

Calculus Formulas

Analytic Geometry

Vectors

Vector joining two points $P = (p_1, \ldots, p_n)$,

 $Q=(q_1,\ldots,q_n)\in\mathbb{R}^n$

$$\vec{PQ} = Q - P = (q_1 - p_1, \dots, q_n - p_n)$$

Dot product $u = (u_1, \dots, u_n), v = (v_1, \dots, v_n) \in \mathbb{R}^n$

$$\mathbf{u} \cdot \mathbf{v} = u_1 v_1 + \ldots + u_n v_n$$

Orthogonal vectors (perpendicular)

$$\mathbf{u} \cdot \mathbf{v} = 0$$

Lines

Vectorial equation of a line that passes through P with direction v

$$P + tV$$

Point-slope equation of a line in \mathbb{R}^2 that passes through (x_0, y_0) with slope m

$$y = y_0 + m(x - x_0)$$

Planes

General equation of a plane in \mathbb{R}^3 that passes through a point (x_0, y_0, z_0) perpendicular to the vector (a, b, c)

$$a(x - x_0) + b(y - y_0) + c(z - z_0) = 0$$

Algebra of derivatives

Sum (u+v)'=u'+v'

Subtraction (u - v)' = u' - v'

Product $(u \cdot v)' = u' \cdot v + u \cdot v'$

Quotient $\left(\frac{u}{v}\right)' = \frac{u' \cdot v - u \cdot v'}{v^2}$

Chain rule $(f \circ g)'(x) = f'(g(x))g'(x)$

Secant and tangent lines

Secant line to the graph of f(x) at points (a, f(a)) and $(a + \Delta x, f(a + \Delta x))$

$$y = f(a) + ARCf[a, a + \Delta x](x - a)$$

Tangent line to the graph of f(x) at point (a, f(a))

$$y = f(a) + f'(a)(x - a)$$

Growth, concavity and extrema

Growth

- $\forall x \in I \ f'(x) \ge 0 \Rightarrow f$ is increasing in I.
- $\forall x \in I \ f'(x) \le 0 \Rightarrow f$ is decreasing in I.

Concavity

- $\forall x \in I \ f''(x) \ge 0 \Rightarrow f$ is concave up in I.
- $\forall x \in I \ f''(x) \le 0 \Rightarrow f$ is concave down in I.

Extrema If f'(a) = 0 (critical point)

- $f''(a) < 0 \Rightarrow f$ has a local maximum at x = a.
- $f''(a) > 0 \Rightarrow f$ has a local minimum at x = a.

Derivatives of functions of one variable

Concept of derivative

Average rate of change of a function f(x) in an interval $[a, a + \Delta x]$

$$\mathsf{ARC}f[a, a + \Delta x] = \frac{\Delta y}{\Delta x} = \frac{f(a + \Delta x) - f(a)}{\Delta x}$$

Instantaneous rate of change (Derivative) of a function f(x) at point x = a

$$f'(a) = \lim_{\Delta x \to 0} \frac{\Delta y}{\Delta x} = \lim_{\Delta x \to 0} \frac{f(a + \Delta x) - f(a)}{\Delta x}$$

Function approximation

Variation of a function

$$\Delta y \approx f'(a)\Delta x$$

Taylor polynomial of order n of f(x) at point x = a

$$P_{f,a}^{n}(x) = f(a) + f'(a)(x-a) + \frac{f''(a)}{2}(x-a)^{2} + \dots + \frac{f^{n}(a)}{n!}(x-a)^{n}$$

Maclaurin polynomial of order n of f(x)

$$P_{f,0}^n(x) = f(0) + f'(0)x + \frac{f''(0)}{2}x^2 + \dots + \frac{f^n(0)}{n!}x^n$$



Differential equations

First order differential equation

First order ordinary differential equation

$$F(x, y, y') = 0$$

Initial value problem

$$\begin{cases} F(x, y, y') = 0, & \text{First order ODE;} \\ y(x_0) = y_0, & \text{Initial condition.} \end{cases}$$

Tangent line and normal plane in the space

Tangent line to a trajectory in the space

$$f(t) = (x(t), y(t), z(t))$$
 at time $t = a$

$$(x(a), y(a), z(a)) + t(x'(a), y'(a), z'(a))$$

Normal plane to a trajectory in the space

$$f(t) = (x(t), y(t), z(t))$$
 at time $t = a$

$$x'(a)(x-x(a))+y'(a)(y-y(a))+z'(a)(z-z(a))=0$$

Solving first order ODE

Separable differential equation

$$y'g(y) = f(x)$$

Solution:

$$\int g(y)\,dy = \int f(x)\,dx + C.$$

Linear differential equation

$$y' + g(x)y = h(x)$$

Solution:

$$y = e^{-\int g(x) dx} \left(\int h(x) e^{\int g(x) dx} dx + C \right).$$

Derivatives of vectorial functions

Derivative of a vectorial function

If
$$f(t) = (x_1(t), \dots, x_n(t))$$
 then

$$f'(t) = (x_1'(t), \ldots, x_n'(t))$$

Derivatives of functions of several variables

Partial derivatives

Gradient vector

$$\nabla f = \left(\frac{\partial f}{\partial x_1}, \dots, \frac{\partial f}{\partial x_n}\right)$$

