$$\frac{Jh}{dt} = J_{1} (1 - h - J) - J_{1} h \qquad (1)$$

$$\frac{Jh}{dt} = J_{2} (1 - h - J) - J_{2} d \qquad (2)$$

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$$J_{3} - J_{4} d \qquad J_{4} + J_{4} d \qquad J_{4}$$

$$= \frac{\sqrt{K_1 K_2}}{\sqrt{K_1 K_2 + \sqrt{(1+K_1)}}} = \frac{K_1 K_2}{K_1 K_2 + 1 + K_1} = \frac{K_1 K_2}{1 + K_1(1+K_2)}$$

$$R_{\infty} = \frac{J_{1}(1-J_{\infty})}{J_{1}+J_{1}} = \frac{J_{1}}{J_{1}+K_{1}J_{1}} \left(1 - \frac{K_{1}K_{2}}{1+K_{1}+K_{1}K_{2}}\right) = \frac{1}{1+K_{1}} \frac{1+K_{1}+K_{1}K_{2}-K_{1}K_{2}}{1+K_{1}+K_{1}K_{2}} = \frac{1}{1+K_{1}} \cdot \frac{1+K_{1}}{1+K_{1}+K_{1}K_{2}} = \frac{1}{1+K_{1}(1+K_{2})}$$

$$h_{\infty} = \frac{1}{1 + K_1 (1 + K_2)} \qquad (A2a)$$

$$d_{\infty} = K_1 K_2 R_{\infty} \qquad (A2B)$$

$$K_1 = K_2 =$$

$$\begin{cases}
k_1 = K_2 = \frac{1}{1 + K + K^2} \\
d_{\infty} = K^2 k_{\infty}
\end{cases}$$

$$(A.3)$$

$$\frac{1}{2} \frac{1}{2} \frac{1}$$

Associated honogeneous equation:

$$\frac{d}{dt}\begin{pmatrix} f_1 \\ d \end{pmatrix} = \begin{pmatrix} -d_1 - \beta_1 & -d_1 \\ -\beta_2 & -d_2 - \beta_2 \end{pmatrix}\begin{pmatrix} f_1 \\ d \end{pmatrix} = \overrightarrow{X}$$

$$\begin{pmatrix} -d_1 - \beta_1 & -d_1 \\ -\beta_2 & -d_1 - \beta_2 \end{pmatrix} = A$$

$$det(A + \lambda I) = det\begin{pmatrix} -\lambda_1 - \beta_1 + \lambda & -\lambda_1 \\ -\beta_2 & -\lambda_2 - \beta_2 + \lambda \end{pmatrix} =$$

$$= \left(-\lambda_{1} - \beta_{1} + \lambda\right) \left(-\lambda_{2} - \beta_{2} + \lambda\right) - \lambda_{1} \beta_{2} =$$

$$= \lambda_{1} \lambda_{2} + \lambda_{2} \beta_{2} - \lambda \lambda_{1} + \lambda_{2} \beta_{1} + \beta_{1} \beta_{2} - \lambda \beta_{1} - \lambda \lambda_{2} - \lambda \beta_{2} + \lambda^{2} - \lambda \beta_{2} =$$

$$= \lambda^{2} + \lambda \left(-\lambda_{1} - \beta_{1} - \lambda_{2} - \beta_{2}\right) + \lambda_{1} \lambda_{2} + \beta_{1} \left(\lambda_{2} + \beta_{2}\right) =$$

$$= \lambda^{2} + \lambda \left(-\lambda_{1} - \beta_{1} - \lambda_{2} - \beta_{2}\right) + \lambda_{1} \lambda_{2} + \beta_{1} \left(\lambda_{2} + \beta_{2}\right) =$$

$$= \lambda^{2} + \lambda \left(-\lambda_{1} - \beta_{1} - \lambda_{2} - \beta_{2}\right) + \lambda_{1} \lambda_{2} + \beta_{1} \left(\lambda_{2} + \beta_{2}\right) =$$

