T-type current

Activation gate (Wang et al 1991, Kynnghwa et al 2015)

 $V_{1/2}^{(4_3)} \simeq -42.75$ 

 $\frac{ds}{dt} = \frac{s_{\infty}(V) - s}{\tau_{c}(V)}$ 

$$S = \frac{1}{1 + \exp \left[-(V - V_{1/2}^{(s)})/k^{(s)}\right]}$$
 $k^{(t_0)} \simeq 7.36$ 
 $a_{t_3} \simeq 0.88$ 

$$t_{s} = \frac{1}{a_{t_{s}} + e \kappa \rho \left[ -(v - v_{1/2}^{(t_{s})}) / k^{(t_{s})} \right]}$$

$$v_{1/2}^{(t_{s})} \simeq -23.21$$

$$k^{(t_{s})} \simeq 7.23$$

$$k = \frac{1}{1 + \exp\left[ (V - V_{1/2}^{(k)}) / k^{(k)} \right]} \qquad k^{(k)} \simeq -58.2$$

$$V_{1/2}^{(R)} \simeq -58.2$$
 $k^{(R)} \simeq 7.14$ 

$$\dot{k} = \frac{1}{\tau_L} \left[ \frac{1-d}{1+\kappa} - k \right]$$

$$\dot{d} = \frac{1}{r_2} \left[ \frac{\kappa(L-R)}{1+\kappa} - d \right]$$

$$\frac{\dot{k}}{\dot{k}} = \frac{1}{L_{1}} \left( \frac{1 - \ell - \delta}{\delta} \right) - \frac{\beta_{L} \ell}{\delta}$$

$$\frac{\dot{k}}{\dot{k}} = \frac{1}{\beta_{L}} \left( \frac{1 - \ell - \delta}{\delta} \right) - \frac{\beta_{L} \ell}{\delta}$$

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$$\frac{\dot{k}}{\dot{k}} = \frac{1}{\lambda_{L} \ell} \left( \frac{1 - \ell - \delta}{\delta} \right)$$

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$$\frac{\dot{k}}{\dot{k}}$$

$$\hat{k} = \frac{1}{T_{1}(I+K)} (I-k-d) - \frac{K}{T_{1}(I+K)} \hat{k} = \frac{1}{T_{1}(I+K)} \left[ L-k-d-KR \right] = \frac{1}{T_{1}(I+K)} \left[ L-k(L+K)-d \right]$$

$$\hat{d} = \frac{K}{T_{2}(I+K)} \left[ L-k-d \right] - \frac{1}{T_{2}(I+K)} d = \frac{1}{T_{2}(I+K)} \left[ K(L-k-d)-d \right]$$

$$\dot{k} = \frac{1}{T_{1}(1+K)} \left[ 1 - k(1+K) - d \right] = \frac{1 - d}{T_{1}(1+K)} - \frac{k}{T_{1}} = \frac{1}{T_{1}(1+K)}$$

$$\dot{J} = \frac{1}{T_1} \left[ \frac{1-d}{L+K} - R \right]$$

$$\dot{J} = \frac{1}{T_2 \left[ \frac{1+K}{L+K} \right]} \left[ \frac{K(L-R) - J(1+K)}{L+K} \right] = \frac{1}{T_2} \left[ \frac{K(L-R)}{L+K} - J \right]$$

$$\frac{d}{dt}\begin{pmatrix} h \\ d \end{pmatrix} = \begin{pmatrix} -d_1 - \beta_1 & -d_1 \\ -\beta_2 & -d_2 - \beta_2 \end{pmatrix} \begin{pmatrix} h \\ d \end{pmatrix}$$

Sum of exponentials and geting time constants

$$\frac{dm}{dt} = \frac{m\omega - m}{T_m}; \quad \frac{dh}{dt} = \frac{h\omega - h}{T_R}$$
 (1)

$$I(t) = g m^{p} h (V - E)$$
 (2)

$$n(0) = l(0) = 0$$
 ) =>  $n(t) = m_{\infty} (1 - e^{-t/\tau_{m}})$   
 $p = 3$   $l(t) = l_{\infty} (1 - e^{-t/\tau_{k}}) =>$ 

