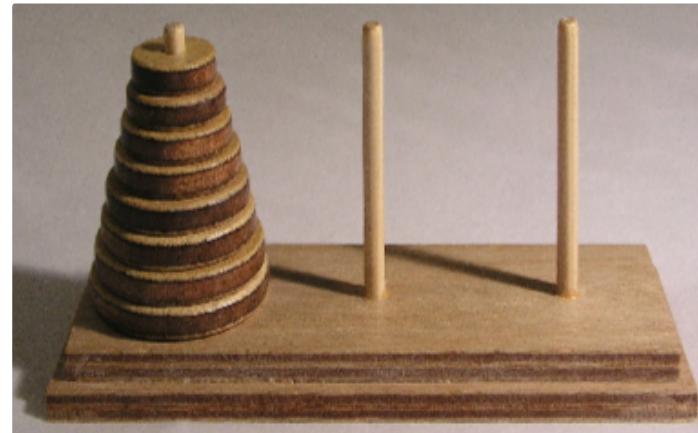
3. **Weakness**: needs a *shallow search space*

Game of Go



Depth $d < 19^2 = 391$

Tower of Hanoi

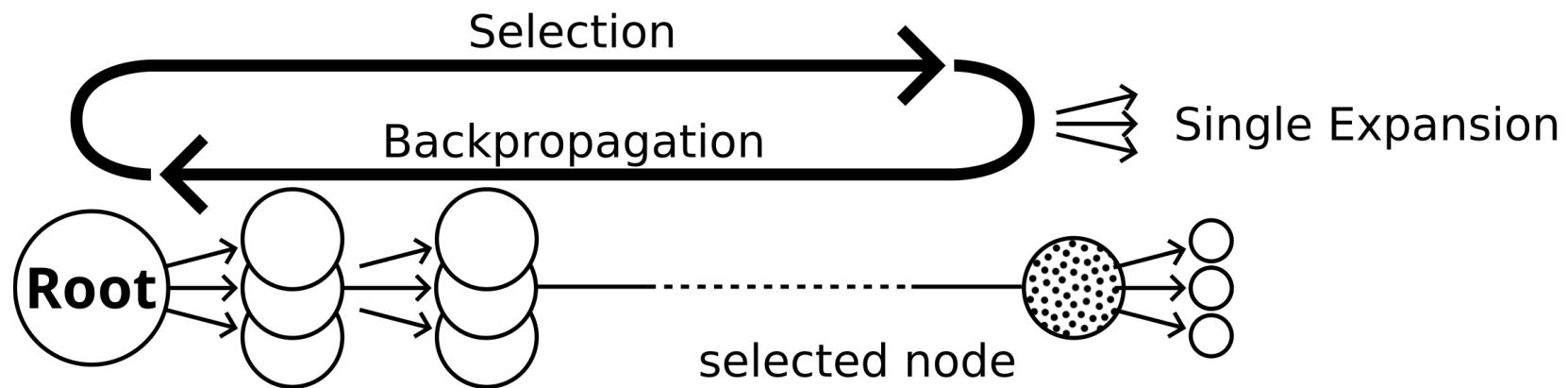


Depth $d = 2^k - 1$ (k disks)

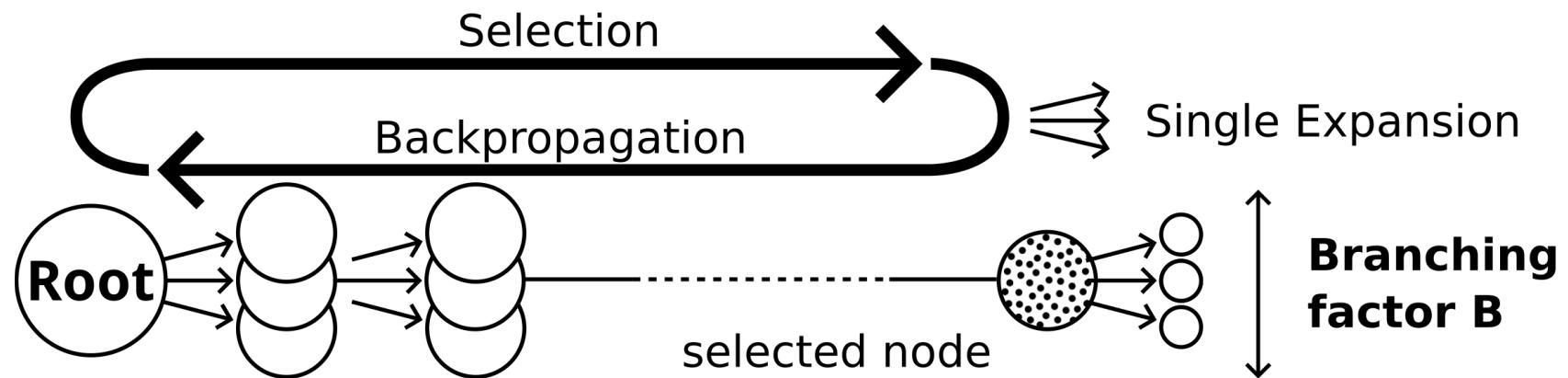
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Single Player Planning often requires an *exponential* depth!

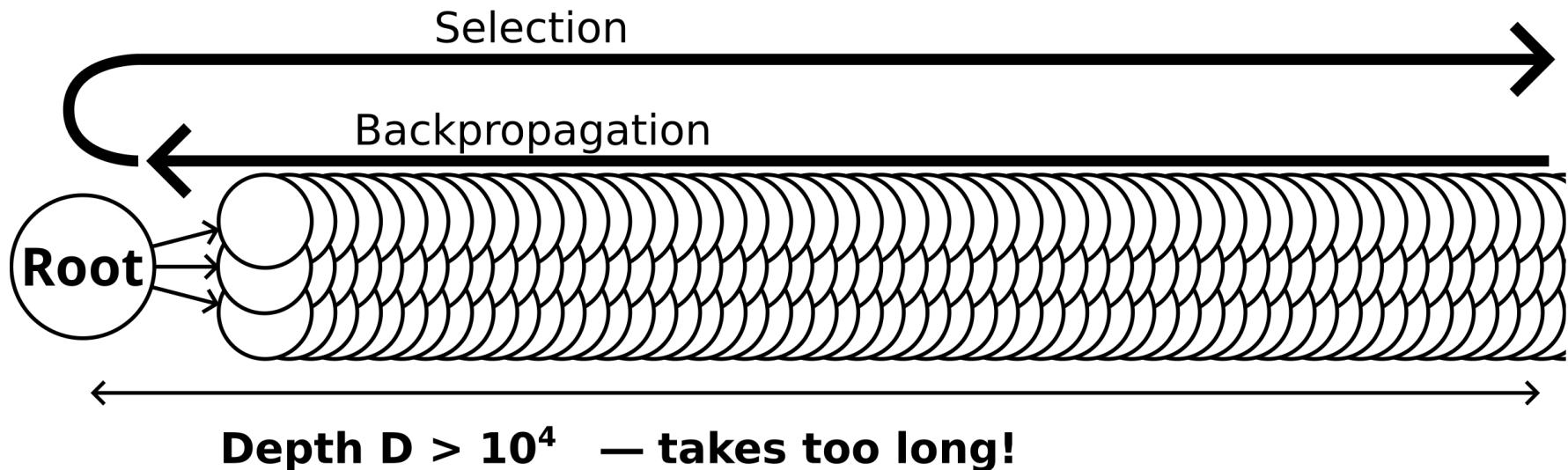
4. **Weakness**: Larger $d \rightarrow$ Slower MCTS



