Day 3: Overfitting and Generalization Summer STEM: Machine Learning

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- What if we have multivariate data with **x** being a vector?
- Ex: $\mathbf{x}_i = [x_{i1}, x_{i2}]^T$

$$\hat{y}_1 = w_0 + w_1 x_{11} + w_2 x_{12}$$

$$\hat{y}_2 = w_0 + w_1 x_{21} + w_2 x_{22}$$

$$\vdots$$

$$\hat{y}_N = w_0 + w_1 x_{N1} + w_2 x_{N2}$$

lacksquare The model can be written as $\hat{y_i} = egin{bmatrix} 1 & x_{i1} & x_{i2} \end{bmatrix} egin{bmatrix} w_0 \ w_1 \ w_2 \end{bmatrix}$



■ In matrix-vector form

$$\begin{bmatrix} \hat{y}_1 \\ \hat{y}_2 \\ \vdots \\ \hat{y}_n \end{bmatrix} = \begin{bmatrix} 1 & x_{11} & x_{12} \\ 1 & x_{21} & x_{22} \\ \vdots & \vdots & \vdots \\ 1 & x_n & x_{n2} \end{bmatrix} \begin{bmatrix} w_0 \\ w_1 \\ w_2 \end{bmatrix}$$

- Solution remains the same $\mathbf{w} = (X^T X)^{-1} X^T Y$
- Exercise: open demo_multilinear.ipynb



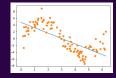
Outline

- 1 Polynomial Regression
- 2 Train and Test Error, Overfittin
- 3 Regularization



Polynomial Fitting

- We have been using linear model to fit our data. But it doesn't work well every time
- Some data have more complex relation that cannot be fitted well using a straight line
 - Ex: Projectile motion, Coulomb's law, Exponential growth/decay, ...



- Linear model does not look like a good fit for this data
- Can we use some other model to fit this data?



Polynomial Fitting

- Can we use a polynomial to fit our data?
- Polynomial: A sum of different powers of a variable
 - **Examples:** $y = x^2 + 2$, $y = 5x^3 3x^2 + 4$



■ New model: $f(x) = w_0 + w_1 x + w_2 x^2 + w_3 x^3 + ...$



Polynomial Fitting

- The process of fitting a polynomial is similar to linearly fitting multivariate data
- Recall the multivariable linear model
- $f(x) = w_0 + w_1x_1 + w_2x_2 + w_3x_3 + \dots$
 - Where x_1 , x_2 , x_3 ... are different features
- If we treat x^2 as our second feature, x^3 as our third feature, x^4 as our fourth feature.... We can use the same procedure in multivariate regression.



Design matrix with the original feature:

$$X = \begin{vmatrix} 1 & x_1 \\ 1 & x_2 \\ \vdots & \vdots \\ 1 & x_N \end{vmatrix}$$

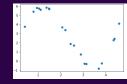
■ Design matrix with augmented polynomial features:

$$\Phi(X) = \begin{bmatrix} 1 & x_1 & x_1^2 & \cdots & x_1^D \\ 1 & x_2 & x_2^2 & \cdots & x_2^D \\ \vdots & & \ddots & & \vdots \\ 1 & x_N & x_N^2 & \cdots & x_N^D \end{bmatrix}$$

■ For the polynomial fitting, we just added columns of features that are powers of the original feature



■ You are given the data set below with x and y values



- Try to fit the data using a polynomial with a certain degree
- Calculate mean square error between the sample y and your predicted y
- Try different polynomial degree and see if you can improve the mse
- Plot your polynomial over the data points



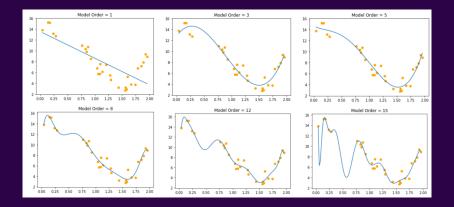
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- We learned how to fit our data using polynomials of different order
- With a higher model order, we can fit the data with increasing accuracy
- As you increase the model order, at certain point it is possible find a model that fits your data perfectly (ie. zero error)
- What could be the problem?