= d, d2 (1+K))

$$T_{r} = -\left(\frac{1}{2} + \frac{1}{2} + \frac{1}{2} + \frac{1}{2}\right) = -\left(\frac{1}{2} + \frac{1}{2}\right)$$

$$D = \frac{1}{2} \cdot \frac{1}{2} + \beta_{1} \left(\frac{1}{2} + \beta_{2}\right) = \frac{1}{2} \cdot \frac{1}{2} + \frac{1}{2} \cdot \frac{1}{2} + \frac{1}{2} \cdot \frac{1}{2} = \frac{1}{2} \cdot \frac{1}{2} \cdot \frac{1}{2} + \frac{1}{2} \cdot \frac{1}{2} = \frac{1}{2} \cdot \frac{1}{2} \cdot \frac{1}{2} \cdot \frac{1}{2} \cdot \frac{1}{2} = \frac{1}{2} \cdot \frac{1}$$

$$K_{1} = \frac{\beta_{1}}{\lambda_{1}} \quad J = 0 \quad \beta_{1} = K_{1}\lambda_{1}$$

$$T_{1} = \frac{1}{\lambda_{1} + \lambda_{1}} \quad J = 0 \quad T_{1} = \frac{1}{\lambda_{1}(1+K_{1})} \quad J = 0 \quad \lambda_{1} = \frac{1}{T_{1}(1+K_{1})}$$

$$Sinilarly : \lambda_{2} = \frac{1}{T_{2}(1+K_{1})}$$

$$\int = \frac{1 + K \left(1 + K \right)}{T_1 T_2 \left(1 + K \right)^2}$$

$$\begin{split} \lambda_{1}, \lambda_{2} &= \frac{1}{2} \left[-T_{r} + \sqrt{T_{r}^{2} - 4D} \right] \\ -T_{r}^{2} - 4D &= \left(\frac{1}{t_{1}} + \frac{1}{t_{2}} \right)^{2} - \frac{4(1+K(1+K))}{t_{1}T_{2}(1+K)^{2}} = \\ &= \left(\frac{1}{t_{1}} - \frac{1}{t_{2}} \right)^{2} + \frac{4}{t_{1}T_{2}} - \frac{4(1+K(1+K))}{T_{1}T_{2}(1+K)^{2}} = \left(\frac{1}{t_{1}} - \frac{1}{t_{2}} \right)^{2} + \frac{4(1+K)^{2} - 4 - 4K - 4K^{2}}{t_{1}T_{2}(1+K)^{2}} = \\ &= \left(\frac{1}{t_{1}} - \frac{1}{t_{2}} \right)^{2} + \frac{4K}{T_{1}T_{2}(1+K)^{2}} + \frac{4K}{T_{1}T_{2}(1+K)^{2}} + \frac{4K}{T_{1}T_{2}(1+K)^{2}} \right] \\ \lambda_{1}, \lambda_{2} &= \frac{1}{2} \left[\left(\frac{1}{t_{1}} + \frac{1}{t_{2}} \right) + \sqrt{\left(\frac{1}{t_{1}} - \frac{1}{t_{2}} \right)^{2} + \frac{4K}{T_{1}T_{2}(1+K)^{2}}} \right] \\ &= \left(\frac{1}{t_{1}} + \frac{1}{t_{2}} \right) + \sqrt{\left(\frac{1}{t_{1}} - \frac{1}{t_{2}} \right)^{2} + \frac{4K}{T_{1}T_{2}(1+K)^{2}}} \\ \lambda_{1}, \lambda_{2} &= \frac{1}{2} \left[\left(\lambda_{1} + \lambda_{2} \right) + \sqrt{\left(\lambda_{1} + \lambda_{2} \right)^{2} - \frac{4(1+K)^{2}\lambda_{1}\lambda_{2}}{1+K(1+K)}}} \right] \end{split}$$

Measurable time constants in experiments are λ_1^{-1} and λ_2^{-1} (i.e. $\tau_{\rm e}$ and $\tau_{\rm r}$).

general solution for d and
$$h$$
:
$$A_{o}^{(l)} + A_{i}^{(l)} \exp(-\lambda_{i} t) + A_{i}^{(l)} \exp(-\lambda_{i} t)$$
where $l = \{d, h\}$

Approximations:

$$T_1 \simeq \lambda_1^{-1}$$

$$T_2 \simeq \lambda_2^{-1} \left[1 + K(1+K) \right] / (1+K)^2$$

$$d = \beta_2 (1 - R - d) - b_2 d$$
 (2)