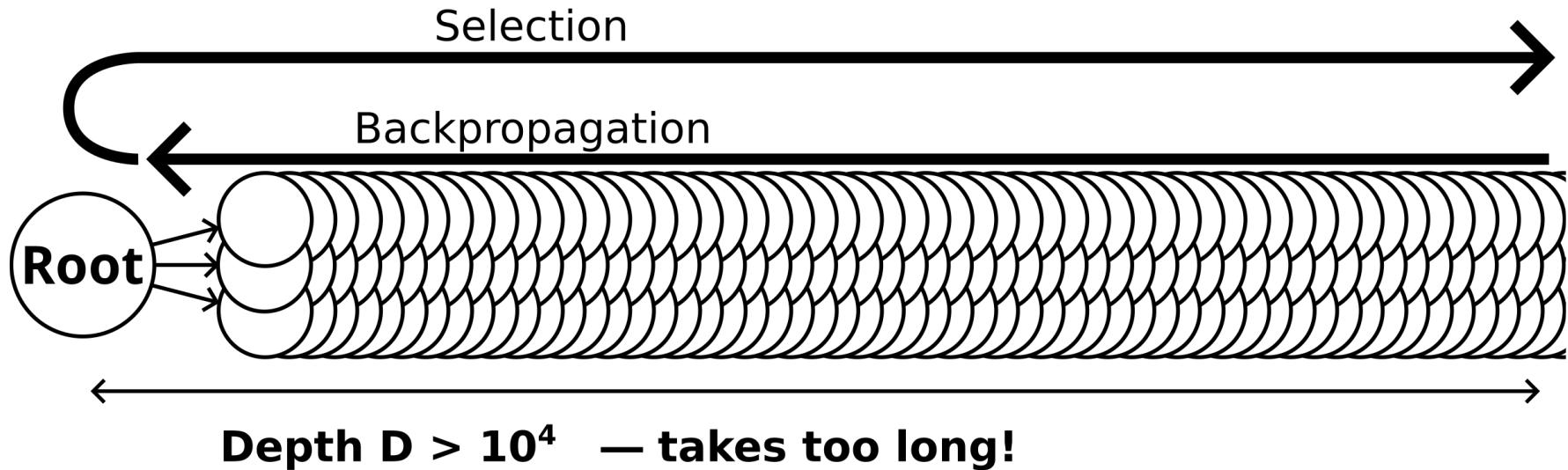
4.1. **Weakness**: Larger $d \rightarrow$ Slower MCTS



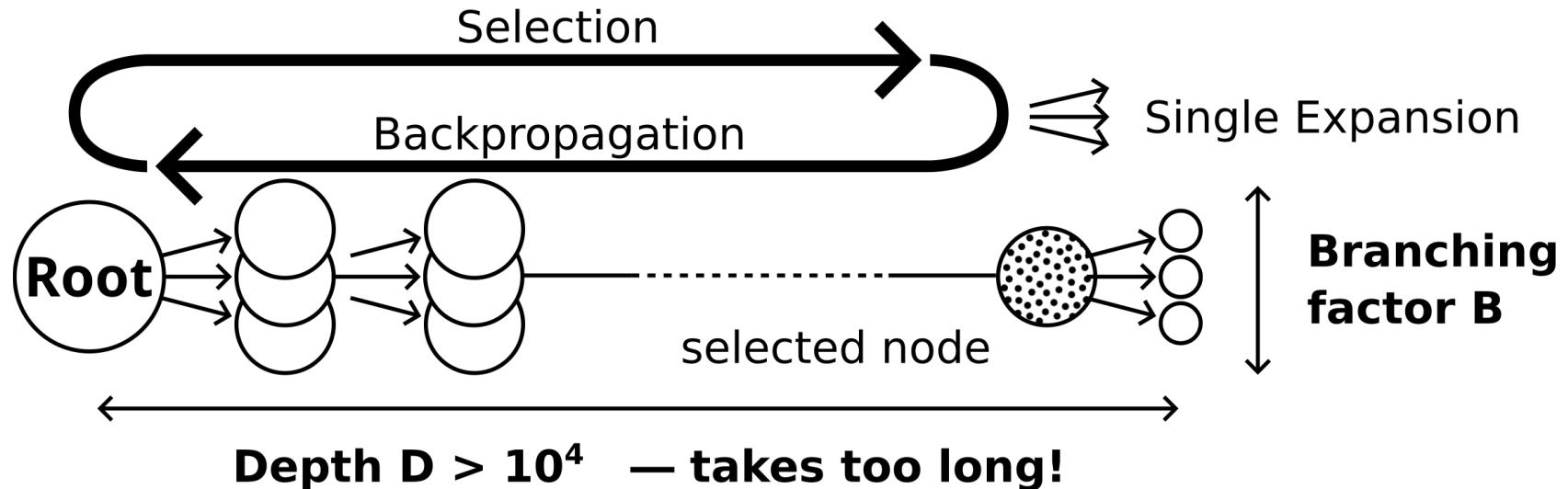
4.2. Weakness: Larger $d \rightarrow$ Slower MCTS