)=> 
$$I(t) = g m_{\infty}^{3} (1-e^{-t/\tau_{m}})^{3} h_{\infty} (1-e^{-t/\tau_{k}}) (V-E) =$$

$$= g m_{\infty}^{3} (1-e^{-3t/\tau_{m}} - 3e^{-t/\tau_{m}} + 3e^{-2t/\tau_{m}}) h_{\infty} (1-e^{-t/\tau_{k}}) (V-E) =$$

$$= g m_{\infty}^{3} (1-3e^{-t/\tau_{m}}) h_{\infty} (1-e^{-t/\tau_{k}}) (V-E) =$$

$$= g m_{\infty}^{3} h_{\infty} (1-e^{-t/\tau_{k}}) h_{\infty} (1-e^{-t/\tau_{k}}) (V-E) =$$

$$= g m_{\infty}^{3} h_{\infty} (1-e^{-t/\tau_{k}} - 3e^{-t/\tau_{m}}) (V-E) =$$

$$= g m_{\infty}^{3} h_{\infty} (1-e^{-t/\tau_{k}} - 3e^{-t/\tau_{m}}) (V-E) =$$

$$= g m_{\infty}^{3} h_{\infty} (V-E) - g m_{\infty}^{3} h_{\infty} (V-E) e^{-t/\tau_{k}} - 3g m_{\infty}^{3} h_{\infty} (V-E) e^{-t/\tau_{m}}$$

$$= g m_{\infty}^{3} h_{\infty} (V-E) - g m_{\infty}^{3} h_{\infty} (V-E) e^{-t/\tau_{k}} - 3g m_{\infty}^{3} h_{\infty} (V-E) e^{-t/\tau_{k}}$$

$$= g m_{\infty}^{3} h_{\infty} (V-E) - g m_{\infty}^{3} h_{\infty} (V-E) e^{-t/\tau_{k}} - 3g m_{\infty}^{3} h_{\infty} (V-E) e^{-t/\tau_{k}}$$

$$I_{t-ansient}(t) = A_1 e^{-t/\tau_m} + A_2 e^{-t/\tau_g}$$

$$A_1 = -3 g m_{\infty}^3 k_{\infty} (v - E)$$

$$A_2 = -g m_{\infty}^3 k_{\infty} (v - E)$$

Thus, In and Te can be directly fitted by recorded transient currents It-ansient

$$\frac{Jh}{dt} = J_{1} (1 - h - J) - J_{1} h \qquad (1)$$

$$\frac{Jh}{dt} = J_{2} (1 - h - J) - J_{2} d \qquad (2)$$

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$$J_{3} - J_{4} d \qquad J_{4} + J_{5} d \qquad J_{4} \qquad J_{5}$$

$$J_{4} + J_{5} d \qquad J_{4} - J_{5} d \qquad J_{5}$$

$$J_{4} + J_{5} d \qquad J_{5} - J_{5} d \qquad J_{5}$$

$$J_{4} + J_{5} d \qquad J_{5} - J_{5} d \qquad J_{5}$$

$$J_{4} + J_{5} d \qquad J_{5} - J_{5} d \qquad J_{5}$$

$$J_{5} - J_{5} J_{5} + J_{5} d \qquad J_{5}$$

$$J_{5} - J_{5} J_{5}$$

$$J_{5} J_{5} J_{$$

$$= \frac{\sqrt{K_1 K_2}}{\sqrt{K_1 K_2 + \sqrt{(1+K_1)}}} = \frac{K_1 K_2}{K_1 K_2 + 1 + K_1} = \frac{K_1 K_2}{1 + K_1(1+K_2)}$$

$$R_{\infty} = \frac{J_{1}(1-J_{\infty})}{J_{1}+J_{3}} = \frac{J_{1}}{J_{1}+K_{1}J_{3}} \left(1 - \frac{K_{1}K_{2}}{1+K_{1}+K_{1}K_{2}}\right) = \frac{1}{1+K_{1}+K_{1}J_{3}} = \frac{1}{1+K_{1}+K_{1}J_{3}} = \frac{1}{1+K_{1}+K_{1}J_{3}} = \frac{1}{1+K_{1}+K_{1}J_{3}} = \frac{1}{1+K_{1}+K_{1}J_{3}} = \frac{1}{1+K_{1}(1+K_{2})}$$

