



Title

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1 Introduction

Partial differential equations are one of the most powerful tools for the study of physical and biological phenomena. They allow us to represent in a simplified way, the dynamics between the spatial and temporal variables of any phenomenon and to take this dynamics to a mathematical model, whose solution describes in a great way the behavior of the studied system[1]. This has led partial differential equations to become a tool of great use in areas such as fluid dynamics, electromagnetism, optics, magnetism, among others[2]; these areas being dominated by PDEs such as Maxwell's Equations and Navier-Stokes Equations, the latter being the object of study of the present work.

However, PDEs, given their complex structure, are usually models whose analytical solutions are difficult or impossible to find, being even the solutions already found for some PDEs so complex that it is preferred to use other methods to solve the problem[3]. This is why, in recent years, the development of multiple numerical methods to solve this type of equations has been one of the major topics of study of the scientific community, being this an important issue to study, and that although there are already multiple methods developed, if these are not applied correctly can lead to solutions far from the real solution of the problem and therefore lead to erroneous conclusions about the behavior of the system under study.

One of the most commonly used numerical method for solving Partial Differential Equations is the Finite Element Method (FEM), a numerical method consisting on the discretization of the problem's domain, to later solve a variational formulation of the problem with determined test functions, to obtain an algebraic system of equations, which, when solved, gives the approximated solution of the problem. However, due to the large amount of degrees of freedom it needs in order to correctly solve the PDE, it remains as an extremely expensive method both in terms of CPU and memory demand, therefore not being too useful for real-time contexts[4][5]. As a consequence, models such as reduced basis models (RBMs) and physically informed neural networks (PINNs) have been developed and have become important methods in the study of PDEs.

This project focuses on the implementation of artificial intelligence models for the solution of PDEs, specifically Physical Informed Neural Networks (PINNs) and Neural Network assisted Reduced Basis Models (NN-RBM), seeking to obtain a reduced computational cost in a real-time simulation context. The Navier-Stokes equations, and in particular, a simulation problem of blood flow through the carotid artery, will be used as an object of study, to observe and compare the performance of these methods versus the FEM in an on-line simulation process.

2 Statement of the problem

2.1 Statement of the problem (4 a 5 párrafos)

For solving fluid dynamics problems, Computational Fluid Dynamics (CFD) mainly uses three methods: The Finite Difference Method, The Finite Volumes Method, and the Finite Element Method. In the finite difference method, the derivatives of the problem are usually replaced by truncated expansions of the Taylor series, this method is straightforward for regular geometries, but when working with irregular geometries it is necessary to perform transformations to the equations before the expansion is carried out[6]. In the finite volume method, the discretization is performed by partitioning the spatial domain into a mesh, in which each of its elements will be called a control volume. The idea is to perform the integration of the dominant equations of the problem through each control volume, balancing the fluxes across the boundaries of the individual volumes and getting what is called a balance equation. Then the set of balance equations will be discretized with respect to a set of discrete unknowns to finally get the solution to the problem[7]. In a topologically regular mesh, these calculations are done quite easily, but when working with irregular meshes, this calculation will result in an unbearable amount of fluxes and a significant accounting effort to ensure that all fluxes have been calculated correctly[6].

Finally, the finite element method is a numerical method highly used in computational fluid dynamics to solve problems whose domain is defined by irregular geometries. The method makes it possible to find the numerical solution to these problems by dividing the initial domain of the same (a continuous element) into a large number of non-intersecting subdomains, called finite elements. Each element will have a set of representative points called nodes, which will make up the complete grid of the problem, on which the calculations will be performed. At last, the formulation of a boundary value problem ends up giving a system of algebraic equations, which are then solved using variational methods in order to approximate a solution, minimizing an associated error function[8]

2.2 Formalization of the problem

In a domain $\Omega \subset \mathbb{R}^2$ Quateroni[9] define incompressible Navier-Stokes Equations as follows

$$\begin{cases} \nabla \cdot \mathbf{u} = 0 & \mathbf{x} \in \Omega, t > 0 \\ \mathbf{u}_t - \nabla \cdot [\nu(\nabla \mathbf{u} + \nabla \mathbf{u}^T)] + (\mathbf{u} \cdot \nabla) \mathbf{u} + \nabla p = \mathbf{f} & \mathbf{x} \in \Omega, t > 0 \end{cases} \quad (1)$$