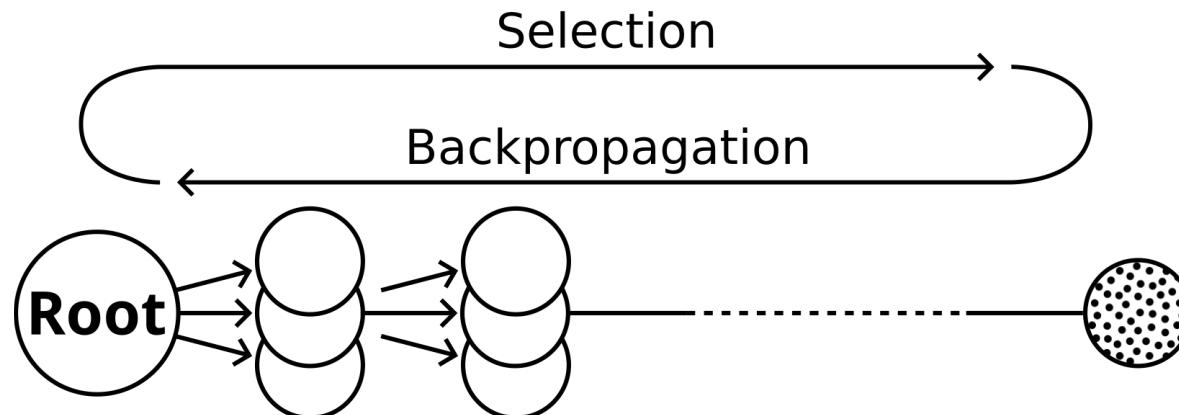
5. Proposed: Bilevel MCTS



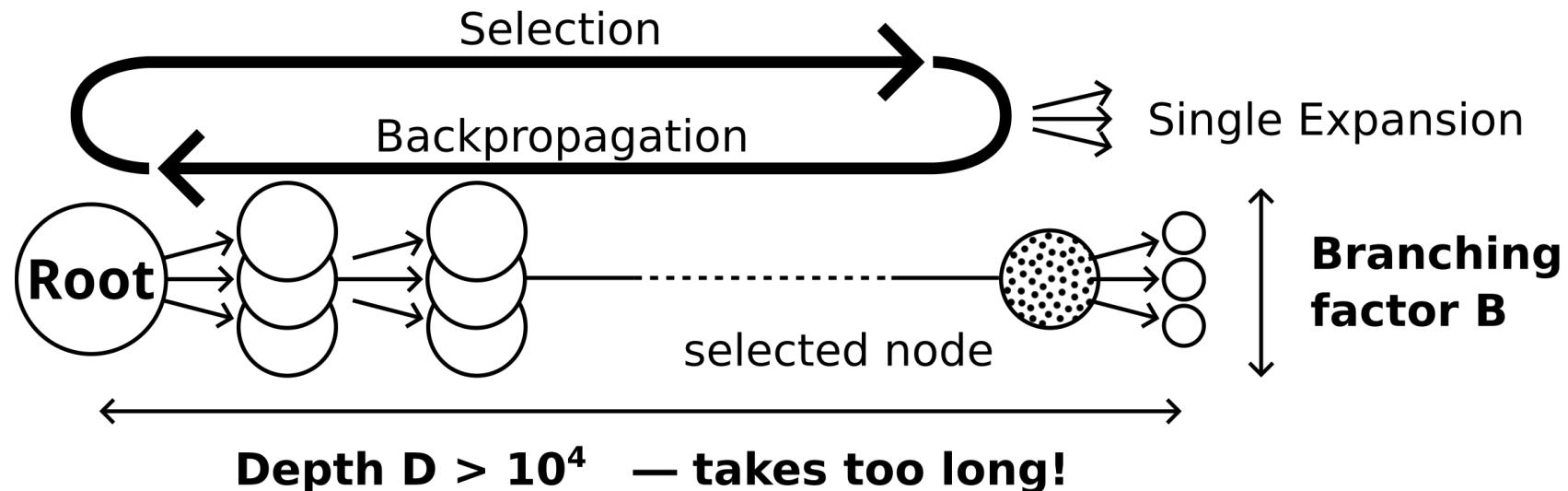
5.1. Proposed: Bilevel MCTS



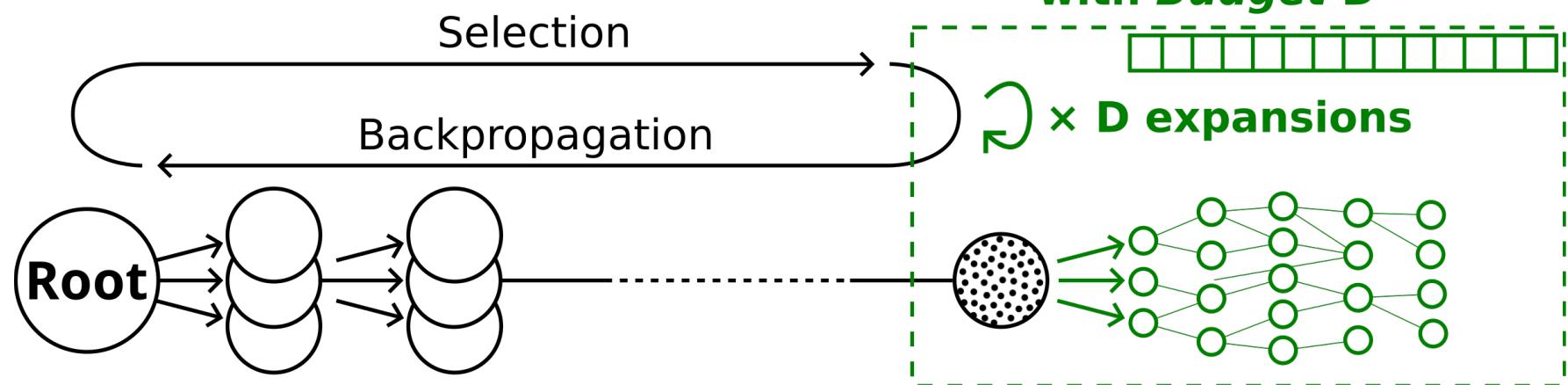
