

Linear Algebra in Neuroscience

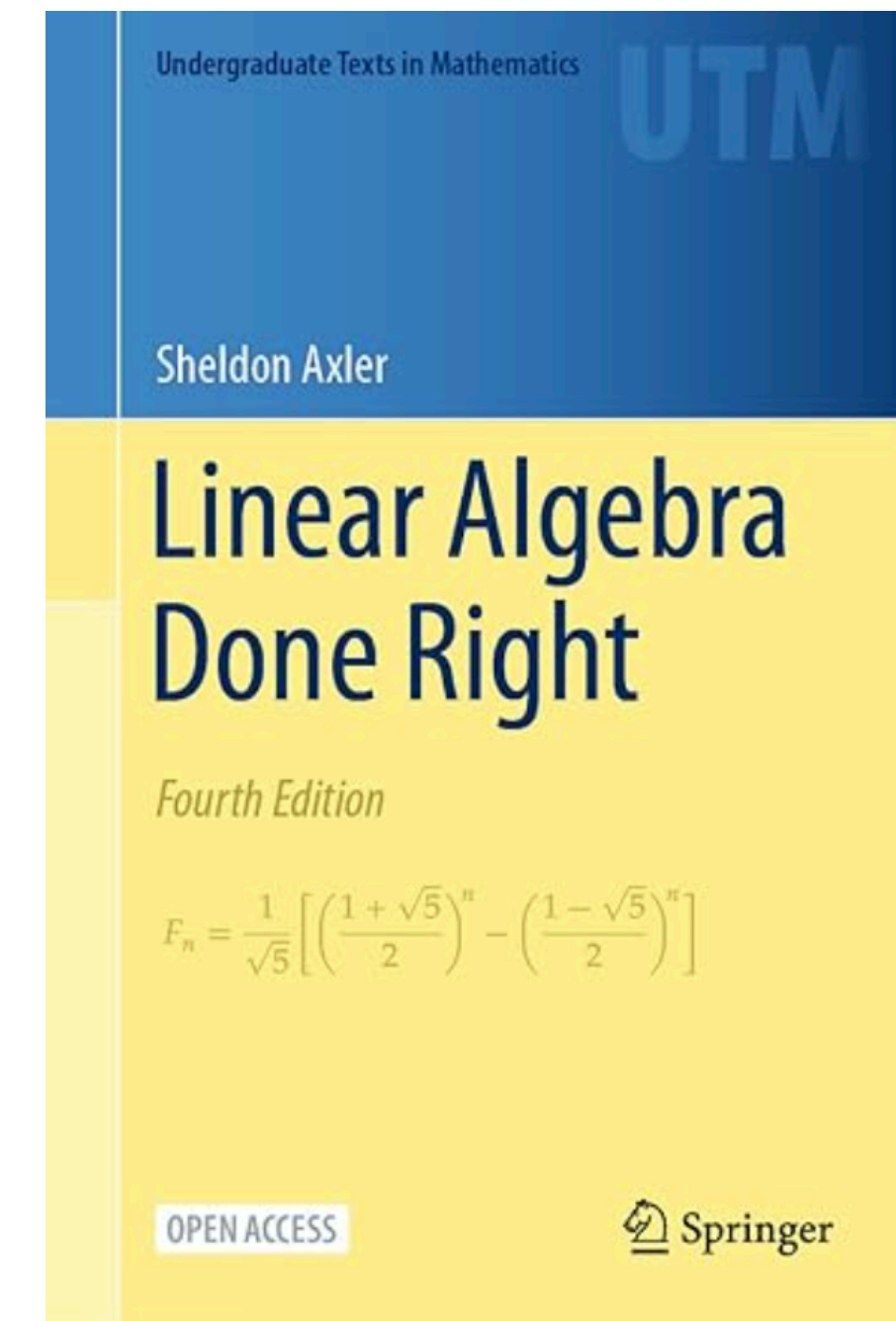
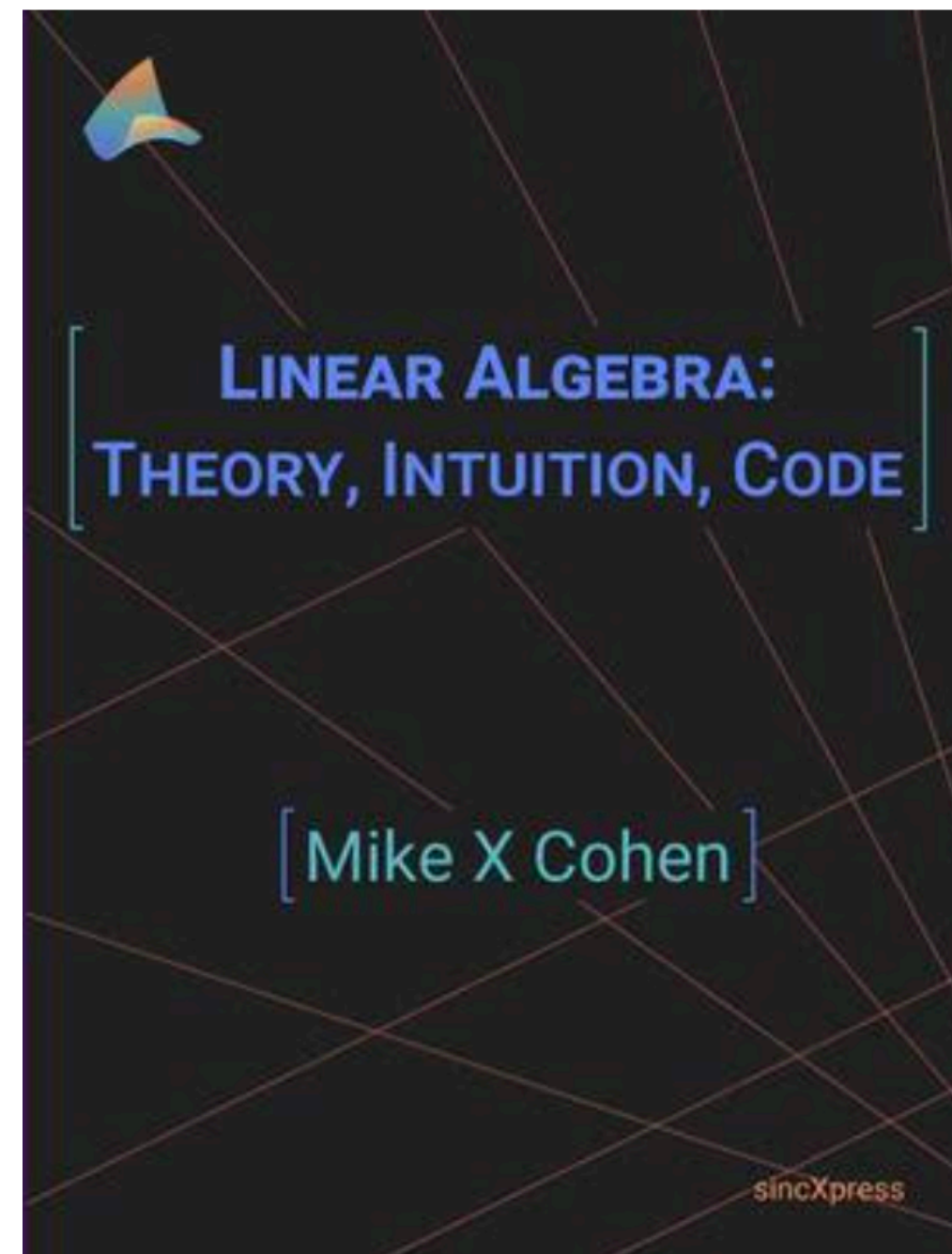
Introduction to dimensionality reduction techniques

