INTERACTION-GROUNDED LEARNING FOR RECOMMENDER SYSTEMS

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Implicit user feedback is not the true satisfaction signal!

INTERACTION-GROUNDED LEARNING (IGL)

Premise: learner optimizes for latent rewards by interacting with the environment and associating observed feedback with the unobservable true reward

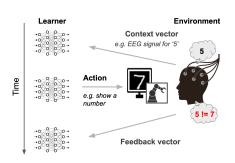


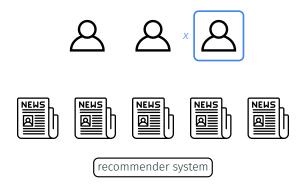
Figure 1: Original motivation for IGL [8]

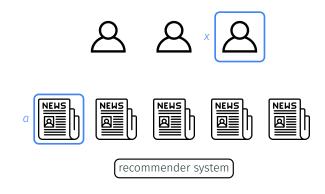


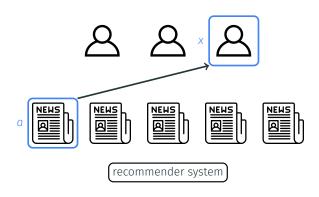
Figure 2: EEG signals¹

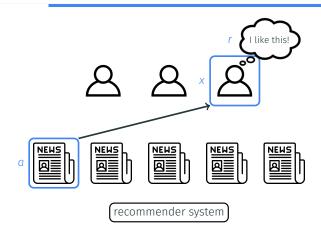
¹https://team.inria.fr/potioc/old-research-topics/eeg-signal-processing/

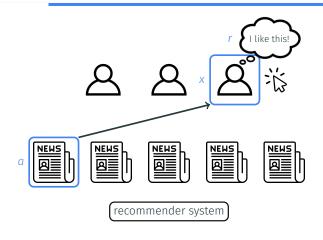


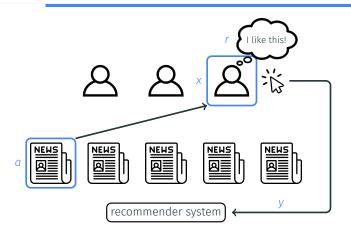


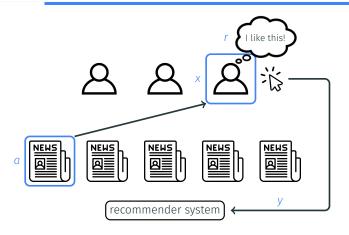




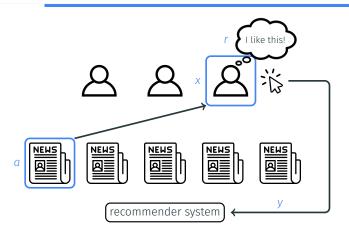








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Consistent communication assumption: $y \perp a | x, r$

ARE 2 LATENT STATES SUFFICIENT FOR RECOMMENDER SYSTEMS?

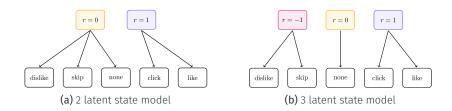


Figure 3: Example of the latent reward structure for a music recommendation system. In Fig. 1a, r=0 corresponds to anything other than the user actively enjoying the content, whereas in Fig. 1b, lack of user enjoyment is split into indifference and active dissatisfaction.

IGL-P(2): AN ALGORITHM FOR TWO LATENT STATES

Algorithm idea: anytime the posterior probability of an action is predicted to be more than twice the prior probability, we deduce $r \neq 0$.

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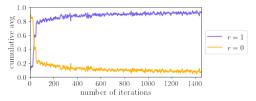


Figure 4: Performance of IGL-P(2) when there are two latent states.

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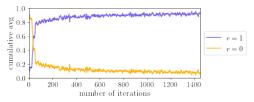


Figure 4: Performance of IGL-P(2) when there are two latent states.

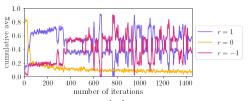


Figure 5: Performance of IGL-P(2) when there are three latent states.

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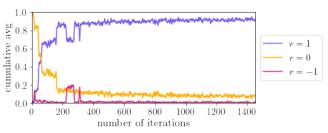


Figure 6: IGL-P(3) successfully maximizes user satisfaction while minimizing dissatisfaction.

PRODUCTION SETTING: WINDOWS SPOTLIGHT



Figure 7: An example of a Windows Spotlight lock screen. Users can interact with the interface using 'click', 'like' or 'dislike' feedback.

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PRODUCTION RESULTS

Algorithm	IGL-P(2)	IGL-P(3)
Clicks	[0.926, 1.005, 1.091]	[0.999, 1.067, 1.152]
Likes	[0.914, 0.949, 0.988]	[0.985, 1.029, 1.054]
Dislikes	[1.141, 1.337, 1.557]	[0.999, 1.067, 1.152] [0.985, 1.029, 1.054] [0.751, 1.072, 1.274]

Table 1: Relative metrics lift over a production baseline. The production baseline uses a hand-engineered reward function which is not available to IGL algorithms. Shown are point estimates and associated bootstrap 95% confidence regions. IGL-P(2) erroneously increases dislikes to the detriment of other metrics. IGL-P(3) directionally improves over the hand-engineered reward function.

BENEFITS OF IGL



Cheaper than manual feature engineering

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Easily adapt to evolving systems and users

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Improved fairness for diverse users



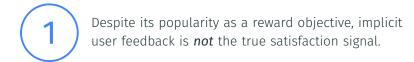
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The Interaction-Grounded Learning (IGL) framework directly targets the underlying user satisfaction.



2 The Interaction-Grounded Learning (IGL) framework directly targets the underlying user satisfaction.

IGL outperforms state-of-the-art real world systems by learning personalized reward functions for users.

THANK YOU! ANY QUESTIONS?

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