Bilevel MCTS



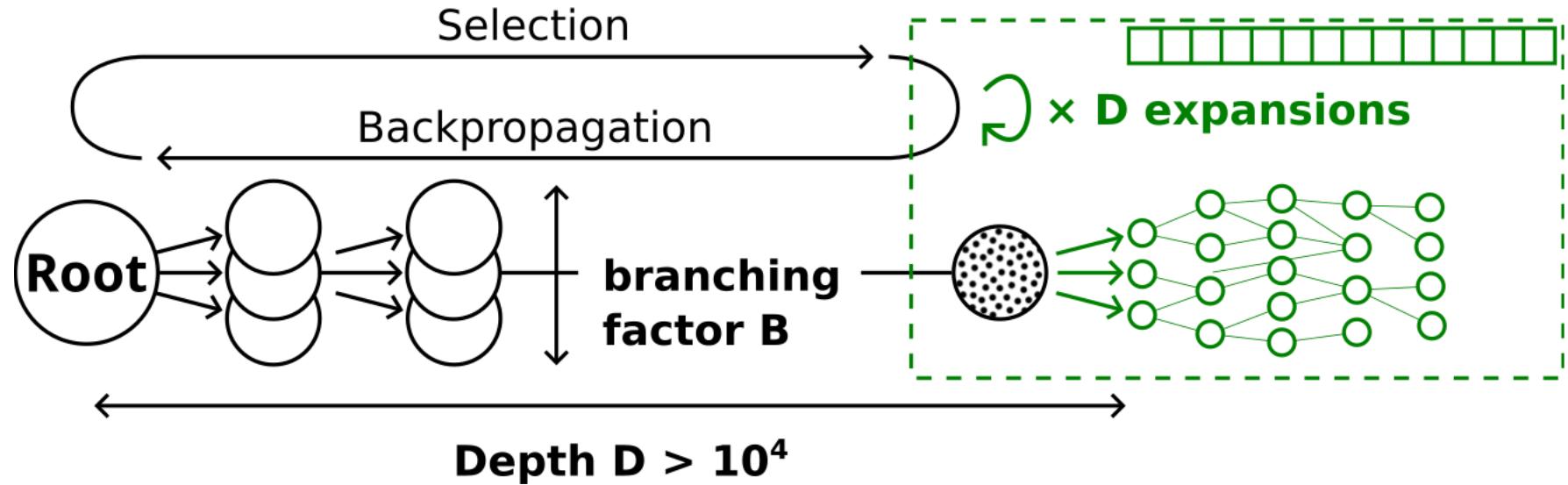
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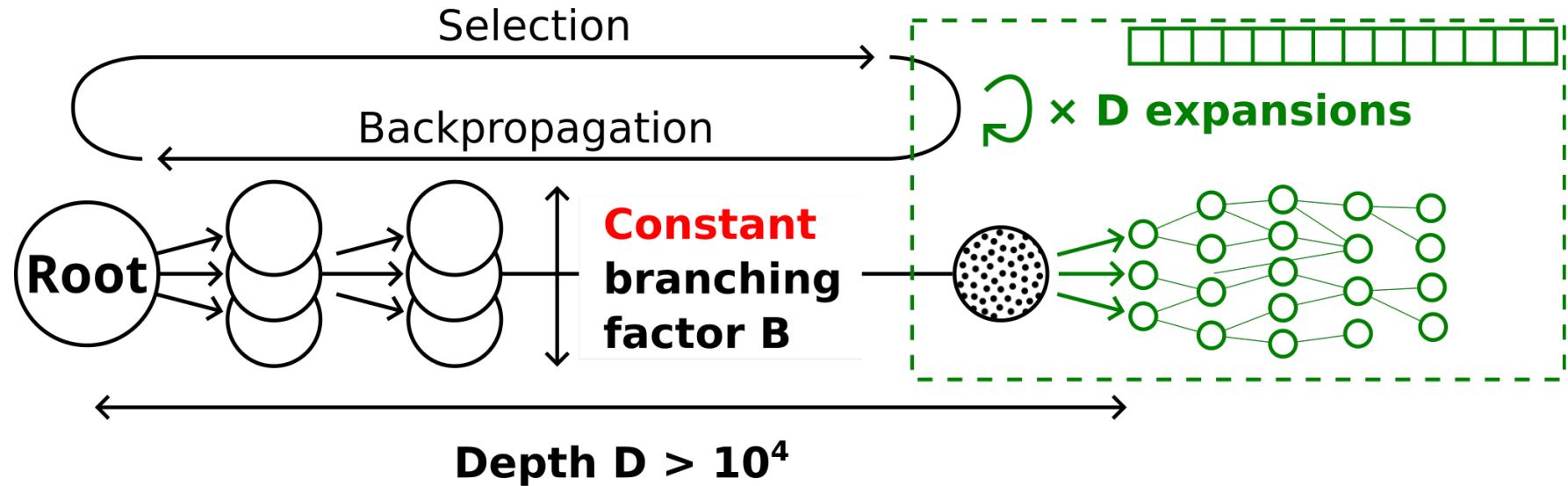
Bilevel MCTS