University of Helsinki
Aniol Santo-Angles, March 2025

Outline

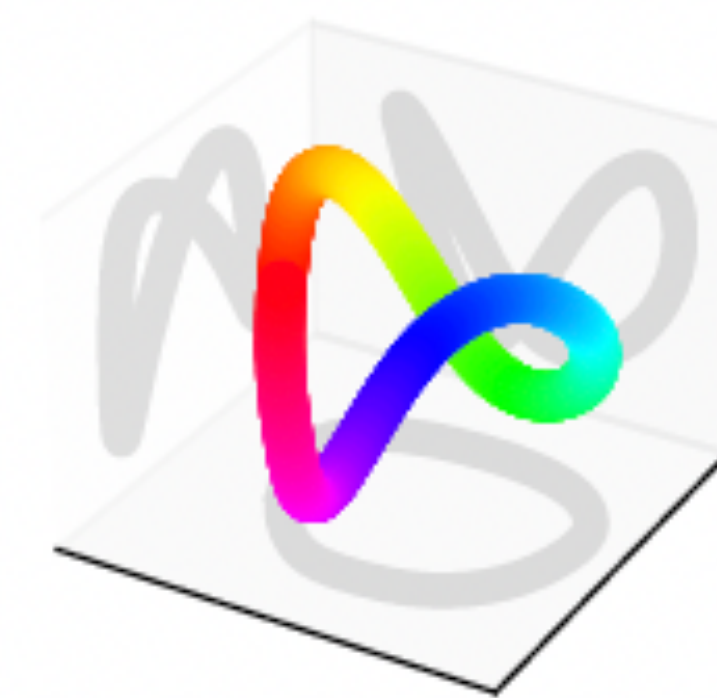
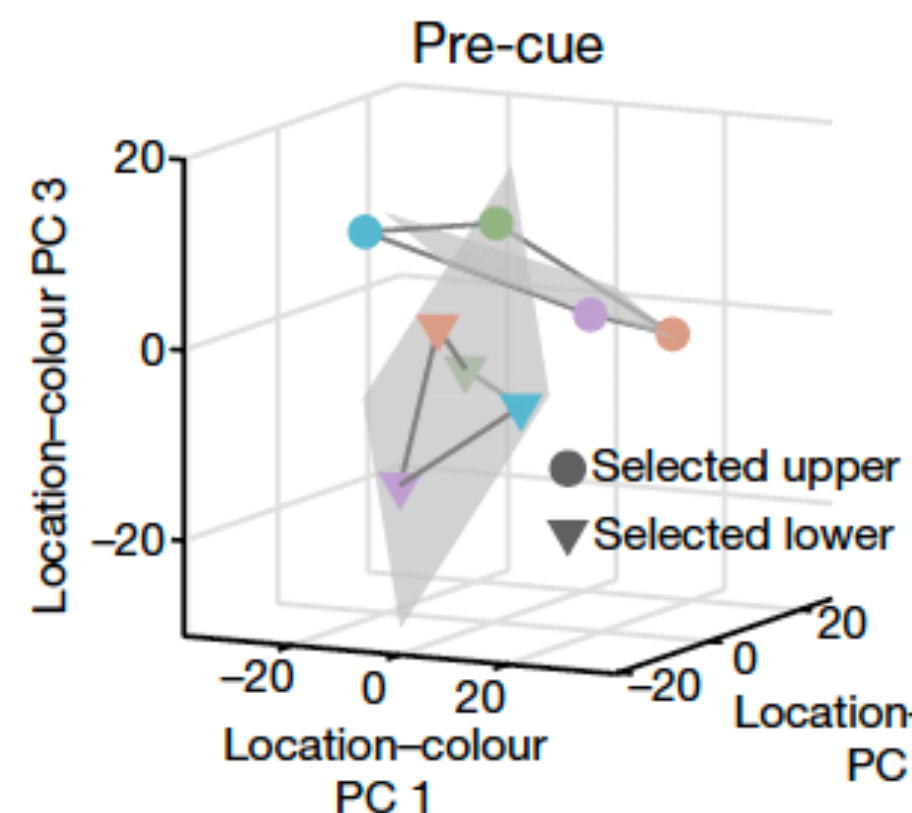
and resources

- Overview
- Eigendecomposition
- SVD
- PCA
- GED
- Hands-on



Overview

- Dimensionality reduction techniques allows to address the curse of dimensionality in large-scale neural recordings (Cunningham, 2014).
- High-dimensional neural activity is constrained to a lower-dimensional, structured subspace (neural manifold) where neural computations take place, enabling efficient information processing, generalization, and robustness to noise (Thibeault, 2023; Langdon, 2023;).
- Neural subspaces encode multiple-item working memory contents (Xie, 2022; Panichello, 2021).
- Head direction cells in mouse projects into a low dimensional ring structure (Duszkiewicz, 2024), consistent across sessions and subjects (Barbosa, 2024)



Linear algebra basics

Apologies in advance for the mathematicians!

* **vector space:** where the vectors live and move according to some rules (addition and scaling)

$$u = [2, 1] \in \mathbb{R}^2$$

$$v = [1, 2, 3] \in \mathbb{R}^3$$

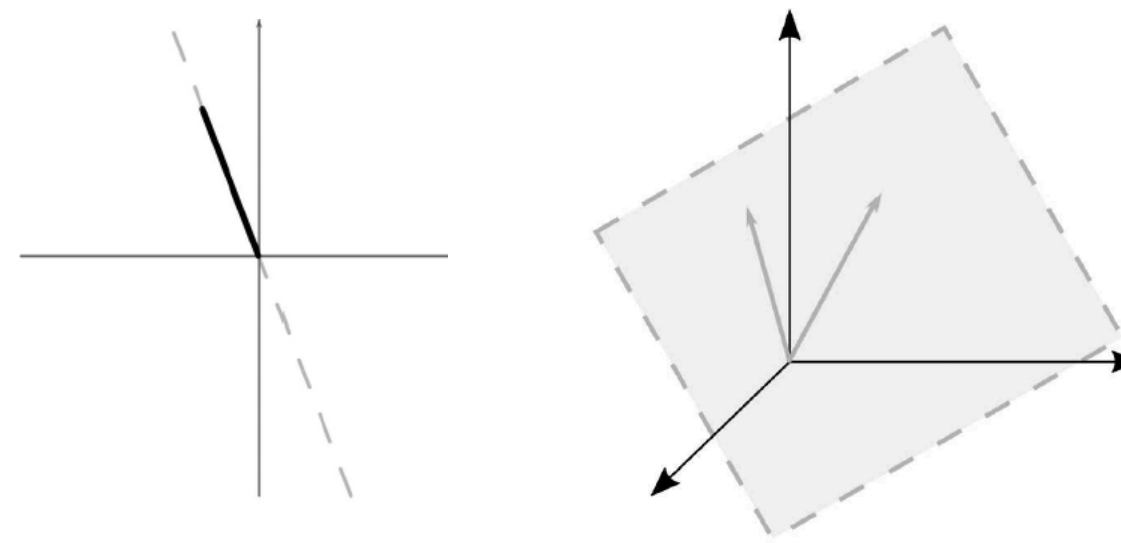
$$v = [1, 2, 3] \notin \mathbb{R}^2$$

* **basis of space:** set of independent vectors that **span** the vector space (ruler of the space) - simplest one are the cartesian basis vectors

$$\mathbb{R}^2 : \left\{ \begin{bmatrix} 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \end{bmatrix} \right\}$$

* **Span:** all points you can reach by stretching and combining a collection of vectors

* **subspace:** the subset of a vector space, which is also a vector space.

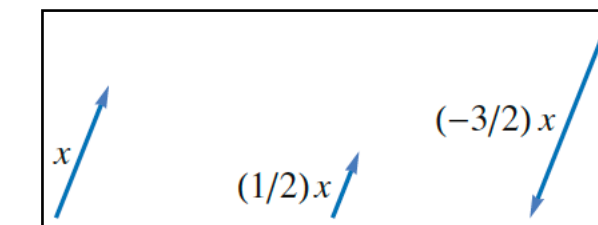


$$T = \{ c [-1, 2] \mid c \in \mathbb{R} \} \subset \mathbb{R}^2$$

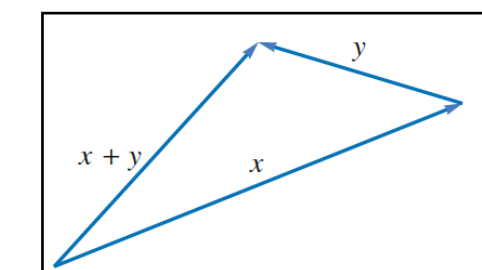
$$S = \{ [x, y, 0] \mid x, y \in \mathbb{R} \} \subset \mathbb{R}^3$$

How vectors 'move' in vector spaces?

