ENME202 Matlab

POLYNOMIALS

Polynominal Functions:

- polyval() -- Evaluate a polynomial for a given input value
- roots() -- Find the roots of a polynomial
- conv() -- Multiply polynomials (convolution)
- deconv() -- Divide polynomials (deconvolution)
- poly() -- Create a polynomial from its roots
- polyfit() -- Create a polynomial to fit data points

Polynomials can be represented in Matlab by arrays of coefficients, starting with the highest power of x.

For example, the following array can be used to represent $p(x) = 2x^3 + 8x^2 + 12x + 8$:

polyval() evaluates a polynomial at a specified point, i.e. for a specific numerical value of the independent variable:

```
polyval(p, 0) % evaluate p(x) @ x=0
```

ans = 8

```
ans = 90.6568
```

Just to verify Matlab's answer manually:

-10.0000 -8.2980 -6.7840

```
x = 2.15;

2*x^3 + 8*x^2 + 12*x + 8
```

```
ans = 90.6567
```

In the previous example, x was a single value, but polyval can also evaluate the polynomial across an entire array of points:

```
x = -3:.1:3;
polyval(p, x) % returns an array with length(x) values
```

```
ans = 1×61
-10.0000 -8.2980 -6.7840 -5.4460 -4.2720 -3.2500 -2.3680 -1.6140 -0.9760
```

Of course, we could do the same thing with regular Matlab array arithmetic:

```
2*x.^3 + 8*x.^2 + 12*x + 8

ans = 1×61
```

-5.4460 -4.2720 -3.2500 -2.3680

-1.6140

-0.9760

The REAL reason for using Matlab's polynomial representation is that you can use a host of other polynomial functions. Let's check some of those out.

ROOTS

$$p = [1 \ 0 \ 0 \ 0 \ -1]$$

$$p = 1 \times 5$$

$$1 \ 0 \ 0 \ 0 \ -1$$

p is the array for the polynomial $p(x) = x^4 - 1$

Note that coefficients of "missing" powers of x are represented by zeros in the appropriate position of the coefficient array.

The **roots()** function will find the roots (zeros) of an arbitrary order polynomial. Since there are as many roots as the order of p (highest power of x), roots() will return an *array* with all the roots:

```
r = roots(p) % +/-1, +/-i (4 roots)

r = 4×1 complex
-1.0000 + 0.0000i
0.0000 + 1.0000i
0.0000 - 1.0000i
1.0000 + 0.0000i
```

Try with our earlier polynomial:

```
p = [2 8 12 8]; % 3rd order polynomial (4 elements)
r = roots(p) % 3 roots: -2, -1+/-i

r = 3×1 complex
    -2.0000 + 0.0000i
    -1.0000 + 1.0000i
    -1.0000 - 1.0000i
```

Since the roots function finds roots numerically, evaluating the polynomial at each root produces a number close, but not equal, to 0 due to numerical error!

```
polyval(p, r(1)) % ans = -1.5987e-014
ans = -8.8818e-15
```

POLYNOMIAL ARITHMETIC

Polynomial <u>addition</u> and <u>subtraction</u> is equivalent to adding/subtracting the coefficients of each array (but arrays must be same length!):

```
p1 = [1 \ 2 \ 3]; % p1(x) = x^2+2x+3

p2 = [3 \ 1]; % p2(x) = 3x+1

% p3 = p1 + p2; % Won't work -- arrays are different lengths
```

Need to "pad" the shorter coefficient array with leading zeros to make it the same length as the longer array in order to enable addition/subtraction:

```
p2 = [0 \ 3 \ 1]; % p2(x) = 0x^2 + 3x + 1

p3 = p1 + p2 % works!

p3 = 1 \times 3
```

Polynomial multiplication:

5

1

Uh oh...what went wrong?

Polynomial multiplication is much more complicated than addition. Matlab has a special function called **conv()** (convolution) for polynomial multiplication:

```
conv(p1,p2)

ans = 1×8

6  8  16  0  0  3  4  8
```

Note that no padding is needed for conv()

Above is the coefficient array for the product of $(2x^5+1)$ * $(3x^2+4x+8)$, which you can verify is correct by longhand calculation if you are particularly masochistic.

BUILDING A POLYNOMIAL FROM ITS ROOTS

What if we were given the roots, and needed to find the corresponding polynomial?

We could use the roots to assemble the polynomial in its factored form by multiplying together all N of the first order factors (x-r(k)), where k = 1, 2, ..., N.