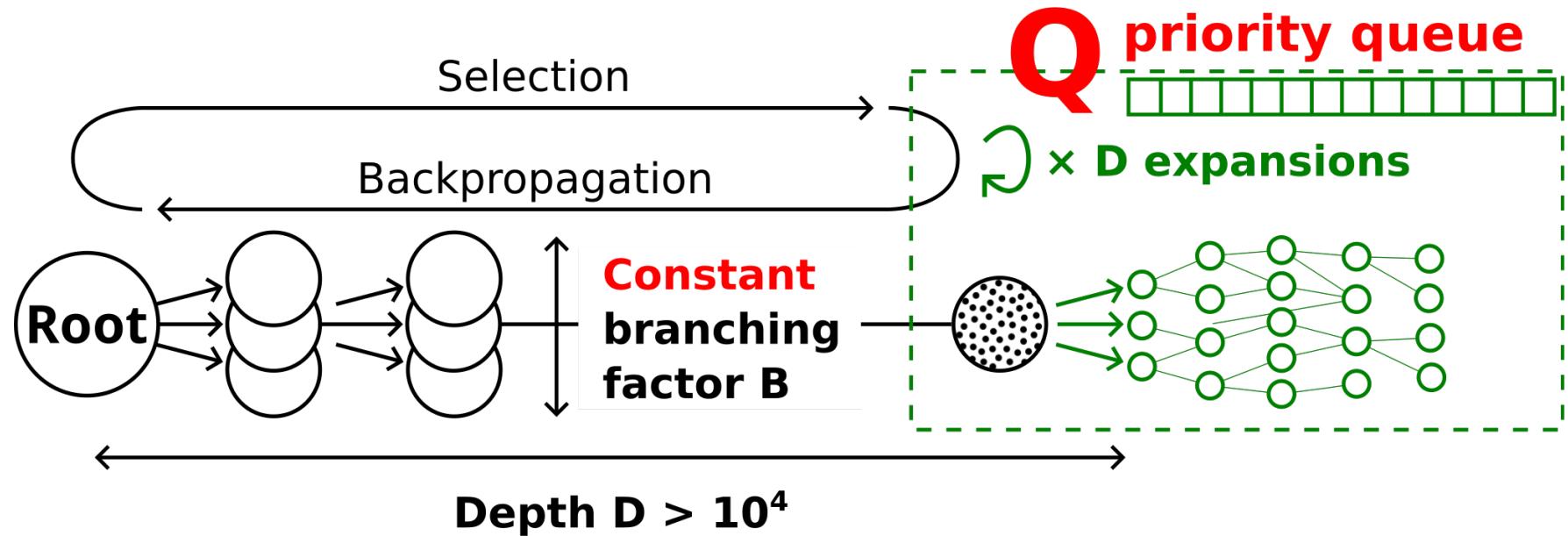
6. Theoretical Results



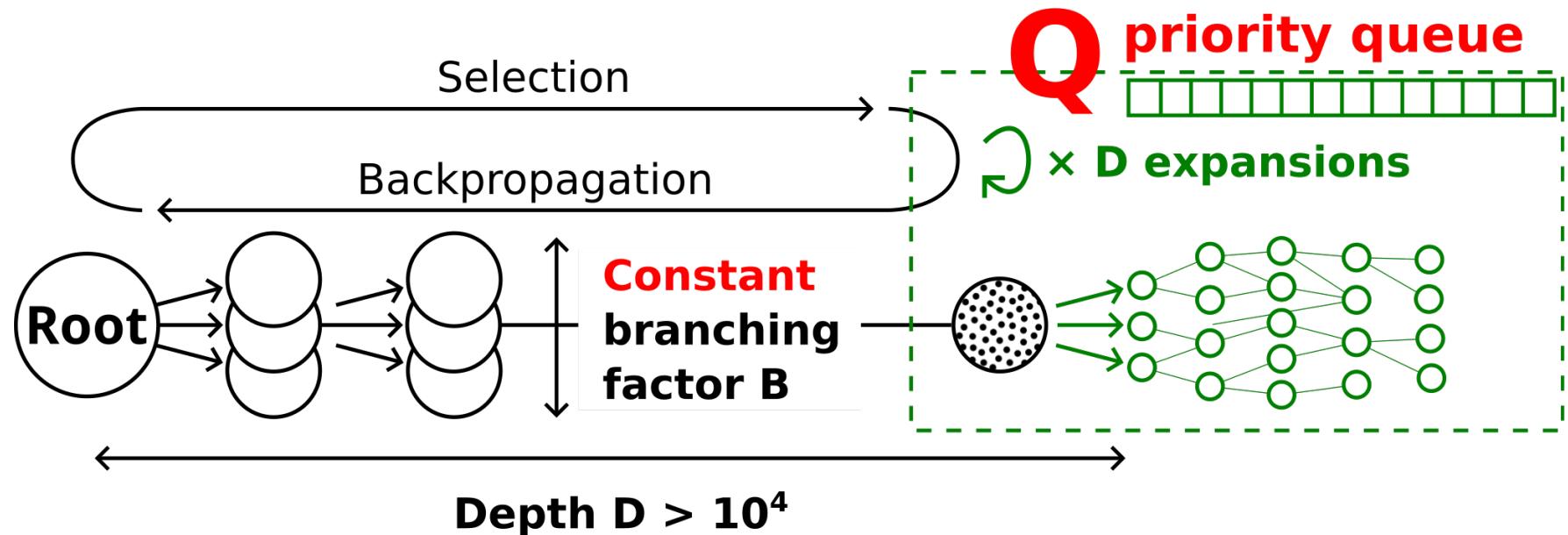
6.1. Theoretical Results



6.2. Theoretical Results



6.3. Theoretical Results



MCTS *runtime per node*

$$O(BD) = O(\log N) \cdot N : \text{number of nodes}$$

Bilevel MCTS amortized runtime per node over D expansions

$$O(\log \log N) \text{ if } Q = \text{heap}$$

$$O(1) \text{ if } Q = \text{array-based priority queue} \text{ (Dial 1969, Burns 2012)}$$

7. Evaluation on IPC 2018+2023

Instances solved in 5 min

| | GBFS | Softmin | MCTS | Bilevel |
|--------------|-------------|----------------|-------------|----------------|
| cea/18 | 40 | 48.4 | 50.2 | 53.8 |
| cea/23 | 30 | 34.2 | 25.8 | 30.8 |
| cg/18 | 35 | 59.2 | 42.4 | 56.2 |
| cg/23 | 36 | 39.4 | 25 | 41.6 |
| ff/18 | 60 | 80.2 | 79.8 | 87.4 |
| ff/23 | 51 | 55.4 | 23.8 | 58.2 |
| total | 252 | 316.8 | 247 | 328 |

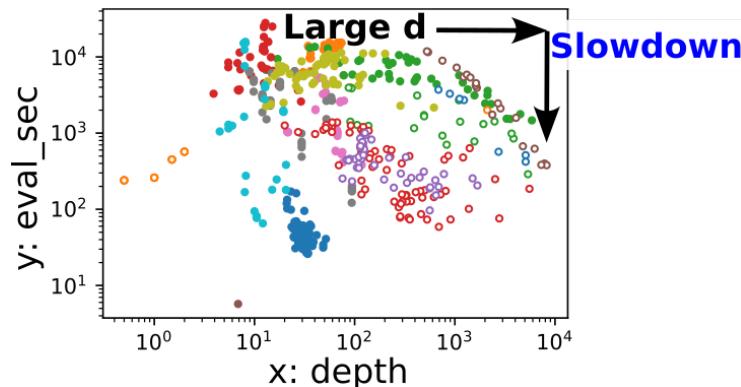
IPC Agile scores

| | GBFS | Softmin | MCTS | Bilevel |
|--------------|--------------|----------------|--------------|----------------|
| cea/18 | 17.7 | 20.6 | 23.8 | 22.4 |
| cea/23 | 23.1 | 24.1 | 21.5 | 23.8 |
| cg/18 | 18.4 | 27.2 | 19.9 | 26.1 |
| cg/23 | 23.6 | 24.8 | 16.4 | 25.5 |
| ff/18 | 30.4 | 37.7 | 40.4 | 43.0 |
| ff/23 | 31.0 | 35.5 | 19.0 | 32.9 |
| total | 144.2 | 169.9 | 141.0 | 173.8 |

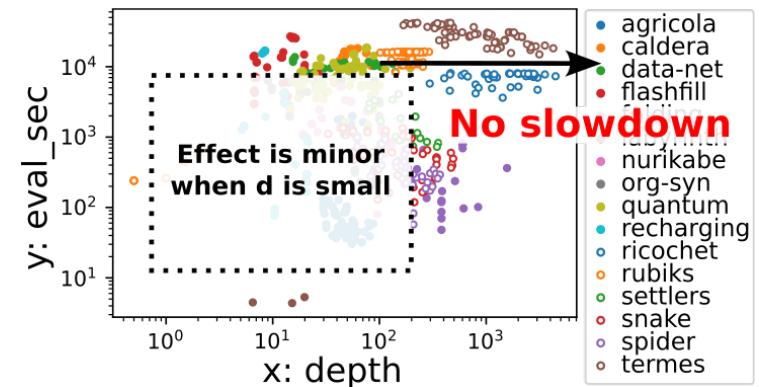
Softmin: Softmin-type-h (Kuroiwa and Beck 2022)