As (1) describes much faster process than (2), the authors used rapid equilibrium hypothesis on the former assume steady state

$$\xi = \frac{\frac{1}{\lambda_1 + \beta_1}}{\frac{1}{\lambda_1 + \beta_1}} = 0$$

$$j = 3 = \beta_2 \left(1 - \frac{\lambda_1 (1 - 0)}{\lambda_1 + \beta_1} - \lambda \right) - \lambda_2 \lambda =$$

$$= \beta_2 - \frac{\lambda_1 \beta_2 (1-b)}{\lambda_1 + \beta_1} - \beta_2 \lambda - \lambda_2 \lambda =$$

$$\frac{d}{dt} = \frac{d_{1}d_{2}K^{2}(1-d) - d_{1}d_{2}d - d_{1}d_{2}Kd}}{d_{1}+d_{1}K} = \frac{d_{2}(K^{2}-K^{2}d-d-Kd)}{1+K} = \frac{d_{2}(K^{2}-d(1+K(1+K)))}{1+K} = \frac{d_{2}(K^{2}-d(1+K(1+K))}{1+K} = \frac{d_{2}(K^{2}-d(1+K(1+K)))}{1+K} = \frac{d_{2}(K^{2}-d(1+K(1+K)))}{1+K} = \frac{d_{2}(K^{2}-d(1+K(1+K)))}{1+K} = \frac{d_{2}(K^{2}-d(1+K(1+K)))}{1+K} = \frac{d_{2}(K^{2}-d(1+K(1+K)))}{1+K} = \frac{d_{2}(K^{2}-d(1+K(1+K))}{1+K} = \frac{d_{2}(K^{2}-d(1+K(1+K)))}{1+K} = \frac{d_{2}(K^{2}-d(1+K(1+K)))}{1+K} = \frac{d_{2}(K^{2}-d(1+K(1+K))}{1+K} = \frac{d_{2}(K^{2}-d(1+K))}{1+K} = \frac{d_{2}(K^{2}-d(1+K))}{1+K} = \frac{d_{2}(K^{2}-d(1+K))}{1+K} = \frac{d_{2}(K^{2}-d(1+K))}{1+K} = \frac{d_{2}(K^{2}-d(1+K)}{1+K} = \frac{d_{2}(K^{2}-d(1+K))}{1+K} = \frac{d_{2}(K^{2}-d(1+K))}{1+K} = \frac{d_{2}(K^{2}-d(1+K))}{1+K} = \frac{d_{2}(K^{2}-d(1+K))}{1+K} = \frac{d_{2}(K^{2}-d(1+K))}{1+K} = \frac{d_{2}(K^{2}-d(1+K))}{1+K} = \frac{d_{2}(K^{2}-d(1+K)}{1+K} = \frac{d_{2}(K^{2}-d(1+K)}{1+K} = \frac{d_{2}(K^{2}-d(1+K))}{1+K} = \frac{d_{2}(K^{2}-d(1+K))}{1+K} = \frac{d_{2}(K^{2}-d(1+K))}{1+K} = \frac{d_{2}(K^{2}-d(1+K))}{1+K} = \frac{d_{2}(K^{2}-d(1+K)}{1+K} = \frac{d_{2}(K^{2}-d(1+K)}{1+K} =$$

$$\frac{1+K}{J_{2}(1+K(1+K))} = \lambda_{2}^{-1}$$

$$\lambda_{2}^{-1}J_{2} = -J_{2} + \frac{K^{2}}{1+K(1+K)}$$

$$\lambda_{3}^{-1}J_{4} = -J_{4} + \frac{K^{2}}{1+K(1+K)}$$

$$\lambda_{4}^{-1}J_{5} = \lambda_{5}^{-1}$$

$$\lambda_{5}^{-1}J_{5} = \lambda_{5}^{-1}$$

$$\lambda_{2}^{-1} = \frac{1+K}{\lambda_{2}(1+K(1+K))}$$

$$= \lambda_{2}^{-1} = \frac{1}{\tau_{2}(1+K)^{2}}$$

$$= \lambda_{2}^{-1} = \frac{\tau_{2}(1+K)^{2}}{1+K(1+K)}$$

$$= \tau_{2}^{-1} = \frac{\eta_{2}^{-1}(1+K(1+K))}{(1+K)^{2}}$$