```
□ int main(void) {
         Complex z;
         Complex res;
         Cout << "Enter real and imag parts of z: ";
         Cin >> z; // Converts to operator>>(cin,z)
          res = z*2.5; // Converts z*2.5 to operator*(z,2.5)
         cout << "z*2.5 = " << res << endl; // Converts to operator<</pre>
          res = 2.5*z; // Converts 2.5*z to operator*(2.5,z)
     ☐ Complex operator*(Complex foo, float f) {
          Complex bas;
          bas.a = foo.a * f;
         bas.b = foo.b * f;
          return bas;
37 	☐ Complex operator+(Complex foo, Complex bar) {
         // Implement rules of complex number addition
         bas.a = foo.a + bar.a;
         bas.b = foo.b + bar.b;
         return bas;
```



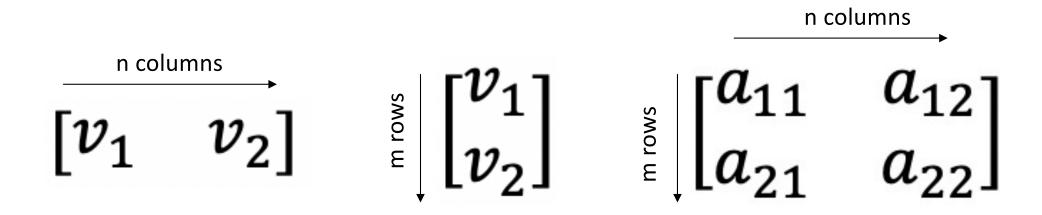
ENME 202

Linear Algebra Review

Vectors and Matrices



- A row vector is a 1 x n (rows x columns) list of values
- A column vector is an m x 1 (rows x columns) list of values
- A matrix is an m x n (rows x columns) array of values



1x2 row vector

2x1 column vector

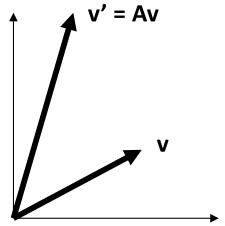
2x2 matrix

Vectors and Matrices



- An nx1 column vector can be interpreted as a <u>line</u> in n-dimensional space
- An mxn matrix can be interpreted as a <u>transformation</u> acting on a column vector

$$\begin{bmatrix} v_1' \\ v_2' \end{bmatrix} = \begin{bmatrix} a_{11} & a_{12} \\ a_{21} & a_{22} \end{bmatrix} \begin{bmatrix} v_1 \\ v_2 \end{bmatrix}$$



Dot Product



Dot product of two row vectors *v* and *w*:

$$v \cdot w = vw^T = \begin{bmatrix} v_1 & v_2 \end{bmatrix} \begin{bmatrix} w_1 \\ w_2 \end{bmatrix} = v_1w_1 + v_2w_2$$

The dot product of a vector with itself is equal to the square of the magnitude (length) of the vector:

$$||v||^2 = v \cdot v = v_1^2 + v_2^2 + \dots + v_n^2$$

→ The dot product can provide a measure of vector length

The dot product is also defined geometrically as:

$$v_1 \cdot v_2 = ||v_1|| ||v_2|| \cos \theta$$

→ The dot product can provide a measure of the angle between two vectors

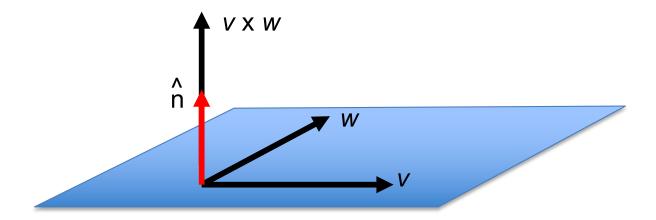
Cross Product



Cross product of two vectors *v* and *w*:

$$v \times w = ||v|| ||w|| \sin \theta \hat{n}$$

• \hat{n} is a unit vector perpendicular to v and w, with direction defined by the *right hand rule*



 \rightarrow The cross product can be used to define the <u>plane</u> in which vectors v and w lie

Matrix Addition



Addition

$$\begin{bmatrix} a & b \\ c & d \end{bmatrix} + \begin{bmatrix} e & f \\ g & h \end{bmatrix} = \begin{bmatrix} a+e & b+f \\ c+g & d+h \end{bmatrix}$$