8. Expansion Speed [Nodes / sec]

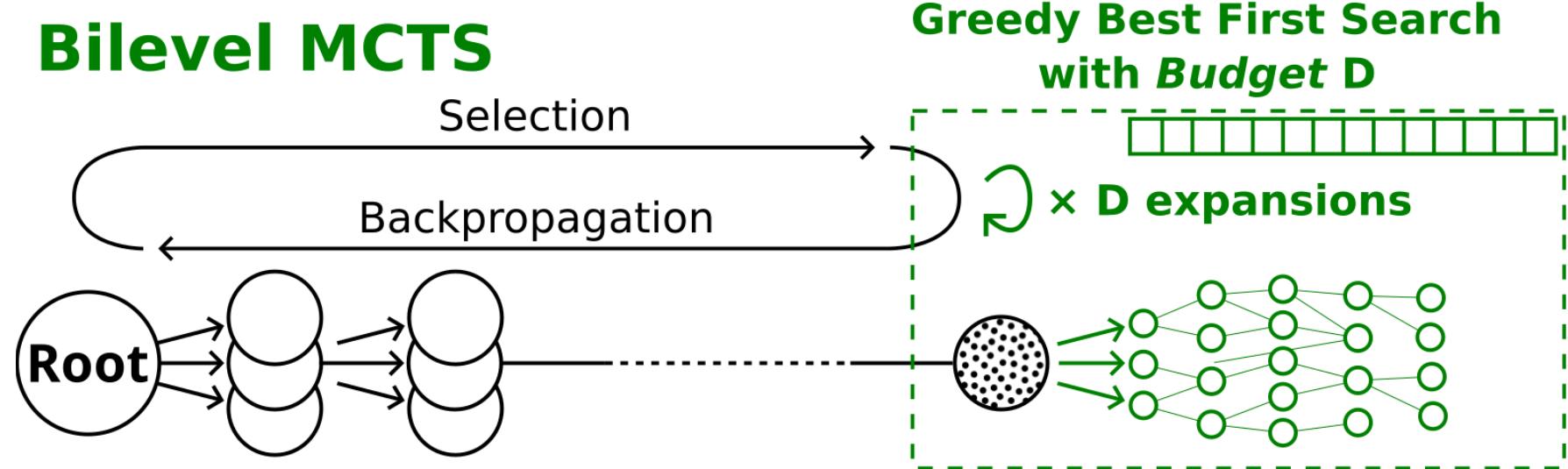
MCTS



Bilevel MCTS

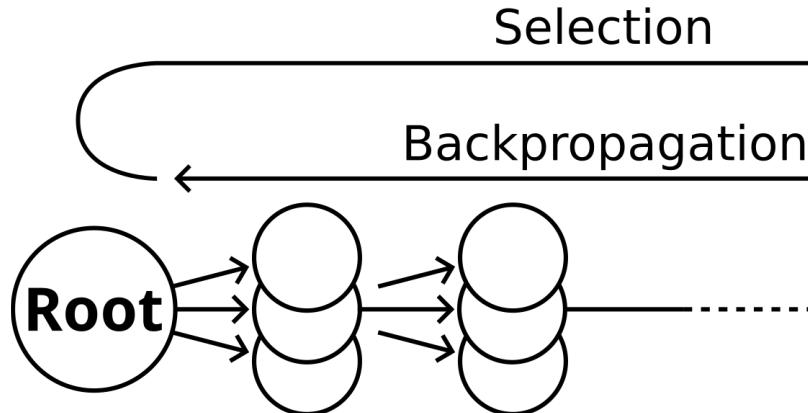


9. Bilevel MCTS uses a *Dynamic Depth Budget*

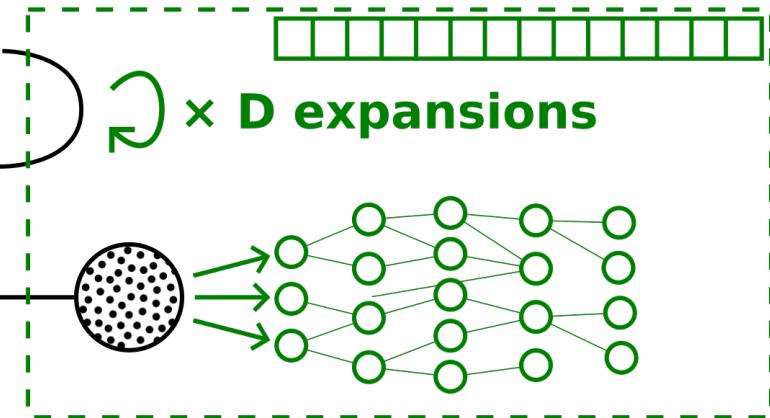


9.1. Bilevel MCTS uses a *Dynamic Depth Budget*

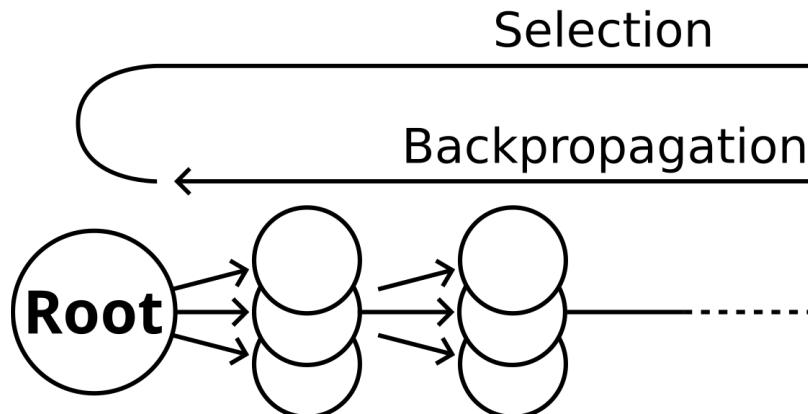
Bilevel MCTS



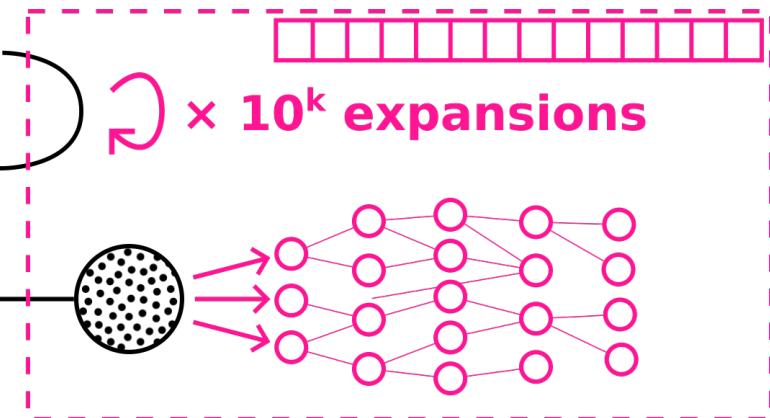
Greedy Best First Search with *Budget D*



Fixed Budget Bilevel



Greedy Best First Search with *Budget 10^k*



10. **Fixed Budget** $b = 10^k$ vs. **Depth Budget** $b = d$

Instances solved in 5 min

| | $b=1$ | 10 | 10^2 | 10^3 | 10^4 | $b=d$ |
|--------|-------------------------|------------------------|--------------------------|--------------------------|--------------------------|-------------------------|
| cea/18 | 50.2 | 57.6 | 51.8 | 49 | 46.6 | 53.8 |
| cea/23 | 25.8 | 32.4 | 36.8 | 33.8 | 33.6 | 30.8 |
| cg/18 | 42.4 | 51.6 | 55.8 | 48.6 | 48.8 | 56.2 |
| cg/23 | 25 | 34.2 | 42.2 | 44 | 42.2 | 41.6 |
| ff/18 | 79.8 | 85.8 | 83.4 | 82.2 | 72.8 | 87.4 |
| ff/23 | 23.8 | 45.4 | 56.8 | 60 | 58.6 | 58.2 |
| total | 247 | ↗ 307 | ↗ 326.8 ↴ | 317.6 ↴ | 302.6 | 328 |