$$h_{\infty} = \frac{1}{1 + K_1 (1 + K_2)} \qquad (A2a)$$

$$d_{\infty} = K_1 K_2 R_{\infty} \qquad (A2B)$$

$$K_1 = K_2 =$$

$$\begin{cases} k_1 = K_2 = \frac{1}{1 + K + K^2} \\ d_{\infty} = K^2 k_{\infty} \end{cases}$$

$$(A.3)$$

$$\frac{1}{2} \frac{1}{2} \frac{1}$$

Associated honogeneous equation:

$$\frac{d}{dt}\begin{pmatrix} f_1 \\ d \end{pmatrix} = \begin{pmatrix} -d_1 - \beta_1 & -d_1 \\ -\beta_2 & -d_2 - \beta_2 \end{pmatrix}\begin{pmatrix} f_1 \\ d \end{pmatrix} = \overrightarrow{X}$$

$$\begin{pmatrix} -d_1 - \beta_1 & -d_1 \\ -\beta_2 & -d_1 - \beta_2 \end{pmatrix} = A$$

$$det(A + \lambda I) = det\begin{pmatrix} -\lambda_1 - \beta_1 + \lambda & -\lambda_1 \\ -\beta_2 & -\lambda_2 - \beta_2 + \lambda \end{pmatrix} =$$

$$= (-\lambda_{1} - \beta_{1} + \lambda)(-\lambda_{2} - \beta_{2} + \lambda) - \lambda_{1}\beta_{2} =$$

$$= \lambda_{1}\lambda_{2} + \lambda_{1}\beta_{2} - \lambda\lambda_{1} + \lambda_{2}\beta_{1} + \beta_{1}\beta_{2} - \lambda\beta_{1} - \lambda\lambda_{2} - \lambda\beta_{2} + \lambda^{2} - \lambda\beta_{2} =$$

$$= \lambda^{2} + \lambda(-\lambda_{1} - \beta_{1} - \lambda_{2} - \beta_{2}) + \lambda_{1}\lambda_{2} + \beta_{1}(\lambda_{2} + \beta_{2}) =$$

$$= \lambda^{2} + \lambda(-\lambda_{1} - \beta_{1} - \lambda_{2} - \beta_{2}) + \lambda_{1}\lambda_{2} + \beta_{1}(\lambda_{2} + \beta_{2}) =$$

$$= \lambda^{2} + \lambda(-\lambda_{1} - \beta_{1} - \lambda_{2} - \beta_{2}) + \lambda_{1}\lambda_{2} + \beta_{1}(\lambda_{2} + \beta_{2}) =$$

$$T_{r} = -( +_{1} + \beta_{1} + b_{2} + \beta_{2}) = -( -_{1} + -_{1} + -_{2} )$$

$$D = \lambda_{1} b_{2} + \beta_{1} ( +_{2} + \beta_{2} ) = \lambda_{1} b_{2} + K b_{1} ( +_{2} + K b_{2} ) =$$

$$= \lambda_{1} b_{2} ( 1 + K ( 1 + K ) )$$

$$K_{1} = \frac{\beta_{1}}{\lambda_{1}} = \sum_{j=1}^{N} \beta_{j} = K_{1}\lambda_{1}$$
 $T_{1} = \frac{1}{\lambda_{1} + \beta_{1}} = \sum_{j=1}^{N} T_{1} = \frac{1}{\lambda_{1}(1+K_{1})} = \sum_{j=1}^{N} T_{1}(1+K_{1})$ 
 $Sinilarly: \lambda_{2} = \frac{1}{T_{2}(1+K_{1})}$ 