When ν is constant, we obtain

$$\nabla \cdot [\nu(\nabla \mathbf{u} + \nabla \mathbf{u}^T)] = \nu(\Delta \mathbf{u} + \nabla(\nabla \cdot \mathbf{u})) = \nu \Delta \mathbf{u}$$

and therefore the equations are written as

$$\begin{cases} \nabla \cdot \mathbf{u} = 0 & \mathbf{x} \in \Omega, t > 0 \\ \mathbf{u}_t - \nu \Delta \mathbf{u} + (\mathbf{u} \cdot \nabla) \mathbf{u} + \nabla p = \mathbf{f} & \mathbf{x} \in \Omega, t > 0 \end{cases} \quad (2)$$

Being \mathbf{u} the fluid velocity field, p the pressure divided by the density ρ , ν the kinematic viscosity define as $\frac{\mu}{\rho}$ with μ being the dynamic viscosity and \mathbf{f} a forcing term per unit mass.

For the purpose of this work the domain Ω must also be bounded, and it is therefore necessary to assign initial and suitable boundary conditions for the problem to be well posed.

$$\begin{cases} \mathbf{u}(\mathbf{x}, 0) = \mathbf{u}_0(\mathbf{x}) & \forall \mathbf{x} \in \Omega \\ \mathbf{u}(\mathbf{x}, t) = \varphi(\mathbf{x}, t) & \forall \mathbf{x} \in \Gamma_D, t > 0 \\ (\nu \frac{\partial \mathbf{u}}{\partial \mathbf{n}} - p \mathbf{n})(\mathbf{x}, t) = \psi(\mathbf{x}, t) & \forall \mathbf{x} \in \Gamma_N, t > 0 \end{cases}$$

Where \mathbf{u}_0 is a divergence free vector field, φ and ψ are given vector functions, Γ_D and Γ_N provide a partition of the boundary $\partial\Omega$ and \mathbf{n} , as usual, represents the outward unit normal vector to $\partial\Omega$.

3 Objectives

3.1 General objective (**sólo uno**)

Compare the performance of Neural Network asisted Reduced Basis Models (NN-RBMs) and Physical Informed Neural Networks (PINNs) against the Finite Element Method on a real-time context, by performing multiple simulations of the blood flow through the carotid artery.

3.2 Specific objectives (**3 o 4 objetivos**)

- Identify the principal differences on the implementation of NN-RBMs and PINN like models and FEM in a fluid mechanic context.
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4 Justification (**4 o 5 párrafos**)

5 Scope (**2 o 3 párrafos**)

The principal results expected from this project are

Now then, it is clear that for this kind of project one of the biggest obstacles that it is possible to encounter when researching and implementing the model is the impossibility of carrying out analytical validation of the solution obtained by the method, since as it is known, the Navier-Stokes equations, due to their high complexity, do not have an analytical solution against which to compare the numerical solution. However, since multiple models are implemented, and having the FEM as a commonly accepted method for the solution of Parameterized PDEs, it's solution will be used as an accepted solution for validating the implemented models.

6 State of the art (5 a 6 párrafos)

7 Proposed methodology (5 o 6 párrafos)

As a means to achieve the objectives set for this project, a 4-stage methodology is proposed in which various mathematical methods will be worked. In the first stage, the interpretation of angiograms obtained on the web will be performed and then a two-dimensional geometry of the carotid artery will be recreated to be used as the spatial domain of the simulations to be performed. In the second stage, a computational implementation of the finite element method for obtaining an initial solution for the implementation and validation of the other models. The third stage involves the implementation of NN-RBMs and PINNs using the results obtained before as a basis for this models and the simulation fo multiple study cases. And finally, in the fourth stage, a comparison of the results obtained for each implmented model, as well as their simulation-time and memory usage is performed, to analyze the performance of each model.

8 Schedule, commitments and deliverables

Table 1: Schedule

Activity	Weeks																	
	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	16	17	18
Literature Review																		
Research proposal writting																		
Activity 3																		
Results Analysis and comparison																		
Final Report writting																		

9 Intellectual property

According to the internal regulation on intellectual property within Universidad EAFIT, the results of this research practice are product of *Alejandro Salazar Arango* and *Cristhian David Zambrano Mora*.

In case further products, beside academic articles, that could be generated from this work, the intellectual property distribution related to them will be directed under the current regulation of this matter determined by [10].

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