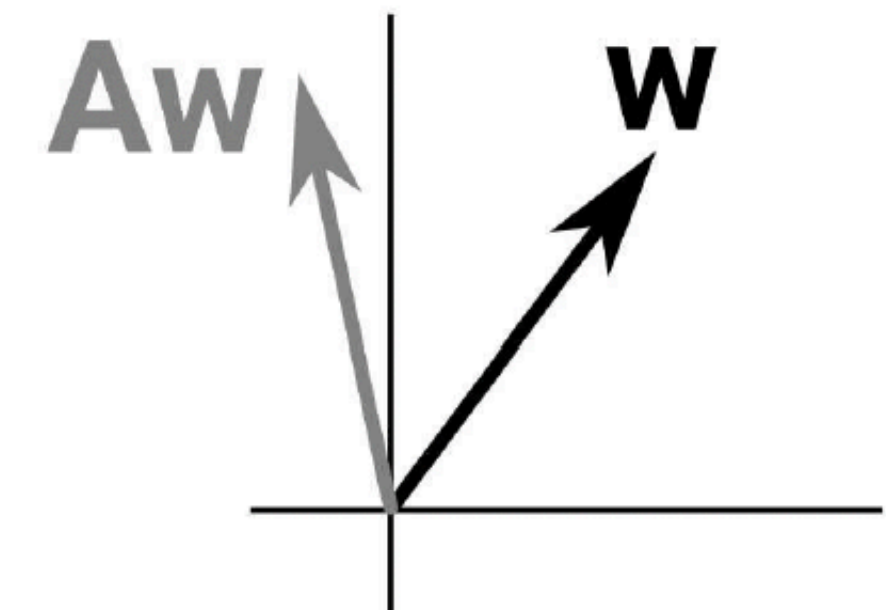
* **Scalar multiplication:** λx



* **Vector addition:** $x + y$



* **Matrix-vector multiplication:** Aw



Eigendecomposition

a.k.a. eigenvalue decomposition, eigenvector decomposition, diagonalization

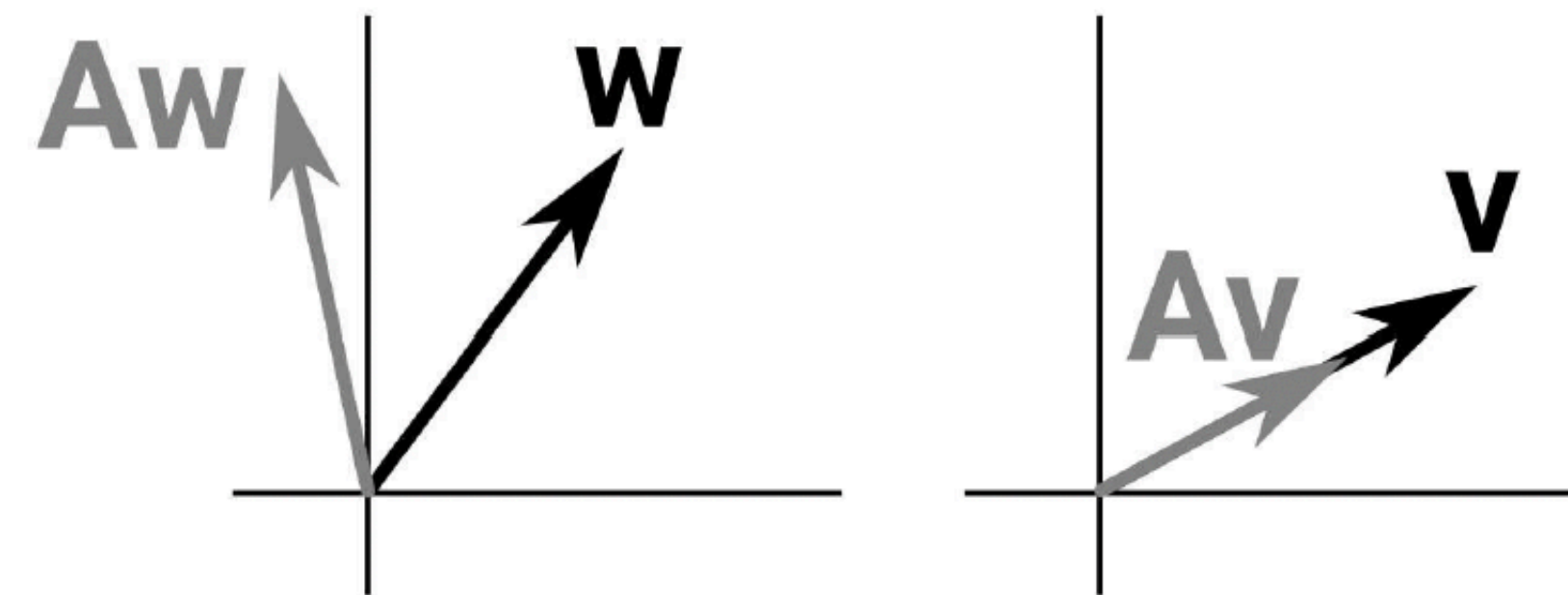
- Eigendecomposition applies only to square matrices
- Goal: extract ‘features’ called eigenvalues (λ , scalar) and eigenvectors (\mathbf{v} , vector)

$$\begin{matrix} M \\ \\ \\ \\ \\ \\ \\ \\ \\ \\ M \end{matrix} \Rightarrow \begin{matrix} \lambda_1 & \lambda_2 & & \lambda_m \\ \left[\begin{matrix} \mathbf{v}_1 \end{matrix} \right] & \left[\begin{matrix} \mathbf{v}_2 \end{matrix} \right] & \dots & \left[\begin{matrix} \mathbf{v}_m \end{matrix} \right] \end{matrix}$$

- Eigenvalue equation

$$A\mathbf{v} = \lambda\mathbf{v}$$

- Effect of matrix is the same as the effect of scalar multiplication

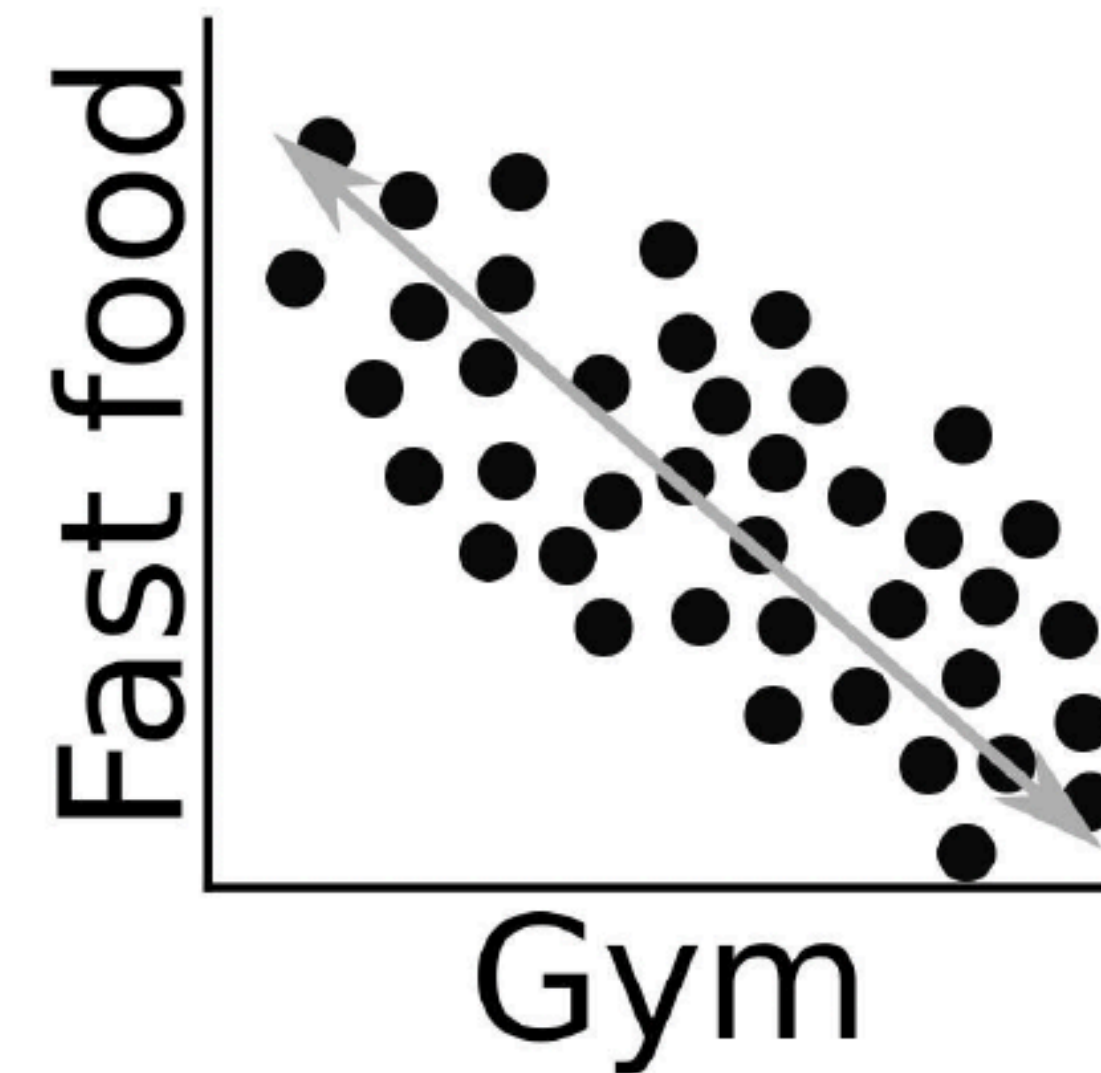


Eigendecomposition

a.k.a. eigenvalue decomposition, eigenvector decomposition, diagonalization

- Eigendecomposition applies only to square matrices
- Goal: extract ‘features’ called eigenvalues (λ , scalar) and eigenvectors (\mathbf{v} , vector)
- Interpretation

$$M \begin{matrix} \left[\right. \\ \\ \\ \left. \right] \\ M \end{matrix} \Rightarrow \begin{matrix} \lambda_1 & \lambda_2 \\ \left[\right. & \left[\right. \\ \mathbf{v}_1 & \mathbf{v}_2 \\ \left. \right] & \left[\right. \\ & \vdots \\ & \left[\right. \\ & \mathbf{v}_m \\ & \left. \right] \end{matrix}$$



Eigendecomposition

Finding eigenvalues and eigenvectors

- Find eigenvalues

$$Av = \lambda v$$

$$Av - \lambda v = 0$$

$$Av - \lambda I v = 0$$

$$(A - \lambda I)v = 0$$

* matrix A shifted by λ , multiplied by a vector v , gives zero vector = null space of matrix $A - \lambda I$

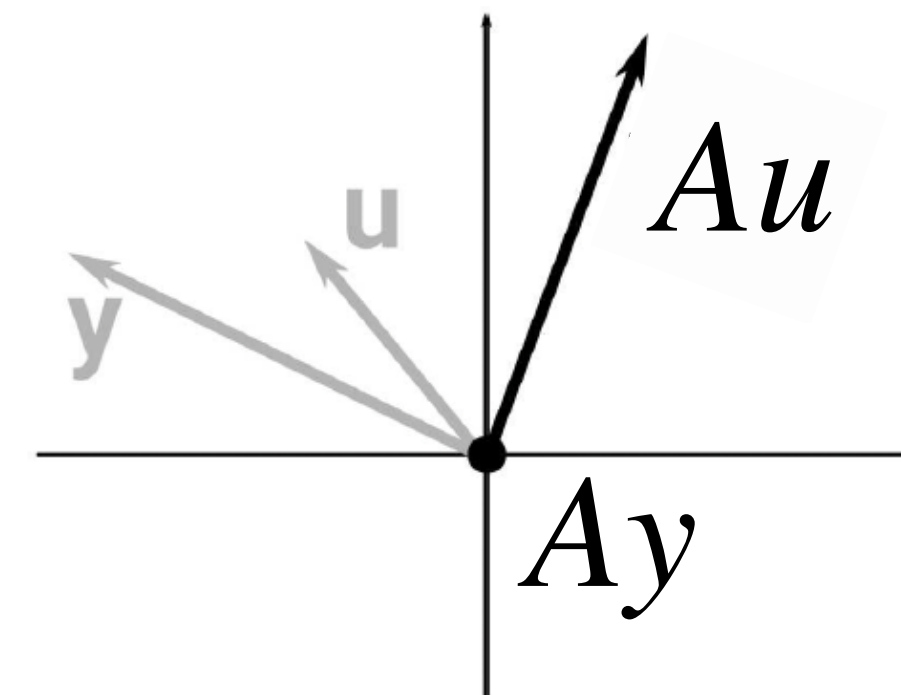
$$|A - \lambda I| = 0$$

* determinant of $A - \lambda I$ is zero

(Any square matrix with a non-trivial null space has determinant zero)