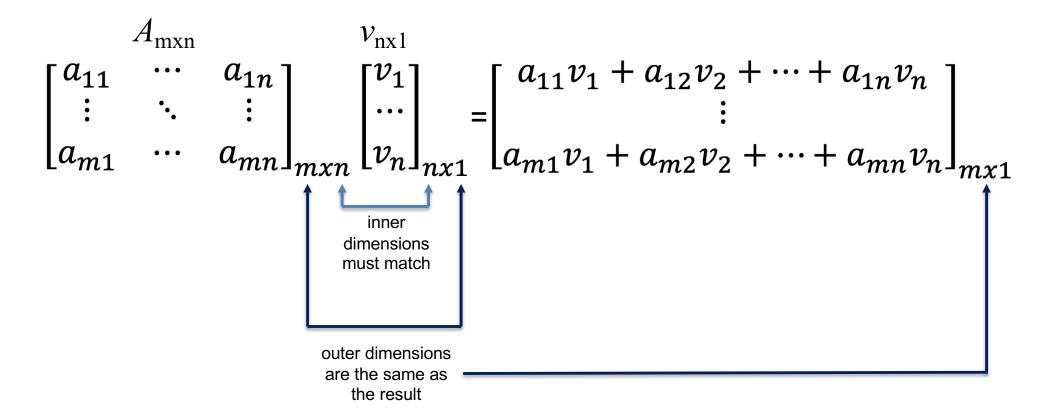
Subtraction

$$\begin{bmatrix} a & b \\ c & d \end{bmatrix} - \begin{bmatrix} e & f \\ g & h \end{bmatrix} = \begin{bmatrix} a - e & b - f \\ c - g & d - h \end{bmatrix}$$

Matrices must have the same dimensions for addition to be valid

Matrix-Vector Multiplication





Matrix-Vector Multiplication



We can instead think about
$$A$$
 as a column vector of row vectors to evaluate the product:
$$\begin{bmatrix} A_1^r \\ A_2^r \\ \vdots \\ A_m^r \end{bmatrix} v = \begin{bmatrix} A_1^r v \\ A_2^r v \\ \vdots \\ A_m^r v \end{bmatrix}$$

Alternately, decompose A into a row vector of column vectors and take the weighted sum:

$$[A_1^c \ A_2^c \ \cdots \ A_n^c] \begin{bmatrix} v_1 \\ v_2 \\ \vdots \\ v_n \end{bmatrix} = A_1^c v_1 + A_2^c v_2 + \cdots + A_n^c v_n$$

Matrix-Matrix Multiplication



$$\begin{bmatrix} a_{11} & a_{12} & \cdots & a_{1n} \\ a_{21} & a_{21} & \cdots & a_{2n} \\ \vdots & \vdots & \ddots & \vdots \\ a_{m1} & a_{m2} & \cdots & a_{mn} \end{bmatrix}_{mxn} \begin{bmatrix} b_{11} \\ b_{21} \\ \vdots \\ b_{n1} \end{bmatrix}$$

← Recall matrix-vector multiplication

$$= \begin{bmatrix} A_1^r \\ A_2^r \\ \vdots \\ A_m^r \end{bmatrix} [B_1^c]$$

$$= \begin{bmatrix} A_1^r B_1^c \\ A_2^r B_1^c \\ \vdots \\ A_m^r B_1^c \end{bmatrix}$$

Matrix-Matrix Multiplication



$$\begin{bmatrix} a_{11} & a_{12} & \cdots & a_{1n} \\ a_{21} & a_{21} & \cdots & a_{2n} \\ \vdots & \vdots & \ddots & \vdots \\ a_{m1} & a_{m2} & \cdots & a_{mn} \end{bmatrix}_{mxn} \begin{bmatrix} b_{11} & b_{12} \\ b_{21} & b_{21} \\ \vdots & \vdots \\ b_{n1} & b_{n2} \end{bmatrix}_{nx2} \leftarrow \text{Add a second column...}$$

$$\begin{bmatrix} b_{11} & b_{12} \ b_{21} & b_{21} \ dots & dots \ b_{n1} & b_{n2} \end{bmatrix}$$

$$= \begin{bmatrix} A_1^r \\ A_2^r \\ \vdots \\ A_m^r \end{bmatrix} \begin{bmatrix} B_1^c & B_2^c \end{bmatrix}$$

$$= \begin{bmatrix} A_1^r B_1^c & A_1^r B_2^c \\ A_2^r B_1^c & A_2^r B_2^c \\ \vdots & \vdots \\ A_m^r B_1^c & A_m^r B_2^c \end{bmatrix}$$

