#### **PRML Final**

https://gym.openai.com/envs/LunarLander-v2/

# LunarLander-v2

Landing pad is always at coordinates (0,0).
Coordinates are the first two numbers in state vector. Reward for moving from the top of the screen to landing pad and zero speed is about 100..140 points. If lander moves away from



landing pad it loses reward back. Episode finishes if the lander crashes or comes to rest, receiving additional -100 or +100 points. Each leg ground contact is +10. Firing main engine is -0.3 points each frame. Solved is 200 points. Landing outside landing pad is possible. Fuel is infinite, so an agent can learn to fly and then land on its first attempt. Four discrete actions available: do nothing, fire left orientation engine, fire main engine, fire right orientation engine.

## Solved is 200 points (over 100 consecutive trials)

## DEEP Q LEARNING with REPLAY BUFFER

### With

```
BUFFER_SIZE = int(1e5)  # replay buffer size

BATCH_SIZE = 128  # minibatch size

GAMMA = 0.99  # discount factor

TAU = 1e-3  # for soft update of target parameters

LR = 1e-3  # learning rate

UPDATE EVERY = 5  # how often to update the network
```