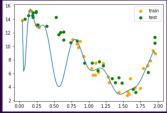




■ Which of these model do you think is the best? Why?

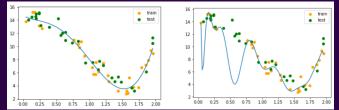


- The problem is that we are only fitting our model using data that is given
- Data usually contains noise
- When a model becomes too complex, it will start to fit the noise in the data
- What happens if we apply our model to predict some data that the model has never seen before? It will not work well.
- This is called over-fitting





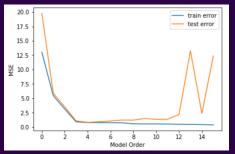
- Split the data set into a train set and a test set
- Train set will be used to train the model
- The test set will not be seen by the model during the training process
- Use test set to evaluate the model when a model is trained



■ With the training and test sets shown, which one do you think is the better model now?

Train and Test Error

- Plot of train error and test error for different model order
- Initially both train and test error go down as model order increase
- But at a certain point, test error start to increase because of overfitting





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■ **Regularization**: methods to prevent overfitting



How can we prevent overfitting without knowing the model order before-hand?

- **Regularization**: methods to prevent overfitting
 - We just covered regularization by model order selection



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- **Regularization**: methods to prevent overfitting
 - We just covered regularization by model order selection
- Is there another way? Talk among your classmates.



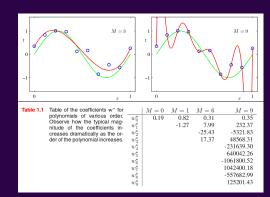
How can we prevent overfitting without knowing the model order before-hand?

- **Regularization**: methods to prevent overfitting
 - We just covered regularization by model order selection
- Is there another way? Talk among your classmates.
 - Solution: We can change our cost function.



Weight Based Regularization

- Looking back at the polynomial overfitting
- Notice that weight-size increases with overfitting





New Cost Function

$$J = \sum_{i=1}^{N} (y_i - \hat{y}_i)^2 + \lambda \sum_{j=1}^{D} (w_j)^2$$

- Penalize complexity by simultaneously minimizing weight values.
- We call λ a **hyper-parameter**
 - lacktriangle λ determines relative importance

Table 1.2 Table of the coefficients \mathbf{w}^* for $M = \lim_{n \to \infty} \lim_{n \to \infty} \lambda = -18 \lim$)
9 polynomials with various values for w_0^* 0.35 0.35 0.11	3
the regularization parameter λ . Note that $\ln \lambda = -\infty$ corresponds to a w_1^* 232.37 4.74 -0.03	5
model with no regularization, i.e., to w_2^{\star} -5321.83 -0.77 -0.00	5
the graph at the bottom right in Fig- w_3^* 48568.31 -31.97 -0.03	5
ure 1.4. We see that, as the value of w_4^* -231639.30 -3.89 -0.00	3
λ increases, the typical magnitude of w_5^* 640042.26 55.28 -0.00 the coefficients gets smaller.	2
w_6^{\star} -1061800.52 41.32 -0.0	l
w_7^* 1042400.18 -45.95 -0.00)
w_8^* -557682.99 -91.53 0.00)
w_9^* 125201.43 72.68 0.0	l



Tuning Hyper-parameters

- Motivation: never determine a hyper-parameter based on training data
- **Hyper-Parameter**: a parameter of the algorithm that is not a model-parameter solved for in optimization.
 - **E**x: λ weight regularization value vs. model weights (**w**)
- Solution: split dataset into three
 - Training set: to compute the model-parameters (w)
 - Validation set: to tune hyper-parameters (λ)
 - **Test set**: to compute the performance of the algorithm (MSE)