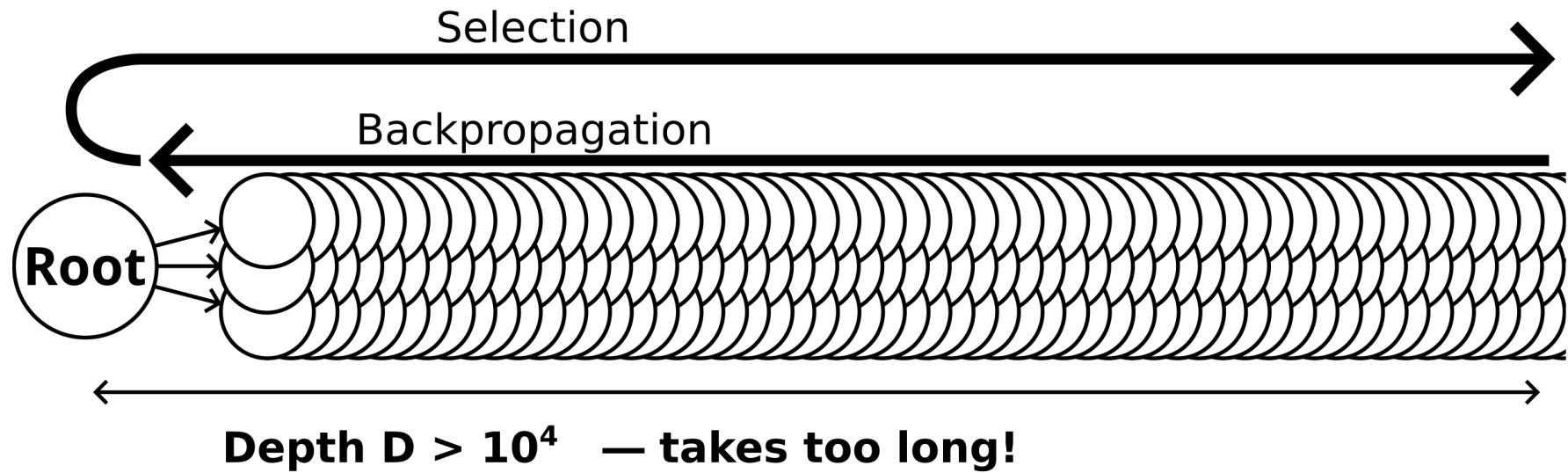
Fixed budget

Too many / few BFS

Dynamic budget

Handles various scenarios well

11. If a large d slows down MCTS, what if we reduce d ?: → Tree Collapsing

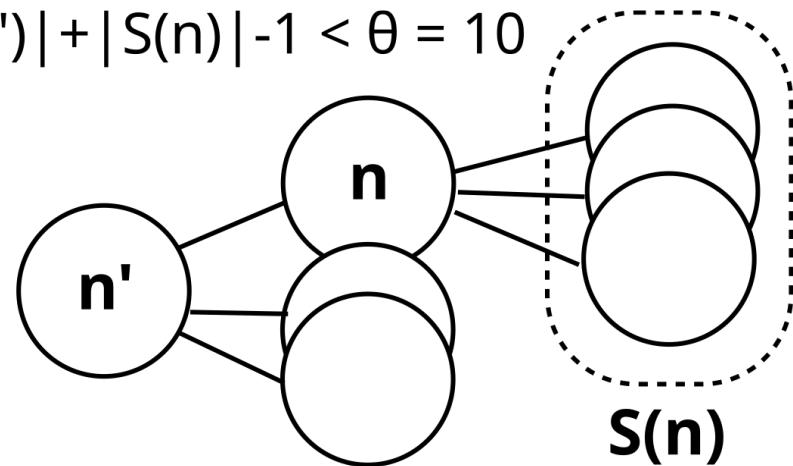


11.1. If a large d slows down MCTS, what if we reduce d ?: → Tree Collapsing

Hyperparameter: θ

When n has too few children ...

$$|S(n')| + |S(n)| - 1 < \theta = 10$$



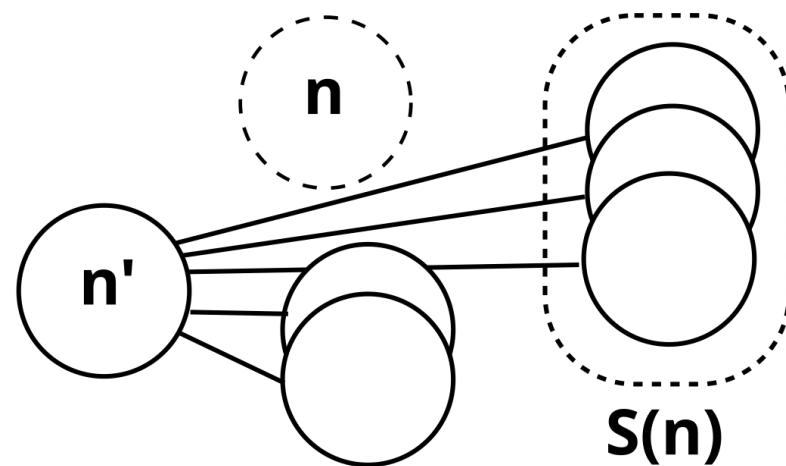
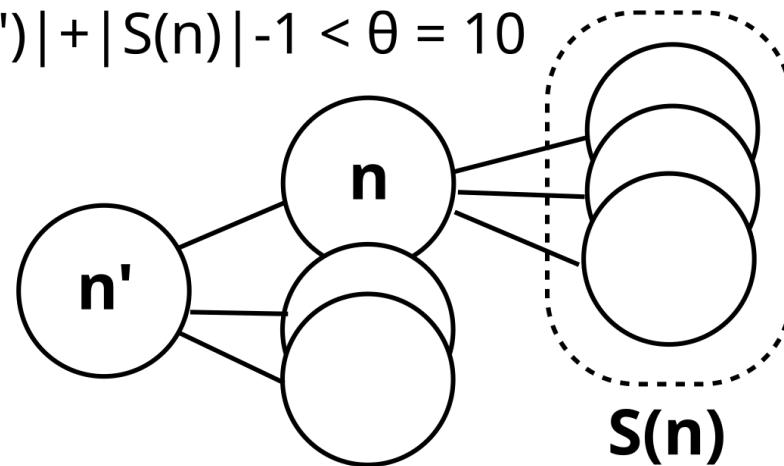
→

11.2. If a large d slows down MCTS, what if we reduce d ?: → Tree Collapsing

Hyperparameter: θ

When n has too few children ... **adopt them to the grandparent n'**

$$|S(n')| + |S(n)| - 1 < \theta = 10$$



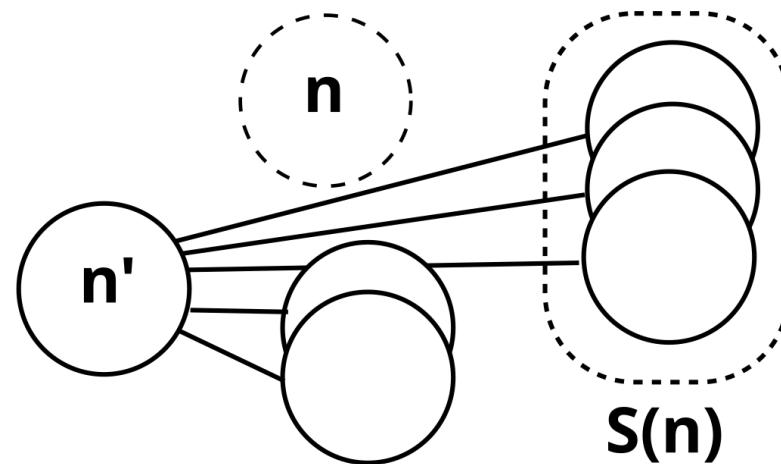
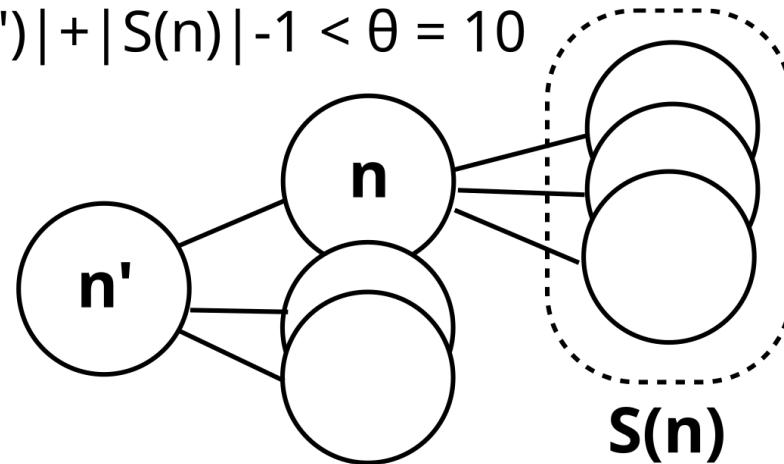
→