* **null space**: subspace containing all vectors (y) that satisfy (non-trivial)

$$Ay = 0$$



Eigendecomposition

Finding eigenvalues and eigenvectors

- Find eigenvalues

$$|A - \lambda I| = 0$$

$$\left| \begin{bmatrix} a & b \\ c & d \end{bmatrix} - \lambda \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \right| = 0$$

$$\begin{vmatrix} a - \lambda & b \\ c & d - \lambda \end{vmatrix} = 0$$

$$(a - \lambda)(d - \lambda) - bc = 0$$

$$\lambda^2 - (a + d)\lambda + (ad - bc) = 0$$

$$\lambda = \frac{-b \pm \sqrt{b^2 - 4ac}}{2a}$$

$$\begin{bmatrix} 1 & 2 \\ 2 & 1 \end{bmatrix} \Rightarrow \begin{vmatrix} 1 - \lambda & 2 \\ 2 & 1 - \lambda \end{vmatrix} = 0$$

$$(1 - \lambda)(1 - \lambda) - 4 = 0$$

$$\lambda^2 - 2\lambda - 3 = 0$$

$$(\lambda - 3)(\lambda + 1) = 0$$

$$\Rightarrow \lambda_1 = 3, \lambda_2 = -1$$

Eigendecomposition

Finding eigenvalues and eigenvectors

- Find eigenvectors

$$(A - \lambda_i I)v_i = 0$$

$$\begin{bmatrix} 1 & 2 \\ 2 & 1 \end{bmatrix} \Rightarrow \lambda_1 = 3, \lambda_2 = -1$$

$$(A - \lambda_i I) \quad (A - \lambda_i I) \quad (A - \lambda_i I)v_i = 0$$

$$\begin{bmatrix} 1-3 & 2 \\ 2 & 1-3 \end{bmatrix} = \begin{bmatrix} -2 & 2 \\ 2 & -2 \end{bmatrix} \Rightarrow \begin{bmatrix} -2 & 2 \\ 2 & -2 \end{bmatrix} \begin{bmatrix} 1 \\ 1 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

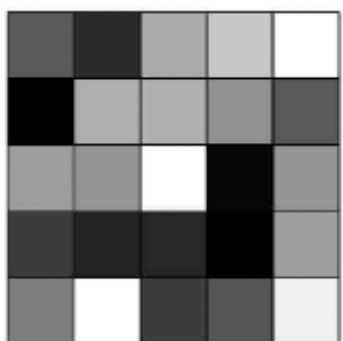
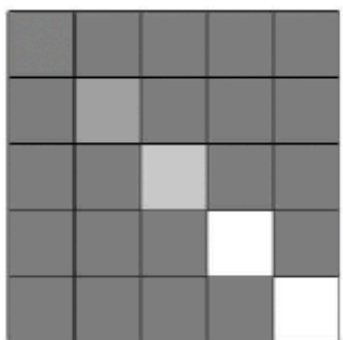
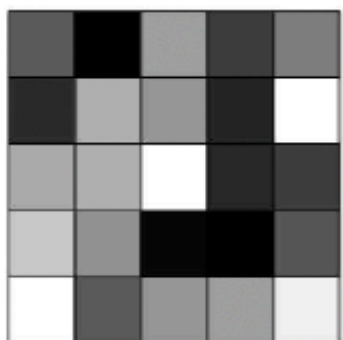
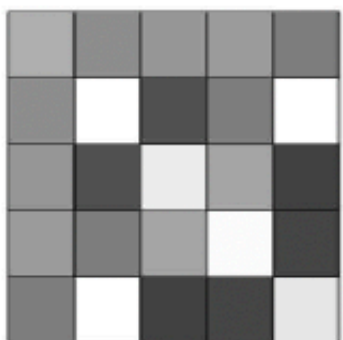
$$\begin{bmatrix} 1-(-1) & 2 \\ 2 & 1-(-1) \end{bmatrix} = \begin{bmatrix} 2 & 2 \\ 2 & 2 \end{bmatrix} \Rightarrow \begin{bmatrix} 2 & 2 \\ 2 & 2 \end{bmatrix} \begin{bmatrix} -1 \\ 1 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

$$\begin{bmatrix} 1 & 2 \\ 2 & 1 \end{bmatrix} \begin{cases} \lambda_1 = 3, & \mathbf{v}_1 = \alpha \begin{bmatrix} 1 & 1 \end{bmatrix}^T, & \alpha \in \mathbb{R} \\ \lambda_2 = -1, & \mathbf{v}_2 = \beta \begin{bmatrix} -1 & 1 \end{bmatrix}^T, & \beta \in \mathbb{R} \end{cases}$$

Eigendecomposition

Summary

- Only for squared matrices.
- Decomposition of a matrix into eigenvectors and eigenvalues.
- Eigenvectors indicate the direction of most variance in A
- Eigenvalues indicate the ‘importance’ of each eigenvector (variance explained)
- Eigenvectors are new basis vectors for A (if A is diagonalizable, which is the case for all symmetric matrices)

$$\mathbf{A} = \mathbf{V} \mathbf{\Lambda} \mathbf{V}^{-1}$$


* matrix inverse:

$$M^{-1}M = I$$

Singular Value Decomposition

SVD as generalization of eigendecomposition

- SVD applies also to non-square matrices
- Goal: extract 'features' called singular values (σ , scalar) and singular vectors (u v, vector)

$$A = U \Sigma V^T$$

$$\begin{array}{c} \boxed{A} \\ (M \times N) \end{array} = \begin{array}{c} \boxed{U} \\ (M \times M) \end{array} \begin{array}{c} \boxed{\Sigma} \\ (M \times M) \end{array} \begin{array}{c} \boxed{V^T} \\ (M \times M) \end{array}$$

$$\begin{array}{c} \boxed{A} \\ (M \times N) \end{array} = \begin{array}{c} \boxed{U} \\ (M \times M) \end{array} \begin{array}{c} \boxed{\Sigma} \\ (M \times N) \end{array} \begin{array}{c} \boxed{V^T} \\ (N \times N) \end{array}$$

$$\begin{array}{c} \boxed{A} \\ (M \times N) \end{array} = \begin{array}{c} \boxed{U} \\ (M \times M) \end{array} \begin{array}{c} \boxed{\Sigma} \\ (M \times N) \end{array} \begin{array}{c} \boxed{V^T} \\ (N \times N) \end{array}$$

- A is matrix (MxN)
- Σ is a diagonal matrix with **singular values** σ (all non-negative, all real-valued)
- U is the **left singular** vectors matrix with columns as orthonormal basis for \mathbb{R}^M
- V is the **right singular** vectors matrix with columns as orthonormal basis for \mathbb{R}^N

Singular Value Decomposition

Finding singular values and singular vectors

$$A = U\Sigma V^T$$

- Finding V and Σ matrices

$$A^T A = V\Sigma^2 V^T$$

(eigendecomposition of the
transpose of A times A)

- Finding U matrix

$$A A^T = U\Sigma^2 U^T$$

(eigendecomposition of A
times the transpose of A)

Singular Value Decomposition

SVD nice properties

- **Rank** of matrix A: number of non-zero elements in the diagonal of Σ

* **rank** of matrix: largest number of columns/rows that form a linearly independent set (full-rank vs reduced-rank or singular matrices)