$$\begin{split} \lambda_{1}, \lambda_{2} &= \frac{1}{2} \left[ -T_{r} + \sqrt{T_{r}^{2} - 4D} \right] \\ -T_{r}^{2} - 4D &= \left( \frac{1}{t_{1}} + \frac{1}{t_{2}} \right)^{2} - \frac{4(1+K(1+K))}{t_{1}T_{2}(1+K)^{2}} = \\ &= \left( \frac{1}{t_{1}} - \frac{1}{t_{2}} \right)^{2} + \frac{4}{t_{1}T_{2}} - \frac{4(1+K(1+K))}{T_{1}T_{2}(1+K)^{2}} = \left( \frac{1}{t_{1}} - \frac{1}{t_{2}} \right)^{2} + \frac{4(1+K)^{2} - 4 - 4K - 4K^{2}}{t_{1}T_{2}(1+K)^{2}} = \\ &= \left( \frac{1}{t_{1}} - \frac{1}{t_{2}} \right)^{2} + \frac{4K}{T_{1}T_{2}(1+K)^{2}} + \frac{4K}{T_{1}T_{2}(1+K)^{2}} + \frac{4K}{T_{1}T_{2}(1+K)^{2}} \right] \\ \lambda_{1}, \lambda_{2} &= \frac{1}{2} \left[ \left( \frac{1}{t_{1}} + \frac{1}{t_{2}} \right) + \sqrt{\left( \frac{1}{t_{1}} - \frac{1}{t_{2}} \right)^{2} + \frac{4K}{T_{1}T_{2}(1+K)^{2}}} \right] \\ &= \left( \frac{1}{t_{1}} + \frac{1}{t_{2}} \right) + \sqrt{\left( \frac{1}{t_{1}} - \frac{1}{t_{2}} \right)^{2} + \frac{4K}{T_{1}T_{2}(1+K)^{2}}} \\ \lambda_{1}, \lambda_{2} &= \frac{1}{2} \left[ \left( \lambda_{1} + \lambda_{2} \right) + \sqrt{\left( \lambda_{1} + \lambda_{2} \right)^{2} - \frac{4(1+K)^{2}\lambda_{1}\lambda_{2}}{1+K(1+K)}}} \right] \end{split}$$

Measurable time constants in experiments are  $\lambda_1^{-1}$  and  $\lambda_2^{-1}$  (i.e.  $\tau_{\rm e}$  and  $\tau_{\rm r}$ ).

general solution for d and 
$$h$$
:
$$A_{o}^{(\ell)} + A_{i}^{(\ell)} \exp(-\lambda_{i} t) + A_{i}^{(\ell)} \exp(-\lambda_{i} t)$$
where  $\ell = \{d, h\}$ 

Approximations:

$$T_1 \simeq \lambda_1^{-1}$$

$$T_2 \simeq \lambda_2^{-1} \left[ 1 + K(1+K) \right] / (1+K)^2$$

$$d = \beta_2 (1 - R - d) - b_2 d$$
 (2)

As (1) describes much faster process than (2), the authors used rapid equilibrium hypothesis on the former assume steady state

$$\xi = \frac{\lambda_1 (1-d)}{\lambda_1 + \beta_1} = 0$$
(2)

$$\int_{-2}^{2} \int_{-2}^{2} \int_{-2}^{2} \left( 1 - \frac{d_{1}(1-d)}{d_{1}+\beta_{1}} - d \right) - d_{2} d =$$

$$= \beta_2 - \frac{\lambda_1 \beta_2 (1-b)}{\lambda_1 + \beta_1} - \beta_2 \lambda - \lambda_2 \lambda =$$

