
```
function [ s ] = Trans( sig,N,U )
d=zeros(length(U),1);
d(N,1)=1;
D=U'*d;
SIG=U'*sig;
S=D.*SIG;
s=U*S;
end
```

Not enough input arguments.

Error in Trans (line 2)
d=zeros(length(U),1);

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