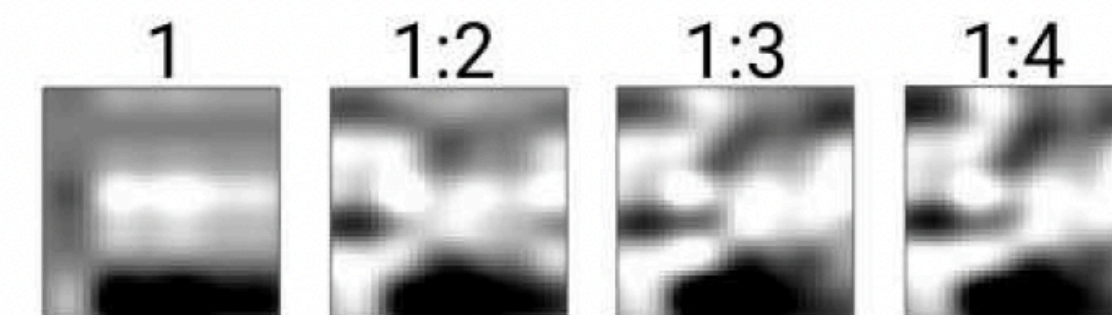
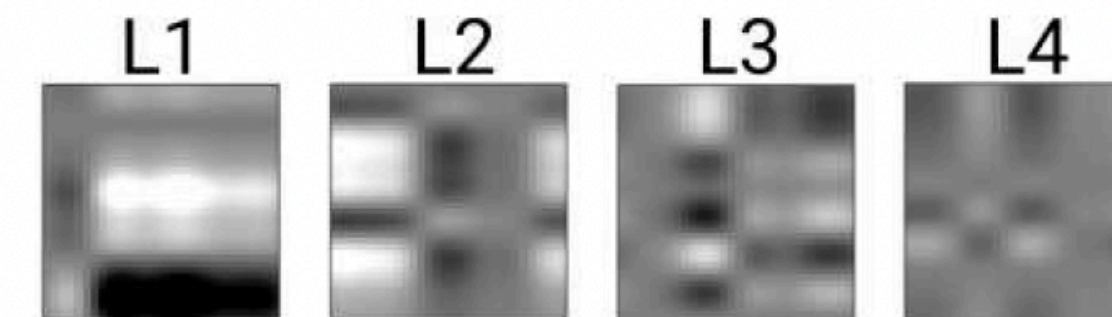
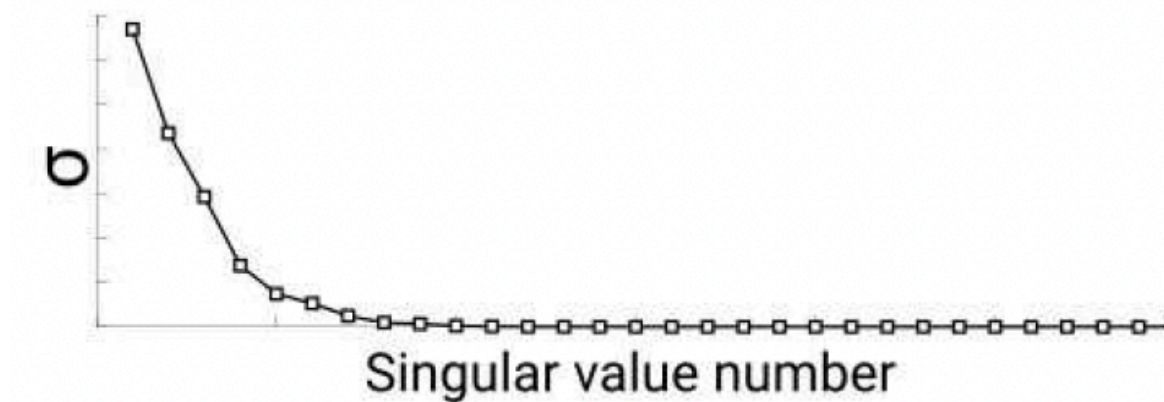
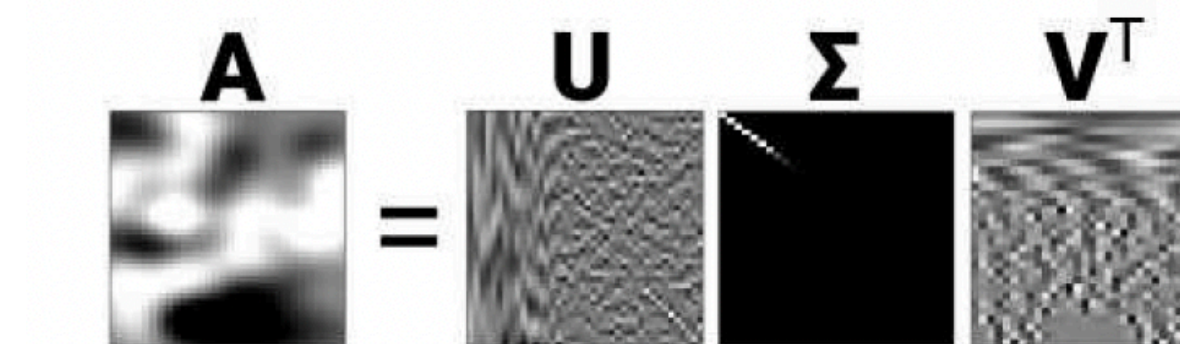
Singular Value Decomposition

SVD nice properties

- **Low-rank approximation of A:**

$$\tilde{A} = \sum_{i=1}^k u_i \sigma_i v_i^T$$

- noise reduction
- ML classification
- data compression



Principal Component Analysis

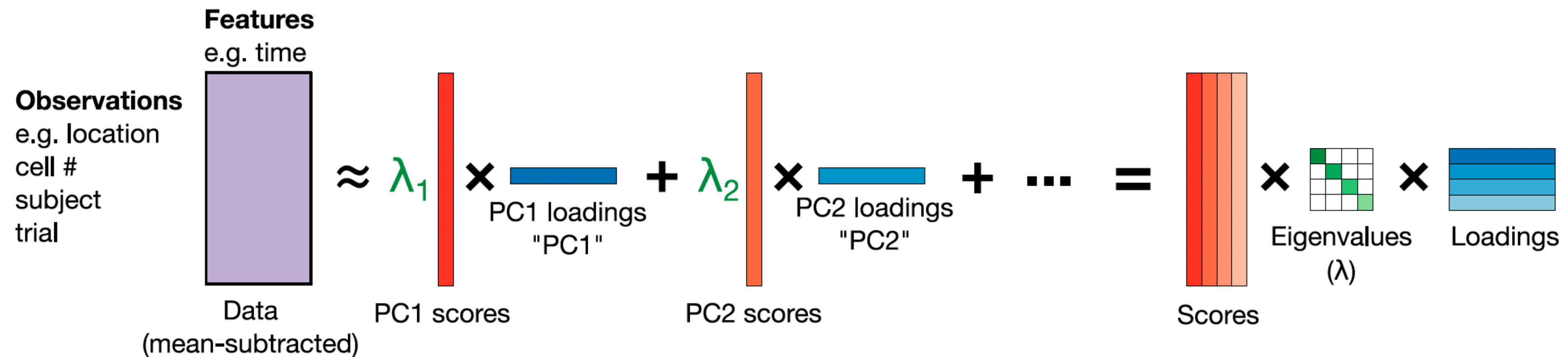
Linear algebra aspects of PCA

- Multivariate dataset (X matrix) with observations (rows) and features (columns) - reduce dimensionality on features
- Example 1:
 - Observations (rows): subjects
 - Columns (features): clinical scores
- Example 2:
 - Observations (rows): stimulus
 - Columns (features): neurons

Principal Component Analysis

Linear algebra aspects of PCA

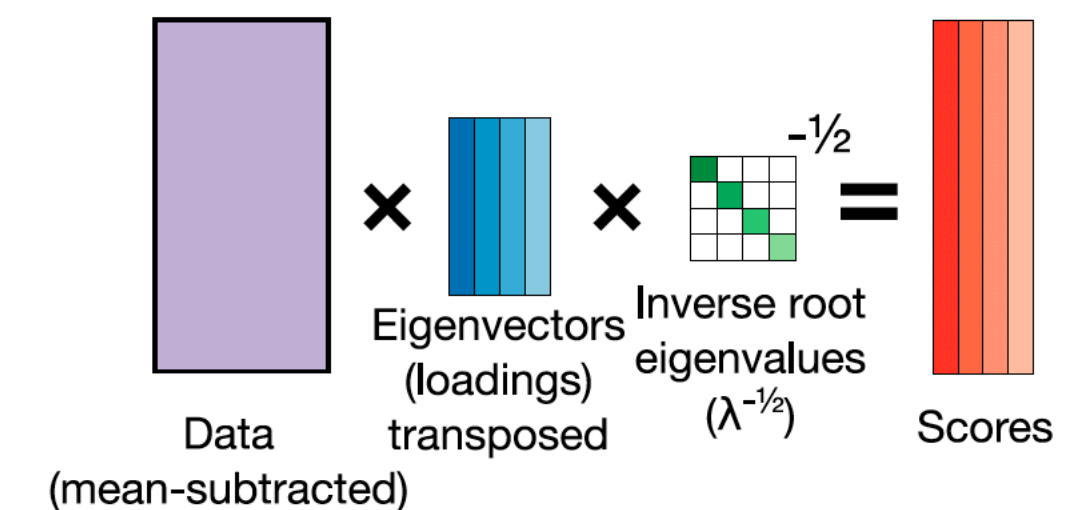
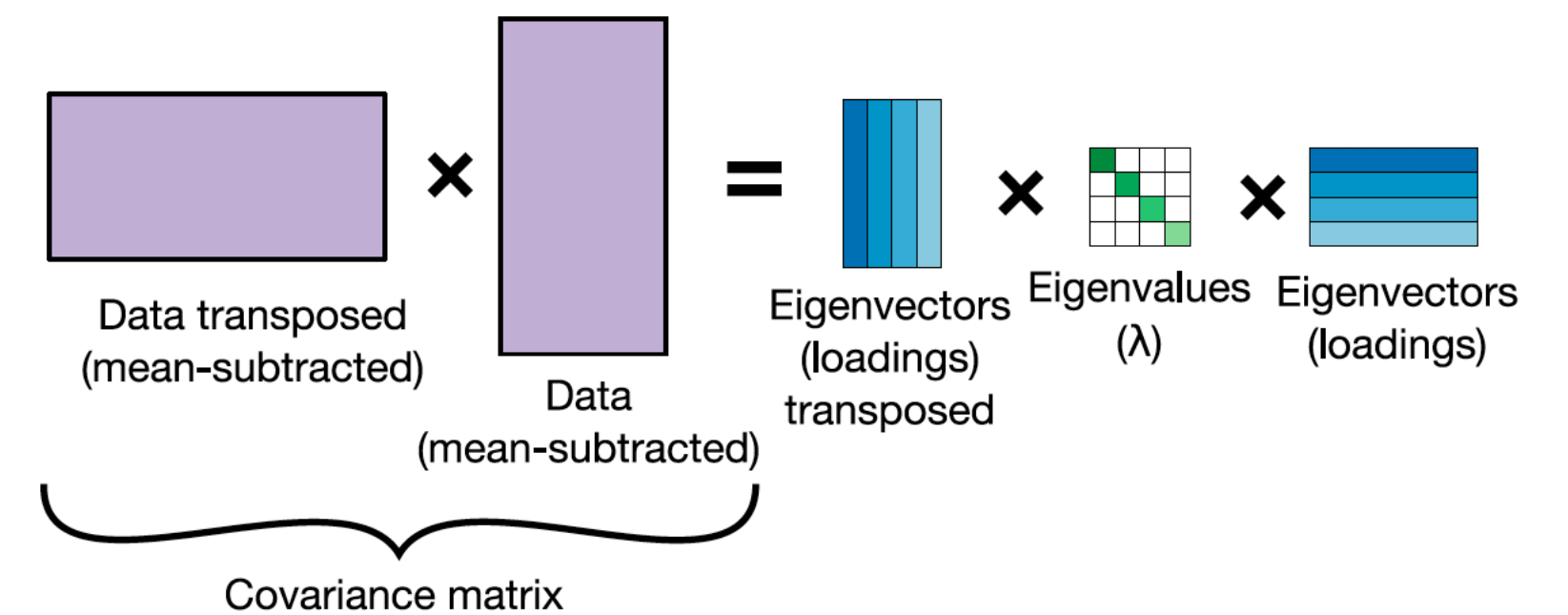
- Goal PCA: decompose multivariate dataset into Principal Components (PCs), including scores and loadings.