Let's start with the just two roots (since conv only takes two arguments):

```
p1 = conv([1 - r(1)], [1 - r(2)])

p1 = 1 \times 3 complex
```

```
1.0000 + 0.0000i 3.0000 - 1.0000i 2.0000 - 2.0000i
```

Then multiply the third polynomial by the result of the first product stored in the variable (here pt):

Check against original polynomial:

```
p % [2 8 12 8] = 2 * p2

p = 1×4

2 8 12 8
```

Note that the original polynomial isn't "monic", so we need to multiply the product of the factors by the coef of the highest power of x to recover the original polynomial:

```
2 * p2 % ans = [2 8 12 8]

ans = 1×4 complex
2.0000 + 0.0000i 8.0000 + 0.0000i 12.0000 + 0.0000i 8.0000 + 0.0000i
```

We could also nest multiple conv() functions to accomplish the above in a single line:

```
2 * conv( conv([1 -r(1)], [1 -r(2)]), [1 -r(3)])

ans = 1×4 complex
2.0000 + 0.0000i 8.0000 + 0.0000i 12.0000 + 0.0000i 8.0000 + 0.0000i
```

Ok, well that was a lot of work!! Now, let's do it the easy way using **poly()**.

poly() is a built-in command to expand a polynomial as the product of its first-order factors:

```
pp = poly(r) % pp = [1 4 6 4]

pp = 1×4

1.0000 4.0000 6.0000 4.0000
```

Same (monic) result as we got from conv above, but with a single function call. Very convenient!

POLYNOMIAL CURVE FITTING

Matlab can create a polynomial to fit a data set based on a least squares algorithm. Before investigating this, let's talk about saving and loading Matlab data files using the save() and load() functions:

- save(filename) --> save current workspace variables to the named file
- load(filename) --> load vaiables from named file to current workspace

Let's load two array variables from a file called sunspots.txt. This is a text file containing two columns: column 1 = observation year, and column 2 = average monthly number of sunspots observed.

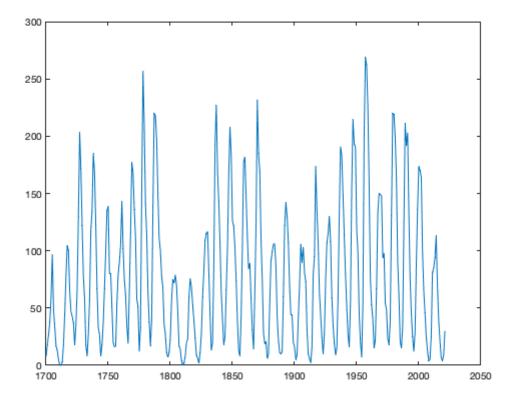
```
load('sunspots.txt', 'ascii') % sunspots.txt must be in current path
```

The "ascii" part of this function tells Matlab to load the data from a plain ASCII text file. After loading, there will be a new workspace variable with the same name as the file name (sunspots), which is an array containing the two data columns from the file:

```
sunspots
sunspots = 322 \times 2
                           8
         1700
         1701
                          18
                          27
         1702
         1703
                          38
         1704
                          60
                          97
         1705
         1706
                          48
         1707
                          33
         1708
                          17
         1709
                          13
```

Break 'sunspots' up into two separate variables for easier manipulation:

```
year = sunspots(:,1); % slice 1st column
spots = sunspots(:,2); % slice 2nd column
plot(year, spots)
```



Let's look only at the data since 1980. An easy way to do this is with the find() function:

```
idx = find(year==1980); % returns a single index
```

```
year = year(idx:end);
spots = spots(idx:end);
```

...or an alternate version of find():

```
indices = find(year>=1980); % returns an array of indices
year = year(indices);
spots = spots(indices);
```

Plot the result:

```
plot(year, spots, 'o-')
xlabel('Year')
ylabel('# of sunspots')
```

Now let's fit a polynominal curve to the data. The **polyfit()** function returns an array of coefficients for the polynomial that best fits the given data by minimizing the square of the error between the polynomial and data values (least squares method).

The polyfit() fuction takes 3 arguments:

- 1. x coordinates of data
- 2. y coordinates of data
- 3. order of the polynomial to fit

First, let's convert the year to a relative year (since 1980). The reason for this will be explained shortly:

```
delta_year = year - min(year);
pp = polyfit(delta_year, spots, 3);
```

Recall that polyval() converts a polynomial to an array of y-axis values for a given array of x-values. Let's use this to evaluate the polynomial against the original x data coordinates to see how well the function fits the data:

```
hold on
fit = polyval(pp, delta_year);
plot(year, fit, 'r-')
```

Not very well here for a third order poly, so try a higher order:

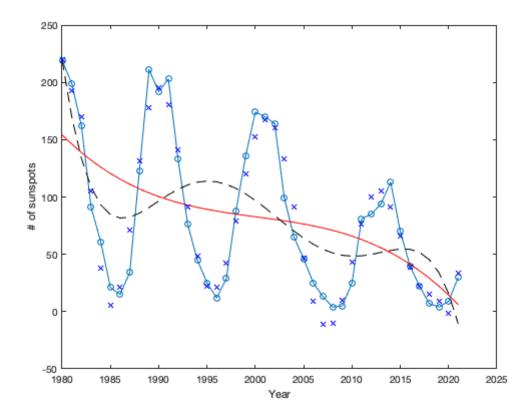
```
pp = polyfit(delta_year, spots, 5);
fit = polyval(pp, delta_year);
plot(year, fit, 'k--')
```

Even higher order:

```
pp = polyfit(delta_year, spots, 12);
```

Warning: Polynomial is badly conditioned. Add points with distinct X values, reduce the de

```
fit = polyval(pp, delta_year);
plot(year, fit, 'bx')
```



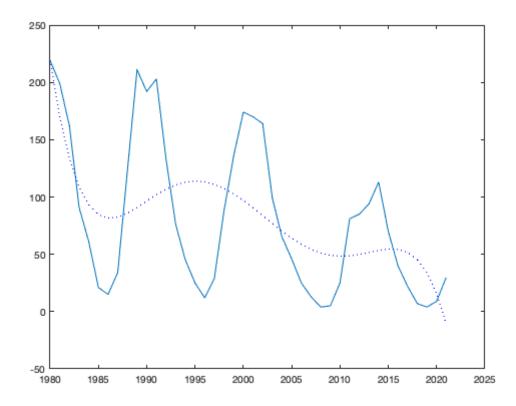
The resulting 12th order polynomial is "ill conditioned", meaning that in the calculation of the polynomial there was an operation that involved a near-singular matrix (a matrix close to not having an inverse). This is not necessarily a problem, but it is important to check the result to make sure the fit is acceptable.

What would have happened if we used the *absolute* year instead of the relative year?

```
clf
pp = polyfit(year, spots, 5);

Warning: Polynomial is badly conditioned. Add points with distinct X values, reduce the de

plot(year, spots)
hold on
plot(year, polyval(pp, year), 'b:')
```



What happened? The polynomial is trying to fit data far from the origin, without any intervening data to "guide" the fit, resulting in a poor fit.

POLYNOMIAL DIVISION

Like polynomial multiplication, Matlab can also do polynomial division using the **deconv()** function.

Note that in general:

```
p1(x)/p2(x) = q(x) + r(x)/p2(x)
```

- q(x) is the "quotient" polynomial
- r(x) is the "remainder" polynomial

$$p1 = [2 6 8 4];$$
 % $p1(x) = 2x^3+6x^2+8x+4$
 $p2 = [1 2 2];$ % $p2(x) = x^2+2x+2$
 $[q,r] = deconv(p1,p2)$

$$q = 1 \times 2$$
 $2 \qquad 2$
 $r = 1 \times 4$
 $0 \qquad 0 \qquad 0 \qquad 0$

If you do this by hand, you should find that

$$p1(x)/p2(x) = x+4$$
 with remainder -2x-4

So in Matlab, q(x) = x+4 for this problem, and r(x) = -2x-4

Given q,r we can reconstruct the original polynomial as:

$$p1(x) = q(x)*p2(x) + r(x)$$

Note that r is automatically padded to the correct length so that we can reconstruct the original (p1) polynomial from:

$$conv(q, p2) + r$$
 % ans = [1 6 8 4]
ans = 1×4
2 6 8 4

A different example:

```
p2 = [1 1];
                    % p2 = x + 1
[q,r] = deconv(p1, p2) % x^3+6x^2+8x+4 / x+1
q = 1 \times 3
     2
           4
                  4
r = 1 \times 4
     0
                        0
conv(q, p2) + r
                            % same quotient as above but new remainder
ans = 1 \times 4
     2
                        4
           6
                  8
```

A note about Matlab data files:

The above year & spot data were loaded from a text file (ascii format containing values separated by white space or commas). However, data can also be saved in a '.mat' data file, which may be in a custom format defined by Matlab via the "save workspace" command.

Use the "load" command to load data from a .mat file (the extension may be ommitted). For example, if you have a file called mydata.mat, load the data as:

load('mydata')

or

load mydata

A new variable called mydata will be created automatically.

When loading plain ascii text data, give the full file name (with extension), and add '-ascii' to the load command:

load('mydata.txt', '-ascii')