$$\frac{d}{dt} = \frac{d_1 d_2 K^2 (1-d) - d_1 d_2 d_1 - d_1 d_2 K d_1}{d_1 + d_1 K} = \frac{d_2 (K^2 - K^2 d_1 - d_1 - K d_1)}{1 + K} = \frac{d_2 (K^2 - d_1 (1 + K (1 + K)))}{1 + K} = \frac{d_2 (K^2 - d_1 (1 + K (1 + K)))}{1 + K} = \frac{d_2 (K^2 - d_1 (1 + K (1 + K)))}{1 + K} = \frac{d_2 (K^2 - d_1 (1 + K (1 + K)))}{1 + K} = \frac{d_2 (K^2 - d_1 (1 + K (1 + K)))}{1 + K} = \frac{d_2 (K^2 - d_1 (1 + K (1 + K)))}{1 + K} = \frac{d_2 (K^2 - d_1 (1 + K (1 + K)))}{1 + K} = \frac{d_2 (K^2 - K^2 d_1 - d_1 - K d_1)}{1 + K} = \frac{d_2 (K^2 - K^2 d_1 - d_1 - K d_1)}{1 + K} = \frac{d_2 (K^2 - K^2 d_1 - d_1 - K d_1)}{1 + K} = \frac{d_2 (K^2 - K^2 d_1 - d_1 - K d_1)}{1 + K} = \frac{d_2 (K^2 - K^2 d_1 - d_1 - K d_1)}{1 + K} = \frac{d_2 (K^2 - K^2 d_1 - d_1 - K d_1)}{1 + K} = \frac{d_2 (K^2 - K^2 d_1 - d_1 - K d_1)}{1 + K} = \frac{d_2 (K^2 - K^2 d_1 - d_1 - K d_1)}{1 + K} = \frac{d_2 (K^2 - K^2 d_1 - d_1 - K d_1)}{1 + K} = \frac{d_2 (K^2 - K^2 d_1 - d_1 - K d_1)}{1 + K} = \frac{d_2 (K^2 - K^2 d_1 - d_1 - K d_1)}{1 + K} = \frac{d_2 (K^2 - K^2 d_1 - d_1 - K d_1)}{1 + K} = \frac{d_2 (K^2 - K^2 d_1 - d_1 - K d_1)}{1 + K} = \frac{d_2 (K^2 - K^2 d_1 - d_1 - K d_1)}{1 + K} = \frac{d_2 (K^2 - K^2 d_1 - d_1 - K d_1)}{1 + K} = \frac{d_2 (K^2 - K^2 d_1 - d_1 - K d_1)}{1 + K} = \frac{d_2 (K^2 - K^2 d_1 - d_1 - K d_1)}{1 + K} = \frac{d_2 (K^2 - K d_1 - d_1 - K d_1)}{1 + K} = \frac{d_2 (K^2 - K d_1 - d_1 - K d_1)}{1 + K} = \frac{d_2 (K^2 - K d_1 - d_1 - K d_1)}{1 + K} = \frac{d_2 (K^2 - K d_1 - d_1 - K d_1)}{1 + K} = \frac{d_2 (K^2 - K d_1 - d_1 - K d_1)}{1 + K} = \frac{d_2 (K^2 - K d_1 - d_1 - K d_1)}{1 + K} = \frac{d_2 (K^2 - K d_1 - d_1 - K d_1)}{1 + K} = \frac{d_2 (K^2 - K d_1 - d_1 - K d_1)}{1 + K} = \frac{d_2 (K^2 - K d_1 - d_1 - K d_1 - K d_1)}{1 + K} = \frac{d_2 (K^2 - K d_1 - d_1 - K d_1)}{1 + K} = \frac{d_2 (K^2 - K d_1 - d_1 - K d_1)}{1 + K} = \frac{d_2 (K^2 - K d_1 - d_1 - K d_1)}{1 + K} = \frac{d_2 (K^2 - K d_1 - d_1 - K d_1 - K d_1)}{1 + K} = \frac{d_2 (K^2 - K d_1 - d_1 - K d_1 - K d_1)}{1 + K} = \frac{d_2 (K^2 - K d_1 - d_1 - K d_1 - K d_1)}{1 + K} = \frac{d_2 (K^2 - K d_1 - K d_1 - K d_1 - K d_1 - K d_1)}{1 + K} = \frac{d_2 (K d_1 - K d_1)}{1 + K} = \frac{d_$$

$$\frac{1+K}{J_{2}(1+K(1+K))} = \lambda_{2}^{-1}$$

$$\lambda_{2}^{-1}d = -J + \frac{K^{2}}{1+K(1+K)}$$

$$\lambda_{3}^{-1}d = -J + \frac{K^{2}}{1+K(1+K)}$$

$$\lambda_{2}^{-1} = \frac{1+K}{\lambda_{2}(1+K(1+K))}$$

$$= \lambda_{2}^{-1} = \frac{1}{\tau_{2}(1+K)^{2}}$$

$$= \lambda_{2}^{-1} = \frac{\tau_{2}(1+K)^{2}}{1+K(1+K)}$$

$$= \tau_{2}^{-1} = \frac{\eta_{2}^{-1}(1+K(1+K))}{(1+K)^{2}}$$

$$\frac{dR}{dt} = \frac{\phi \left( k_{\infty} - R \right)}{T_{R}(V)}$$

$$k_{\infty}(V) = \frac{1}{1 + e_{R/2} \left[ \left( V - \Theta_{R} \right) / k_{R} \right]}$$

$$T_{R}(V) = k_{\infty}(V) e_{R/2} \left( \left( V + 162.3 \right) / 17.8 \right) + 20$$