Principal Component Analysis

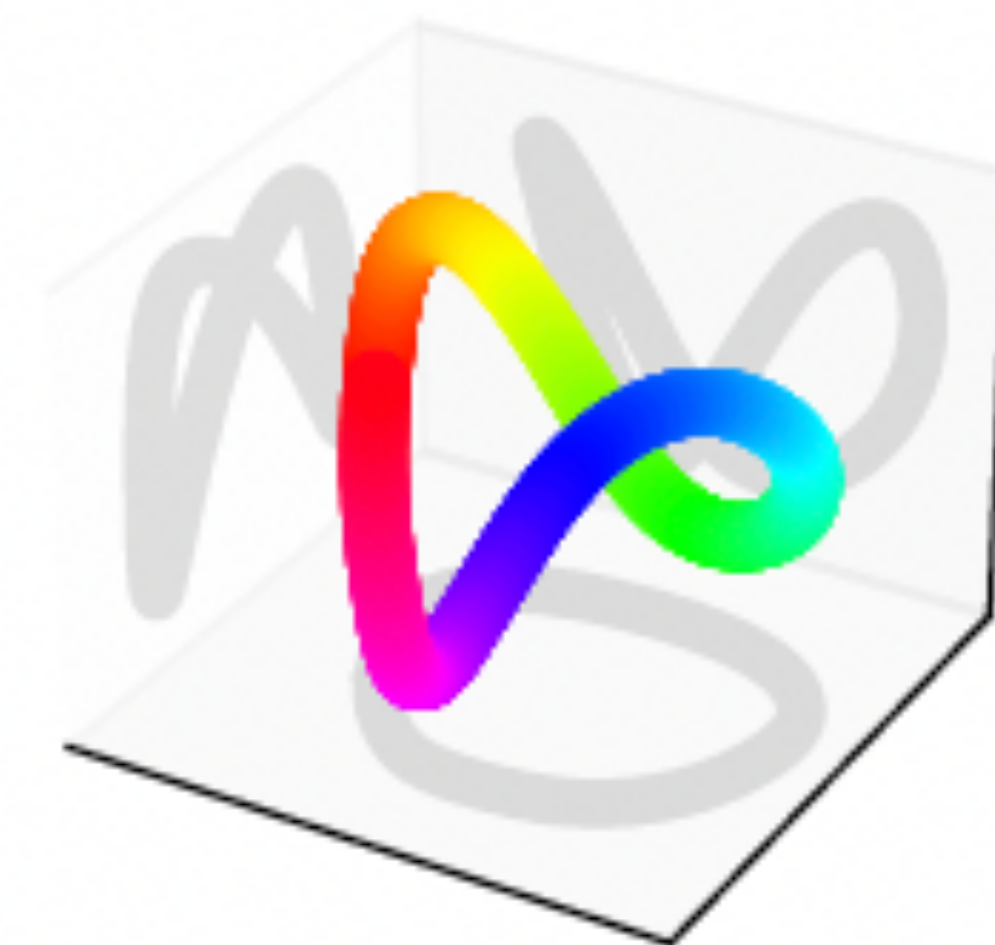
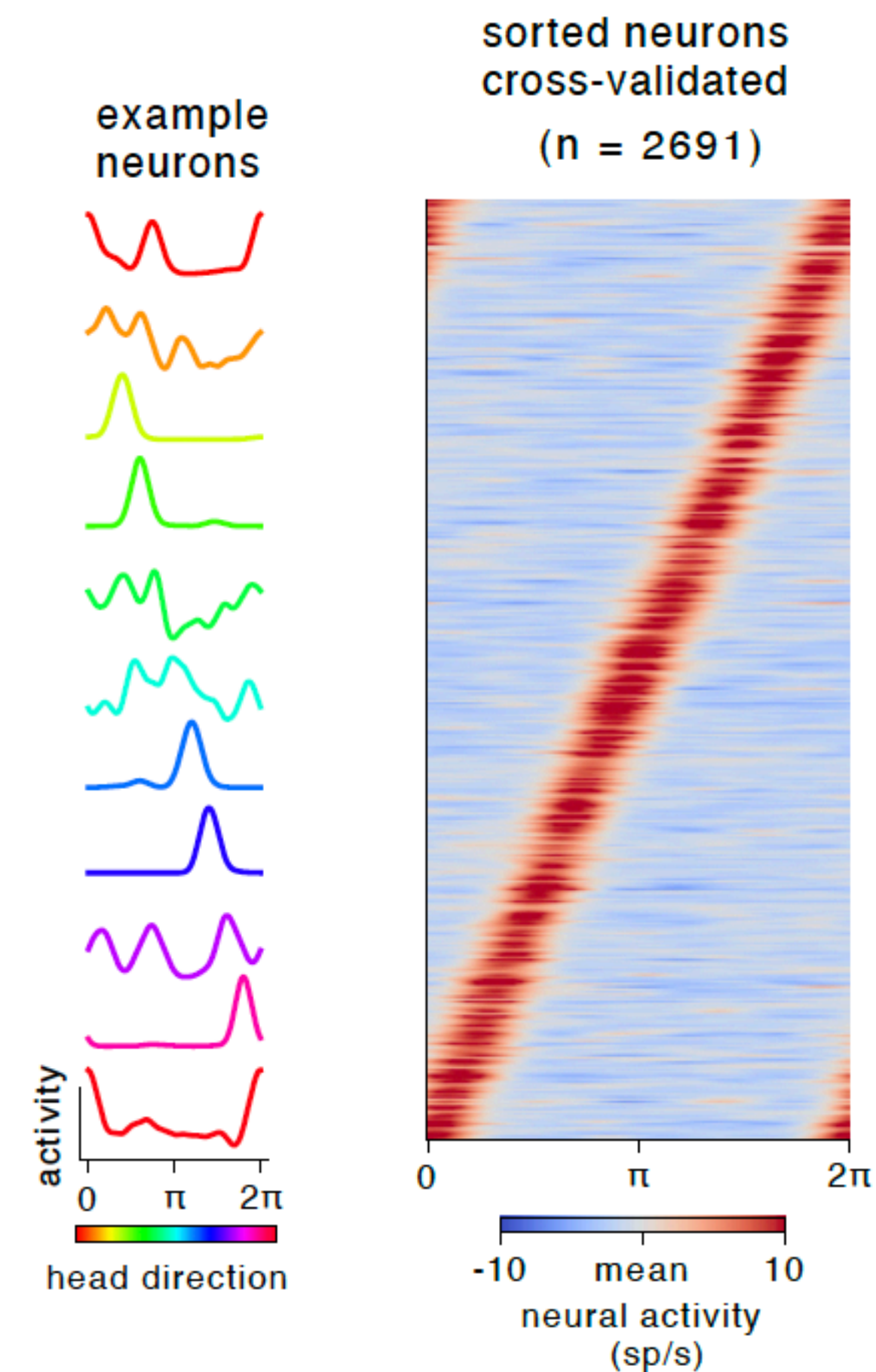
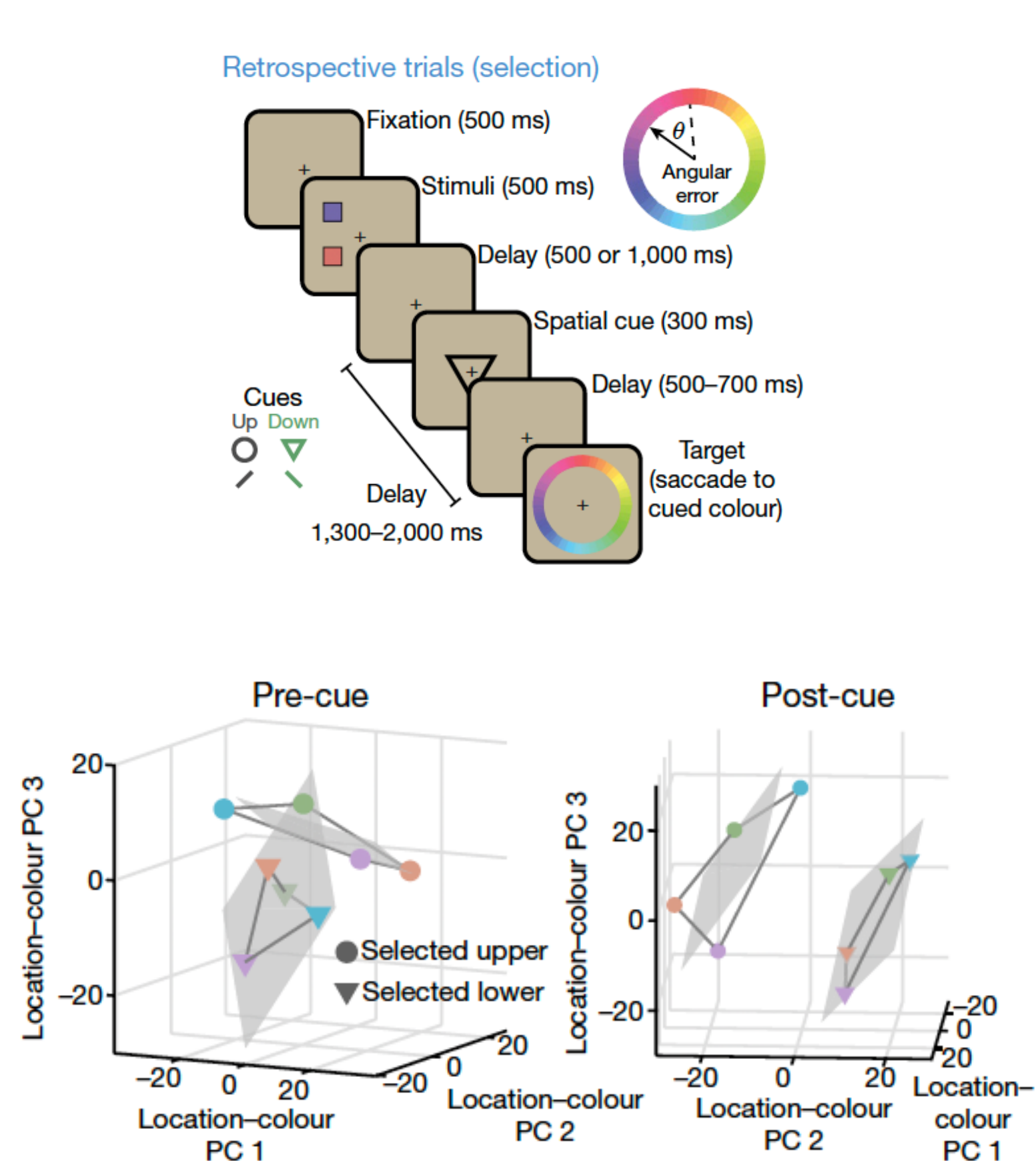
How to compute