Hessian Matrix

$$\nabla^{2}f = \begin{pmatrix} \frac{\partial^{2}f}{\partial x_{1}^{2}} & \frac{\partial^{2}f}{\partial x_{1}\partial x_{2}} & \cdots & \frac{\partial^{2}f}{\partial x_{1}\partial x_{n}} \\ \frac{\partial^{2}f}{\partial x_{2}\partial x_{1}} & \frac{\partial^{2}f}{\partial x_{2}^{2}} & \cdots & \frac{\partial^{2}f}{\partial x_{2}\partial x_{n}} \\ \vdots & \vdots & \ddots & \vdots \\ \frac{\partial^{2}f}{\partial x_{n}\partial x_{1}} & \frac{\partial^{2}f}{\partial x_{n}\partial x_{2}} & \cdots & \frac{\partial^{2}f}{\partial x_{n}^{2}} \end{pmatrix}$$

Hessian

$$Hf(P) = |\nabla^2 f(P)|$$

Directional derivative of f at a point P along the direction of v

 $f_{\mathsf{V}}'(P) = \nabla f(P) \frac{\mathsf{V}}{|\mathsf{V}|}$

Chain rule

$$f(g(t))' = \nabla f(g(t))g'(t)$$

Tangent and normal lines in the plane

Tangent line to a trajectory in the plane

$$f(t) = (x(t), y(t))$$
 at time $t = a$

$$(x(a), y(a)) + t(x'(a), y'(a))$$
 or $(x - x(a))y'(a) - (y - y(a))x'(a) = 0$

Normal line to a trajectory in the plane

f(t) = (x(t), y(t)) at time t = a

$$(x(a), y(a)) + t(y'(a), -x'(a))$$
 or $(x - x(a))x'(a) + (y - y(a))y'(a) = 0$

Tangent and normal lines in the plane

Normal line to a trajectory in the plane f(x, y) = 0 at point P = (a, b)

$$P + t\nabla f(P) = (a, b) + t\nabla f(a, b)$$
 or $(x - a)\frac{\partial f}{\partial y}(a, b) - (y - b)\frac{\partial f}{\partial x}(a, b) = 0$

Tangent line to a trajectory in the plane f(x, y) = 0 at point P = (a, b)

$$(x-a)\frac{\partial f}{\partial x}(a,b) + (y-b)\frac{\partial f}{\partial y}(a,b) = 0$$



Normal line and tangent plane in the space

Normal line to a surface in the space f(x, y, z) = 0 at point P = (a, b, c)

$$P + t\nabla f(P) = (a, b, c) + t\nabla f(a, b, c)$$

Tangent plane to a surface in the space f(x, y, z) = 0 at point P = (a, b, c)

$$(x-a)\frac{\partial f}{\partial x}(a,b,c)+(y-b)\frac{\partial f}{\partial y}(a,b,c)+(z-c)\frac{\partial f}{\partial z}(a,b,c)=0$$

Implicit derivatives

Implicit derivative of a function f(x, y) = 0

$$y' = \frac{-\frac{\partial f}{\partial x}}{\frac{\partial f}{\partial y}}$$
 and $x' = \frac{-\frac{\partial f}{\partial y}}{\frac{\partial f}{\partial x}}$

Implicit partial derivatives of a function f(x, y, z) = 0

$$\frac{\partial z}{\partial x} = \frac{-\frac{\partial f}{\partial x}}{\frac{\partial f}{\partial z}} \quad \text{and} \quad \frac{\partial z}{\partial x} = \frac{-\frac{\partial f}{\partial y}}{\frac{\partial f}{\partial z}}$$

Extrema and saddle points

- 1. Compute the critical points $\nabla f(P) = 0$.
- 2. At any critical point *P* compute the Hessian:
 - Hf(P) > 0 and $\frac{\partial^2 f}{\partial x^2}(P) > 0 \Rightarrow f$ has a local minimum at P.
 - Hf(P) > 0 and $\frac{\partial^2 f}{\partial x^2}(P) < 0 \Rightarrow f$ has a local maximum at P.
 - $Hf(P) < 0 \Rightarrow f$ has a saddle point at P.

Function approximation

Taylor polynomial of second order of f(x, y) at point P = (a, b)

$$\begin{split} P_{f,P}^2(x,y) &= f(a,b) + \nabla f(a,b)(x-a,y-b) + \\ &+ \frac{1}{2}(x-a,y-b) \nabla^2 f(a,b)(x-a,y-b) \end{split}$$

Maclaurin polynomial of second order of f(x, y)

$$P^2_{f,(0,0)}(x,y) = f(0,0) + \nabla f(0,0)(x,y) + \frac{1}{2}(x,y) \nabla^2 f(0,0)(x,y)$$