11.3. If a large d slows down MCTS, what if we reduce d ?: → Tree Collapsing

Hyperparameter: θ

When n has too few children ... **adopt them to the grandparent n'**

$$|S(n')| + |S(n)| - 1 < \theta = 10$$



→ We also made θ dynamic ($\theta = d$)

11.4. If a large d slows down MCTS, what if we reduce d ?: → Tree Collapsing

Number of instances solved (5 min)

| | no TC | $\theta = 10$ | 20 | 40 | 80 | 160 | Dynamic |
|--------------|--------------|---------------|-------------|----------------|-----------|-------------|----------------|
| cea/18 | 53.8 | 56.4 | 61.4 | 58.6 | 58.8 | 57.8 | 61 |
| cea/23 | 30.8 | 32 | 32.2 | 34.2 | 33 | 34.4 | 33.4 |
| cg/18 | 56.2 | 58.4 | 59.6 | 60.2 | 59.8 | 56.2 | 57.6 |
| cg/23 | 41.6 | 41.6 | 42 | 45.8 | 45.4 | 43.4 | 46.4 |
| ff/18 | 87.4 | 87.2 | 88.6 | 90.4 | 90.6 | 91.4 | 90.2 |
| ff/23 | 58.2 | 56.8 | 57.8 | 58 | 56.2 | 55 | 58.4 |
| total | 328 | ↗332.4 | ↗341.6 | ↗ 347.2 | ↘343.8 | ↘338.2 | 347 |

Dynamic: Not always the best ($\theta = 40$) but is **robust**

12. N ϵ bula = Bilevel MCTS + LAMA + BFWS

N ϵ bula : **3 best practices** in a single planner

Search algorithm : Bilevel MCTS + dynamic tree collapsing

Heuristics : LAMA (2010)'s boosted alt queue + h^{FF} + h^{LMcount}

State-based Exploration : Prioritize states with Novelty Metric (2017)

Codebase : Fast Downward

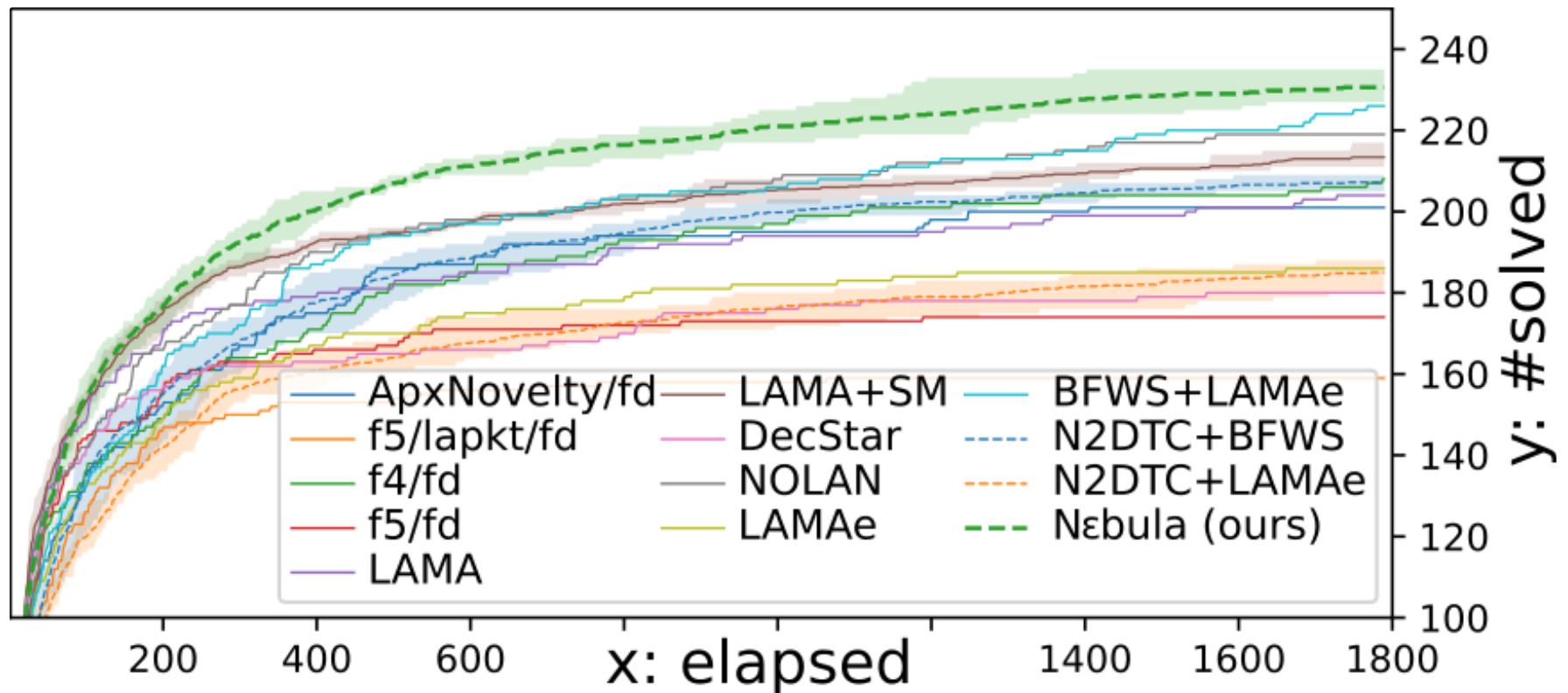
Eager search : Laziness hurts this MCTS so far

12.1. Results

| IPC18+IPC23 with 5 min and 30 min limits | LAMA | SM-Type | Dec | NO | Nε bula |
|---|--------------|----------------|------------|-----------|---------------------------------------|
| | -LAMA | Star | LAN | | |
| solved instances ($T = 300$) | 177 | 186.4 | 162 | 177 | 192.2 |
| IPC Agile score ($T = 300$) | 95.4 | 99.3 | 93.7 | 92.8 | 99.4 |
| solved instances ($T = 1800$) | 204 | 213.4 | 180 | 219 | 230.6 |
| IPC Agile score ($T = 1800$) | 117.6 | 123.4 | 112.0 | 118.7 | 126.8 |

$$\text{IPC Agile score} = \sum_i \min\{1, \log t_i / \log T\}$$

12.2. Runtime Histogram



13. Conclusion

Recursive selection is a bottleneck in MCTS (causes $O(\log N)$)

- Large depth d hurts
- Bilevel MCTS: Amortize the bottleneck with a **budgeted BFS**
 - $O(\log \log N)$ or $O(1)$
- Tree Collapsing: Reduce the depth d

N_ε bula : SotA by combining MCTS+LAMA+BFWS