1. Mean-center columns of X , then compute **covariance matrix** $\text{cov}(X - \text{mean}(X))$, dimension features by features.
 2. **Eigendecomposition of $\text{cov}(X - \text{mean}(X))$** . Eigenvectors are **PC loadings**.
 3. Compute 'components scores' (**PC scores**) as the weighted combination of all data features: $v_i^T X$ for component i .
 4. Convert eigenvalues to **variance explained**.
- PCA in Matlab and Python is implemented with SVD, since works better for large datasets



Principal Component Analysis

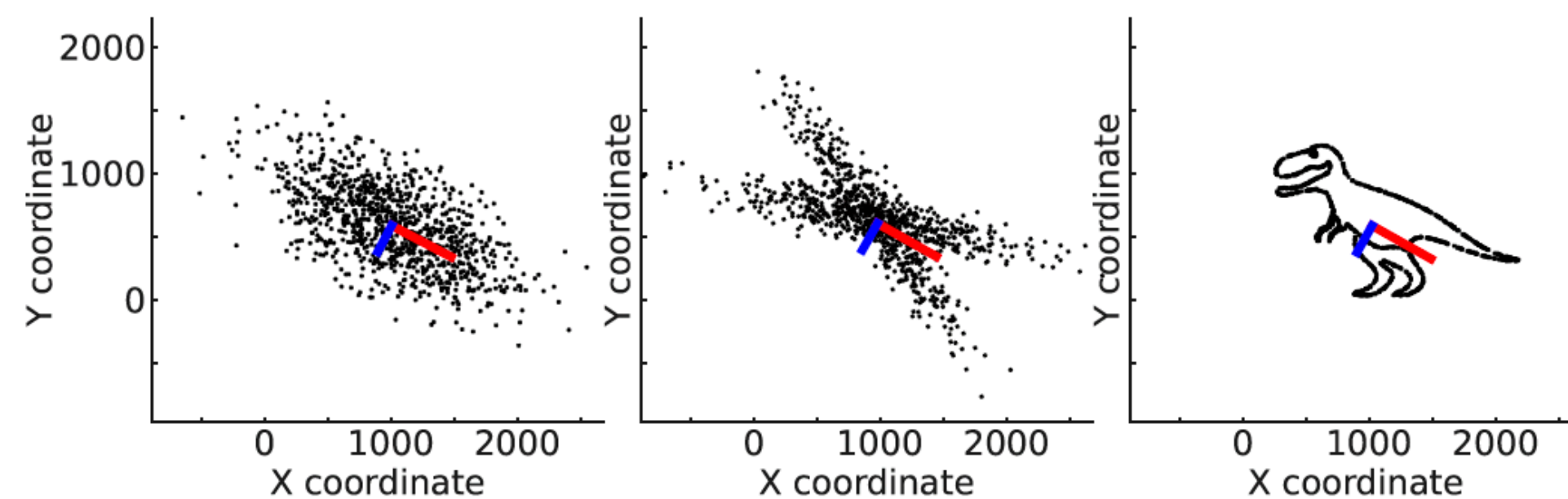
Applications



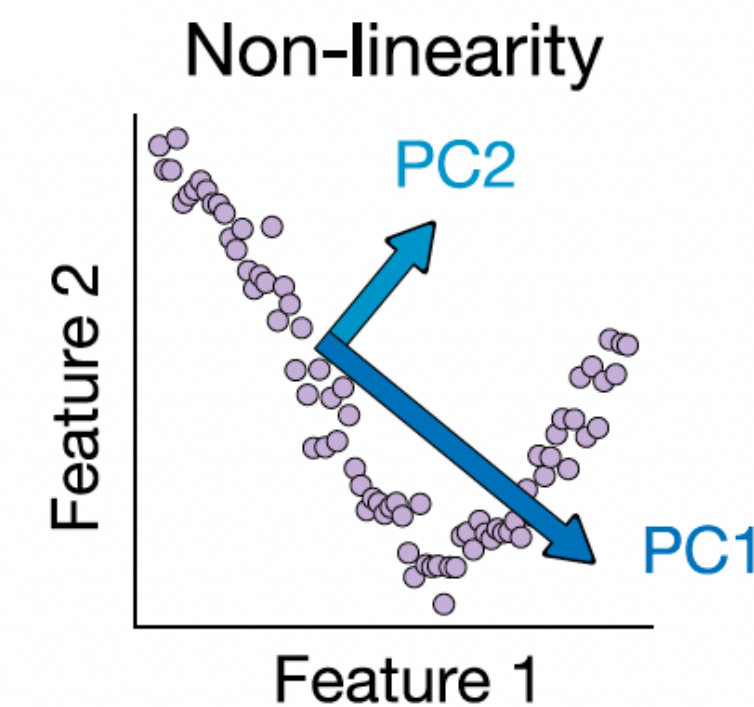
Principal Component Analysis

Limitations

- PCA assumes that directions of maximal variability are the most important (**variance-centric**):
 - unable to separate correlated sources.
 - maximal variance does not mean biologically meaningful
- PCA over data with smoothness and shifting in time or space (most of neuroscience data) produce '**phantom oscillations**' (Shinn, 2023)
- Blind to **non-linear** relationships.



Dyer and Kording, 2023



Shinn, 2023

Generalized eigendecomposition

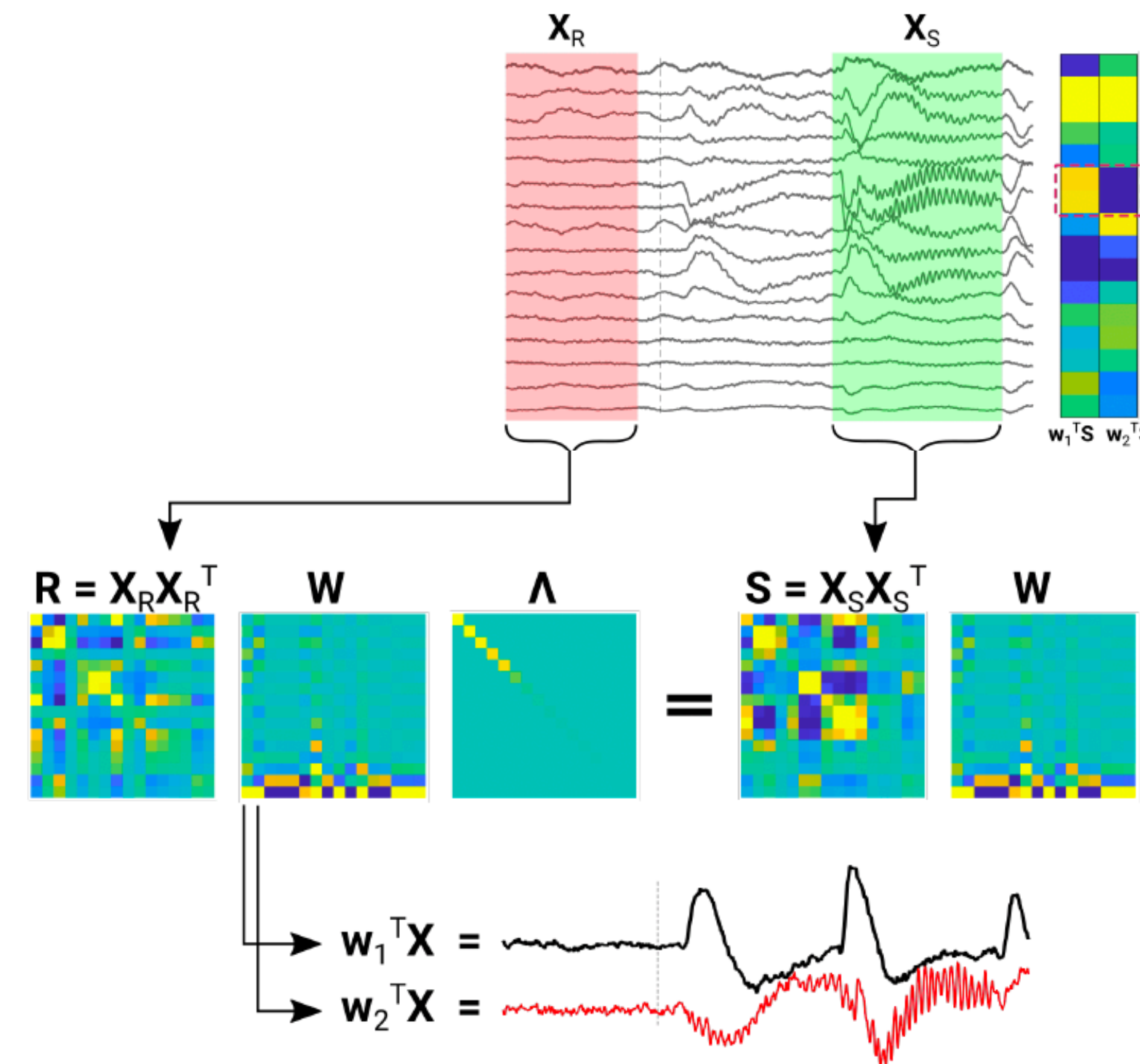
a.k.a. simultaneous diagonalization of two matrices