Matrix-Matrix Multiplication



$$\begin{bmatrix} a_{11} & a_{12} & \cdots & a_{1n} \\ a_{21} & a_{21} & \cdots & a_{2n} \\ \vdots & \vdots & \ddots & \vdots \\ a_{m1} & a_{m2} & \cdots & a_{mn} \end{bmatrix}_{mxn} \begin{bmatrix} b_{11} & b_{12} & \cdots & b_{1p} \\ b_{21} & b_{21} & \cdots & b_{2p} \\ \vdots & \vdots & \ddots & \vdots \\ b_{n1} & b_{n2} & \cdots & b_{np} \end{bmatrix}_{nxp}$$

$$= \begin{bmatrix} A_1^r \\ A_2^r \\ \vdots \\ A_m^r \end{bmatrix} \begin{bmatrix} B_1^c & B_2^c & \cdots & B_p^c \end{bmatrix} = \begin{bmatrix} A_1^r B_1^c & A_1^r B_2^c & \cdots & A_1^r B_p^c \\ A_2^r B_1^c & A_2^r B_2^c & \cdots & A_n^r B_p^c \\ \vdots & \vdots & \ddots & \vdots \\ A_m^r B_1^c & A_m^r B_2^c & \cdots & A_m^r B_p^c \end{bmatrix}_{mxp}$$

• 2x2 example:

$$\begin{bmatrix} a & b \\ c & d \end{bmatrix} \begin{bmatrix} e & f \\ g & h \end{bmatrix} = \begin{bmatrix} ae + bg & af + bh \\ ce + dg & cf + dh \end{bmatrix}$$

Note that matrix multiplication is not commutative

Identity Matrix



Identity matrix (3x3):

$$I = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

For any <u>square</u> matrix A:

$$AI = IA = A$$

Some square matrices have an <u>inverse</u>, such that:

$$AA^{-1} = A^{-1}A = I$$

Determinant of a Matrix: |A|



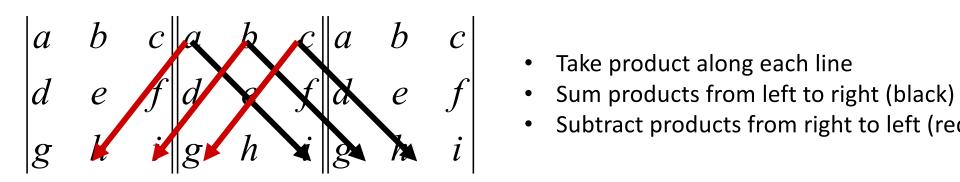
- The determinant can be interpreted as a <u>scaling</u> factor for the linear transformation defined by the matrix
- If |A| = 0 then A has no inverse
- Determinant of a 2x2 Matrix:

$$A = \begin{bmatrix} a & b \\ c & d \end{bmatrix} \qquad |A| = ad - bc$$

Determinant of a 3x3 Matrix



$$\begin{vmatrix} a & b & c \\ d & e & f \\ g & h & i \end{vmatrix} = aei + bfg + cdh - afh - bdi - ceg$$



- Take product along each line
- Subtract products from right to left (red)

Matrix Inversion



adjoint matrix cofactor matrix
$$A^{-1} = \frac{adj(A)}{|A|} = \frac{cof(A)^{T}}{|A|}$$

The <u>cofactor</u> matrix is a matrix formed by the determinants of the minors of A_{ij} multiplied by -1^{i+j} .

Each <u>minor</u> term is defined by the matrix A with the ith row and jth column removed.

$$A = \begin{bmatrix} a & b \\ c & d \end{bmatrix} \qquad A^{-1} = \frac{1}{ad - bc} \begin{bmatrix} d & -b \\ -c & a \end{bmatrix}$$