- Eigendecomposition: $A\mathbf{v} = \lambda\mathbf{v}$
- GED: $A\mathbf{v} = \lambda B\mathbf{v}$
- Interpretation: spatial filters created by GED are designed to maximize a contrast between two features of the data

$$(B^{-1}A)\mathbf{v} = \lambda\mathbf{v}$$

$$C\mathbf{v} = \lambda\mathbf{v}$$

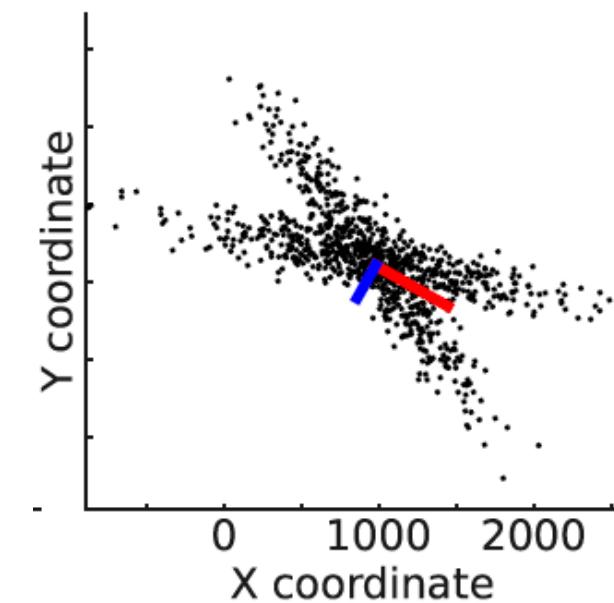
$$C = B^{-1}A$$



Generalized eigendecomposition

advantages

- Based on specific hypotheses
 - experimental vs control condition,
 - pre stimulus vs post stimulus period,
 - trial-averaged vs single-trial,
 - narrowband vs broadband.
- Null hypothesis is that contrast ratio of 1 (no differences between S and R).
- Inferential statistics about the significance of components.
- Ability to separate correlated sources (more biologically plausible).
- Easy to apply as fast to compute.



Other dimensionality reduction techniques

Linear methods

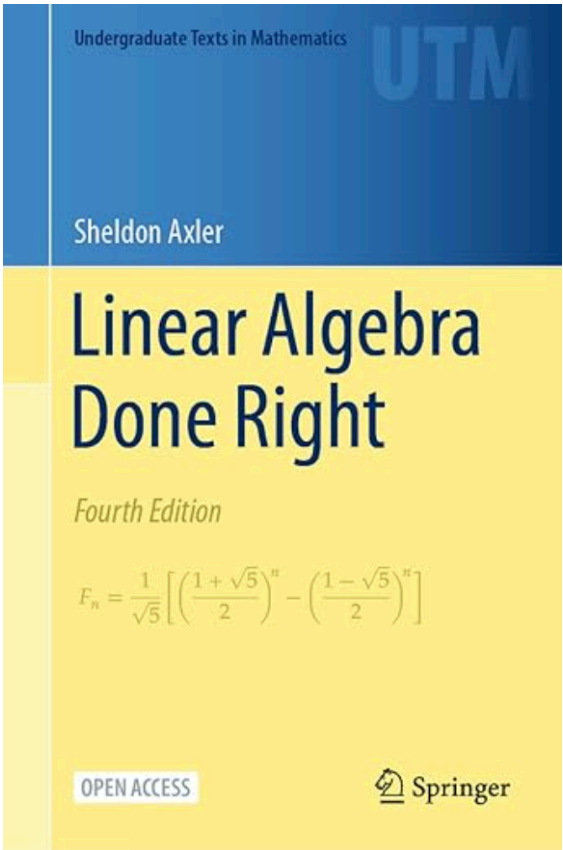
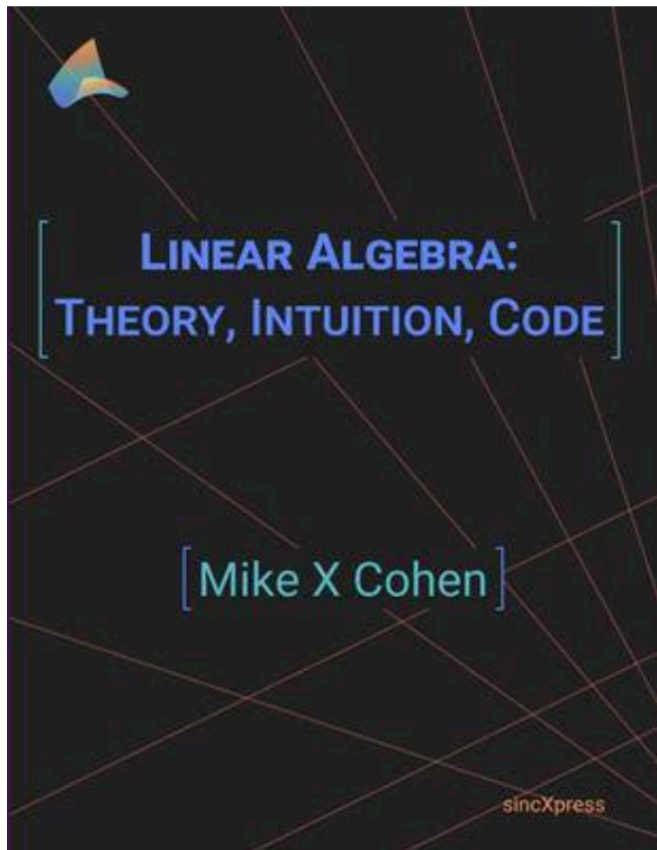
- Independent Component Analysis
- Factor analysis
- Fourier transform
- Linear discriminant analysis
- Canonical correlation analysis (CCA)
- Partial Least Squares (PLS)
- **Complex PCA**

Non-linear methods

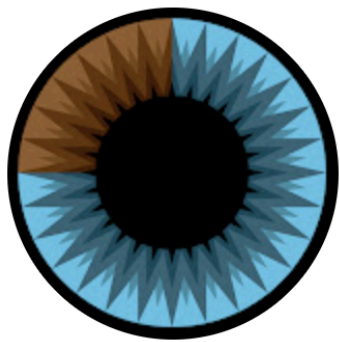
- **CEBRA (Consistent EmBeddings of high-dimensional Recordings using Auxiliary variables)**
- Kernel PCA
- Isomap
- Locally linear embedding (LLE)
- Hessian LLE
- Laplacian eigenmaps
- Generalized discriminant analysis (GDA)
- Autoencoders
- Nonnegative matrix factorization (NMF)
- t-SNE
- t-STE
- UMAP
- Poincaré
- GloVe
- Word2Vec

Resources

Books (open source)

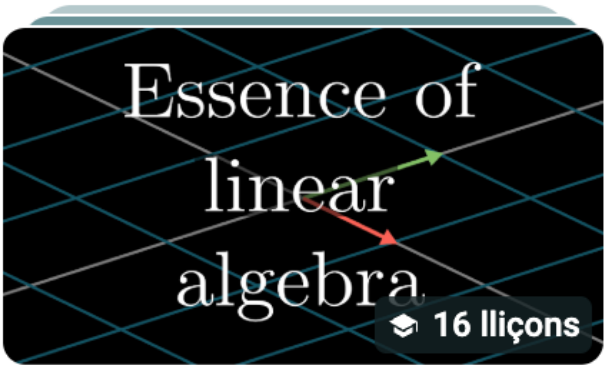


Videos

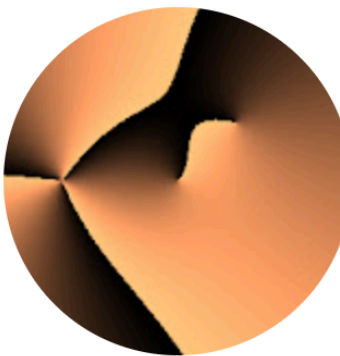


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My name is Grant Sanderson. Videos he
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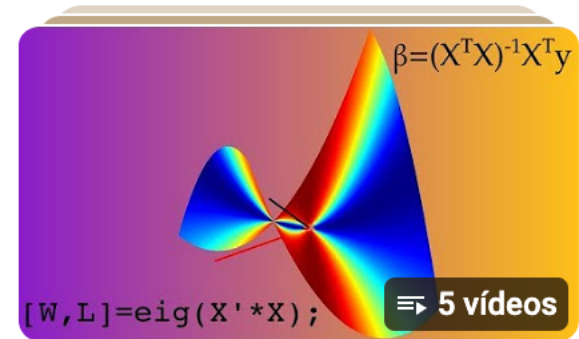


Essence of linear algebra
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Mike X Cohen
@mikexcohen1 · 37,1 k subscriptors
Welcome to my youtube channel, whi

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Linear algebra: theory and implementation

Thanks!